

Asynchronous Development

Lecture 5

Asynchronous Development

- Concurrency
- Asynchronous Executor
- Future s
- Communication between tasks



Concurrency

Preemptive and Cooperative

Bibliography

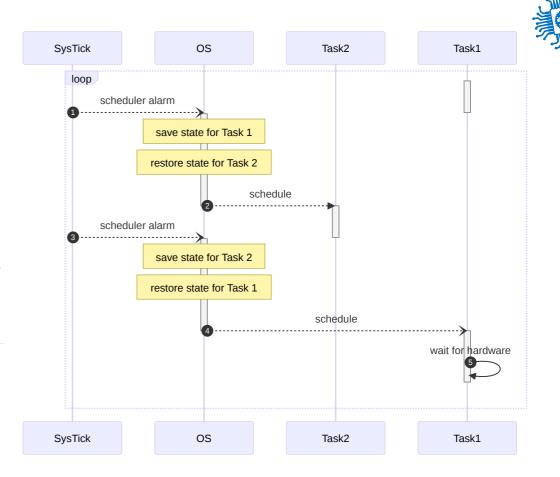
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Brad Solomon, Async IO in Python: A Complete Walkthrough



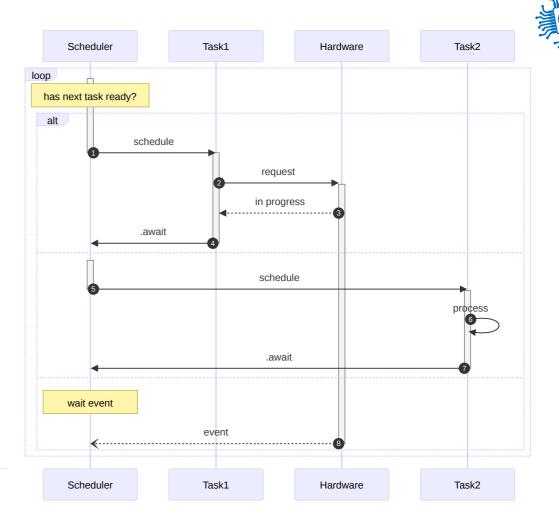
Preemptive Concurrency

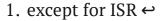
- MCUs are usually *single core*[1]
- Tasks in parallel require an OS^[2]
- Tasks can be suspended at any time
- Switching the task is expensive
- Tasks that do a lot of I/O which makes the switching time longer than the actual processing time
- 1. RP2040 is a dual core MCU, we use only one core ←
- 2. Running in an ISR is not considered a normal task ↔



Cooperative Concurrency

- tasks cannot be interrupted^[1]
- hardware works in an asynchronous way
- tasks cooperate
 - give up the MCU for other tasks to use it while they wait for hardware
- there is no need for an OS,
 everything is done in one single
 flow
- no penalty for saving and restoring the state







Asynchronous Executor

of Embassy

Bibliography

for this section

Embassy Documentation, *Embassy executor*



Tasks



- #[embassy_executor::main]
 - starts the Embassy scheduler
 - defines the main task
- #[embassy_executor::task] defines a new
 task
 - pool_size -is optional and defines how many
 identical tasks can be spawned
- the main task
 - initializes the the led
 - spawns the led_blink task (adds to the scheduler)
 - uses .await to give up the MCU while waiting form the button

```
#[embassy executor::task(pool size = 2)]
     async fn led blink(mut led:Output<'static, PIN X>) {
         loop {
             led.toogle();
             Timer::after secs(1).await;
 8
     #[embassy executor::main]
     async fn main(spawner: Spawner) {
11
12
         // init led
         spawner.spawn(led blink(led)).unwrap();
14
15
         info!("task started");
16
         // init button
18
         loop {
             button.wait for rising edge().await;
19
20
             info!("button pressed");
```

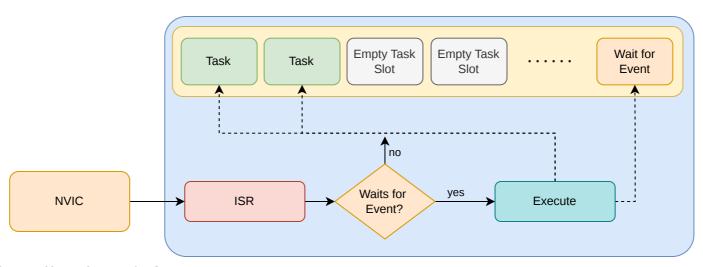
Tasks can stop the executor

- unless awaited, async functions are not executed
- tasks have to use .await in loops, otherwise they block the scheduler

```
#[embassy executor::task]
     async fn led blink(mut led:Output<'static, PIN X>) {
         loop {
             led.toogle();
             // this does not execute anything
             Timer::after secs(1);
             // infinite loop without `.await`
             // that never gives up the MCU
11
     #[embassy executor::main]
     async fn main(spawner: Spawner) {
         loop {
             button.wait for rising edge().await;
             info!("button pressed");
19 }
```

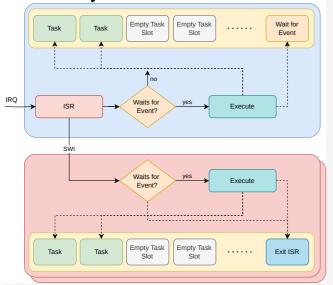






- sleep when all tasks wait for events
- after an ISR is executed
 - if waiting for events, ask every task if it can execute (if the IRQ was what the task was .await ing for)
 - if a task is executing, continue the task until it .await s
- if a task never . await s, the executor does not run and never executes another task

Priority Tasks



```
#[interrupt]
unsafe fn SWI_IRQ_1() {
    EXECUTOR_HIGH.on_interrupt()
}
#[interrupt]
unsafe fn SWI_IRQ_0() {
    EXECUTOR_MED.on_interrupt()
}
```

```
static EXECUTOR HIGH: InterruptExecutor = InterruptExecutor::new();
     static EXECUTOR MED: InterruptExecutor = InterruptExecutor::new();
     static EXECUTOR LOW: StaticCell<Executor> = StaticCell::new();
     #[entry]
     fn main() -> ! {
         // High-priority executor: SWI IRQ 1, priority level 2
         interrupt::SWI IRQ 1.set priority(Priority::P2);
         let spawner = EXECUTOR HIGH.start(interrupt::SWI IRQ 1);
 9
10
         spawner.spawn(run high()).unwrap();
11
12
         // Medium-priority executor: SWI IRQ 0, priority level 3
13
         interrupt::SWI IRQ 0.set priority(Priority::P3);
         let spawner = EXECUTOR MED.start(interrupt::SWI IRQ 0);
14
15
         spawner.spawn(run med()).unwrap();
16
17
         // Low priority executor: runs in thread mode, using WFE/SEV
         let executor = EXECUTOR LOW.init(Executor::new());
18
19
         executor.run(|spawner| {
20
             unwrap!(spawner.spawn(run low()));
21
         });
22
```

priority executors run in ISRs, lower priority tasks are interrupted



The Future type

a.k.a Promise in other languages

Bibliography

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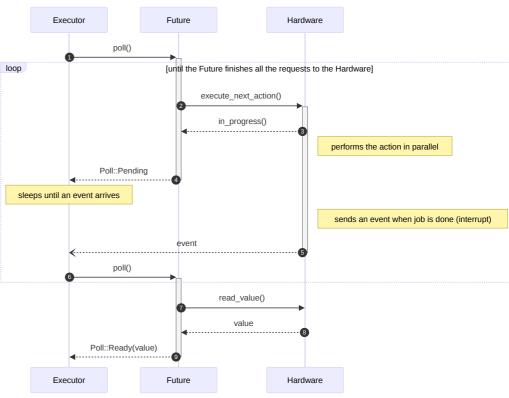
Bert Peters, *How does async Rust work*



Future

```
enum Poll<T> {
    Pending,
    Ready(T),
trait Future {
   type Output;
   fn poll(&mut self) -> Poll<Self::Output>;
fn execute<F>(mut f: F) -> F::Output
where
  F: Future
  loop {
   match f.poll() {
      Poll::Pending => wait_for_event(),
      Poll::Ready(value) => break value
```





Implementing a Future

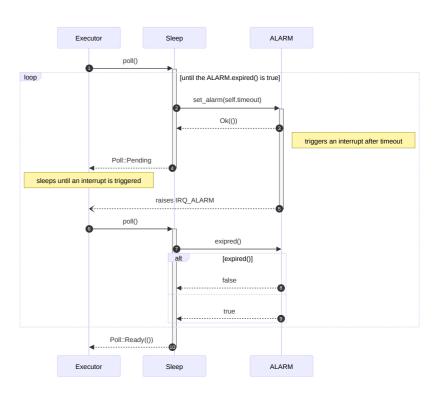
```
enum SleepStatus {
         SetAlarm.
         WaitForAlarm.
     struct Sleep {
         timeout: usize,
         status: SleepStatus,
 9
10
11
     impl Sleep {
         pub fn new(timeout: usize) -> Sleep {
12
13
             Sleep {
14
                 timeout,
15
                 status: SleepStatus::SetAlarm,
16
18 }
```

```
impl Future for Sleep {
   type Output = ();
    fn poll(&mut self) -> Poll<Self::Output> {
       match self.status {
            SleepStatus::SetAlarm => {
               ALARM.set alarm(self.timeout);
                self.status = SleepStatus::WaitForAlarm;
                Poll::Pending
            SleepStatus::WaitForAlarm => {
                if ALARM.expired() {
                    Poll::Ready(())
               } else {
                    Poll::Pending
```

Executing Sleep

```
道图》
```

```
impl Future for Sleep {
    type Output = ();
    fn poll(&mut self) -> Poll<Self::Output> {
        match self.status {
            SleepStatus::SetAlarm => {
                ALARM.set alarm(self.timeout);
                self.status = SleepStatus::WaitForAlarm;
                Poll::Pending
            SleepStatus::WaitForAlarm => {
                if ALARM.expired() {
                    Poll::Ready(())
               } else {
                    Poll::Pending
```



Async Rust

```
async fn blink(mut led: Output<'static, PIN_X>) {
    led.on();
    Timer::after_secs(1).await;
    led.off();
}
```

Rust rewrites

```
struct Blink {
    // status
    status: BlinkStatus,
   // local variables
    led: Output<'static, PIN X>,
    timer: Option<impl Future>,
impl Blink {
  pub fn new(led: Output<'static, PIN X>) -> Blink {
    Blink { status: BlinkStatus::Part1, led, timer: None }
fn blink(led: Output<'static, PIN_X>) -> Blink {
    Blink::new(led)
```



```
impl Future for Blink {
 type Output = ();
 fn poll(&mut self) -> Poll<Self::Output> {
   loop {
     match self.status {
        BlinkStatus::Part1 => {
          self.led.on();
          self.timer1 = Some(Timer::after secs(1));
          self.status = BlinkStatus::Part2:
        BlinkStatus::Part2 => {
          if self.timer.unwrap().poll() == Poll::Pending {
            return Poll::Pending;
         } else {
            self.status = BlinkStatus::Part3;
        BlinkStatus::Part3 => {
          self.led.off();
         return Poll::Ready(());
```

Async Rust



- the Rust compiler rewrites async function into Future
- it does not know how to execute them
- executors are implemented into third party libraries

```
use engine::execute;
     // Rust rewrites the function to a Future
     async fn blink(mut led: Output<'static, PIN_X>) {
         led.on();
         Timer::after_secs(1).await;
         led.off();
 9
     #[entry]
     fn main() -> ! {
12
         blink(); // this returns the Blink future, but does not execute it
13
         blink().await; // does not work, as 'main' is not an 'async' function
14
         execute(blink()); // this works, as `execute` executes the Blink future
15 }
```





```
static TASKS: [Option<impl Future>; N] = [None, N];
     fn executor() {
         loop {
             // ask all tasks to continue if they have available data
             for task in TASKS.iter mut() {
                 if let Some(task) = task {
                     if Poll::Ready( ) = task.poll() {
                         *task = None
11
12
13
             // wait for interrupts
14
             cortex m::asm::wfi();
15
16
```

- this is a simplified version, Option<impl Future> does not work
- the executor is not able to use TASKS like this
- an efficient executor will not poll all the tasks, it uses a waker that tasks use to signal the executor

The Future trait

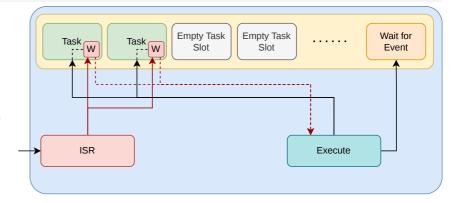


that Rust provides

```
trait Future {
    type Output;

fn poll(mut self: std::pin::Pin<&mut Self>, cx: &mut Context<'_>) -> Poll<Self::Output>;
}
```

- Pin to mut self, which means that self cannot be moved
- Context which provides the waker
 - tasks are polled only if they ask the executor (by using the wake function)
- embassy-rs provides the execution engine





Communication

between tasks



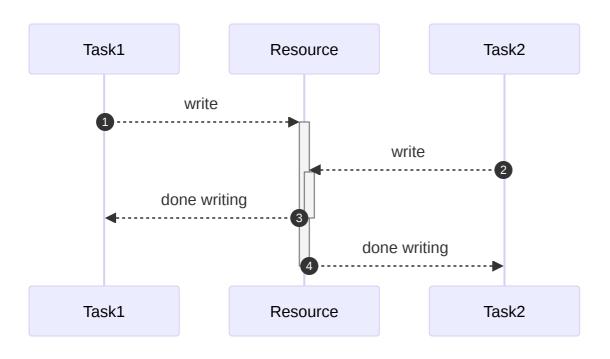
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Omar Hiari, Sharing Data Among Tasks in Rust Embassy: Synchronization Primitives

Simultaneous Access

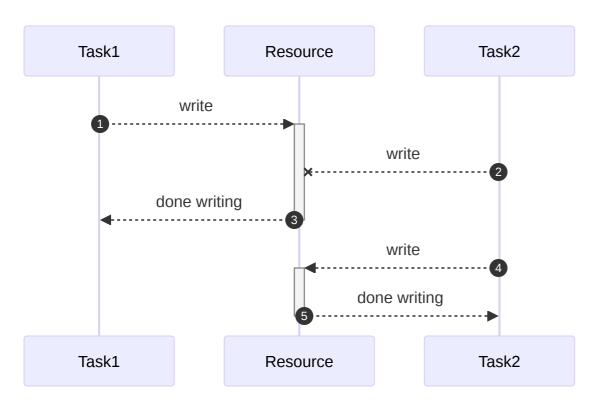
Rust forbids simultaneous writes access





Exclusive Access

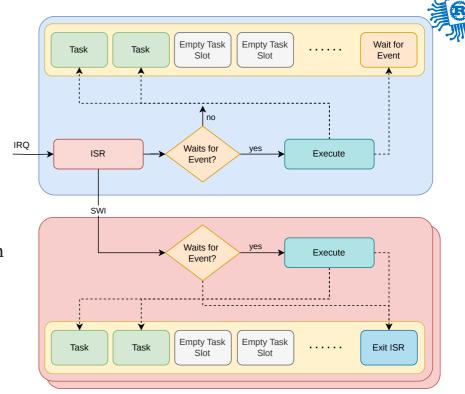
we want to sequentiality access the resource



Synchronization

safely share data between tasks

- NoopMutex used for data shared between tasks
 within the same executor
- Critical SectionMutex used for data shared
 between multiple executors, ISRs and cores
- ThreadModeMutex used for data shared between tasks within low priority executors (not running in ISRs mode) running on a single core



- ISRs are executed in parallel with tasks
- embassy allows registering priority executors, that run tasks in ISRs
- some MCUs have multiple cores

Blocking Mutex



no .await allowed while the mutex is held

```
use embassy sync::blocking mutex::Mutex;
     struct Data {/* ... */ }
     static SHARED_DATA: Mutex<ThreadModeRawMutex, RefCell<Data>> = Mutex::new(RefCell::new(Data::new(/* ... */)));
 6
     #[embassy executor::task]
     async fn task1() {
         // Load value from global context, modify and store
         SHARED_DATA.lock(|f| {
10
             let data = f.borrow_mut();
11
12
            // edit data
13
            f.replace(data);
14
        });
15 }
```



Async Mutex

. await is allowed while the Mutex is held, it will release the Mutex while await ing

```
use embassy sync::mutex::Mutex;
     struct Data {/* ... */ }
     static SHARED: Mutex<ThreadModeRawMutex, Data> = Mutex::new(Data::new(/* ... */));
 6
     #[embassy executor::task]
     async fn task1() {
         // Load value from global context, modify and store
10
             let mut data = SHARED_DATA.lock().await;
11
12
             // edit *data
13
             Timer::after(Duration::from_millis(1000)).await;
14
15 }
```





send data from a task to another

Embassy provides four types of channels synchronized using Mutex s

Type	Description
Channel	A Multiple Producer Multiple Consumer (MPMC) channel. Each message is only received by a single consumer.
PriorityChannel	A Multiple Producer Multiple Consumer (MPMC) channel. Each message is only received by a single consumer. Higher priority items are shifted to the front of the channel.
Signal	Signalling latest value to a single consumer.
PubSubChannel	A broadcast channel (publish-subscribe) channel. Each message is received by all consumers.

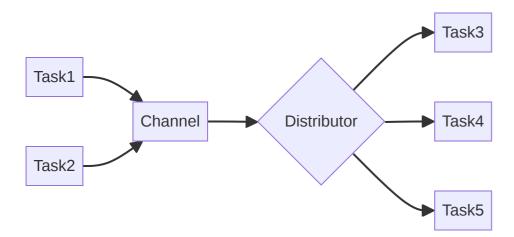
Channel and Signal



sends data from one task to another

Channel - A Multiple Producer Multiple Consumer (MPMC) channel. Each message is only received by a single consumer.

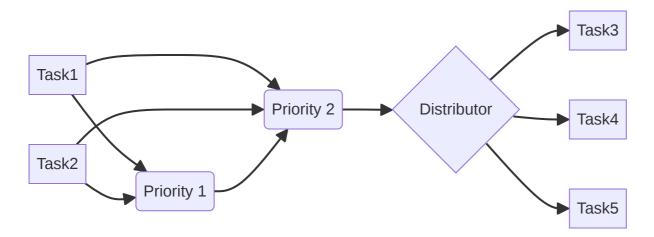
Signal - Signalling latest value to a single consumer.





sends data from one task to another with a priority

PriorityChannel - A Multiple Producer Multiple Consumer (MPMC) channel. Each message is only received by a single |consumer. Higher priority items are shifted to the front of the channel.

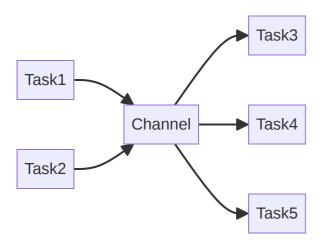






sends data from one task to all receiver tasks

PubSubChannel - A broadcast channel (publish-subscribe) channel. Each message is received by all consumers.





Channel Example

```
enum LedState { On, Off }
     static CHANNEL: Channel<ThreadModeRawMutex, LedState, 64> = Channel::new();
     #[embassy executor::main]
     async fn main(spawner: Spawner) {
         // init led
         spawner.spawn(execute led(CHANNEL.sender(), Duration::from millis(500))));
         loop {
             match CHANNEL.receive().await {
                 LedState::On => led.on(),
10
                 LedState::Off => led.off()
11
12
13
14
15
     #[embassy executor::task]
16
     async fn execute led(control: Sender<'static, ThreadModeRawMutex, LedState, 64>, delay: Duration) {
17
18
         let mut ticker = Ticker::every(delay);
19
         loop {
             control.send(LedState::On).await;
20
             ticker.next().await;
21
             control.send(LedState::Off).await;
22
23
             ticker.next().await;
24
```

Conclusion

we discussed about

- Preemptive & Cooperative Concurrency
- Asynchronous Executor
- Future s and how Rust rewrites async function
- Communication between tasks

