

The Bellman-Ford Algorithm

Algorithms: Design and Analysis, Part II

Space Optimization

Quiz

Question: How much space does the basic Bellman-Ford algorithm require? [Pick the strongest true statement.] [m = # of edges, n = # of vertices]

- A) $\Theta(n^2) \to \Theta(1)$ for each of n^2 subproblems
- B) ⊖(*mn*)
- C) $\Theta(n^3)$
- D) $\Theta(m^2)$

Predecessor Pointers

$$A[i, v] = \min \left\{ \begin{array}{l} A[i-1, v] \\ \min_{(w,v) \in E} \{A[i-1, w] + c_{wv}\} \end{array} \right\}$$

Note: Only need the A[i-1, v]'s to compute the A[i, v]'s.

 \Rightarrow Only need O(n) to remember the current and last rounds of subproblems [only O(1) per destination!]

Concern: Without a filled-in table, how do we reconstruct the actual shortest paths?

Exercise: Find analogous optimizations for our previous DP algorithms.

Computing Predecessor Pointers

Idea: Compute a second table B, where B[i,v]=2nd-to-last vertex on a shortest $s \to v$ path with $\leq i$ edges (or NULL if no such paths exist)

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("Predecessor pointers")
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Reconstruction: Assume the input graph G has no negative cycles and we correctly compute the B[i, v]'s.

Then: Tracing back predecessor pointers – the B[n-1, v]'s (= last hop of a shortest s-v path) – from v to s yields a shortest s-v path.

[Correctness from optimal substructure of shortest paths]

Computing Predecessor Pointers

Recall:

$$A[i, v] = \min \left\{ \begin{array}{l} (1) \ A[i-1, v] \\ (2) \ \min_{(w,v) \in E} \{A[i-1, w] + c_{wv}\} \end{array} \right\}$$

Base case: B[0, v] = NULL for all $v \in V$

To compute B[i, v] with i > 0:

Case 1: B[i, v] = B[i - 1, v]

Case 2: B[i, v] = the vertex w achieving the minimum (i.e., the new last hop)

Correctness: Computation of A[i, v] is brute-force search through the (1+in-deg(v)) possible optimal solutions, B[i, v] is just caching the last hop of the winner.

To reconstruct a negative-cost cycle: Use depth-first search to check for a cycle of predecessor pointers after each round (must be a negative cost cycle). (Details omitted)