Fiscal Rule

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Let D_t denote the government's outstanding real debt. T_t is total tax revenue, T_t^H is total household transfers, G_t is government purchases of goods, L_t is the real value of purchases of labor services, and S_t is subsidies to government run firms.

$$D_{t+1} = D_t(1+r_t) - T_t + T_t^H + G_t + L_t + S_t \tag{1}$$

Letting a carat denote the ratio of a variable to GDP, we can rewrite this as follows:

$$(1+g_{Yt})\hat{D}_{t+1} = \hat{D}_t(1+r_t) - \hat{T}_t + \hat{T}_t^H + \hat{G}_t + \hat{L}_t + \hat{S}_t$$
 (2)

We need to adopt a government fiscal rule that determines how our residual expenditure \hat{G}_t evolves over time.

One way is to adopt a balanced budget rule which keeps the debt-to-GDP ratio constant at it's initial value of \hat{D}_0 .

$$(1+g_{Yt})\hat{D}_0 = \hat{D}_0(1+r_t) - \hat{T}_t + \hat{T}_t^H + \hat{G}_t + \hat{L}_t + \hat{S}_t$$
$$\hat{G}_t = \hat{D}_0(g_{Yt} - r_t) + \hat{T}_t - \hat{T}_t^H - \hat{L}_t - \hat{S}_t$$
(3)

Another rule is to hold govenrment spending constant and let debt evolve as it will for several period. Then in period T impose fiscal austerity which forces \hat{G}_t to adjust over time so that \hat{D}_t goes to a steady value.

$$\hat{G}_t - \bar{G} = \rho_t(\hat{D}_t - \bar{D}); \quad \rho_t < 0 \tag{4}$$

Substituting this into (2) gives:

$$(1+g_{Yt})\hat{D}_{t+1} = \hat{D}_t(1+r_t) - \hat{T}_t + \hat{T}_t^H + \rho_t(\hat{D}_t - \bar{D}) + \bar{G} + \hat{L}_t + \hat{S}_t$$
$$\hat{D}_{t+1} = \frac{\hat{D}_t(1+r_t) - \hat{T}_t + \hat{T}_t^H + \rho_t(\hat{D}_t - \bar{D}) + \bar{G} + \hat{L}_t + \hat{S}_t}{1+g_{Yt}}$$
(5)

Consider the steady state version of this.

$$(1 + \bar{g}_Y)\bar{D} = \bar{D}(1 + \bar{r}) + \bar{T} - \bar{T}^H + \rho_t(\bar{D} - \bar{D}) + \bar{G} + \bar{L} + \bar{S}_t$$
$$\bar{G} = \bar{D}(\bar{g}_Y - \bar{r}) + \bar{T} - \bar{T}^H - \bar{L} - \bar{S}$$
(6)

This tells us the long-run value of government spending to GDP that will maintain the debt to GDP target.

In order for (5) to be a contraction mapping over \hat{D} and thus converge to a steady state, we must put bounds on ρ_t . Rearranging (5) and using (6):

$$(1+g_{Yt})\hat{D}_{t+1} = \hat{D}_{t}(1+r_{t}) - \hat{T}_{t} + \hat{T}_{t}^{H} + \rho_{t}(\hat{D}_{t} - \bar{D}) + \hat{L}_{t} + \hat{S}_{t} + \bar{D}(\bar{g}_{Y} - \bar{r}) + \bar{T} - \bar{T}^{H} - \bar{L} - \bar{S}$$

$$(1+g_{Yt})\hat{D}_{t+1} = \hat{D}_{t}(1+r_{t}) - \hat{T}_{t} + \hat{T}_{t}^{H} + \rho_{t}\hat{D}_{t} - \rho_{t}\bar{D} + \hat{L}_{t} + \hat{S}_{t} + \bar{g}_{Y}\bar{D} - \bar{r}\bar{D} + \bar{T} - \bar{T}^{H} - \bar{L} - \bar{S}$$

$$(1+g_{Yt})\hat{D}_{t+1} = \hat{D}_{t}(1+r_{t}) + \rho_{t}(\hat{D}_{t} - \bar{D}) + (\bar{g}_{Y} - \bar{r})\bar{D} - (\hat{T}_{t} - \bar{T}) + (\hat{T}_{t}^{H} - \bar{T}^{H}) + (\hat{L}_{t} - \bar{L}) + (\hat{S}_{t} - \bar{S})$$

$$\hat{D}_{t+1} - \bar{D} = \hat{D}_{t}\frac{1+r_{t}}{1+g_{Yt}} + \frac{\rho_{t}}{1+g_{Yt}}(\hat{D}_{t} - \bar{D}) + (\frac{\bar{g}_{Y} - \bar{r}}{1+g_{Yt}} - 1)\bar{D} + \frac{-(\hat{T}_{t} - \bar{T}) + (\hat{T}_{t}^{H} - \bar{T}^{H}) + (\hat{L}_{t} - \bar{L}) + (\hat{S}_{t} - \bar{S})}{1+g_{Yt}}$$

$$\hat{D}_{t+1} - \bar{D} = \frac{1+r_{t}+\rho_{t}}{1+g_{Yt}}(\hat{D}_{t} - \bar{D}) + \frac{-(\hat{T}_{t} - \bar{T}) + (\hat{T}_{t}^{H} - \bar{T}^{H}) + (\hat{L}_{t} - \bar{L}) + (\hat{S}_{t} - \bar{S})}{1+g_{Yt}}$$

$$(7)$$

We need $\frac{\hat{D}_{t+1}-\bar{D}}{\hat{D}_t-\bar{D}}<1$ for stability. Equation (7) gives:

$$\frac{\hat{D}_{t+1} - \bar{D}}{\hat{D}_t - \bar{D}} = \frac{1 + r_t + \rho_t}{1 + g_{Yt}} + \frac{-(\hat{T}_t - \bar{T}) + (\hat{T}_t^H - \bar{T}^H) + (\hat{L}_t - \bar{L}) + (\hat{S}_t - \bar{S})}{(1 + g_{Yt})(\hat{D}_t - \bar{D})} < 1$$

$$\frac{1 + r_t + \rho_t}{1 + g_{Yt}} < \frac{(\hat{T}_t - \bar{T}) - (\hat{T}_t^H - \bar{T}^H) - (\hat{L}_t - \bar{L}) - (\hat{S}_t - \bar{S})}{(1 + g_{Yt})(\hat{D}_t - \bar{D})}$$

$$\rho_t < (1 + r_t) \frac{(\hat{T}_t - \bar{T}) - (\hat{T}_t^H - \bar{T}^H) - (\hat{L}_t - \bar{L}) - (\hat{S}_t - \bar{S})}{\hat{D}_t - \bar{D}} \tag{8}$$