



Model Representation II

To re-iterate, the following is an example of a neural network:

$$\begin{aligned}a_1^{(2)} &= g(\Theta_{10}^{(1)} x_0 + \Theta_{11}^{(1)} x_1 + \Theta_{12}^{(1)} x_2 + \Theta_{13}^{(1)} x_3) \\a_2^{(2)} &= g(\Theta_{20}^{(1)} x_0 + \Theta_{21}^{(1)} x_1 + \Theta_{22}^{(1)} x_2 + \Theta_{23}^{(1)} x_3) \\a_3^{(2)} &= g(\Theta_{30}^{(1)} x_0 + \Theta_{31}^{(1)} x_1 + \Theta_{32}^{(1)} x_2 + \Theta_{33}^{(1)} x_3) \\h_{\Theta}(x) &= a_1^{(3)} = g(\Theta_{10}^{(2)} a_0^{(2)} + \Theta_{11}^{(2)} a_1^{(2)} + \Theta_{12}^{(2)} a_2^{(2)} + \Theta_{13}^{(2)} a_3^{(2)})\end{aligned}$$

In this section we'll do a vectorized implementation of the above functions. We're going to define a new variable $z_k^{(j)}$ that encompasses the parameters inside our g function. In our previous example if we replaced by the variable z for all the parameters we would get:

$$\begin{aligned}a_1^{(2)} &= g(z_1^{(2)}) \\a_2^{(2)} &= g(z_2^{(2)}) \\a_3^{(2)} &= g(z_3^{(2)})\end{aligned}$$

In other words, for layer $j=2$ and node k , the variable z will be:

$$z_k^{(2)} = \Theta_{k,0}^{(1)} x_0 + \Theta_{k,1}^{(1)} x_1 + \dots + \Theta_{k,n}^{(1)} x_n$$

The vector representation of x and $z^{(j)}$ is:

$$x = \begin{bmatrix} x_0 \\ x_1 \\ \dots \\ x_n \end{bmatrix} \quad z^{(j)} = \begin{bmatrix} z_1^{(j)} \\ z_2^{(j)} \\ \dots \\ z_n^{(j)} \end{bmatrix}$$

Setting $x = a^{(1)}$, we can rewrite the equation as:

$$z^{(j)} = \Theta^{(j-1)} a^{(j-1)}$$

We are multiplying our matrix $\Theta^{(j-1)}$ with dimensions $s_j \times (n+1)$ (where s_j is the number of our activation nodes) by our vector $a^{(j-1)}$ with height $(n+1)$. This gives us our vector $z^{(j)}$ with height s_j . Now we can get a vector of our activation nodes for layer j as follows:

$$a^{(j)} = g(z^{(j)})$$