

## Weighted Least Squares

Measurements prone to error.

Recall:  $A\vec{x} = \vec{b}$

Choose  $x$  s.t.  $\|b - Ax\|^2$  is minimized

If  $b \in \text{col sp}(A)$ , then  $\|b - Ax\|^2 = 0$

Error:  $\|b - Ax\|^2 = 0$  if  $b \in \text{col sp}(A)$ .

$\neq 0$  if  $b \notin \text{col. sp}(A)$ .

$\Rightarrow \|b - A\hat{x}\|^2$        $A\hat{x}$ : Proj. of  $b$  onto the  $\text{col. sp}(A)$ .

$\Rightarrow$  We will not solve  $A\vec{x} = \vec{b}$ . Instead, we solve the normal eqn

$$\underline{A^T A \hat{x}} = \underline{A^T b}.$$

If  $\vec{b}$  has measurement errors  $\Rightarrow$  Measurement errors in  $\vec{b}$  are indep r.v.s. with mean 0 & Variance = 1. then minimizing  $\|\vec{b} - A\hat{x}\|^2$  makes sense. Gaussian/Normal.

Suppose if the errors are not indep & are of different variances then  $\|\vec{b} - A\hat{x}\|^2$  minimiz<sup>n</sup> does not make sense.

Measuring resistance values.

	Measurement	1	2	3	4	...
R.	Resistance Val.	102	98	104	95	
	( $\Omega$ )					

What is the true value of R?

$$\begin{array}{rclcl}
 & \text{True} & & \text{Noise} & \\
 & \text{Resistance} & & & \\
 y_1 & = & x \Omega & + & v_1 \\
 y_2 & : & x & + & v_2 \\
 y_3 & : & x & + & v_3 \\
 y_4 & : & x & + & v_4
 \end{array} \left. \vphantom{\begin{array}{rclcl} y_1 \\ y_2 \\ y_3 \\ y_4 \end{array}} \right\}$$

Cost fn: Minimize :  $(y_1 - x)^2 + (y_2 - x)^2 + \dots + (y_4 - x)^2$ .

$$e^2 = \sum_{i=1}^4 \left( \vec{y}_i - \vec{x} \right)^2 = \|\vec{y} - \vec{x}\|^2 = (\vec{y} - \vec{x})^T (\vec{y} - \vec{x}).$$

\* Measure the resistance value across 2 multimeter

M1: Variance  $10 \Omega$

( )

M2 Variance  $1 \Omega$ .

( )

Since  $\sigma_B^2 = 1$  &  $\sigma_A^2 = 10$ , Multimeter B is more reliable than A.

⇒ Give more importance to value measured by B  
& less to the value measured by A.

Incorporating this idea, we get the error that has to be minimized is given as follows.

Minimize 
$$\sum_{i=1}^n \underbrace{(b_i - Ax_i)^2}_{\sigma_i^2}$$

A function that needs to be optimized is called the objective fn / cost fn.

Each  $b_i$  has zero mean & Variance =  $\sigma_i^2$ . → Indep Measurement

$$Z = \frac{X - \mu}{\sigma}$$

$$\text{Mean} = 0 \quad \text{Var}(Z) = 1$$

$$\begin{aligned} \therefore a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n &= b_1 \\ &\vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n &= b_m \end{aligned} \quad \left. \vphantom{\begin{aligned} \therefore a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n &= b_1 \\ &\vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n &= b_m \end{aligned}} \right\} \begin{array}{l} m > n \\ \text{no soln} \end{array}$$

Divide each eqn by  $\sigma_i$ , we have the variance of

$$\frac{b_i}{\sigma_i} = 1.$$

$$V = \begin{bmatrix} \sigma_1^2 & & 0 \\ & \sigma_2^2 & \\ 0 & & \ddots & \\ & & & \sigma_m^2 \end{bmatrix}^{m \times m}$$

$$V^{1/2} =$$

$$A \vec{x} = \vec{b}$$

Dividing both sides by  $\sigma_i$  we get

$$\Rightarrow V^{-1/2} A \vec{x} = V^{-1/2} \vec{b}$$

$$\text{where } V^{-1/2} = \begin{bmatrix} \frac{1}{\sigma_1} & & \\ & \frac{1}{\sigma_2} & \\ & & \ddots & \\ & & & \frac{1}{\sigma_m} \end{bmatrix}$$

$$\boxed{V^{-1/2} A \hat{x} = V^{-1/2} b}$$

$$\underbrace{V^{-1/2} A}_{M} x = \underbrace{V^{-1/2} b}_{b}$$

$$Mx = b$$

$$M^T M x = M^T b$$

Apply ordinary least sq. here.

$$(V^{-1/2} A)^T V^{-1/2} A x = (V^{-1/2} A)^T V^{-1/2} b$$

$$\Rightarrow A^T V^{-1/2} V^{-1/2} A x = A^T V^{-1/2} V^{-1/2} b$$

$$\Rightarrow \boxed{A^T V^{-1} A x = A^T V^{-1} b} \quad \text{Expression for WLS.}$$

$$\textcircled{V} = \begin{bmatrix} \sigma_1^2 & & & \\ & \sigma_2^2 & & \\ & & \ddots & \\ & & & \sigma_m^2 \end{bmatrix} \Rightarrow V^{-1} = \begin{bmatrix} 1/\sigma_1^2 & & 0 \\ & \ddots & \\ 0 & & 1/\sigma_m^2 \end{bmatrix}$$

Since  $V^{-1}$  has elements  $1/\sigma_i^2$ , more reliable equations (with smaller variance) have larger weights.

Recall: If  $b \notin \text{col. sp}(A)$ , we can only estimate  $\vec{b}$  by taking the proj of  $b$  onto  $\text{col. sp}(A)$ .

$$A \vec{x} = b \Rightarrow A \hat{\vec{x}} = P \vec{b}$$

Find the variance of  $\hat{\vec{x}}$  in order to ascertain the reliability of the whole expt.

$$b = A \hat{\vec{x}}.$$

If  $b$  is zero mean  $\Rightarrow \hat{\vec{x}}$  has also zero mean.

$$\text{CovVar}(\hat{\vec{x}})_{\text{Matrix}} = E \left[ \underbrace{(\hat{\vec{x}} - \vec{x})(\hat{\vec{x}} - \vec{x})^T}_{\Downarrow} \right]. \quad \begin{array}{l} y = 5x. \\ E[x] = 0 \quad E(y) = ? \end{array}$$

$$\text{Cov} = E[(x - \bar{x})(x - \bar{x})^T]$$

$$\boxed{\text{Cov}(\hat{\vec{x}}) = (A^T V^{-1} A)^{-1}}$$

$$y = (a_1 x_1 + a_2 x_2) \quad \underbrace{\begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix}} \underbrace{\begin{bmatrix} a_1 \\ a_2 \end{bmatrix}} = \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}.$$

$$\text{Var}(y) = a_1^2 \text{Var}(x_1) + a_2^2 \text{Var}(x_2) + 2 a_1 a_2 \text{Corr}(x_1, x_2).$$

$$= \begin{bmatrix} a_1 & a_2 \end{bmatrix} \begin{bmatrix} \text{Var}(x_1) & \text{Corr}(x_1, x_2) \\ \text{Corr}(x_1, x_2) & \text{Var}(x_2) \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \end{bmatrix}.$$

$$y = (c_1 x_1 + c_2 x_2) = (b_{11} a_1 + b_{12} a_2) x_1 + (b_{21} a_1 + b_{22} a_2) x_2.$$

$$\text{Var}(y) = (c_1 \quad c_2) \vee \begin{pmatrix} c_1 \\ c_2 \end{pmatrix}.$$

$$= (b_{11} a_1 + b_{12} a_2 \quad b_{21} a_1 + b_{22} a_2) \vee \begin{pmatrix} b_{11} a_1 + b_{12} a_2 \\ b_{21} a_1 + b_{22} a_2 \end{pmatrix}$$

$$= \begin{bmatrix} a_1 & a_2 \end{bmatrix} \begin{bmatrix} b_{11} & b_{21} \\ b_{12} & b_{22} \end{bmatrix} \vee \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix}$$

$$\boxed{\vec{a}^T B^T \vee B \vec{a}}.$$



Ex: Suppose a doctor measures your bp 3 times  
and gets the following numbers.

$$x = b_1, \quad x = b_2, \quad x = b_3$$

$$1x = b_1$$

$$1x = b_2$$

$$1x = b_3$$

$$A = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$$\vec{x} = x.$$

$$\vec{b} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}.$$

$$V = \begin{bmatrix} \sigma_1^2 & 0 & 0 \\ 0 & \sigma_2^2 & 0 \\ 0 & 0 & \sigma_3^2 \end{bmatrix}$$

$$\sigma_1^2 = \frac{1}{9} \quad \sigma_2^2 = \frac{1}{4} \quad \text{and} \quad \sigma_3^2 = 1$$

$$V = \begin{pmatrix} 1/9 & 0 & 0 \\ 0 & 1/4 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$V^{-1} = \begin{pmatrix} 9 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$V^{-1/2} A \hat{x} = V^{-1/2} b$$

$$\begin{bmatrix} 3 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \hat{x} = \begin{bmatrix} 3 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

$$= \begin{aligned} 3 \hat{x} &= 3 b_1 \\ 2 \hat{x} &= 2 b_2 \\ 1 \hat{x} &= 1 b_3. \end{aligned}$$

$$A^T V^{-1} A x = A^T V^{-1} b$$

$$\Rightarrow \begin{bmatrix} 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 9 & & \\ & 4 & \\ & & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \hat{x} = \begin{bmatrix} 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 900 \\ 040 \\ 001 \end{bmatrix}$$

$$\begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 9 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \hat{x} = \begin{bmatrix} 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 9 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 9\hat{x} \\ 4\hat{x} \\ \hat{x} \end{bmatrix} = [9b_1 + 4b_2 + b_3]$$

$$= 14\hat{x} = 9b_1 + 4b_2 + b_3$$

$$\boxed{\hat{x} = \frac{9b_1 + 4b_2 + b_3}{14}}$$

$\Rightarrow$  Weighted  
average of  
 $b_1, b_2, b_3$

Ex: 2

$$x = b_1$$

$$x = b_2.$$

Variances  $\sigma_1^2$  &  $\sigma_2^2$ .

Find the best estimate  $\hat{x}$  based on  $b_1$  &  $b_2$ .

$$A \hat{x} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \hat{x} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix} \quad v = \begin{bmatrix} \sigma_1^2 & 0 \\ 0 & \sigma_2^2 \end{bmatrix}$$

$$V^{-1/2} A \hat{x} = V^{-1/2} b$$

$$= \begin{pmatrix} 1/\sigma_1 & 0 \\ 0 & 1/\sigma_2 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \hat{x} = \begin{pmatrix} 1/\sigma_1 & 0 \\ 0 & 1/\sigma_2 \end{pmatrix} \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}$$

Normal eqn:  $A^T V^{-1} \hat{x} = A^T V^{-1} b.$

$$= \begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} 1/\sigma_1^2 & 0 \\ 0 & 1/\sigma_2^2 \end{bmatrix} \hat{x} = \begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} 1/\sigma_1^2 & 0 \\ 0 & 1/\sigma_2^2 \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$$

$$= \frac{x}{\sigma_1^2} + \frac{x}{\sigma_2^2} = \frac{b_1}{\sigma_1^2} + \frac{b_2}{\sigma_2^2}$$

$$\hat{x} = \frac{\frac{b_1}{\sigma_1^2} + \frac{b_2}{\sigma_2^2}}{\frac{1}{\sigma_1^2} + \frac{1}{\sigma_2^2}}$$

WLS E,

$$\text{If } \sigma_2 = 0 \Rightarrow \hat{x} = \frac{\sigma_2^2 b_1 + \sigma_1^2 b_2}{\sigma_1^2 + \sigma_2^2}$$

$$= \frac{\sigma_1^2 b_2}{\sigma_1^2} = b_2.$$

$$\text{If } \sigma_2 = \infty \Rightarrow \hat{x} = b_1$$

RWLS / Kalman / GMM.

Calculus → Unit 4: Diff, Gradient, Hessian

Derivatives of Matrices

Unit 6. LS, GDA, Optimiz<sup>n</sup> → <sup>Unconst.</sup> Constrained

Lagrangian