

%% Lee controller tuning %%

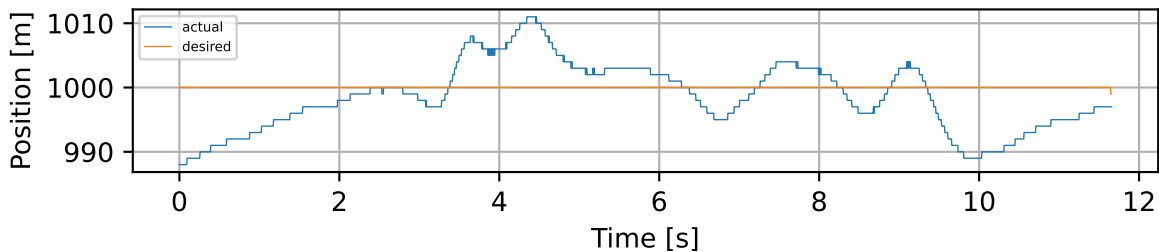
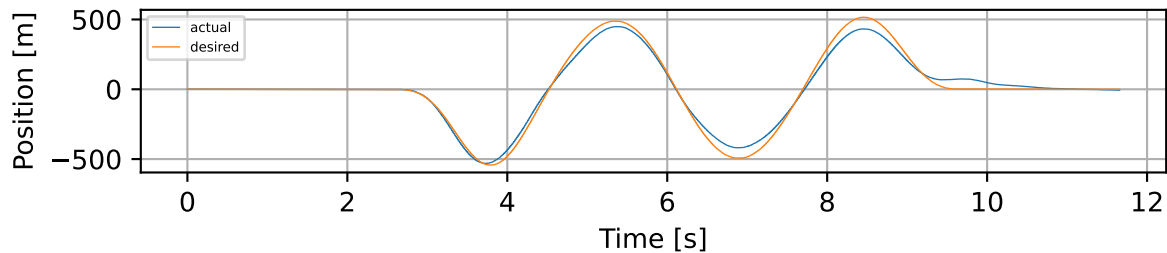
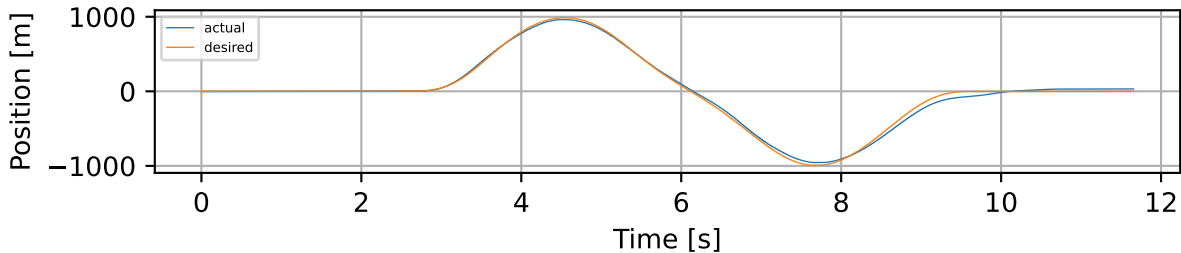
Settings:

data_file: log08
start_time: None
end_time: None

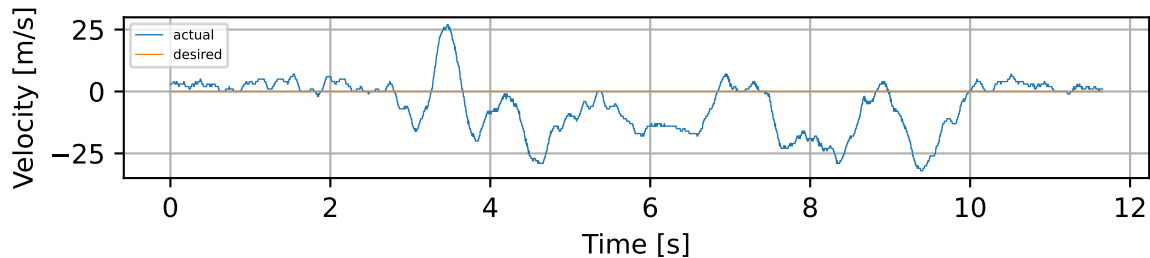
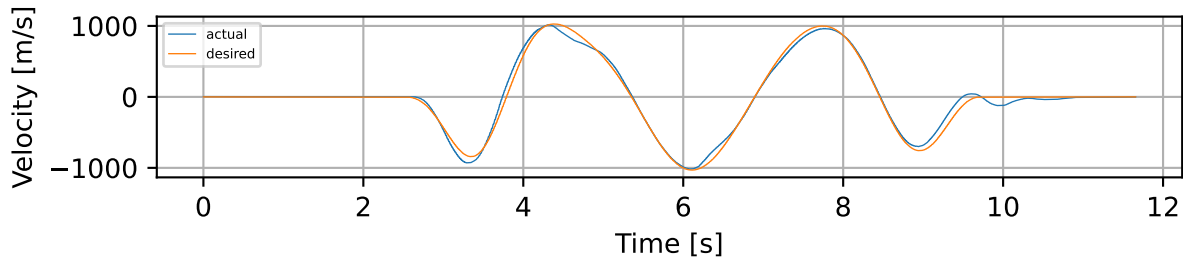
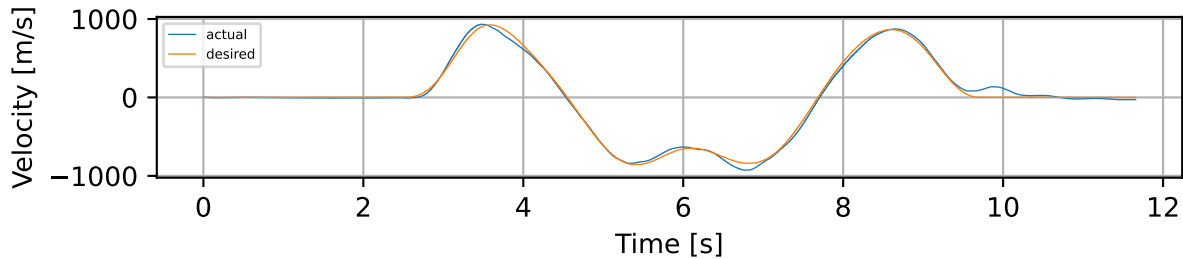
Parameters:

Kpos_Px: 10.0
Kpos_Py: 10.0
Kpos_Pz: 10.0
Kpos_Dx: 7.0
Kpos_Dy: 7.0
Kpos_Dz: 7.0
Kpos_Ix: 5.0
Kpos_Iy: 5.0
Kpos_Iz: 8.0
KR_x: 0.01
KR_y: 0.01
KR_z: 0.012
Kw_x: 0.0013
Kw_y: 0.0013
Kw_z: 0.002
KI_x: 0.012
KI_y: 0.018
KI_z: 0.015
mass: 0.0333

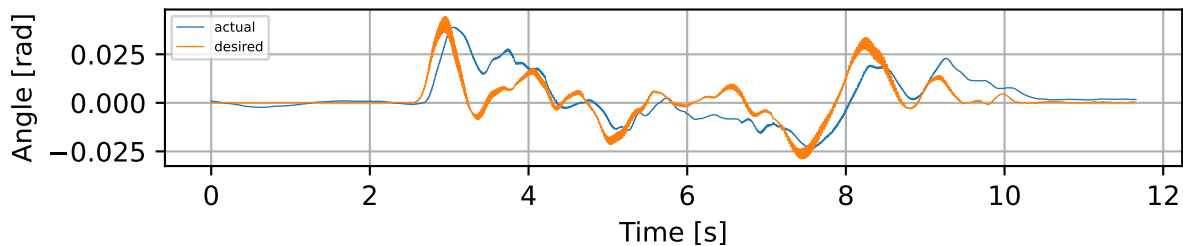
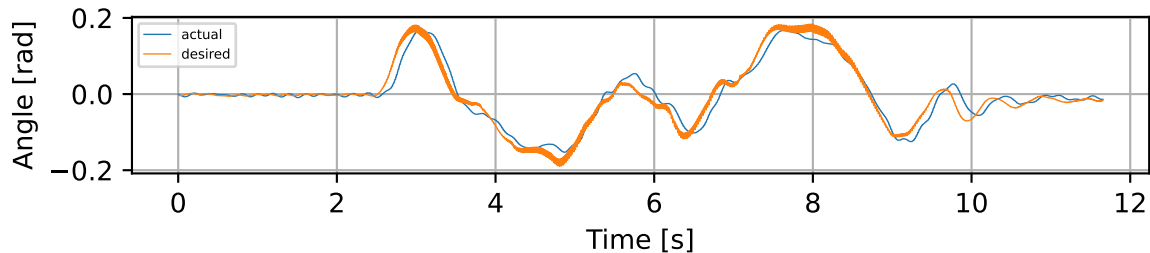
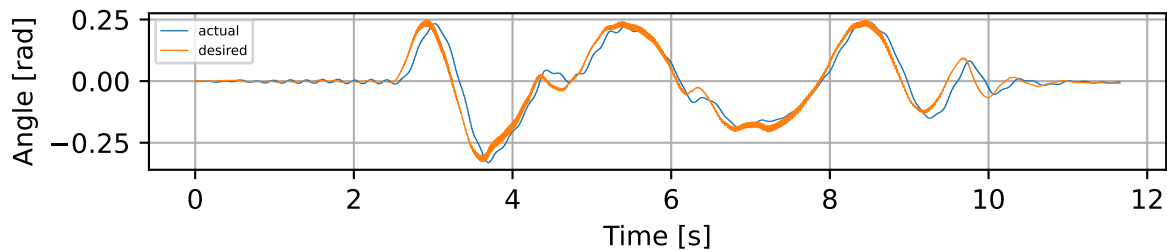
Positions (xyz)



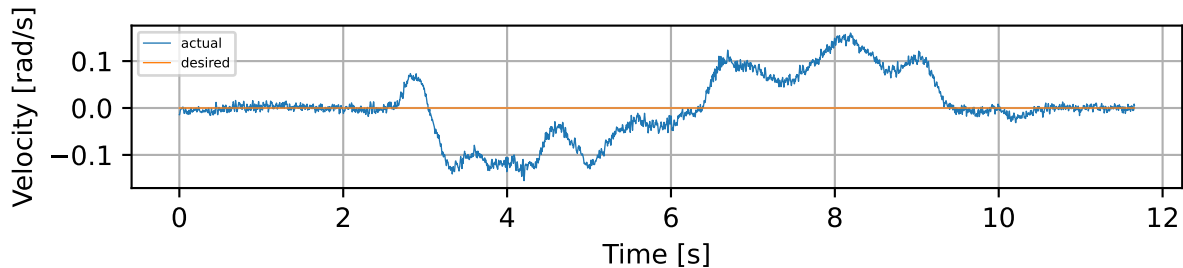
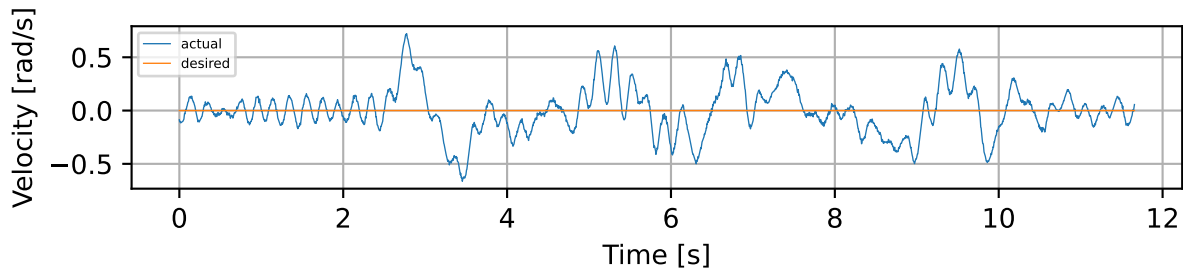
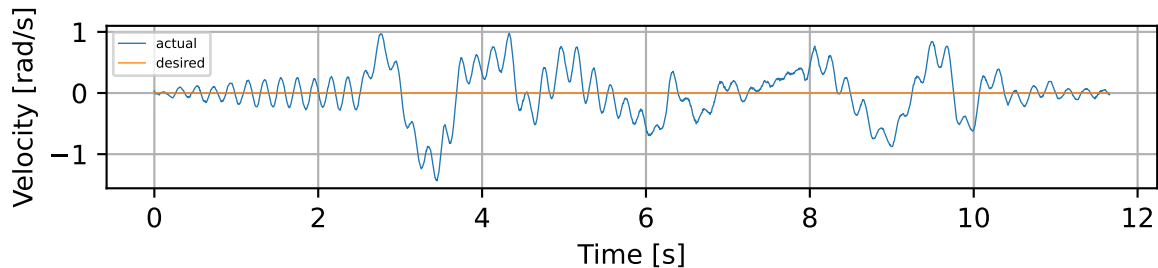
Translation Velocities (xyz)



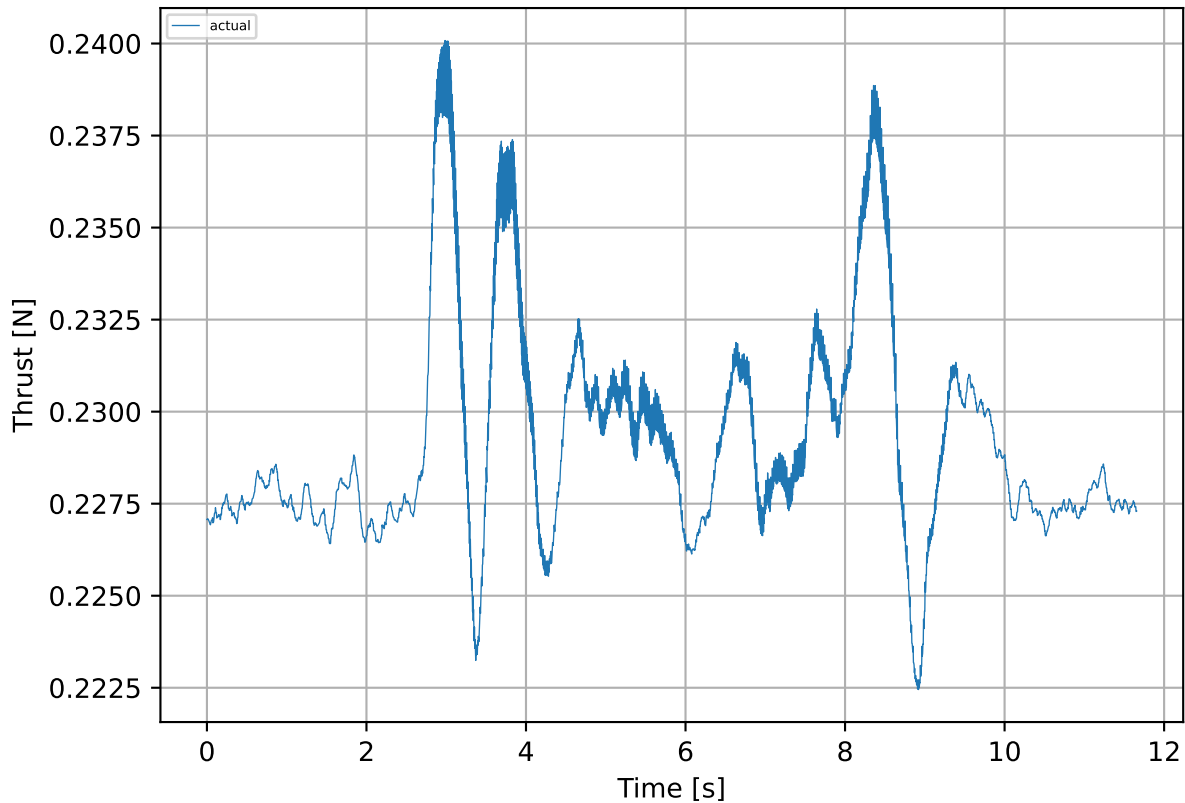
Angles (rpy, xyz)



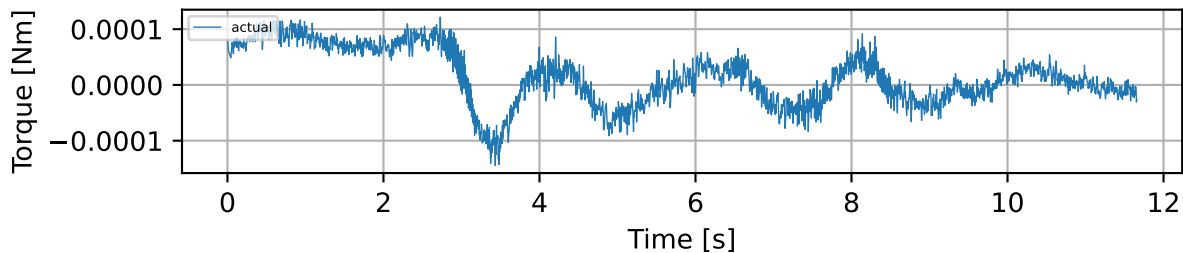
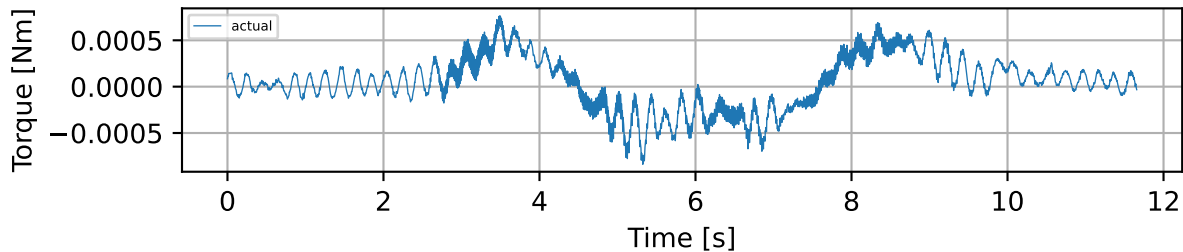
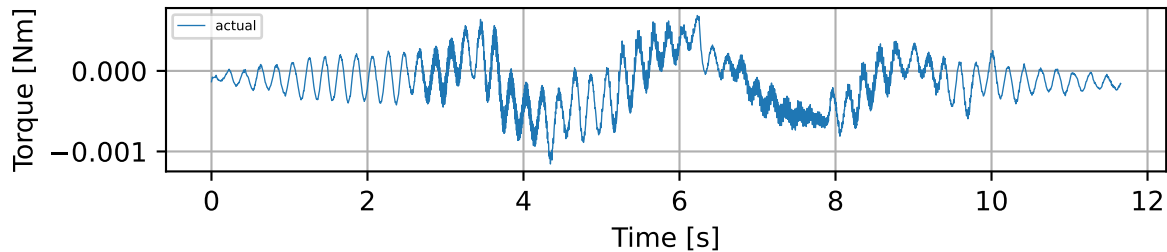
Angular Velocities (xyz)



Thrust



Torques (xyz)



Trajectories

