## importing lab

### In [1]:

```
'''image data generator tries to generate multiple data from
single image like by shrinking, zooming/croping etc.'''
from keras.preprocessing.image import ImageDataGenerator
from keras.models import Sequential #we are using sequential model for classification.
'''Conv is used to exract featurs from images
max pooling reduce the size of image without loosing it's feature
from keras.layers import Conv2D, MaxPooling2D
'''Activation function used to tell the network when to activate neuron
by using Dropout our network doesn't overfit
Flatten convert 2d image into 1d vector
Dense is used to create hidden and output layer'''
from keras.layers import Activation, Dropout,Flatten,Dense
''' backend tells us which channel is come first '''
from keras import backend as k
import numpy as np
from keras_preprocessing import image
```

Using TensorFlow backend.

# Diamensions of the image

### In [2]:

```
img_width, img_height =500,500
train_data_dir ='train/Train2'
test_data_dir ='test1/Test1'
nb_train_samples= 1000
nb_test_saples =100
epochs= 50
batch_size =20
```

### In [3]:

#### %pwd

#### Out[3]:

'C:\\Users\\hp\\cats vs dogs'

### In [4]:

### In [5]:

Found 25000 images belonging to 2 classes. Found 25000 images belonging to 2 classes.

### In [6]:

```
model =Sequential()
model.add(Conv2D(32,(3,3),input_shape=input_shape))
model.add(Activation('relu'))
model.add(MaxPooling2D(pool_size=(2,2)))
model.summary()
model.add(Conv2D(32,(3,3),input_shape=input_shape))
model.add(Activation('relu'))
model.add(MaxPooling2D(pool_size=(2,2)))
model.add(Conv2D(32,(3,3),input_shape=input_shape))
model.add(Activation('relu'))
model.add(MaxPooling2D(pool_size=(2,2)))
model.add(Flatten())
model.add(Dense(64))
model.add(Activation('relu'))
model.add(Dropout(0.5))
model.add(Dense(1))
model.add(Activation('sigmoid'))
model.summary()
model.compile(optimizer='rmsprop',
              loss='binary_crossentropy',
              metrics=['accuracy'])
```

Model: "sequential\_1"

Layer (type)	Output Shape	Param #
conv2d_1 (Conv2D)	(None, 498, 498, 32)	896
activation_1 (Activation)	(None, 498, 498, 32)	0
max_pooling2d_1 (MaxPooling2	(None, 249, 249, 32)	0

Total params: 896 Trainable params: 896 Non-trainable params: 0

Model: "sequential 1	1	
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Layer (type) 	Output	Shape 	Param #
conv2d_1 (Conv2D)	(None,	498, 498, 32)	896
activation_1 (Activation)	(None,	498, 498, 32)	0
max_pooling2d_1 (MaxPooling2	(None,	249, 249, 32)	0
conv2d_2 (Conv2D)	(None,	247, 247, 32)	9248
activation_2 (Activation)	(None,	247, 247, 32)	0
max_pooling2d_2 (MaxPooling2	(None,	123, 123, 32)	0
conv2d_3 (Conv2D)	(None,	121, 121, 32)	9248
activation_3 (Activation)	(None,	121, 121, 32)	0
max_pooling2d_3 (MaxPooling2	(None,	60, 60, 32)	0
flatten_1 (Flatten)	(None,	115200)	0
dense_1 (Dense)	(None,	64)	7372864
activation_4 (Activation)	(None,	64)	0
dropout_1 (Dropout)	(None,	64)	0
dense_2 (Dense)	(None,	1)	65
activation_5 (Activation)	•	•	0
======================================	======	=======================================	======

Total params: 7,392,321 Trainable params: 7,392,321 Non-trainable params: 0

### In [7]:

```
Epoch 1/50
50/50 [=============== ] - 219s 4s/step - loss: 1.0565 - acc
uracy: 0.5340 - val_loss: 0.6713 - val_accuracy: 0.6300
Epoch 2/50
uracy: 0.5750 - val_loss: 0.6874 - val_accuracy: 0.5300
Epoch 3/50
50/50 [=============== ] - 216s 4s/step - loss: 0.7083 - acc
uracy: 0.5810 - val_loss: 0.6948 - val_accuracy: 0.5600
Epoch 4/50
50/50 [=============== ] - 216s 4s/step - loss: 0.7004 - acc
uracy: 0.5800 - val_loss: 0.6521 - val_accuracy: 0.6500
Epoch 5/50
50/50 [============== ] - 216s 4s/step - loss: 0.7008 - acc
uracy: 0.6260 - val_loss: 0.5464 - val_accuracy: 0.6200
Epoch 6/50
50/50 [================ ] - 219s 4s/step - loss: 0.6710 - acc
uracy: 0.6150 - val loss: 0.6181 - val accuracy: 0.6500
Epoch 7/50
50/50 [============= ] - 216s 4s/step - loss: 0.6356 - acc
uracy: 0.6380 - val loss: 0.6432 - val accuracy: 0.5900
Epoch 8/50
50/50 [================ ] - 215s 4s/step - loss: 0.6597 - acc
uracy: 0.6510 - val loss: 0.5824 - val accuracy: 0.6900
Epoch 9/50
uracy: 0.6440 - val loss: 0.6862 - val accuracy: 0.6700
Epoch 10/50
uracy: 0.6560 - val_loss: 0.6116 - val_accuracy: 0.7200
Epoch 11/50
50/50 [=============== ] - 847s 17s/step - loss: 0.6781 - ac
curacy: 0.6830 - val_loss: 0.7193 - val_accuracy: 0.5800
Epoch 12/50
uracy: 0.6510 - val_loss: 0.5982 - val_accuracy: 0.7000
Epoch 13/50
50/50 [============== ] - 218s 4s/step - loss: 0.6341 - acc
uracy: 0.6720 - val_loss: 0.5521 - val_accuracy: 0.7500
Epoch 14/50
50/50 [================ ] - 216s 4s/step - loss: 0.6287 - acc
uracy: 0.6660 - val loss: 0.6645 - val accuracy: 0.6600
Epoch 15/50
50/50 [================ ] - 216s 4s/step - loss: 0.6242 - acc
uracy: 0.6670 - val_loss: 0.6635 - val_accuracy: 0.7200
Epoch 16/50
50/50 [=============== ] - 217s 4s/step - loss: 0.6005 - acc
uracy: 0.6750 - val loss: 0.5201 - val accuracy: 0.7400
Epoch 17/50
50/50 [============ ] - 219s 4s/step - loss: 0.6390 - acc
uracy: 0.6640 - val_loss: 0.4989 - val_accuracy: 0.7600
Epoch 18/50
50/50 [=============== ] - 218s 4s/step - loss: 0.6342 - acc
uracy: 0.6840 - val loss: 0.5466 - val accuracy: 0.6800
Epoch 19/50
50/50 [=============== ] - 217s 4s/step - loss: 0.6042 - acc
uracy: 0.7020 - val_loss: 0.6448 - val_accuracy: 0.6800
Epoch 20/50
50/50 [============ ] - 217s 4s/step - loss: 0.6288 - acc
uracy: 0.6750 - val loss: 0.5446 - val accuracy: 0.7900
Epoch 21/50
```

```
uracy: 0.6990 - val_loss: 0.6850 - val_accuracy: 0.7000
Epoch 22/50
uracy: 0.7030 - val_loss: 0.5231 - val_accuracy: 0.7200
Epoch 23/50
uracy: 0.6900 - val_loss: 0.5737 - val_accuracy: 0.6400
Epoch 24/50
uracy: 0.6880 - val_loss: 0.6281 - val_accuracy: 0.7300
Epoch 25/50
uracy: 0.6910 - val_loss: 0.4895 - val_accuracy: 0.6900
Epoch 26/50
50/50 [============= ] - 216s 4s/step - loss: 0.6180 - acc
uracy: 0.6860 - val_loss: 0.5593 - val_accuracy: 0.7200
Epoch 27/50
uracy: 0.7220 - val_loss: 0.6234 - val_accuracy: 0.7700
Epoch 28/50
50/50 [=============== ] - 218s 4s/step - loss: 0.5967 - acc
uracy: 0.7240 - val loss: 0.6101 - val accuracy: 0.7700
Epoch 29/50
50/50 [================= ] - 217s 4s/step - loss: 0.6000 - acc
uracy: 0.7020 - val_loss: 0.5319 - val_accuracy: 0.7400
Epoch 30/50
uracy: 0.7140 - val_loss: 0.3651 - val_accuracy: 0.7900
Epoch 31/50
uracy: 0.7010 - val_loss: 0.4159 - val_accuracy: 0.7300
Epoch 32/50
50/50 [=============== ] - 217s 4s/step - loss: 0.5774 - acc
uracy: 0.7160 - val_loss: 0.5290 - val_accuracy: 0.7100
Epoch 33/50
uracy: 0.7240 - val_loss: 0.5857 - val_accuracy: 0.6500
Epoch 34/50
uracy: 0.7380 - val_loss: 0.4789 - val_accuracy: 0.6900
Epoch 35/50
uracy: 0.7250 - val_loss: 0.5693 - val_accuracy: 0.7000
Epoch 36/50
uracy: 0.7080 - val_loss: 0.4507 - val_accuracy: 0.7500
Epoch 37/50
uracy: 0.7330 - val_loss: 0.4504 - val_accuracy: 0.7500
Epoch 38/50
50/50 [============= ] - 217s 4s/step - loss: 0.5929 - acc
uracy: 0.7290 - val_loss: 0.5524 - val_accuracy: 0.6600
uracy: 0.7410 - val_loss: 0.5314 - val_accuracy: 0.7300
Epoch 40/50
uracy: 0.7230 - val_loss: 1.1708 - val_accuracy: 0.6500
Epoch 41/50
```

```
uracy: 0.7090 - val_loss: 0.5305 - val_accuracy: 0.7400
Epoch 42/50
50/50 [============ ] - 217s 4s/step - loss: 0.5668 - acc
uracy: 0.7350 - val_loss: 0.3616 - val_accuracy: 0.8000
Epoch 43/50
uracy: 0.7220 - val_loss: 0.5648 - val_accuracy: 0.7800
Epoch 44/50
50/50 [============== ] - 217s 4s/step - loss: 0.5615 - acc
uracy: 0.7280 - val loss: 0.3880 - val accuracy: 0.7800
Epoch 45/50
50/50 [============= ] - 217s 4s/step - loss: 0.5316 - acc
uracy: 0.7380 - val_loss: 0.4999 - val_accuracy: 0.7200
Epoch 46/50
uracy: 0.7650 - val loss: 0.5359 - val accuracy: 0.7500
Epoch 47/50
50/50 [================= ] - 217s 4s/step - loss: 0.5357 - acc
uracy: 0.7240 - val_loss: 0.5853 - val_accuracy: 0.6400
Epoch 48/50
uracy: 0.7170 - val loss: 0.4887 - val accuracy: 0.7300
Epoch 49/50
50/50 [============ ] - 217s 4s/step - loss: 0.5746 - acc
uracy: 0.7010 - val_loss: 0.6177 - val_accuracy: 0.7200
Epoch 50/50
50/50 [============= ] - 215s 4s/step - loss: 0.5862 - acc
uracy: 0.6900 - val loss: 0.7180 - val accuracy: 0.8200
```

### In [12]:

```
import cv2
vidcap = cv2.VideoCapture('dogscats.mp4')
def getFrame(sec):
    vidcap.set(cv2.CAP_PROP_POS_MSEC,sec*1000)
    hasFrames,image = vidcap.read()
    if hasFrames:
        cv2.imwrite("image"+str(count)+".jpg", image) # save frame as JPG file
    return hasFrames
sec = 0
frameRate = 0.2 #//it will capture image in each 0.2 second
count=1
success = getFrame(sec)
while success:
    count = count + 1
    sec = sec + frameRate
    sec = round(sec, 2)
    success = getFrame(sec)
```

#### In [13]:

```
img_pred =image.load_img('vid1/image102.jpg',target_size= (500,500))
img_pred = image.img_to_array(img_pred)
img_pred = np.expand_dims(img_pred,axis=0)
```

### In [14]:

```
rslt =model.predict(img_pred)
print(rslt)
if rslt[0][0]==1:
    prediction ='dog'
else:
    prediction ='cat'

print(prediction)
import matplotlib.pyplot as plt
img = cv2.imread('vid1/image102.jpg')
plt.imshow(img)
plt.show()
```

### [[1.]] dog



### In [15]:

```
img_pred =image.load_img('vid1/image276.jpg',target_size= (500,500))
img_pred = image.img_to_array(img_pred)
img_pred = np.expand_dims(img_pred,axis=0)
```

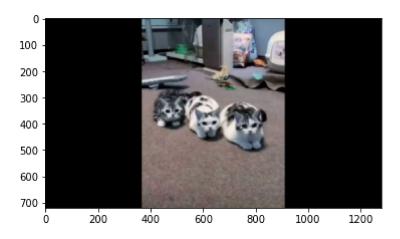
### In [16]:

```
rslt =model.predict(img_pred)
print(rslt)
if rslt[0][0]==1:
    prediction = 'dog'
else:
    prediction = 'cat'

print(prediction)
img = cv2.imread('vid1/image276.jpg')
plt.imshow(img)
plt.show()
```

# [[2.6062375e-17]]

cat



### In [10]:

```
img_pred =image.load_img('test1/Test1/dogs/2.jpg',target_size= (500,500))
img_pred = image.img_to_array(img_pred)
img_pred = np.expand_dims(img_pred,axis=0)
```

### In [11]:

```
rslt =model.predict(img_pred)
print(rslt)
if rslt[0][0]==1:
    prediction ='dog'
else:
    prediction ='cat'

print(prediction)
```

```
[[1.]]
dog
```