



 Uma transformação linear seguida de uma não-linearidade (degrau - também conhecido como função de activação)

$$u_k = \mathbf{w}_k^{\top} \mathbf{x} = w_{0k} + w_{1k} x_1 + \ldots + w_{dk} x_d, \quad k = 1, \ldots, c$$

ou

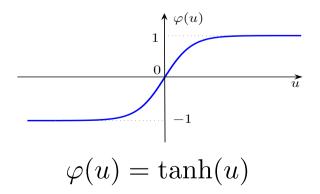
$$\mathbf{u} = \begin{bmatrix} u_1 \\ \dots \\ u_c \end{bmatrix} = \mathbf{W}^\top \mathbf{x}, \qquad \hat{\mathbf{y}} = \varphi(\mathbf{u}) = \begin{bmatrix} \varphi(u_1) \\ \dots \\ \varphi(u_c) \end{bmatrix}$$

•  $\varphi(\cdot)$  é uma de duas funções:

 $\varphi(u) = \frac{1}{1 + e^{-u}}$ 

sigmóide

tangente hiperbólica





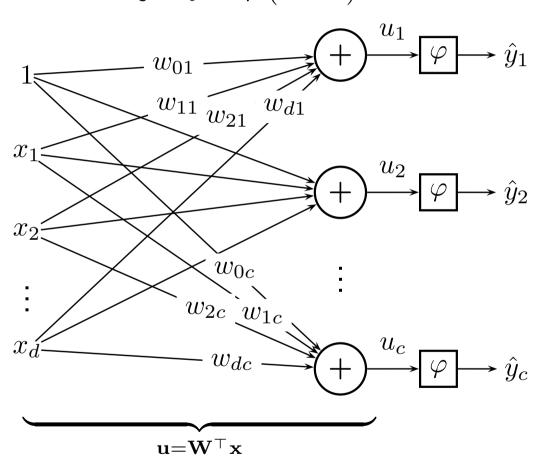
 $m{ ilde{y}}$  Transformação  $\hat{\mathbf{y}} = \varphi\left(\mathbf{W}^{\top}\mathbf{x}\right)$ 

$$\hat{\mathbf{y}} = \begin{bmatrix} \hat{y}_1 \\ \hat{y}_2 \\ \vdots \\ \hat{y}_c \end{bmatrix} = \begin{bmatrix} \varphi(u_1) \\ \varphi(u_2) \\ \vdots \\ \varphi(u_c) \end{bmatrix} = \varphi \left( \underbrace{\begin{bmatrix} w_{01} & w_{11} & w_{21} & \cdots & w_{d1} \\ w_{02} & w_{12} & w_{22} & \cdots & w_{d2} \\ \vdots & & & \vdots \\ w_{0c} & w_{1c} & w_{2c} & \cdots & w_{dc} \end{bmatrix} \begin{bmatrix} 1 \\ x_1 \\ x_2 \\ \vdots \\ x_d \end{bmatrix} \right)$$

- x vector de entrada
- ullet Cada coluna  $\mathbf{w}_k$  de  $\mathbf{W}$  (linha k de  $\mathbf{W}^{ op}$ ) só afecta a saída  $\hat{y}_k$



ullet Transformação  $\hat{\mathbf{y}} = arphi \left( \mathbf{W}^{ op} \mathbf{x} \right)$ 



#### Fase de Treino

- Objectivo: estimar a matriz W
- Dados disponíveis:
  - $oldsymbol{\mathcal{S}}$  Conjunto de N vectores  $\mathcal{X} = \{\mathbf{x}_1, \dots, \mathbf{x}_N\}$  (dados entradas)
  - $oldsymbol{\mathcal{Y}}$  Conjunto  $\mathcal{Y} = \{\mathbf{y}_1, \dots, \mathbf{y}_N\}$  (classificações saídas desejadas)

#### Saídas desejadas:

$$\mathbf{se} \ \mathbf{x} \in \varpi_k, \quad \mathbf{y} = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \longleftarrow \mathbf{linha} \ k \qquad \text{ou} \ \mathbf{y} = \begin{bmatrix} -1 \\ \vdots \\ -1 \\ +1 \\ -1 \\ \vdots \\ -1 \end{bmatrix}$$

$$\operatorname{com} \varphi(u) = \frac{1}{1+e^{-u}}$$

$$\mathsf{com}\;\varphi(u)=\tanh(u)$$

#### Fase de Treino

- Objectivo: estimar a matriz W
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  - $m{\mathcal{Y}} = \{\mathbf{y}_1, \dots, \mathbf{y}_N\}$  (classificações saídas desejadas)
- ullet Minimizar erro quadrático médio:  $\mathcal{E}(\mathbf{W}) = rac{1}{N} \sum_{n=1}^N \|\mathbf{y}_n \hat{\mathbf{y}}_n\|^2$
- Adaptação da matriz W: máxima descida de gradiente

$$\begin{split} \mathbf{W}(i+1) &= \mathbf{W}(i) + \Delta \mathbf{W}(i) \\ &\text{com} \quad \Delta \mathbf{W}(i) = -\eta \frac{\partial \mathcal{E}(\mathbf{W}(i))}{\partial \mathbf{W}} \\ &\text{ou} \quad \Delta \mathbf{W}(i) = -\eta \mathbf{z}(i) = -\eta \left( \frac{\partial \mathcal{E}(\mathbf{W}(i))}{\partial \mathbf{W}} + \alpha \mathbf{z}(i-1) \right) \end{split}$$



#### Fase de Classificação

Objectivo: classificar um vector x

• Transformar:  $\hat{\mathbf{y}} = \varphi(\mathbf{W}^{\top}\mathbf{x})$ 

• Classificar:  $\mathbf{x} \in \varpi_k$ , se  $y_k = \arg\max_i(\hat{y}_i)$  com  $i = 1, \ldots, c$ 



Exemplo: Dados 3D, e 2 classes

$$\hat{\mathbf{y}} = \begin{bmatrix} \hat{y}_1 \\ \hat{y}_2 \end{bmatrix} = \begin{bmatrix} \varphi(u_1) \\ \varphi(u_2) \end{bmatrix} \quad \mathbf{u} = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \mathbf{W}^\top \mathbf{x} = \begin{bmatrix} w_{01} & w_{11} & w_{21} & w_{31} \\ w_{02} & w_{12} & w_{22} & w_{32} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$u_1 = \mathbf{w}_1^{\top} \mathbf{x} = w_{01} + w_{11} x_1 + w_{21} x_2 + w_{31} x_3$$
  $\mathbf{w}_1 : \mathbf{1}^{\mathbf{a}} \text{ coluna da matriz } \mathbf{W}$ 

$$u_2 = \mathbf{w}_2^{\top} \mathbf{x} = w_{02} + w_{12} x_1 + w_{22} x_2 + w_{32} x_3$$
  $\mathbf{w}_2$  : 2a coluna da matriz  $\mathbf{W}$ 

$$\mathbf{W} = \begin{bmatrix} w_{01} & w_{02} \\ w_{11} & w_{12} \\ w_{21} & w_{22} \\ w_{31} & w_{32} \end{bmatrix} = \begin{bmatrix} \mathbf{w}_1 & \mathbf{w}_2 \end{bmatrix}$$



Exemplo: Dados 3D, e 2 classes

$$\mathcal{E}(\mathbf{W}) = \frac{1}{N} \sum_{n=1}^{N} \|\mathbf{y}_n - \hat{\mathbf{y}}_n\|^2$$
$$\|\mathbf{y} - \hat{\mathbf{y}}\|^2 = (y_1 - \hat{y}_1)^2 + (y_2 - \hat{y}_2)^2 = (y_1 - \varphi(\mathbf{w}_1^\top \mathbf{x}))^2 + (y_2 - \varphi(\mathbf{w}_2^\top \mathbf{x}))^2$$
$$\frac{\partial \mathcal{E}(\mathbf{W})}{\partial \mathbf{W}} = \frac{1}{N} \sum_{n=1}^{N} \frac{\partial \|\mathbf{y}_n - \hat{\mathbf{y}}_n\|^2}{\partial \mathbf{W}}$$

$$\frac{\partial \|\mathbf{y} - \hat{\mathbf{y}}\|^{2}}{\partial \mathbf{W}} = \begin{bmatrix}
\frac{\partial \|\mathbf{y} - \hat{\mathbf{y}}\|^{2}}{\partial w_{01}} & \frac{\partial \|\mathbf{y} - \hat{\mathbf{y}}\|^{2}}{\partial w_{02}} \\
\frac{\partial \|\mathbf{y} - \hat{\mathbf{y}}\|^{2}}{\partial w_{11}} & \frac{\partial \|\mathbf{y} - \hat{\mathbf{y}}\|^{2}}{\partial w_{12}} \\
\frac{\partial \|\mathbf{y} - \hat{\mathbf{y}}\|^{2}}{\partial w_{21}} & \frac{\partial \|\mathbf{y} - \hat{\mathbf{y}}\|^{2}}{\partial w_{22}} \\
\frac{\partial \|\mathbf{y} - \hat{\mathbf{y}}\|^{2}}{\partial w_{31}} & \frac{\partial \|\mathbf{y} - \hat{\mathbf{y}}\|^{2}}{\partial w_{32}}
\end{bmatrix} = \begin{bmatrix}
\frac{\partial \|\mathbf{y} - \hat{\mathbf{y}}\|^{2}}{\partial \mathbf{w}_{1}} & \frac{\partial \|\mathbf{y} - \hat{\mathbf{y}}\|^{2}}{\partial \mathbf{w}_{2}} \\
\frac{\partial \|\mathbf{y} - \hat{\mathbf{y}}\|^{2}}{\partial w_{31}} & \frac{\partial \|\mathbf{y} - \hat{\mathbf{y}}\|^{2}}{\partial w_{32}}
\end{bmatrix}$$



#### Exemplo: Dados 3D, e 2 classes

Derivada da sigmóide:

$$\varphi(u) = \frac{1}{1 + e^{-u}}$$

$$\frac{\partial \varphi(u)}{\partial u} = \frac{e^{-u}}{(1 + e^{-u})^2} = \varphi(u) - \varphi(u)^2$$

Derivada da tangente hiperbólica:

$$\varphi(u) = \tanh(u) = \frac{e^u - e^{-u}}{e^u + e^{-u}}$$
$$\frac{\partial \varphi(u)}{\partial u} = 1 - \tanh^2(u) = 1 - \varphi(u)^2$$



#### Exemplo: Dados 3D, e 2 classes

$$\mathcal{E}(\mathbf{W}) = \frac{1}{N} \sum_{n=1}^{N} \|\mathbf{y}_n - \hat{\mathbf{y}}_n\|^2$$

$$\|\mathbf{y} - \hat{\mathbf{y}}\|^2 = (y_1 - \hat{y}_1)^2 + (y_2 - \hat{y}_2)^2 = (y_1 - \varphi(u_1))^2 + (y_2 - \varphi(u_2))^2$$

$$\frac{\partial \|\mathbf{y} - \hat{\mathbf{y}}\|^2}{\partial \mathbf{w}_1} = \frac{\partial \|\mathbf{y} - \hat{\mathbf{y}}\|^2}{\partial \hat{y}_1} \times \frac{\partial \hat{y}_1}{\partial u_1} \times \frac{\partial u_1}{\partial \mathbf{w}_1} = -2(y_1 - \hat{y}_1)(\hat{y}_1 - \hat{y}_1^2) \mathbf{x}$$

$$\frac{\partial \|\mathbf{y} - \hat{\mathbf{y}}\|^2}{\partial \mathbf{w}_2} = \frac{\partial \|\mathbf{y} - \hat{\mathbf{y}}\|^2}{\partial \hat{y}_2} \times \frac{\partial \hat{y}_2}{\partial u_2} \times \frac{\partial u_2}{\partial \mathbf{w}_2} = -2(y_2 - \hat{y}_2)(\hat{y}_2 - \hat{y}_2^2) \mathbf{x}$$

$$\frac{\partial \|\mathbf{y} - \hat{\mathbf{y}}\|^2}{\partial \mathbf{W}} = \begin{bmatrix} \frac{\partial \|\mathbf{y} - \hat{\mathbf{y}}\|^2}{\partial \mathbf{w}_1} & \frac{\partial \|\mathbf{y} - \hat{\mathbf{y}}\|^2}{\partial \mathbf{w}_2} \end{bmatrix}$$

$$\frac{\partial \mathcal{E}(\mathbf{W})}{\partial \mathbf{W}} = \frac{1}{N} \sum_{n=1}^{N} \frac{\partial ||\mathbf{y}_n - \hat{\mathbf{y}}_n||^2}{\partial \mathbf{W}}$$



#### Exemplo: Dados 3D, e 2 classes

$$\mathcal{E}(\mathbf{W}) = \frac{1}{N} \sum_{n=1}^{N} \|\mathbf{y}_n - \hat{\mathbf{y}}_n\|^2 = \frac{1}{N} \sum_{n=1}^{N} \|\mathbf{e}_n\|^2 \quad \text{com } \mathbf{e} = \begin{bmatrix} y_1 - \hat{y}_1 \\ y_2 - \hat{y}_2 \end{bmatrix}$$

$$\frac{\partial \|\mathbf{y} - \hat{\mathbf{y}}\|^2}{\partial \mathbf{w}_1} = -2 (y_1 - \hat{y}_1) (\hat{y}_1 - \hat{y}_1^2) \mathbf{x} = -2 \mathbf{x} \left( e_1 \frac{\partial \varphi(u_1)}{\partial u_1} \right)$$

$$\frac{\partial \|\mathbf{y} - \hat{\mathbf{y}}\|^2}{\partial \mathbf{w}_2} = -2 (y_2 - \hat{y}_2) (\hat{y}_2 - \hat{y}_2^2) \mathbf{x} = -2 \mathbf{x} \left( e_2 \frac{\partial \varphi(u_2)}{\partial u_2} \right)$$

$$\frac{\partial \|\mathbf{y} - \hat{\mathbf{y}}\|^2}{\partial \mathbf{W}} = -2 \begin{bmatrix} 1 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix} \begin{bmatrix} e_1(\hat{y}_1 - \hat{y}_1^2) & e_2(\hat{y}_2 - \hat{y}_2^2) \end{bmatrix}$$

$$\frac{\partial \mathcal{E}(\mathbf{W})}{\partial \mathbf{W}} = \frac{1}{N} \sum_{n=1}^{N} \frac{\partial ||\mathbf{y}_n - \hat{\mathbf{y}}_n||^2}{\partial \mathbf{W}}$$

#### Generalização: Dados a d-dimensões, e com c classes

$$ullet$$
 Transformação  $\hat{\mathbf{y}} = arphi \left( \mathbf{W}^{ op} \mathbf{x} \right) = egin{bmatrix} arphi(u_1) & \dots & arphi(u_c) \end{bmatrix}^{ op}$ 

• Erro quadrático médio: 
$$\mathcal{E}(\mathbf{W}) = \frac{1}{N} \sum_{n=1}^{N} \|\mathbf{y}_n - \hat{\mathbf{y}}_n\|^2$$

Derivada do erro: 
$$\frac{\partial \mathcal{E}(\mathbf{W})}{\partial \mathbf{W}} = \frac{1}{N} \sum_{n=1}^{\infty} \frac{\partial \|\mathbf{y}_n - \mathbf{y}_n\|^2}{\partial \mathbf{W}}$$

$$\int_{\mathbf{W}} \frac{\partial \|\mathbf{y} - \hat{\mathbf{y}}\|^2}{\partial \mathbf{W}} = -2 \begin{bmatrix} 1 \\ x_1 \\ x_2 \\ \vdots \\ x_d \end{bmatrix} \begin{bmatrix} e_1(\hat{y}_1 - \hat{y}_1^2) & e_2(\hat{y}_2 - \hat{y}_2^2) & \dots & e_c(\hat{y}_c - \hat{y}_c^2) \end{bmatrix}$$

e com 
$$\varphi(u) = rac{1}{1 + e^{-u}}$$



#### Outro exemplo:

Três classes (dados 2D - 500pts/classe)

#### Código Python:

(com import numpy.random as rd)

#### Geração dos dados

```
x1=np.dot(np.diag((0.125,0.25)),rd.randn(2,500))
x1[0,:]=x1[0,:]-0.5
x2=np.dot(np.diag((0.125,0.25)),rd.randn(2,500))
x2[0,:]=x2[0,:]+0.5
x3=np.dot(np.diag((0.5,0.125)),rd.randn(2,500))
x3[1,:]=x3[1,:]+1
X=np.mat((np.ones(1500),np.hstack((x1,x2,x3))))
```

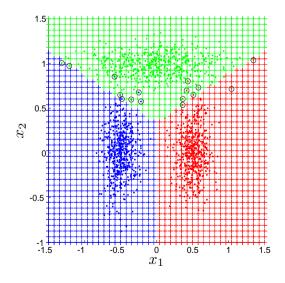
#### Saídas desejadas (classes)

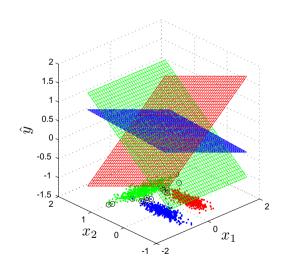
```
Y=np.array(-np.zeros((3,1500)))
Y[0,0:500]=1. Y[1,500:1000]=1. Y[2,1000:1500]=1.
```

#### Outro exemplo:

■ Discriminantes <u>Lineares</u>: solução analítica  $\mathbf{W} = (\mathbf{X}\mathbf{X}^{\top})^{-1}\mathbf{X}\mathbf{Y}^{\top}$ 

```
W =np.dot(sp.linalg.pinv(np.dot(X, X.T)), npdot(X, Y.T)) =
+0.4735 +0.4680 +0.0585 Três planos (1 por classe)
-0.6682 +0.6741 -0.0059 \hat{y}_1 = \mathbf{w}_1^{\top} \mathbf{x}
\hat{y}_2 = \mathbf{w}_2^{\top} \mathbf{x}
\hat{y}_3 = \mathbf{w}_3^{\top} \mathbf{x}
```







#### Outro exemplo:

- Discriminantes Logísticos: descida de gradiente Pseudo-Código:
  - Calcular saídas:

```
Yh = (1+np.exp(-np.dot(W.T,X))) **(-1)
```

Calcular gradiente:

```
qW = (-2 * np.dot ((Y-Yh) * (Yh-Yh**2), X.T)).T
```

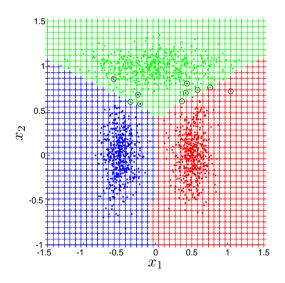
Adaptar pesos:

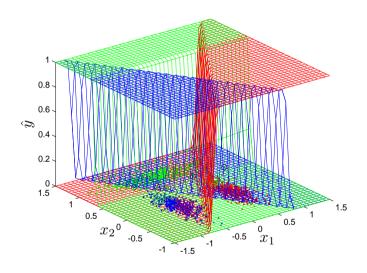
```
W=W-eta*qW;
```



### Outro exemplo:

- Discriminantes Logísticos
  - Resultados ligeiramente melhores do que os obtidos com discriminantes lineares.

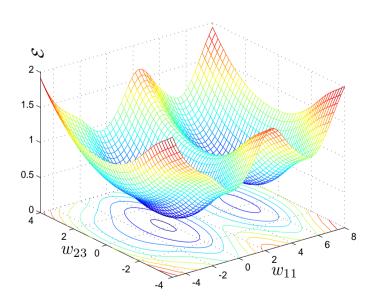






#### Outro exemplo:

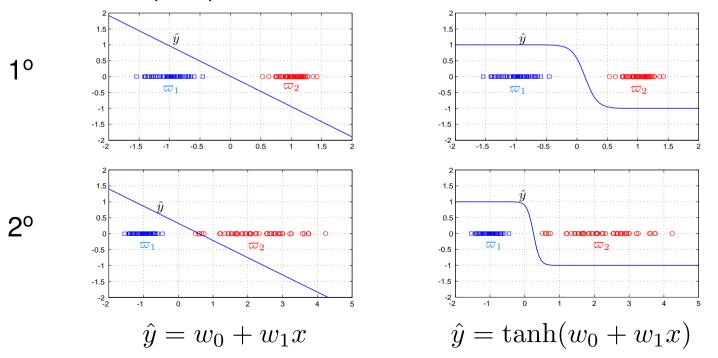
- Discriminantes Logísticos
  - Resultados ligeiramente melhores do que os obtidos com discriminantes lineares.
  - Função do erro não é uma parábola. Podemos ficar presos em mínimos locais!



Função do erro em termos de dois pesos,  $w_{11}$  e  $w_{23}$  da matriz  $\mathbf{W}$ . Os restantes pesos foram fixados nos valores óptimos.

#### Vantagens relativamente a discriminantes lineares

- Saídas  $\hat{y}$  com valores limitados (podem-se aproximar mais facilmente das saídas desejadas y).
  - Classes com pontos espalhados já não causam problemas.
     2 Exemplos: pontos 1D, duas classes





#### Vantagens relativamente a discriminantes lineares

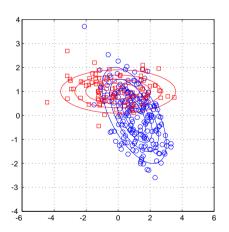
- Saídas  $\hat{y}$  com valores limitados (podem-se aproximar mais facilmente das saídas desejadas y).
- Saídas podem ser convertidas em probabilidades. Podemos obter um grau de confiança sobre os resultados de classificação.

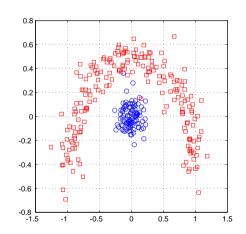


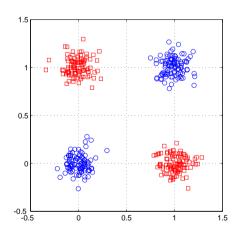
#### Limitações:

- Fronteiras de decisão lineares
- Problemas quando os dados de uma classe estão repartidos por regiões distintas

#### Exemplos







Diferentes inicializações podem obter diferentes resultados