# Math 502AB - Lecture 18

Dr. Jamshidian

October 30, 2017

# 1 Lecture - Part 1

# 1.1 Relationships Between Various Modes of Convergence

1.  $X_n \xrightarrow{D} X \not\Rightarrow X_n \xrightarrow{P} X$ 

# Example:

Let  $X \sim unif(-1,1)$ . This implies that  $-X \sim unif(-1,1)$ .

$$X_n = \begin{cases} x & \text{if } n \text{ is odd} \\ -x & \text{if } n \text{ is even} \end{cases}$$

Clearly, we have:

$$X_n \xrightarrow{\mathrm{D}} X$$

However, consider:

$$|X_n - X| = \begin{cases} 0 & \text{if } n \text{ is odd} \\ 2|X| & \text{if } n \text{ is even} \end{cases}$$

Let  $\epsilon = 1$ . Then:

$$P(|X_n - X| < 1) = \begin{cases} 1 & \text{if } n \text{ is odd} \\ P(2|X| < 1) = P(|X| < \frac{1}{2}) = \frac{1}{2} & \text{if } n \text{ is even} \end{cases}$$

This shows the above: that convergence in *distribution* does not imply convergence in *probability*.

2. **Theorem:** If  $X_n \xrightarrow{P} X$ , then  $X_n \xrightarrow{D} X$ . This essentially says that convergence in *distribution* is the weakest kind of convergence we ahve talked about.

3. Theorem:  $X_n \xrightarrow{P} a \iff X_n \xrightarrow{D} a$ Proof:

 $(\Rightarrow)$ : This follows from the above theorem.

 $(\Leftarrow)$ : Assume that  $X_n \xrightarrow{\mathcal{D}} a$ . This means that:

$$F_{X_n}(x) \to F_X(x) = \begin{cases} 1 & x \ge a \\ 0 & x < a \end{cases}$$

Let  $\epsilon > 0$ . We then look at the limit:

$$\lim_{n \to \infty} P[|X_n - a| < \epsilon] = \lim_{n \to \infty} P[a - \epsilon \le X_n \le a + \epsilon]$$

$$= \lim_{n \to \infty} F_{X_n}(a + \epsilon) - F_{X_n}(a - \epsilon)$$

$$= 1$$

- 4. **Theorem:** Suppose that  $X_n \xrightarrow{D} X$ , and that g is a continuous function on the support of X. Then  $g(X_n) \xrightarrow[n \to \infty]{D} g(x)$ . (The proof of this theorem requires measure theory)
- 5. **Theorem:** (Slutsky's Theorem) Let  $X_n \xrightarrow{D} X$  and  $Y_n \xrightarrow{P} a$ . Then:
  - (a)  $X_n Y_n \xrightarrow{D} aX$
  - (b)  $X_n + Y_n \xrightarrow{D} X + a$

Example: Show that:

$$\frac{\sqrt{n}(\overline{X}_n - \mu)}{S_n} \xrightarrow{\mathbf{D}} N(0, 1)$$

If  $\lim_{n\to\infty} Var(S_n^2) = 0$ , then we have  $S_n^2 \xrightarrow{\mathcal{P}} \sigma^2$ . This implies that:

$$\Rightarrow \frac{S_n^2}{\sigma^2} \xrightarrow{P} 1 \Rightarrow \sqrt{\frac{S_n^2}{\sigma^2}} = \frac{S_n}{\sigma} \xrightarrow{P} 1$$

By the Central Limit Theorem:

$$\frac{\sqrt{n}(\overline{X}_n - \mu)}{\sigma} \xrightarrow{\mathcal{D}} N(0, 1)$$

By **Slutsky's theorem**, if we multiply this by  $\frac{\sigma}{S_n}$  (which converges to 1 as shown above), we get the Example result.

#### 1.2 The Delta Method

**Idea:** The general idea of the delta method is to approximate non-linear functions by their Taylor expansion (a polynomial) and deal with them in an easier way. For example, if we had  $\log(X)$  and wanted to write the expected value, , we don't have a good formula for it. But if we *expand* it, and we know moments of x, we can approximate it.

Let g(x) be a function with n+1 continuous derivatives. Then for a given real value  $x_0$ :

$$g(x) = g(x_0) + g'(x_0)(x - x_0) + \frac{g''(x_0)}{2!}(x - x_0)^2 + \dots$$
$$+ \frac{g^n(x_0)}{n!}(x - x_0)^n + \frac{g^{(n+1)}(\eta)}{(n+1)!}(x + x_0)^{n+1}$$

Where  $\eta$  is a number between x and  $x_0$ . **Note:** This is *not* an approximation to g(x), but the answer itself (for some  $\eta$ ).

## 1.2.1 Linear Approximation

Let's begin with a linear approximation of a function g(x), around  $x_0 = a$ .

$$g(x) = g(a) + g'(a)(x - a) + o(|x - a|)$$

**Note:** In terms of *convergence in probability*, we write:

$$Y_n = o_p(X_n) \iff \frac{Y_n}{X_n} \xrightarrow[n \to \infty]{P} 0$$

### **Examples:**

1. Suppose we wanted to find E[q(x)]. Then, we would have:

$$E[g(X)] \cong E[g(a) + g'(a)(x - a)]$$

In particular, let  $a = E[X] = \mu$ . Then:

$$E[g(X)] \cong E[g(\mu) + g'(\mu)(X - \mu)]$$
  
=  $g(\mu) = g(E[X])$ 

This says that if g(x) is a function that is approximated well with a line near  $x = \mu$ , you can use this linear approximation. To find the variance, similarly we have:

$$Var[g(X)] = Var[g(\mu) + g'(\mu)(X - \mu)]$$
$$= (g'(\mu))^{2} Var(X)$$

2. Let  $X_1, \ldots, X_n \sim Bernoulli(p)$  (iid). Consider the sample proportion,  $\hat{p} = \frac{\sum X_i}{n}$ .

$$E[\hat{p}] = E[X_i] = p$$

To estimate the odds,  $\frac{p}{1-p}$ , we use  $\frac{\hat{p}}{1-\hat{p}}$ . The question is, what is our random variable? It is a *non-linear* function of  $\hat{p}$ , so it is non-trivial to calculate the expectation. How would we go about computing the expected value? Consider:

$$g(x) = \frac{x}{1 - x}$$

First, let's find E[g(x)]. Consider  $x = \hat{p}$ . Then:

$$E\left[\frac{\hat{p}}{1-\hat{p}}\right] \cong \frac{p}{1-p}$$

Now, to find the variance:

$$g'(x) = \frac{1}{(1-x)^2}$$

$$\Rightarrow Var[g(x)] \cong [g'(p)]^2 Var(\hat{p})$$

$$= \left(\frac{1}{(1-p)^2}\right)^2 \cdot \frac{p(1-p)}{n} = \frac{p}{n(1-p)^3}$$

This estimator is *approximately* unbiased, and, as n gets large, the variance approaches 0.

3. Let  $X \sim exp(1)$ . Approximate  $E[\log x]$  and  $Var(\log x)$  using the delta method. Well, we know that if we wanted to calculate the exact value of the expected value, we could find the "true" value:

$$E[\log x] = \int_0^\infty (\log x) e^{-x} dx \cong -0.5772$$

We know that

$$E[X] = 1$$
 and  $Var(X) = 1$ 

If we wanted to use the *linear approximation*, we would have:

$$E[g(X)] \cong g(E[X])$$
  
\approx \log 1 = 0

So, let's use the **second order Taylor expansion**. We then have:

$$g(x) \cong g(\mu) + g'(\mu)(x - \mu) + \frac{g''(\mu)}{2}(x - \mu)^2$$

$$g(x) = \log x \quad g'(x) = \frac{1}{x} \quad g''(x) = -\frac{1}{x^2}$$

$$\Rightarrow g(x) \cong \log \mu + \frac{x - \mu}{\mu} - \frac{1}{2\mu^2}(x - \mu)^2$$

$$E[g(x)] \cong \log \mu - \frac{1}{2\mu^2}Var(x)$$

$$E[\log x] \cong \log 1 - \frac{1}{2} = -\frac{1}{2}$$

Thus, we have shown that by increasing the order, we have vastly improved the approximation. If we want to find the **variance**, we will need to find the  $4^{th}$  moment. We need to make an expansion here:

$$g(x) = \log \mu + \frac{1}{\mu}(X - 1) - \frac{1}{2\mu^2}(x^2 - 2\mu x + \mu^2)$$

Then, we have:

$$\begin{split} Var[g(X)] &= \frac{1}{\mu^2} Var(X) - \frac{1}{4\mu^4} Var(X^2) + \frac{1}{\mu^2} Var(X) \\ &- \frac{1}{2\mu^3} Cov(X, X^2) + \frac{1}{\mu^2} Cov(X, X) + Cov\left(-\frac{1}{2\mu^2} X^2, \frac{1}{\mu} X\right) \end{split}$$

With a bit of computation, the results follow.

# 2 Lecture - Part 2

#### 2.1 The General Delta Method Theorem

#### Theorem:

Let  $a_n$  be an increasing sequence of real numbers such that  $a_n \to \infty$  and let  $\theta$  be a fixed value. Furthermore, suppose that g(x) is a continuously differentiable function such that  $g'(\theta) \neq 0$ . Then, if  $Y_n = a_n(X_n - \theta) \xrightarrow[n \to \infty]{D} Y$  where Y is a random variable, and  $X_n$  is a sequence of random variables, then:

$$a_n [g(X_n) - g(\theta)] \xrightarrow{D} g'(\theta) \cdot Y$$

### **Proof:**

By Taylor's Theorem, we have:

$$q(X_n) = q(\theta) + q'(w_n)(X_n - \theta)$$

Where  $w_n$  is between  $X_n$  and  $\theta$  Facts:

1.  $X_n \xrightarrow{P} \theta$ 

**Proof:** We know that  $a_n(X_n - \theta) \xrightarrow{D} Y$ , and that  $\frac{1}{a_n} \xrightarrow{P} 0$ . By **Slutsky's Theorem**, we have:

$$\frac{1}{a_n} a_n (X_n - \theta) \xrightarrow{D} 0$$

$$\Rightarrow X_n - \theta \xrightarrow{D} 0 \Rightarrow X_n \xrightarrow{D} \theta \Rightarrow X_n \xrightarrow{P} \theta$$

2.  $w_n \xrightarrow{P} \theta$ 

**Proof:** Since  $w_n$  is between  $\theta$  and  $x_n$ , we know that

$$|X_n - \theta| \ge |w_n - \theta|$$

This implies that

$$P(|X_n - \theta| < \epsilon) \le P(|w_n - \theta| < \epsilon)$$
  

$$\Rightarrow P(|w_n - \theta| < \epsilon) \to 1$$

3. Since g' is *continuous*, using **fact 2**, we have

$$g'(w_n) \xrightarrow{P} g'(\theta)$$

Now consider, by Taylor's Theorem:

$$a_n(g(X_n) - g(\theta)) = g'(w_n)a_n(X_n - \theta)$$

What do we know about this? Well  $g'(w_n) \xrightarrow{P} g'(\theta)$ , and  $a_n(X_n - \theta) \xrightarrow{D} Y$ . Thus we have, by **Slutsky's Theorem**:

$$a_n(g(X_n) - g(\theta)) \xrightarrow{D} g'(\theta)Y$$

Theorem: (5.5.4)

Let  $Y_n$  be a sequence of random variables that satisfy:

$$\sqrt{n}(Y_n - \theta) \xrightarrow{D} N(0, \sigma^2)$$

for a given function g and a specific value of  $\theta$ . Suppose that  $g'(\theta)$  exists and  $g'(\theta) \neq 0$ . Then:

$$\sqrt{n}[g(Y_n) - g(\theta)] \xrightarrow{\mathcal{D}} N\left(0, \sigma^2\left(g'(\theta)^2\right)\right)$$

For example, if  $Y \sim N(0, \sigma^2)$ , then we would have:

$$g'(\theta)Y \sim N(0, \sigma^2(g'(\theta))^2)$$

## **Multidimensional Generalization**

Let  $g(\vec{x}): \mathbb{R}^n \to \mathbb{R}^1$ . Then for any given vector  $\vec{x_0} \in \mathbb{R}^n$ :

$$g(\vec{x}) = g(\vec{x_0}) + \nabla g(\vec{x_0})^T (\vec{x} - \vec{x_0}) + \frac{1}{2} (\vec{x} - \vec{x_0})^T H(\eta) (x - x_0)$$

Where  $\eta$  is a value between  $\vec{x}$  and  $\vec{x_0}$ , and where:

$$\nabla g(\vec{x}) = \begin{pmatrix} \frac{\partial g}{\partial x_1} \\ \vdots \\ \frac{\partial g}{\partial x_n} \end{pmatrix}$$

And:

$$H(x) = \begin{pmatrix} \frac{\partial^2 g}{\partial x_1^2} & \cdots & \frac{\partial^2 g}{\partial x_1 \partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial^2 g}{\partial x_n \partial x_1} & \cdots & \frac{\partial^2 g}{\partial x_n \partial x_1} \end{pmatrix}$$

Let  $\vec{X} = (X_1, ..., X_n)^T$  be a random vector with mean  $\vec{\mu} = (\mu_1, ..., \mu_n)^T$ . (Note that:  $E[X_i] = \mu_i$ ). Then,

$$g(\vec{X}) \cong g(\vec{\mu}) + \nabla g(\mu)^T (x - \mu)$$

We can now have:

$$E[g(\vec{X})] \cong g(\vec{\mu})$$

$$Var[g(\vec{X})] = \nabla g(\vec{\mu})^T Cov(\vec{X}) \nabla g(\vec{\mu})$$
Where,  $Cov(\vec{X}) = \begin{pmatrix} \sigma_{11} & \sigma_{12} & \cdots & \sigma_{1n} \\ \sigma_{21} & \sigma_{22} & \cdots & \sigma_{2n} \\ \vdots & \ddots & \vdots & \vdots \\ \sigma_{n1} & \sigma_{n2} & \cdots & \sigma_{nn} \end{pmatrix}$ 

## Example:

The position of an aircraft relative to an observer is estimated by measuring the aircraft distance R from the observer, and an angle  $\Theta$  which is the angle from the observer to the aircraft, relative to the horizon. We then have the altitude of the aircraft  $Y = R\sin(\Theta)$ .

Suppose that both  $\Theta$  and R are subject to random errors, and that R and  $\Theta$  are independent. Provided that  $E[R]=1000,\, E[\Theta]=\frac{\pi}{4},\, Var(R)=10,\, {\rm and}$  $Var(\Theta) = \frac{\pi^2}{100}$ , obtain the approximate variance of the altitude of the plane. First, we note that  $g(R,\Theta) : \mathbb{R}^2 \to \mathbb{R}^1$ . Thus we have:

$$g(R,\Theta) = R\sin\Theta$$

$$\nabla g(R,\Theta) = \begin{pmatrix} \sin\Theta \\ R\cos\Theta \end{pmatrix}$$

$$\vec{\mu} = \begin{pmatrix} E[R] \\ E[\Theta] \end{pmatrix} = \begin{pmatrix} 1000 \\ \frac{\pi}{4} \end{pmatrix}$$

$$\Rightarrow \nabla g(\vec{\mu}) = \begin{pmatrix} \sin\frac{\pi}{4} \\ 1000\cos\frac{\pi}{4} \end{pmatrix}$$

$$Cov(R,\Theta) = \begin{pmatrix} Var(R) & Cov(R,\Theta) \\ Cov(R,\Theta) & Var(\Theta) \end{pmatrix}$$

$$Var(Y) = \left(\sin\frac{\pi}{4} & 1000\cos\frac{\pi}{4}\right) \begin{pmatrix} 10 & 0 \\ 0 & \frac{\pi^2}{100} \end{pmatrix} \begin{pmatrix} \sin\frac{\pi}{4} \\ 1000\cos\frac{\pi}{4} \end{pmatrix}$$

$$= 10\sin^2\frac{\pi}{4} + 10^4\pi^2\cos^2\frac{\pi}{4}$$