

%% Lee controller tuning %%

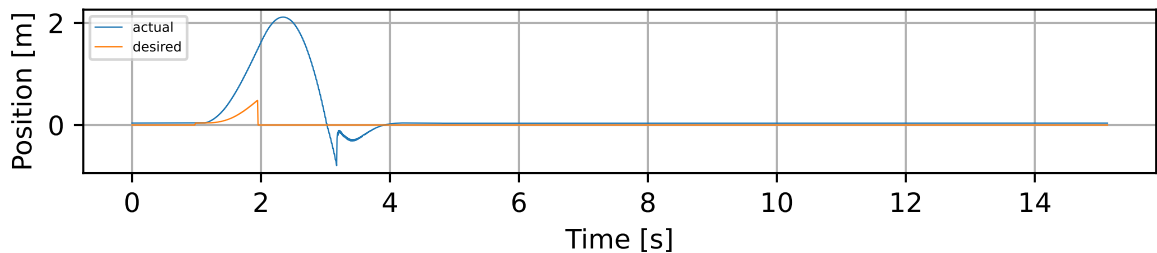
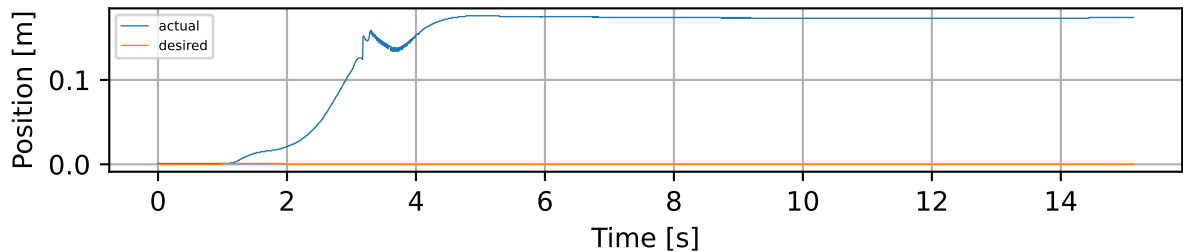
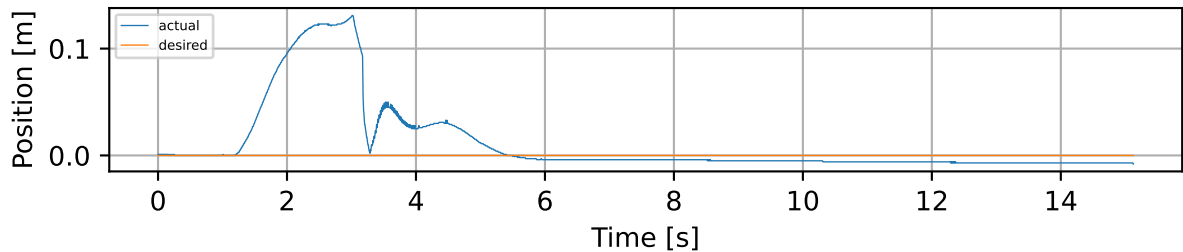
Settings:

data_dir: logs
data_file: log25
start_time: None
end_time: None

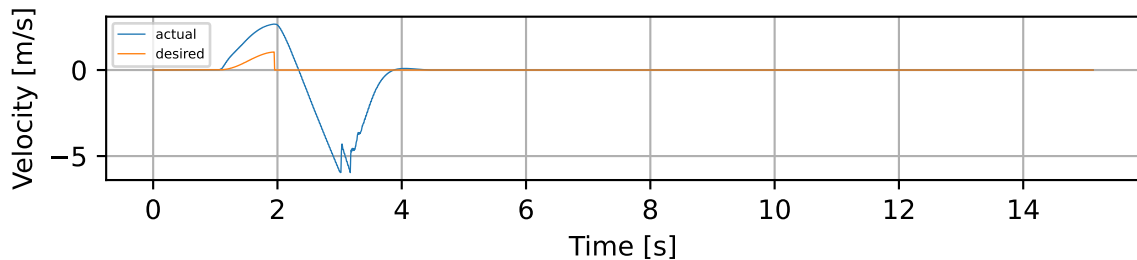
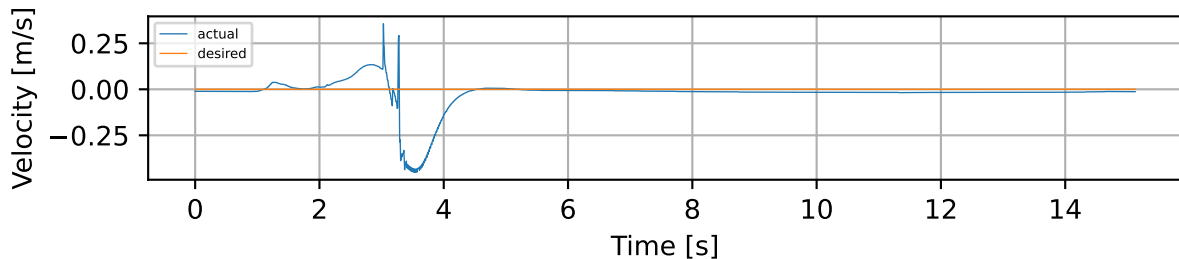
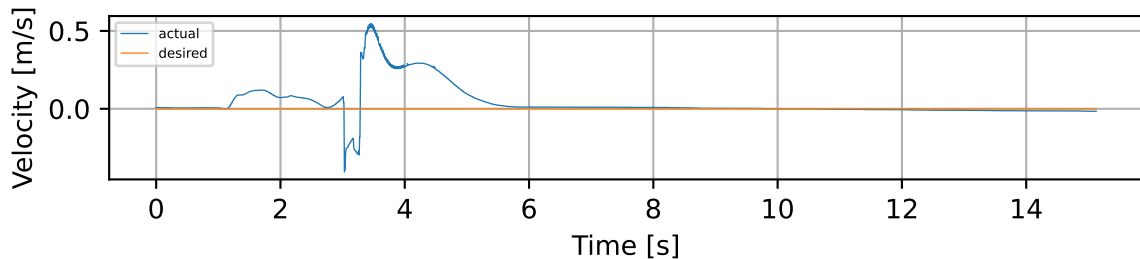
Parameters:

Kpos_Px: 1.0
Kpos_Py: 1.0
Kpos_Pz: 1.0
Kpos_Dx: 1.0
Kpos_Dy: 1.0
Kpos_Dz: 1.0
Kpos_Ix: 0.0
Kpos_Iy: 0.0
Kpos_Iz: 5.0
KR_x: 0.008
KR_y: 0.008
KR_z: 0.009
Kw_x: 0.001
Kw_y: 0.001
Kw_z: 0.0012
KI_x: 0.015
KI_y: 0.015
KI_z: 0.018
mass: 0.0368

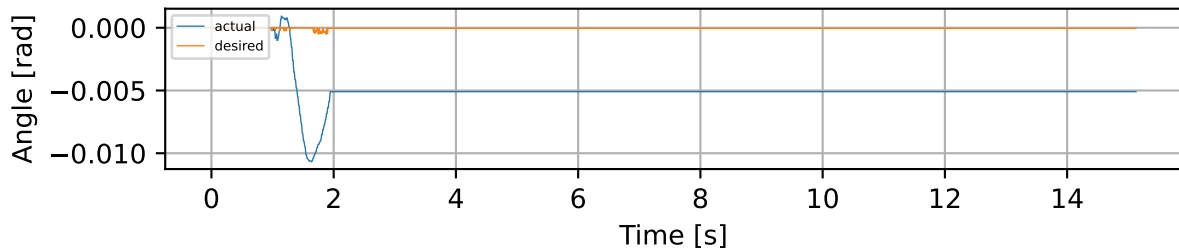
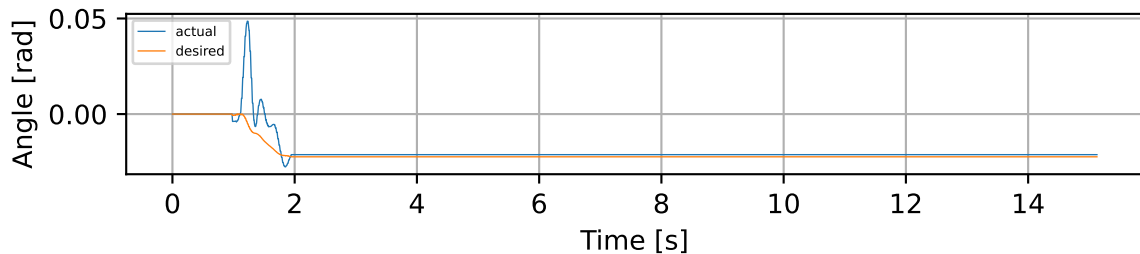
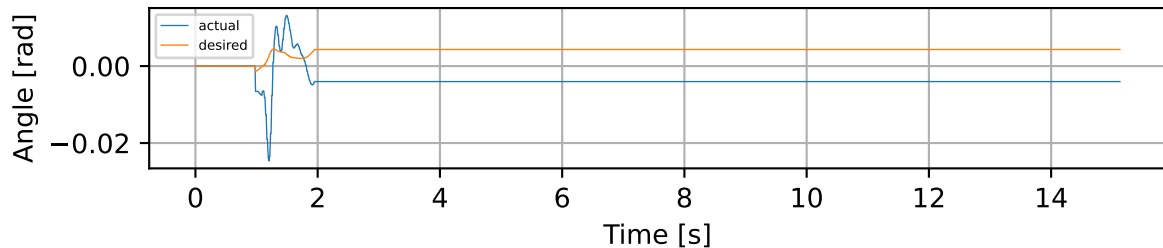
Positions (xyz)



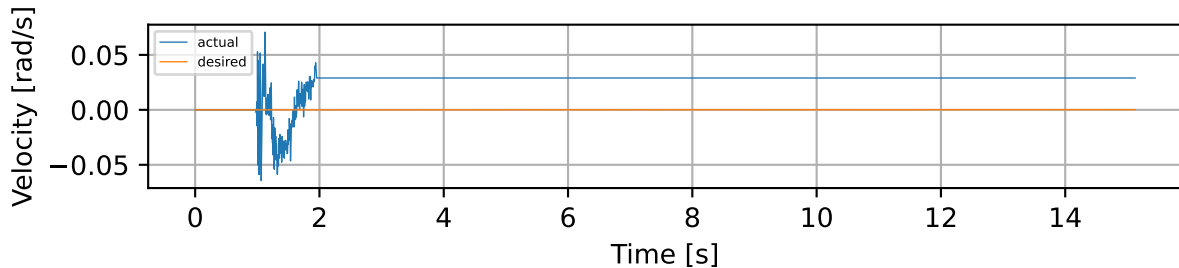
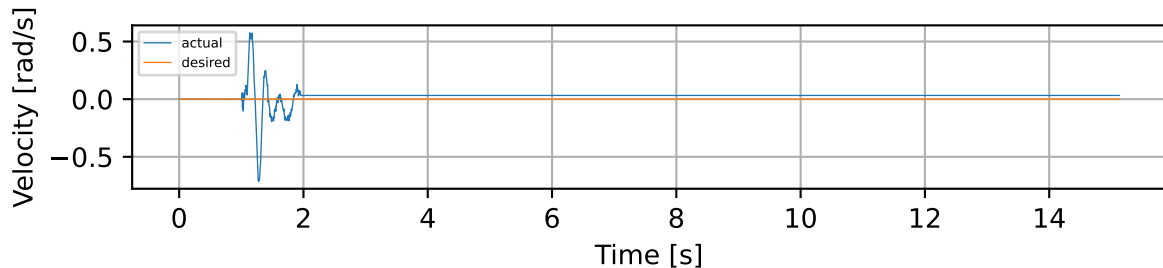
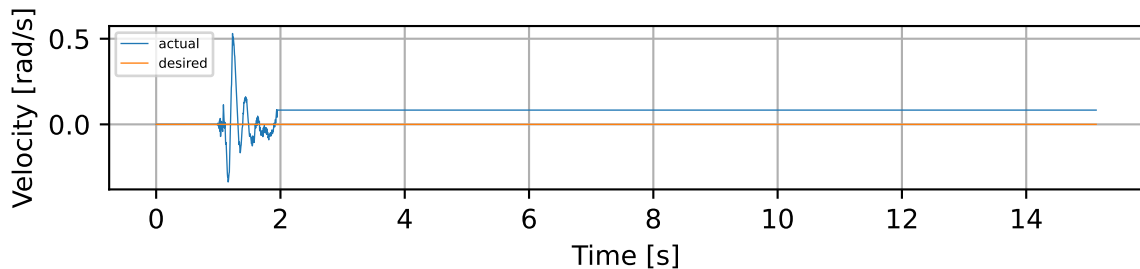
Translation Velocities (xyz)



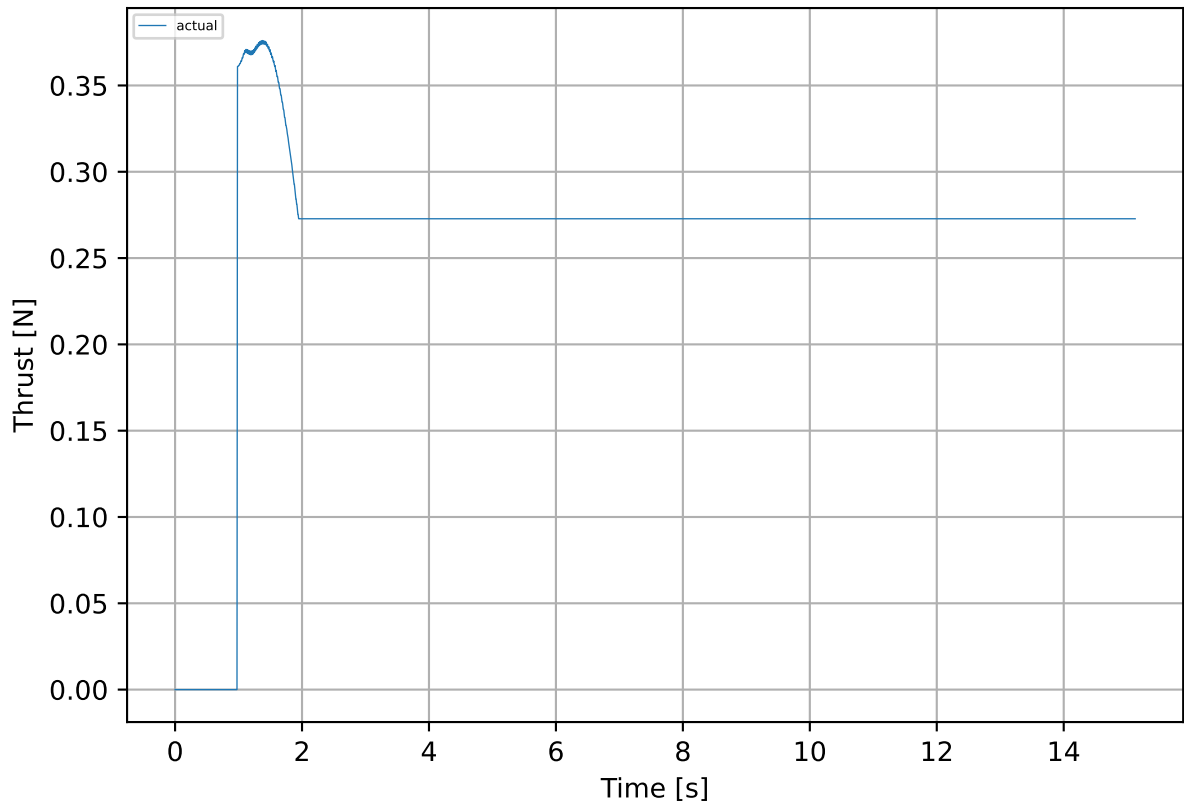
Angles (rpy, xyz)



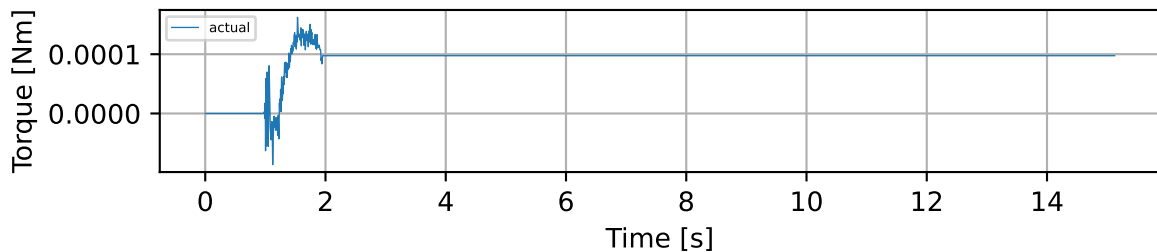
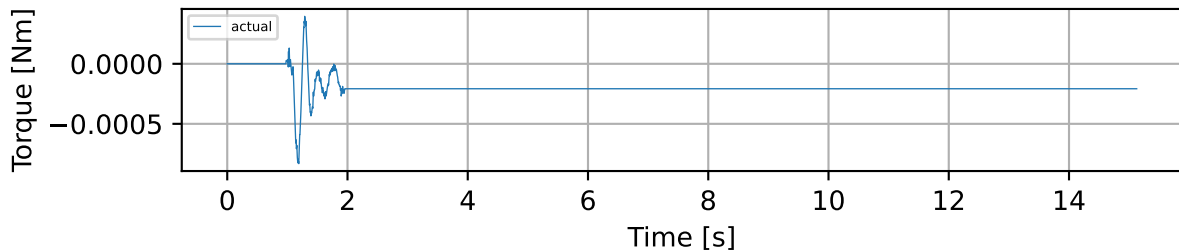
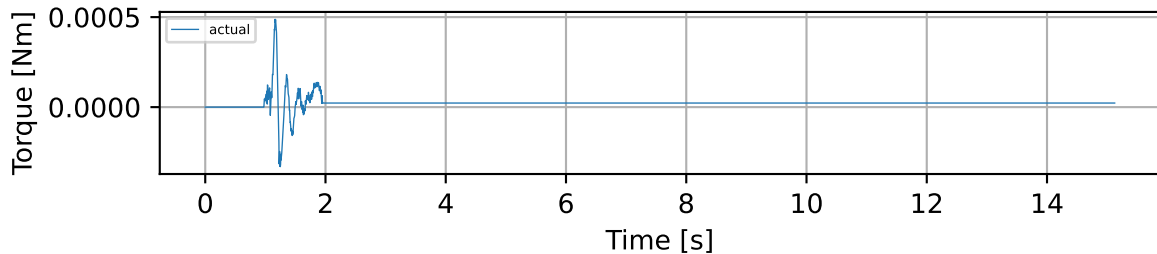
Angular Velocities (xyz)



Thrust



Torques (xyz)



Trajectories

