

Trees and Graphs

→ It is a non-linear data structure.

Tree - collection of nodes and edges.

* It is a finite non-empty set of elements.

* It is an abstract model of a hierarchical structure.

Applications:-

→ Organisation charts

→ File Systems

→ Programming environments

Tree terminology:- Root, siblings, internal node, external node, ancestors

Root - node without a parent Eg: A

Siblings - nodes share the same parent

Eg: siblings for B is C, D

Internal node - a node with atleast one children

Eg: A, B, C, D, E, F, J, I

External node - a node without children.

Eg: G, H, I, J, K, L, O, P

ancestors - parent, grandparent, grand-grand parents ---

Eg: ancestors for F - B, A

K - E, B, A

Descendent - child, grand child, grand-grand child ---

Eg: descendent of a node C - G

B - E, F, J, K, L, M, N

Depth of a node - no. of ancestors

Eg: Depth of I - 2

K - 3

C - 1

A - 0

J - 3

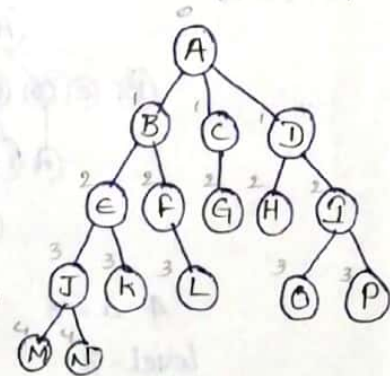
Height of a node - no. of nodes which are present in longest children path of a node.

Height of a tree - maximum depth of any node.

Eg:

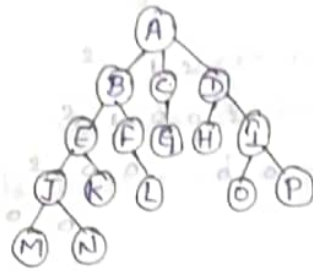
M	N	K	L	G	H	O	P
4	4	3	3	2	2	3	3

 Height of a tree = 4



Degree of a node - no. of it's children

A-3, B-2, C-1, D-2, E-2, F-1, G-0, H-0,
I-2, J-2, K, L, M, N, O, P-0

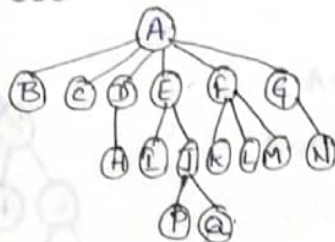


Degree of a tree - the max. degree of any node in a tree

A=3

degree of tree = 3

Level of a tree :-



level

0

1

2

3

4-1=3

level=3

Root = A

Leaves = B, C, H, I, P, Q, K, L, M, N

Internal nodes = A, D, E, F, J, G

Children of A = B, C, D, E, F, G

" " D = H

" " E = I, J

" " F = K, L, M

" " G = N

discendants of A = B, C, D, E, F, G, H, I, J, K, L, M, N, P, Q

" " E = I, J, P, Q

Siblings = {B, C, D, E, F, G}, {I, J}, {K, L, M}, {P, Q}

ancestors of H = A, D

" " P = A, E, J

" " K = A, F

If root 'A' is removed then the tree become a forest.

{B}, {C}, {D, H}, {E, I, J, P, Q}, {F, K, L, M}, {G, N}

Degree of a tree = 6 [no of children of a node 'A']

(2)

Binary tree/Dyadic tree:-

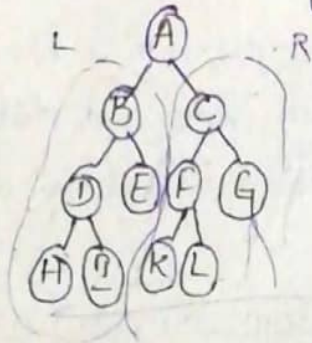
1) A binary tree is a tree with at most two children for each node. (or)

2) A binary tree either

(i) is empty (no nodes) or

(ii) has a root node, a left binary tree, and a right binary tree.

→ Each node in a binary tree has exactly two subtrees (one or both of these subtrees may be empty).



Difference between tree and binary tree:-

→ A tree can never be empty but binary tree may be empty.

6-02-17 → A node in a binary tree may have at most two children, whereas a node in a tree may have any no. of children.

→ The subtrees of each node in a binary tree are ordered; i.e., we distinguish between the left and right sub-trees. The subtrees in a tree are unordered.

Binary tree properties:-

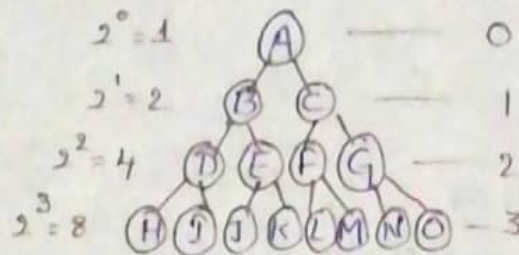
→ The maximum no. of nodes at level i is 2^i .

→ A binary tree of height h ($h \geq 0$) has at least $h+1$ and at most $2^{h+1} - 1$ nodes in it.

→ Every binary tree with n nodes ($n \geq 0$) has exactly

$n-1$ edges.

→ The height of the binary tree containing n ($n \geq 0$) nodes is at most $n-1$ and at least $\lceil \log_2(n+1) \rceil$.



Example of point 1

Height of a tree = no. of edges which are in longest path of a tree.

Representation of a binary tree:-

→ A binary tree must represent a hierarchical relationship between a parent node and child nodes.

→ There are 2 common methods used to represent a binary tree

- * linear / Sequential: representation using arrays
- * linked: representation using linked list.

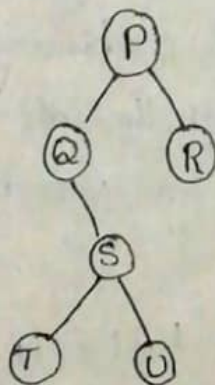
$$= 2^{n+1} - 1$$

$$= 2^{3+1} - 1$$

$$= 2^4 - 1$$

$$= 16 - 1$$

$$= 15$$



1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
P	Q	R		S					T	U				

17-02-17

Advantages of array representation

→ Any node can be accessed randomly by calculating the right index.

→ Programming languages such as BASIC, FORTRAN does not have dynamic memory allocation statistics.

→ In these languages, arrays are the only one method to store trees.

Disadvantages:-

→ Other than the binary tree the max. elements majority of the array of tree causing wastage of memory.

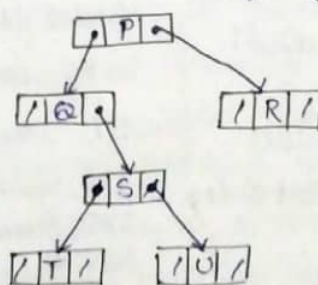
→ It is no way possible to enhance the tree structure if the array size is limited.

→ Inserting & deleting operations are inefficient in array representation.

Linked Representation:-

→ THIS TYPE of representation is efficient to represent a binary tree over arrays.

→ In this structure Every node consisting of 2 parts one for data and other to store address of left chain and another to store address of right chain.

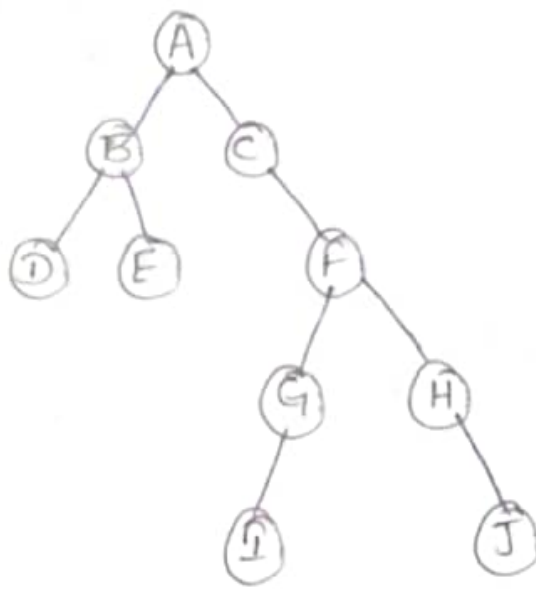


Operations on binary tree

→ Inserting a node into a tree

→ deleting a node from a tree

$$(A+B) * (C-D-E) / F - G$$



Pre-Order

In order :- DBEACFGFHJ

Post Order :-

Q-02-H

ALGORITHM FOR TRANSVERSAL OF BINARY TREE :-

BT-Recursive Inorder

BT-Recursive Preorder

//input is root node of a binary

//t- a node in the binary tree

//lchild - left child of a node

//rchild - right child of a node

i) BT_recursive(t → lchild)

ii) visit(t) [::root]

iii) BT_recursive(t → Rchild)

i) visit(t)

ii) BT_recursive(t → lchild)

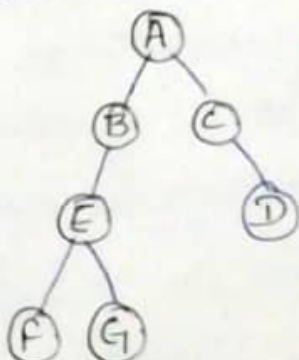
iii) BT_recursive(t → Rchild)

Post Order :-

i) BT_recursive(t → lchild)

ii) BT_recursive(t → Rchild)

iii) visit(t)



L	Root	R
---	------	---

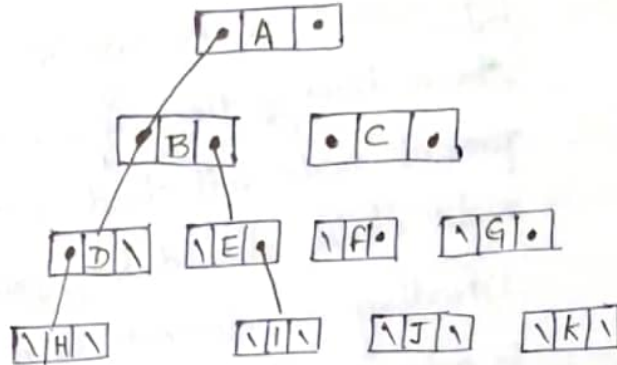
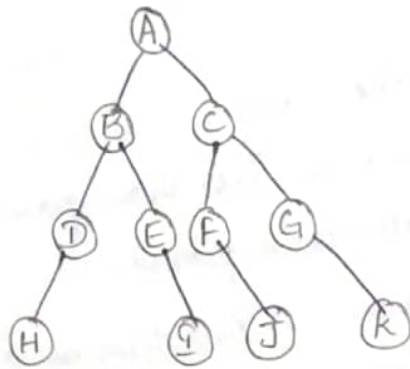
FGEBCDA - Post order

FEGBACD - Inorder

ABEFG(CD) - Pre Order

(4)
EMPTYED BINARY TREE:- If a binary tree is having n nodes then there must be a null no of null pointers.

ie we are wasting the space to represent null pointers.



Null pointers = $n+1 = 19+1 = 20$

Inorder: HDBEJATFCGK

17
Expression Trees:-

1) $((2*4)-3)+5$

postfix

2

4

2 4 *

* 3

* 3 -

- 5

- 5 +

* 3

2 4

2 4

2 4

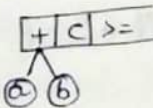
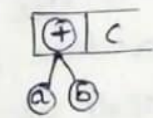
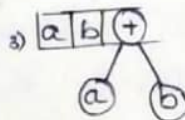
2 4

2) $((a+b)>=c) \&\&(d>e)$

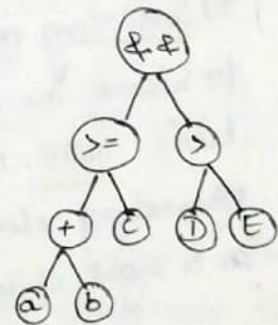
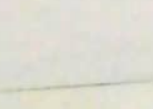
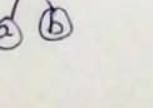
$ab+c >= de \&\&$

1) a 2) b

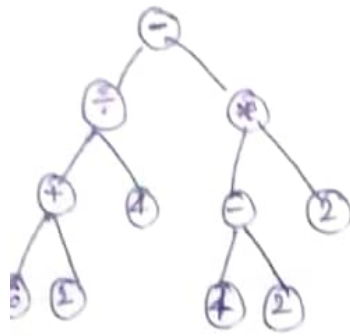
postfix



$>= d e > \&\&$



$$(6+2) \div 4 - (4-2) \times 2$$

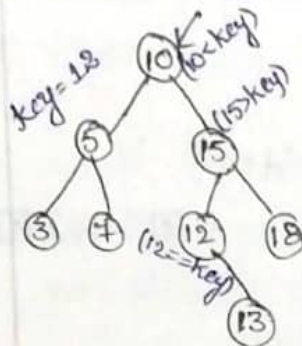


Operations on binary tree :-

In a binary tree if we take any parent node left child should be less than parent & right child should be greater than parent.

- 1) Finding an element in a tree
- 2) Inserting an element in a tree
- 3) deleting element from a tree.

1) Finding an element in a tree :- key element is compared with root node if (key == root)



else if (key > root) find in right child of root
else if (key < root) find in left child of root

2) Inserting an element in a tree :- There are 3 cases to insert an element into a tree i) root is null (empty tree)

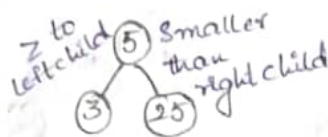
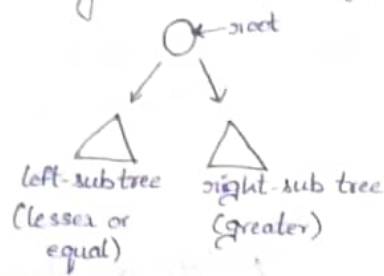
NOTE: INSERTING ELEMENT AS A ROOT NODE
ii) inserting element as a left child iii) Inserting element as a right child.

09-08-17

Applications of Queues:-

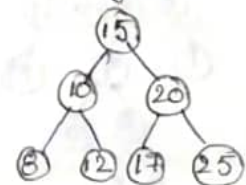
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Binary Search tree:- A binary tree in which for each node, value of all the nodes in left subtree is lesser or equal and value of all the nodes in right sub-tree is greater.



Binary search tree is a binary tree which follows the below condition:

→ if you take any node in the binary tree it should be \geq to its left child and $<$ right child



Operations on binary search tree:-

- 1) Searching an element
- 2) Inserting an element
- 3) Deleting an element

Searching an element in binary Search tree:

bool search(BST node * root, int data)

```

{
    if (root == NULL)
    {
        return false;
    }
    else if (root->data == data)
    {
        return true;
    }
    else if (data < root->data)
    {
        return search(root->left, data);
    }
    else
    {
        return search(root->right, data);
    }
}

```

Insertion Operation:-

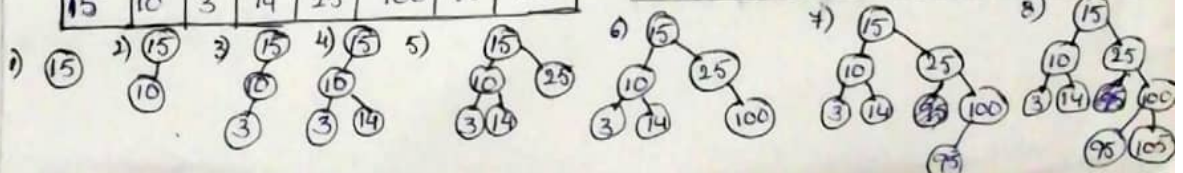
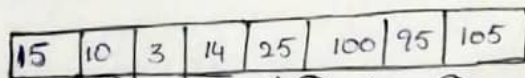
// to insert data in BST, returns address of root node

BSTNode* Insert(BSTNode* root, int data)

```

{
    if (root == NULL) // empty tree
    {
        root = GetNewNode(data);
    }
    // if data to be inserted is lesser,
    // insert in left sub-tree.
    else if (data < root->data)
    {
        root->left = Insert(root->left, data);
    }
    // else, insert in right sub-tree.
    else
    {
        root->right = Insert(root->right, data);
    }
    return root;
}

```



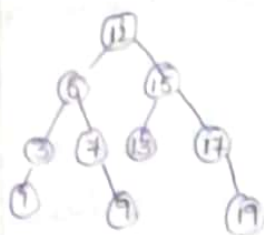
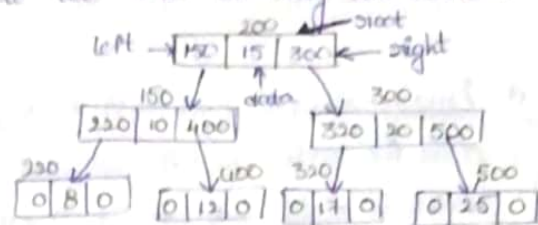
Delete an element:-

These are three situations where we are deleting an element

i) If a node is terminal node

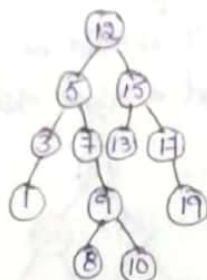
ii) " " " " having 1 child

iii) " " " " " " 2 children

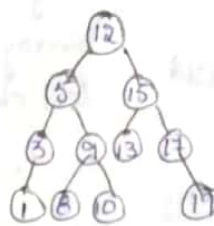


delete 17 In side tree. if you make node 17 right link as null then 17 will be detached from tree.

Delete 7

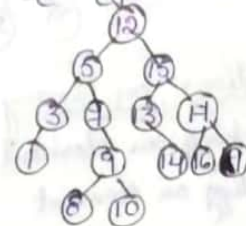


Before



After

Delete an element which is having two children:-



There are 2 methods

Method-1: Find min. node in right sub-tree.

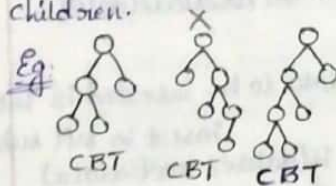
Method-2: Find max. node in left sub-tree.

Method-1: Find min in right sub-tree

i) Identify the minimum elements in its right sub-tree. ii) Copy the identified value in targeted node. iii) Delete duplicate from right sub-tree

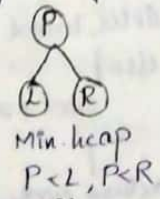
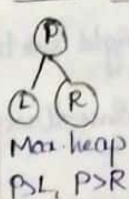
Complete BT: A CBT is a BT which must follow below condition

* Each & every node in the tree must have two children or zero children.



Heap trees: A heap tree is a CBT. It should follow order property.

Order Property: 2 types of order property

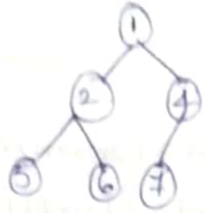


Construction of heap trees:-

Day 3-1

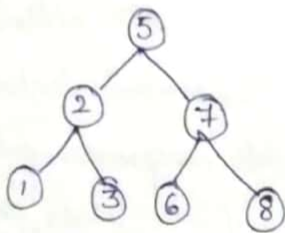
Complete Binary Tree

A binary tree that is completely filled with the exception of the lowest level that is filled from left to right.



Binary Search Tree

- Nodes to the left are less than the root node while nodes to the right are greater than the root node.
- The BST is used in Searching & Sorting techniques.

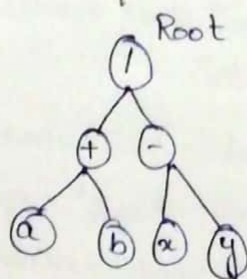


Expression Tree

Used to evaluate Simple arithmetic expression.

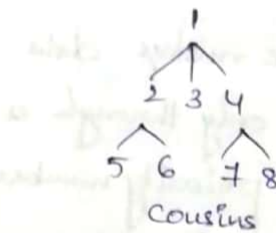
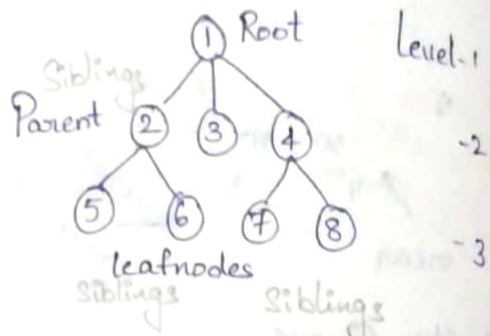
Expression trees are mainly used to solve algebraic Expressions.

$(a+b)/(x-y)$

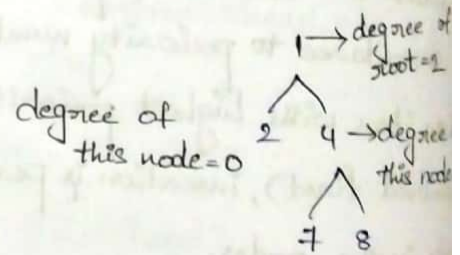


Trees

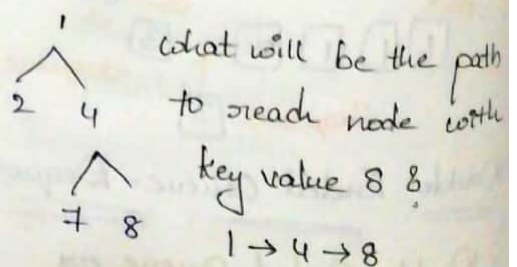
- Non-linear Hierarchical DS.
- Collection of nodes Connected.
- One of the node is designated as root node & remaining - child leaf nodes of the root node.
- Used in many applications in the field.



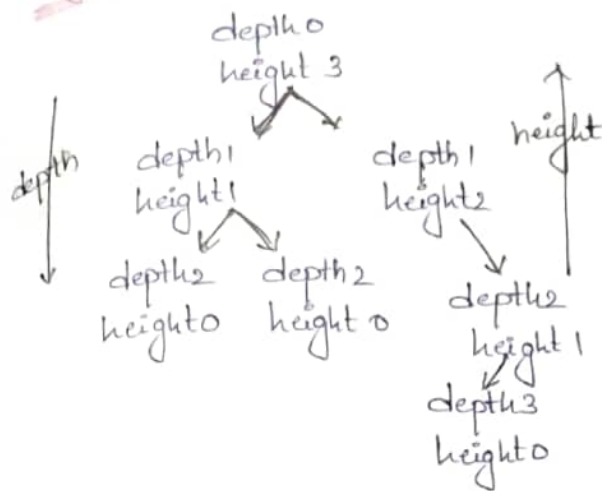
Degree of the tree:-



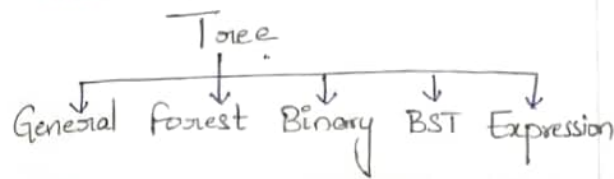
Path of the tree:-



② Height & depth of the tree

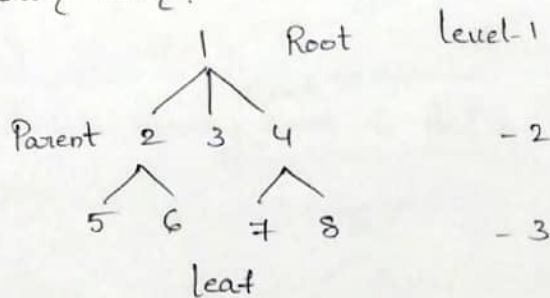


Tree-Types

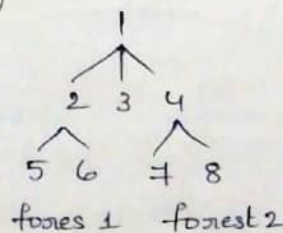


1) General Trees

- Basic representation of a tree
- has node & 1 or more children.
- The root node is present at level 1 & all other nodes may be present at various levels.

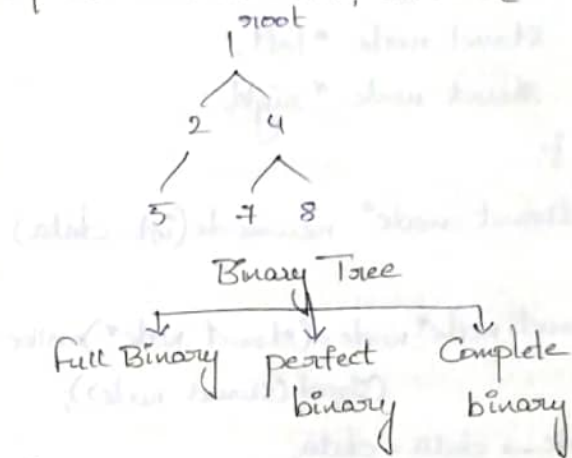


2) Forest - a kind of tree obtained while deleting the root or parent node from the tree.



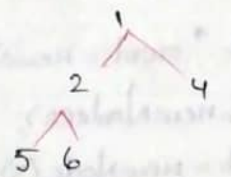
③ Binary Tree - in which each node has atmost 2 child nodes.

- Used in a range of applications like expression evaluation, databases -



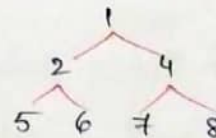
Full Binary Tree:-

- * each node has exactly zero or 2 children.
- * Every node other than leaf nodes has 2 child nodes.



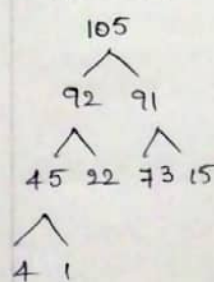
Perfect Binary Tree

- All nodes have 2 children & all leaves are at same level.

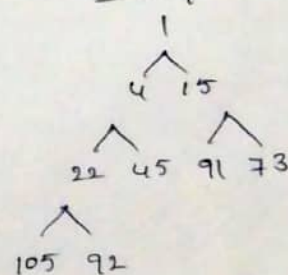


4, 92, 73, 45, 22, 91, 15, 105, 1

Max heap



Min heap

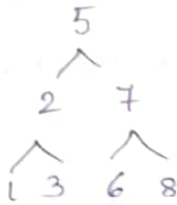


Day 3.2

BST

Nodes to the left are less than the root node while the nodes to the right are greater than the root node.

Used in Searching & Sorting techniques.



Binary Search Tree - Insertion

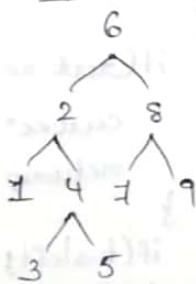
Traverse using in-order traversal.

Eg:

Ip:

6 2 8 7 1 4 5 3 9

Op:

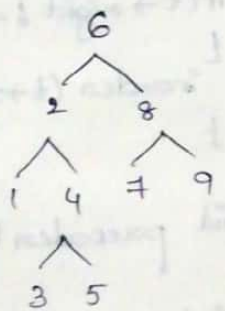


Binary Search Tree - Searching

Given a binary search tree & find a value in it.

Ip: 4

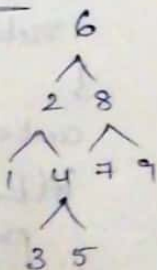
Op: found



Binary Search Tree - Deletion

Given a BST, find & delete the given value from it.

Eg:



Case 1: delete a leaf node

Ip: 3

Case 2: Delete a node with 1 child

Ip: 4

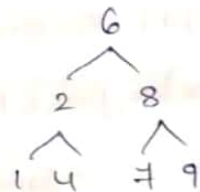
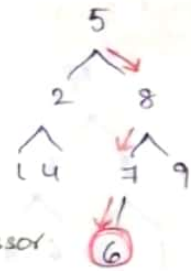
Case 3: delete a node with 2 children

Ip: 5

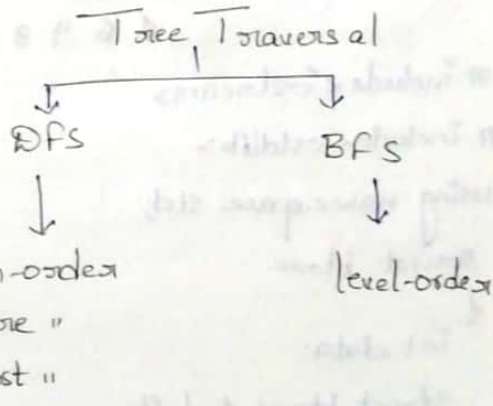
Step 1: find in-order successor of 5.

Step 2: Replace 5 with in-order successor

Step 3: Delete in-order successor



Tree Traversal Techniques



In-order - left Root Right

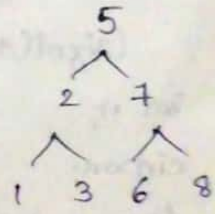
Pre order - Root left Right

Post " - left Right root

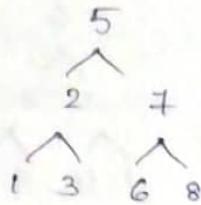
Level " - level wise from left to right

Inorder

1 2 3 5 6 7 8

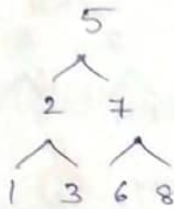


Pre-order



5 2 1 3 7 6 8

Post order



1 3 2 6 8 7 5

Program to create & implement a
BST Using Dfs to display the
elements (in-order, pre & post-order)

Sample i/p:

5
5 8 9 4 6

sample o/p:

4 5 6 8 9
5 4 8 6 9
4 6 9 8 5

```
#include <iostream>
#include <cstdlib>
using namespace std;
struct btree
{
    int data;
    struct btree * left;
    struct btree * right;
};
struct btree * root * temp;
void Create()
{
    temp = (struct btree *) malloc
        (sizeof(struct btree));
    int n;
    cin >> n;
    temp->data = n;
```

```
temp->right = temp->left;
}
void insert(struct btree *t)
{
    if(t->data < temp->data &&
        t->right != NULL) { insert(t->right);
    }
    else if(t->data < temp->data && t->right
        NULL) { t->right = temp;
    }
    else if(t->data > temp->data && t->left
        != NULL) { insert(t->left);
    }
    else if(t->data > temp->data && t->left
        NULL) { t->left = temp;
    }
}
void inorder(struct btree *t)
{
    if(t == NULL)
        return;
    if(t->left != NULL)
        inorder(t->left);
    cout << t->data << " ";
    if(t->right != NULL)
        inorder(t->right);
}
void preorder(struct btree *t)
{
    if(t == NULL)
        return;
    cout << t->data << " ";
    if(t->left != NULL)
        preorder(t->left);
    if(t->right != NULL)
```



```

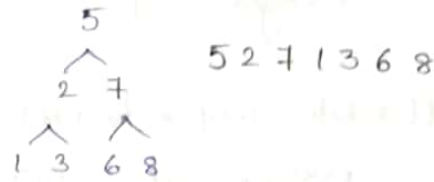
        preorder(t->right);
    }

void postorder(struct btree *t)
{
    if(root == NULL)
    {
        cout << "No element";
        return;
    }
    if(t->left != NULL)
        postorder(t->left);
    if(t->right != NULL)
        postorder(t->right);
    cout << t->data << " ";

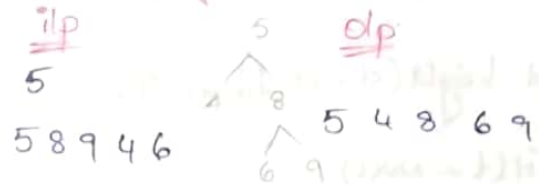
int main()
{
    int n;
    cin >> n;
    root = 0;
    for(int i=0; i<n; i++)
    {
        create();
        if(root == NULL)
            root = temp;
        else
            insert(root);
    }
    inorder(root);
    cout << endl;
    preorder(root);
    cout << endl;
    postorder(root);
}

```

Level Order Traversal



Write a program to create and implement a BST structure. Use BFS to display the elements (level-order)



```

#include <iostream>
#include <cstdlib>
using namespace std;

struct btree
{
    int data;
    struct btree *left;
    struct btree *right;
};

struct btree *root, *temp;

void create()
{
    temp = (struct btree *) malloc(sizeof(struct btree));
    int n;
    cin >> n;
    temp->data = n;
    temp->right = temp->left = NULL;
}

void insert(struct btree *t)
{
    if(t->data < temp->data)
    {
        if(t->left != NULL)
            insert(t->left);
        else
            t->left = temp;
    }
    else if(t->data > temp->data)
    {
        if(t->right != NULL)
            insert(t->right);
        else
            t->right = temp;
    }
}

```

P2

```
t->right == NULL)
t->right = temp;
```

```
}
else if (t->data > temp->data && t->left !=
        NULL) { insert(t->left, temp);
}
}
```

P3

```
else if (t->data > temp->data &&
        t->left == NULL) { t->left = temp;
}
}
```

```
int height(struct btree *t)
```

```
{
    if (t == NULL)
```

P4

```
{
    return 0;
}
```

P5

```
else
```

P6

```
{
```

P7

```
int lheight = height(t->left);
```

P8

```
int rheight = height(t->right);
```

P9

```
if (lheight > rheight)
```

P10

```
{
    return lheight + 1;
}
```

P11

```
else
```

P12

```
{
    return rheight + 1;
}
}
```

```
void printgivenlevel(struct btree *t,
                    int i)
```

```
{
    if (t == NULL)
```

```
{
    return;
}
```

```
if (i == 1)
```

```
{
    cout << t->data << " ";
}
```

```
else if (i > 1)
```

```
{
    printgivenlevel(t->left, i-1);
    printgivenlevel(t->right, i-1);
}
```

```
}
```

```
void levelorder(struct btree *root)
```

```
{
    int h = height(t);
```

```
int i;
```

```
for (i = 1; i <= h; i++)
```

```
{
    printgivenlevel(t, i);
}
```

```
}
```

```
int main()
```

```
{
```

```
int n;
```

```
cin >> n;
```

```
for (int i = 0; i < n; i++)
```

```
{
```

```
create();
```

```
if (root == NULL)
```

```
{
```

```
root = temp;
```

```
}
```

```
else
```

```
{
```

```
insert (root);
```

```
}
```

```
}
```

```
levelorder(root);
```

```
}
```