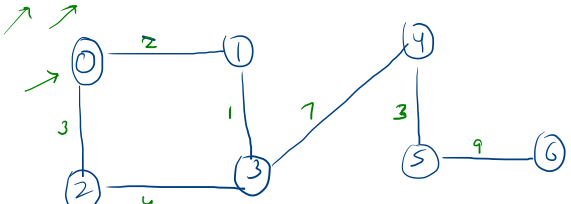
graph

src, des

Vertex => V

8 Vertex

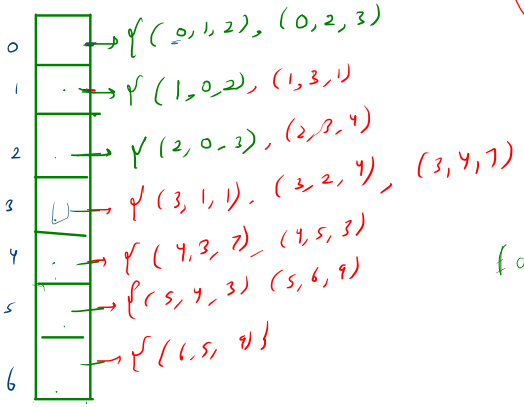
|| nodes



ArrayList<Edge>[] graph = new ArrayList[V]

O(E)

Adjacency list =>

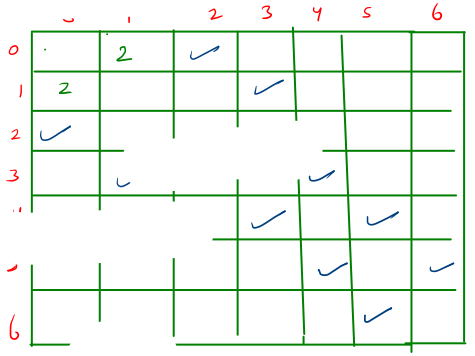


0 → (0,1,2) (0,2,3)

0 → (1,2) (2,3)

Edge d

V

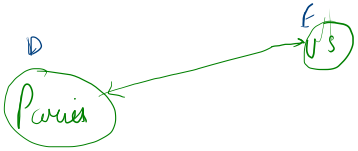


=> adjacency matrix

not efficient

O(V²)

O(V)

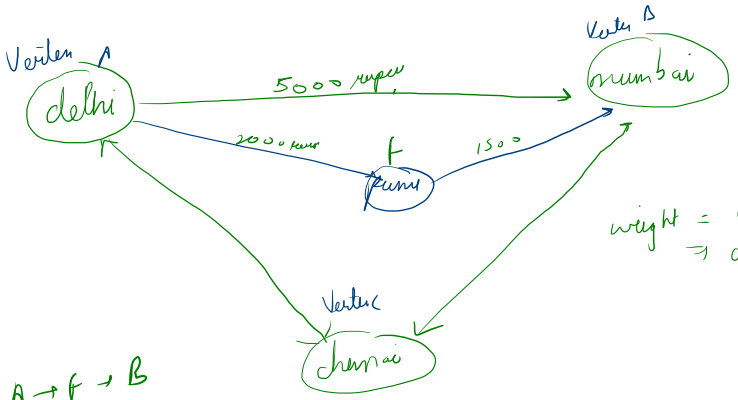


Vertex

edges

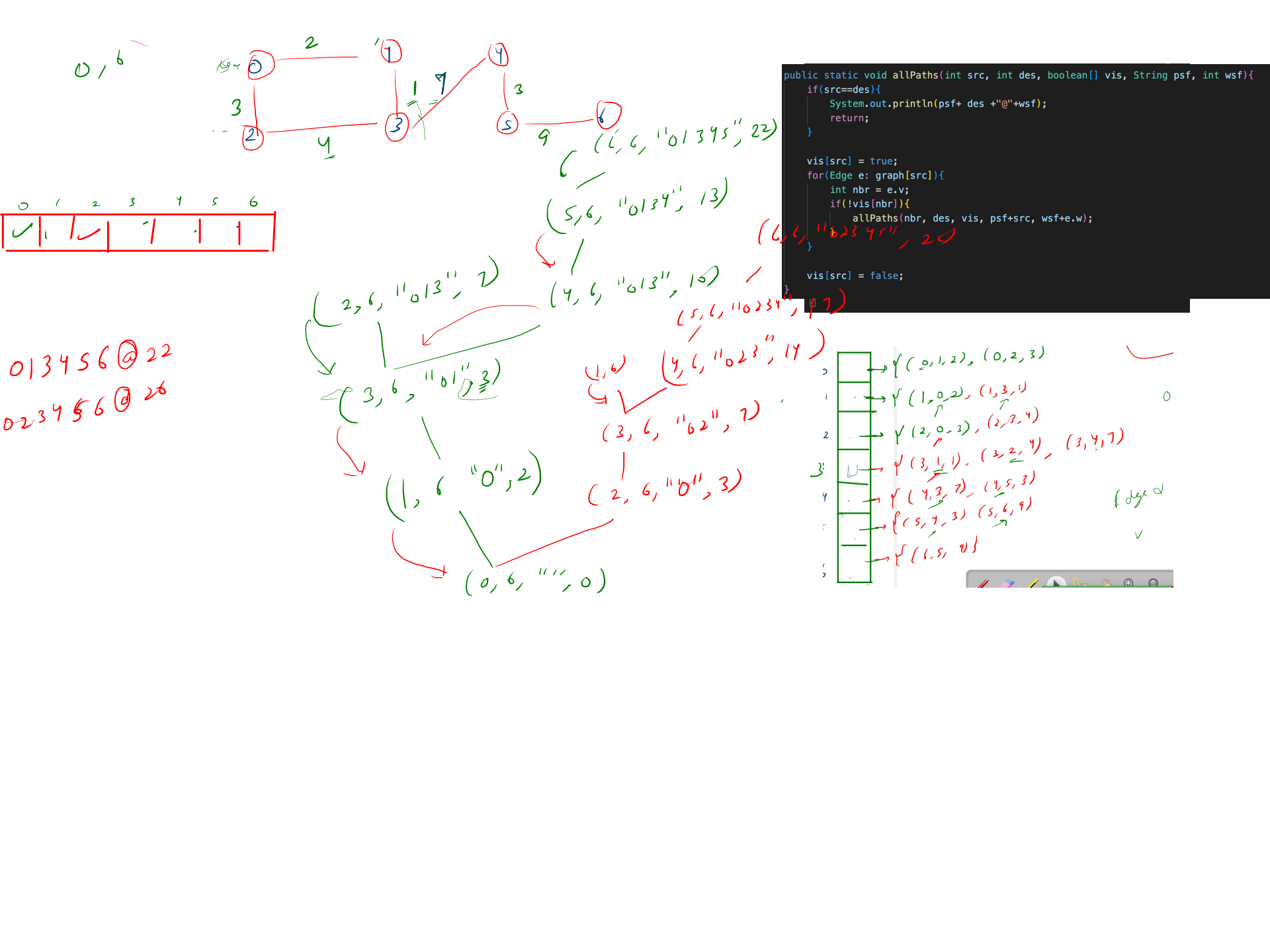
weight

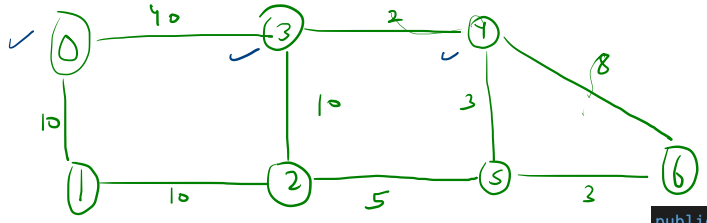
car



weight = cost
=> distance

A → F → B


0, 6
0 1 2 3 4 5 6
0 1 3 4 5 6 @ 22
0 2 3 4 5 6 @ 26
(6, 6, "01345", 22)
(5, 6, "0134", 13)
(4, 6, "013", 10)
(2, 6, "013", 7)
(3, 6, "01", 3)
(1, 6, "0", 2)
(0, 6, "", 0)
(6, 6, "02345", 20)
(5, 6, "0234", 14)
(4, 6, "023", 11)
(3, 6, "62", 7)
(2, 6, "0", 3)
public static void allPaths(int src, int des, boolean[] vis, String psf, int wsf){
if(src==des){
System.out.println(psf+ des +"@"+wsf);
return;
}
vis[src] = true;
for(Edge e: graph[src]){
int nbr = e.v;
if(!vis[nbr]){
allPaths(nbr, des, vis, psf+src, wsf+e.w);
}
}
vis[src] = false;
}



src = 0
dest = 6
k = 4
criteria = 40

```
public static void multisolver(ArrayList<Edge>[] graph, int src, int dest, boolean[] visited, int criteri
  if(src==dest){
    pq.add(new Pair(wsf,psf));
    if(pq.size()>k){
        pq.remove();
    }

    if(wsf > lpathwt){
        lpath = psf;
        lpathwt = wsf;
    }

    if(wsf < criteria && wsf > fpathwt){
        fpathwt = wsf;
        fpath = psf ;
    }
  }

  visited[src] = true;

  for(Edge e: graph[src]){
    int nbr = e.nbr;
    if(!visited[nbr]){
        multisolver(graph, nbr, dest, visited, criteria, k, psf+nbr, wsf+e.wt);
    }
  }

  visited[src] = false;
}
```

lpathwt = -∞ 50 66
lpath = 0346 03256

fpathwt = -∞ 28 38
fpath = 1-> 0256 0123456

0346 @ 50
03456 @ 48

kth

03256 @ 66
03256 @ 58

0346 @ 50
0256 @ 28
0123456 @ 38
03256 @ 66
0346 @ 40
03256 @ 58
03456 @ 48