#### 1

## **GATE ASSIGNMENT 4**

# Ananthoju Pranav Sai AI20BTECH11004

Download all python codes from

https://github.com/Ananthoju-Pranav-Sai/EE3900/blob/main/Gate Assignment 4/codes

and latex-tikz codes from

https://github.com/Ananthoju-Pranav-Sai/EE3900/ tree/main/Gate\_Assignment\_4/ Gate Assignment 4.tex

### 1 GATE EC 2000 Q.2.31

Let u(t) be the step function. Plot the wave form corresponding to the convolution of u(t) - u(t-1) with u(t) - u(t-2).

### 2 Solution

We define unit step function as follows

$$u(t) = \begin{cases} 0 & t < 0 \\ 1 & t \ge 0 \end{cases}$$
 (2.0.1)

Now let f(t) = u(t) - u(t-1) and g(t) = u(t) - u(t-2) then,

$$f(t) = \begin{cases} 0 & t < 0 \\ 1 & 0 \le t < 1 \\ 0 & t \ge 1 \end{cases}$$
 (2.0.2)

$$\implies f(t) = rect\left(t - \frac{1}{2}\right) \tag{2.0.3}$$

$$g(t) = \begin{cases} 0 & t < 0 \\ 1 & 0 \le t < 2 \\ 0 & t \ge 2 \end{cases}$$
 (2.0.4)

$$\implies g(t) = rect\left(\frac{t-1}{2}\right)$$
 (2.0.5)

Let y(t) be convolution of f(t) and g(t) So we have,

$$y(t) = \int_{-\infty}^{\infty} f(\tau)g(t-\tau) d\tau \qquad (2.0.6)$$

$$\implies y(t) = \int_0^1 g(t - \tau) d\tau \tag{2.0.7}$$

(2.0.8)

$$y(t) = \begin{cases} 0 & t < 0 \\ \int_0^t 1 \, d\tau & 0 \le t < 1 \end{cases}$$
$$\int_0^1 1 \, d\tau & 1 \le t < 2$$
$$\int_{t-2}^1 1 \, d\tau & 2 \le t < 3$$
$$0 & t \ge 3$$
 (2.0.9)

So we get y(t) as follows

$$y(t) = \begin{cases} 0 & t < 0 \\ t & 0 \le t < 1 \\ 1 & 1 \le t < 2 \\ 3 - t & 2 \le t < 3 \\ 0 & t \ge 3 \end{cases}$$
 (2.0.10)

Fourier Transform of the output

$$Y(\omega) = F(\omega)G(\omega) \tag{2.0.11}$$

We know that the fourier transform

$$rect\left(\frac{t}{\tau}\right) \Longleftrightarrow \tau sinc\left(\frac{\omega\tau}{2}\right)$$
 (2.0.12)

and using the properties of fourier transform

$$x(t \pm t_0) \Longleftrightarrow X(\omega)e^{\pm i\omega t_0}$$
 (2.0.13)

$$x(\alpha t) \Longleftrightarrow \frac{1}{|\alpha|} X\left(\frac{\omega}{\alpha}\right)$$
 (2.0.14)

We get

$$F(\omega) = sinc\left(\frac{\omega}{2}\right)e^{\left(-\frac{i\omega}{2}\right)}$$
 (2.0.15)

$$G(\omega) = 2\operatorname{sinc}(\omega) e^{-i\omega}$$
 (2.0.16)

Using (2.0.11),(2.0.15) and (2.0.16)

$$\implies Y(\omega) = 2 \operatorname{sinc}(\omega) \operatorname{sinc}\left(\frac{\omega}{2}\right) e^{\left(-\frac{3i\omega}{2}\right)} \quad (2.0.17)$$

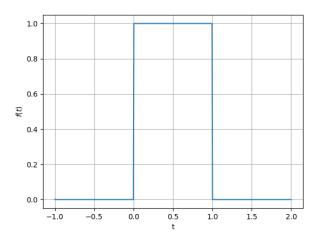


Fig. 0: Plot of f(t)

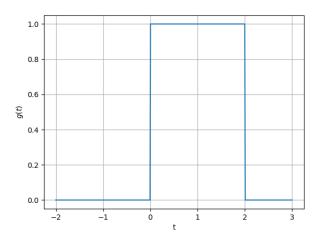


Fig. 0: Plot of g(t)

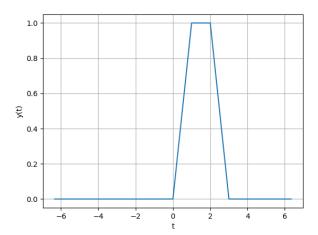


Fig. 0: Simulated plot of output signal y(t)

We can represent the output signal as sum of two shifted triangles as follows. So output signal y(t) can

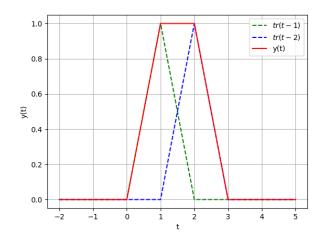


Fig. 0: y(t) as sum of 2 shifted triangles

also be written as

$$y(t) = \triangle(t-1) + \triangle(t-2)$$
 (2.0.18)

where triangular function  $\triangle(t)$  is defined as

$$\Delta(t) = rect(t) * rect(t)$$
 (2.0.19)