6.035

Unoptimized Code Generation

Orientation

- Source code
- Intermediate representation
- Unoptimized assembler
- Executable file
 - Data segments (initialized, zeroed, constant)
 - Code segments

Big Picture

- Starting point Intermediate Representation
- Ending point Generated Assembly Code

- Emphasis on UNOPTIMIZED
- Do simplest possible thing for now
- Will treat optimizations separately

Machines understand...

LOCATION	DATA
0046	8B45FC
0049	4863F0
004c	8B45FC
004f	4863D0
0052	8B45FC
0055	4898
0057	8B048500
	000000
005e	8B149500
	000000
0065	01C2
0067	8B45FC
006a	4898
006c	89D7
006e	033C8500
	000000
0075	8B45FC
0078	4863C8
007ь	8B45F8
007e	4898
0800	8B148500

Machines understand...

LOCATION	DATA	ASSEMBLY INSTRUCTION
0046	8B45FC	movl -4(%rbp), %eax
0049	4863F0	movslq %eax,%rsi
004c	8B45FC	movl -4(%rbp), %eax
004f	4863D0	movslq %eax,%rdx
0052	8B45FC	movl -4(%rbp), %eax
0055	4898	cltq
0057	8B048500	movl B(,%rax,4), %eax
	00000	
005e	8B149500	movl A(,%rdx,4), %edx
	000000	
0065	01C2	addl %eax, %edx
0067	8B45FC	movl -4(%rbp), %eax
006a	4898	cltq
006c	89D7	movl %edx, %edi
006e	033C8500	addl C(,%rax,4), %edi
	00000	
0075	8B45FC	movl -4(%rbp), %eax
0078	4863C8	movslq %eax,%rcx
007b	8B45F8	movl -8(%rbp), %eax
007e	4898	cltq
0800	8B148500	movl B(,%rax,4), %edx

Assembly language

- Advantages
 - Simplifies code generation due to use of symbolic instructions and symbolic names
 - Logical abstraction layer
 - Many different architectures implement same ISA
- Disadvantages
 - Additional process of assembling and linking
 - Assembler adds overhead

Assembly language

- Relocatable machine language (object modules)
 - all locations(addresses) represented by symbols
 - Mapped to memory addresses at link and load time
 - Flexibility of separate compilation
- Absolute machine language
 - addresses are hard-coded
 - simple and straightforward implementation
 - inflexible -- hard to reload generated code
 - Used in interrupt handlers and device drivers

Concept of An Object File

- The object file has:
 - Multiple Segments
 - Symbol Information
 - Relocation Information
- Segments
 - Global Offset Table
 - Procedure Linkage Table
 - Text (code)
 - Data
 - Read Only Data
- To run program, OS reads object file, builds executable process in memory, runs process
- We will use assembler to generate object files

Overview of a modern ISA

- Memory
- Registers
- ALU
- Control

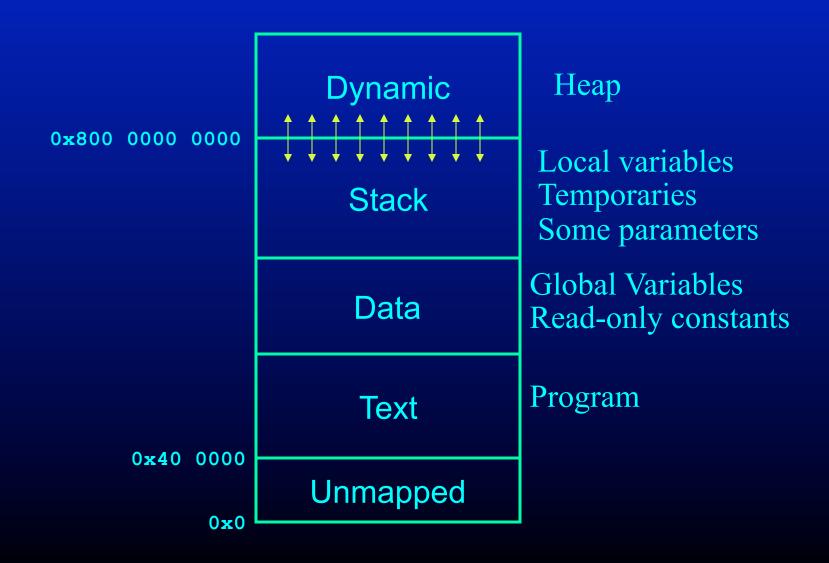


From IR to Assembly

- Data Placement and Layout
 - Global variables
 - Constants (strings, numbers)
 - Object fields
 - Parameters, local variables
 - Temporaries
- Code
 - Read and write data
 - Compute
 - Flow of control



Typical Memory Layout



Generated Assembler

```
int a[10]; int count;
```

```
.bss
.global_count:
    .zero 8
.global_a:
    .zero 80
```

Example (Illustrative, Not Definitive)

```
int PlusOne(int p) {
  int t;
  t = 1;
  return p+t;
}
```

```
.method PlusOne:
  PUSH ALL REGS
  subq $48, %rsp
  movq 128(%rsp), %rax
 movq %rax, 40(%rsp)
.node 41:
  movq 40(%rsp), %rax
  movq %rax, 32(%rsp)
  movq $0, 24(%rsp)
  movq $1, 24(%rsp)
  movq 32(%rsp), %rax
  movq %rax, 16(%rsp)
  movq 24(%rsp), %rax
  movq %rax, 8(%rsp)
  movq 16(%rsp), %rax
  addq 8(%rsp), %rax
  movq %rax, (%rsp)
  movq (%rsp), %rax
  movq %rax, 160(%rsp)
  addq $48, %rsp
  POP ALL REGS
  ret
```

```
int increment() {
  count = count + 1;
  return count;
}
```

```
.method increment:
  PUSH ALL REGS
  subq $24, %rsp
.node 61:
  movq .global count, %rax
  movq %rax, 16(%rsp)
  movq 16(%rsp), %rax
  addq $1, %rax
  movq %rax, 8(%rsp)
  movq 8(%rsp), %rax
  movq %rax, .global count
  movq .global count, %rax
  movq %rax, (%rsp)
  movq (%rsp), %rax
  movq %rax, 136(%rsp)
  addq $24, %rsp
  POP ALL REGS
  ret
```

```
int sign(int p) {
 if (p < 0) {
  return -1;
 } else {
 if (p > 0) {
  return 1;
 } else {
  return 0;
```

```
.method sign:
  PUSH ALL REGS
  subq $48, %rsp
  movq 128(%rsp), %rax
  movq %rax, 40(%rsp)
.node 110:
  movq 40(%rsp), %rax
  movq %rax, 32(%rsp)
  movq 32(%rsp), %rax
  movq %rax, 24(%rsp)
  cmpq $0, 24(%rsp)
  movq $0, %rax
  setl %al
  movq %rax, 16(%rsp)
  cmpq $0, 24(%rsp)
  il .node 111
  jmp .node 112
.node 112:
  movq 32(%rsp), %rax
  movq %rax, 8(%rsp)
  cmpq $0, 8(%rsp)
  movq $0, %rax
  setg %al
  movq %rax, (%rsp)
  movq $0, %rax
  cmpq 8(%rsp), %rax
  il .node 113
  jmp .node 114
```

```
int sign(int p) {
 if (p < 0)
  return -1;
 } else {
 if (p > 0) {
  return 1;
 } else {
  return 0;
```

```
.node 114:
  movq $0, 160(%rsp)
  addq $48, %rsp
  POP ALL REGS
  ret
.node 113:
  movq $1, 160(%rsp)
  addq $48, %rsp
  POP ALL REGS
 ret
.node 111:
  movq $-1, 160(%rsp)
  addq $48, %rsp
  POP ALL_REGS
  ret
```

Exploring Assembly Patterns

```
struct { int x, y; double z; } b;
int g;
int a[10];
char *s = "Test String";
int f(int p) {
 int i;
 int s;
 s = 0.0;
 for (i = 0; i < 10; i++)
  s = s + a[i];
 return s;
```

- gcc g St.c
- vi t.s

Global Variables

```
struct { int x, y; double z; } b;
      int g;
      int a[10];
Assembler directives (reserve space in data segment)
      .comm a,40,4
                                ## (a)a
      .comm b,16,3
                                ## (a)b
              _{g,4,2}
                                ## (a)g
      .comm
                Size
                          Alignment
     Name
```

Addresses

Reserve Memory

```
.comm _a,40,4 ## @a
.comm _b,16,3 ## @b
.comm _g,4,2 ## @g
```

Define 3 constants

_a – address of a in data segment

b – address of b in data segment

_g – address of g in data segment

Struct and Array Layout

- struct { int x, y; double z; } b; − Bytes 0-1: x - Bytes 2-3: y − Bytes 4-7: z • int a[10] - Bytes 0-1: a[0] - Bytes 2-3: a[1]
 - Bytes 18-19: a[9]

Dynamic Memory Allocation

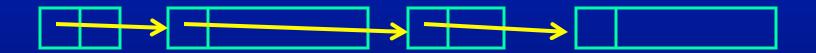
```
typedef struct { int x, y; } PointStruct, *Point;
Point p = malloc(sizeof(PointStruct));
```

What does allocator do?

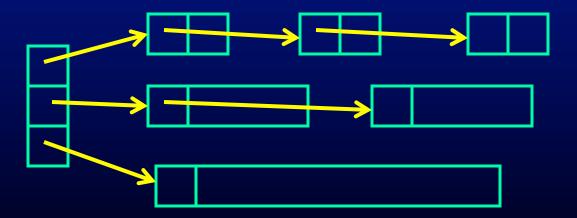
returns next free big enough data block in heap appropriately adjusts heap data structures

Some Heap Data Structures

• Free List (arrows are addresses)



Powers of Two Lists



Getting More Heap Memory

Scenario: Current heap goes from 0x800 0000 000- 0x810 0000 0000

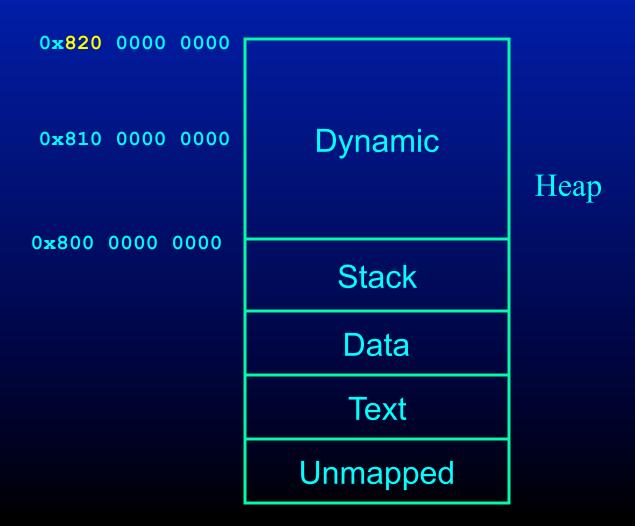
Need to allocate large block of memory

No block that large available

0x810 0000 0000 Heap **Dynamic** 0x800 0000 0000 Stack Data **Text Unmapped**

Getting More Heap Memory

Solution: Talk to OS, increase size of heap (sbrk)
Allocate block in new heap



The Stack

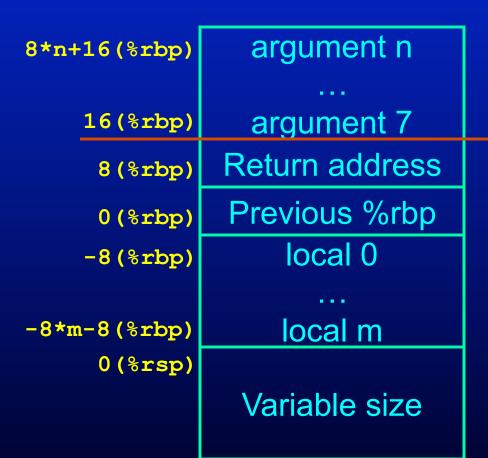
- Arguments 0 to 6 are in:
 - %rdi, %rsi, %rdx,
 - %rcx, %r8 and %r9

%rbp

marks the beginning
 of the current frame

%rsp

- marks the end

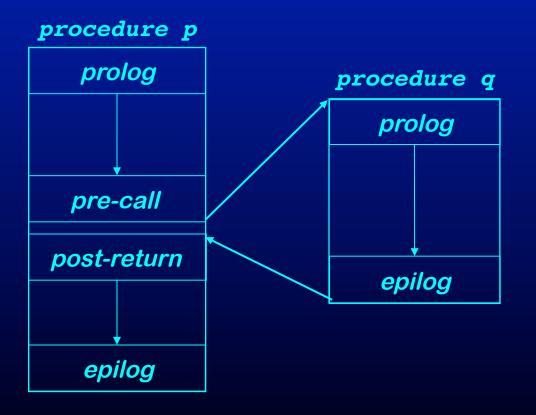


Question:

• Why use a stack? Why not use the heap or preallocated in the data segment?

Procedure Linkages

Standard procedure linkage



Pre-call:

- Save caller-saved registers
- Push arguments

Prolog:

- Push old frame pointer
- Save callee-saved registers
- Make room for temporaries

Epilog:

- Restore callee-saved
- Pop old frame pointer
- Store return value

Post-return:

- Restore caller-saved
- Pop arguments

- Calling: Caller
 - Assume %rcx is live and is caller save
 - Call foo(A, B, C, D, E, F, G, H, I)
 - A to I are at -8(%rbp) to -72(%rbp)

push	%rcx
push	-72(%rbp)
push	-64(%rbp)
push	-56(%rbp)
mov	-48(%rbp), %r9
mov	-40(%rbp), %r8
mov	-32(%rbp), %rcx
mov	-24(%rbp), %rdx
mov	-16(%rbp), %rsi
mov	-8(%rbp), %rdi
call	foo

return address previous frame pointer callee saved registers local variables stack temporaries dynamic area rsp caller saved registers argument 9 argument 8 argument 7 return address

- Calling: Callee
 - Assume %rbx is used in the function and is callee save
 - Assume 40 bytes are required for locals

foo:

push	%rbp
mov	%rsp, %rbp
enter	%rsp, %rbp \$48, \$0
mov	%rbx, -8(%rbp)

return address previous frame pointer calliee saved registers local variables stack temporaries dynamic area caller saved registers argument 9 argument 8 argument 7 return address rsp previous frame pointer calliee saved registers local variables stack temporaries dynamic area

- Arguments
- Call foo(A, B, C, D, E, F, G, H, I)
 - Passed in by pushing before the call

```
      push
      -72 (%rbp)

      push
      -64 (%rbp)

      push
      -56 (%rbp)

      mov
      -48 (%rbp), %r9

      mov
      -40 (%rbp), %r8

      mov
      -32 (%rbp), %rcx

      mov
      -24 (%rbp), %rdx

      mov
      -16 (%rbp), %rsi

      mov
      -8 (%rbp), %rdi

      call
      foo
```

- Access A to F via registers
 - or put them in local memory
- Access rest using 16+xx(%rbp)

```
mov 16(%rbp), %rax mov 24(%rbp), %r10
```

return address previous frame pointer calliee saved registers local variables stack temporaries dynamic area caller saved registers argument 9 argument 8 argument 7 return address previous frame pointer calliee saved registers local variables stack temporaries rsp dynamic area

- Locals and Temporaries
 - Calculate the size andallocate space on the stack

sub \$48, %rsp or enter \$48, 0

Access using -8-xx(%rbp)

mov -28(%rbp), %r10 mov %r11, -20(%rbp) return address
previous frame pointer
calliee saved
registers
local variables

stack temporaries

dynamic area

caller saved registers

argument 9 argument 8 argument 7

return address

previous frame pointer

calliee saved
registers

local variables

stack temporaries

dynamic area

_rbp

rsp

return address
previous frame pointer
callee saved
registers

Returning Callee

- local variables
- Assume the return value is the first temporary
- stack temporaries

Restore the caller saved register

dynamic area

Put the return value in %rax

caller saved registers

Tear-down the call stack

argument 9 argument 8 argument 7



previous frame pointer callee saved

registers

return address

- local variables
- stack temporaries

dynamic area

- rsp

- Returning Caller
- Assume the return value goes to the first temporary
 - Restore the stack to reclaim the argument space
 - Restore the caller save registers
 - Save the return value

call	foo
add	\$24, %rsp
pop	%rcx
mov	%rax, 8(%rbp)

return address previous frame pointer callee saved registers local variables stack temporaries dynamic area caller saved registers argument 9 argument 8 rsp argument 7

Question:

- Do you need the \$rbp?
- What are the advantages and disadvantages of having \$rbp?

So far we covered...

CODE

DATA

Procedures

Control Flow

Statements

Data Access

Global Static Variables

Global Dynamic Data

Local Variables

Temporaries

Parameter Passing

Read-only Data

Outline

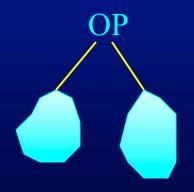
- Generation of expressions and statements
- Generation of control flow
- x86-64 Processor
- Guidelines in writing a code generator

Expressions

- Expressions are represented as trees
 - Expression may produce a value
 - Or, it may set the condition codes (boolean exprs)
- How do you map expression trees to the machines?
 - How to arrange the evaluation order?
 - Where to keep the intermediate values?
- Two approaches
 - Stack Model
 - Flat List Model

Evaluating expression trees

- Stack model
 - Eval left-sub-treePut the results on the stack
 - Eval right-sub-treePut the results on the stack
 - Get top two values from the stack
 perform the operation OP
 put the results on the stack



• Very inefficient!

Evaluating expression trees

- Flat List Model
 - The idea is to linearize the expression tree
 - Left to Right Depth-First Traversal of the expression tree
 - Allocate temporaries for intermediates (all the nodes of the tree)
 - New temporary for each intermediate
 - All the temporaries on the stack (for now)
 - Each expression is a single 3-addr op
 - x = y op z
 - Code generation for the 3-addr expression
 - Load y into register %r10
 - Load z into register %r11
 - Perform op %r10, %r11
 - Store %r11 to x

Issues in Lowering Expressions

- Map intermediates to registers?
 - registers are limited
 - when the tree is large, registers may be insufficient ⇒ allocate space in the stack
- No machine instruction is available
 - May need to expand the intermediate operation into multiple machine ops.
- Very inefficient
 - too many copies
 - don't worry, we'll take care of them in the optimization passes
 - keep the code generator very simple

What about statements?

- Assignment statements are simple
 - Generate code for RHS expression
 - Store the resulting value to the LHS address

But what about conditionals and loops?

Outline

- Generation of statements
- Generation of control flow
- Guidelines in writing a code generator

Two Techniques

- Template Matching
- Short-circuit Conditionals

- Both are based on structural induction
 - Generate a representation for the sub-parts
 - Combine them into a representation for the whole

Template for conditionals

```
if (test)
  true_body
else
  false_body
```

```
<do test>
       joper .LO
        <FALSE BODY>
               .L1
       jmр
.L0:
       <TRUE BODY>
.L1:
```

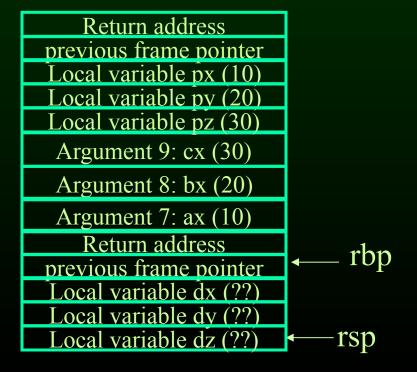
Return address
previous frame pointer
Local variable px (10)
Local variable py (20)
Local variable pz (30)
Argument 9: cx (30)
Argument 8: bx (20)
Argument 7: ax (10)
Return address
previous frame pointer
Local variable dx (??)
Local variable dy (??)
Local variable dz (??)

Local variable dz (??)

```
movq 16(%rbp), %r10
movq 24(%rbp), %r11
cmpq %r10, %r11
jg .L0

<FALSE BODY>
jmp .L1
.L0:
```

<TRUE BODY>



```
16(%rbp), %r10
       movq
                24(%rbp), %r11
       movq
                %r10, %r11
        cmpq
                .L0
        jq
                24(%rbp), %r10
       movq
                16(%rbp), %r11
       movq
                %r10, %r11
        subq
                %r11, -8(%rbp)
       movq
                .L1
        jmр
.L0:
```

<TRUE BODY>

.L1:

Return address
previous frame pointer
Local variable px (10)
Local variable py (20)
Local variable pz (30)
Argument 9: cx (30)
Argument 8: bx (20)
Argument 7: ax (10)
Return address
previous frame pointer
Local variable dx (??)
Local variable dy (??)
Local variable dz (??)
Local variable dz (??)

```
16(%rbp), %r10
       movq
               24(%rbp), %r11
       movq
               %r10, %r11
       cmpq
               .L0
       jq
               24(%rbp), %r10
       movq
               16(%rbp), %r11
       movq
               %r10, %r11
       subq
       movq
               %r11, -8(%rbp)
                .L1
       jmp
.L0:
               16(%rbp), %r10
       movq
               24(%rbp), %r11
       movq
               %r10, %r11
       subq
               %r11, -8(%rbp)
       movq
.L1:
```

Return address
previous frame pointer
Local variable px (10)
Local variable py (20)
Local variable pz (30)
Argument 9: cx (30)
Argument 8: bx (20)
Argument 7: ax (10)
Return address
previous frame pointer
Local variable dx (??)
Local variable dy (??)
Local variable dz (??)

Local variable dz (??)

Template for while loops

```
while (test)
  body
```

Template for while loops

```
while (test)
body
```

Template for while loops

```
while (test)
body
```

An optimized template



Question:

• What is the template for?

```
do
  body
while (test)
```

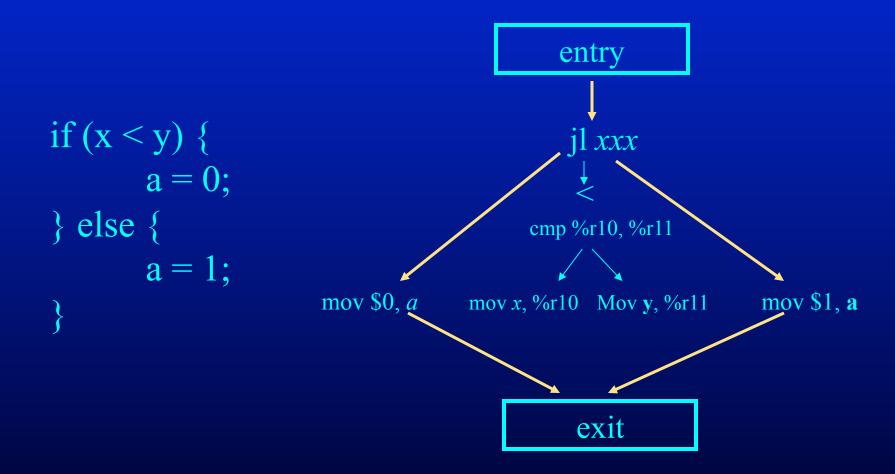
Question:

• What is the template for?

```
do
  body
while (test)
```

Control Flow Graph (CFG)

- Starting point: high level intermediate format, symbol tables
- Target: CFG
 - CFG Nodes are Instruction Nodes
 - CFG Edges Represent Flow of Control
 - Forks At Conditional Jump Instructions
 - Merges When Flow of Control Can Reach A Point Multiple Ways
 - Entry and Exit Nodes



Pattern for if then else

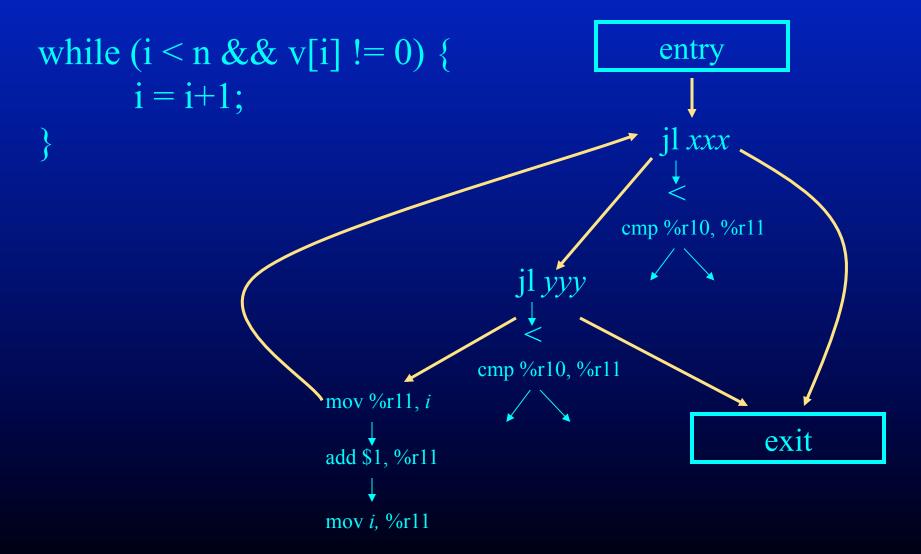
Short-Circuit Conditionals

• In program, conditionals have a condition written as a boolean expression

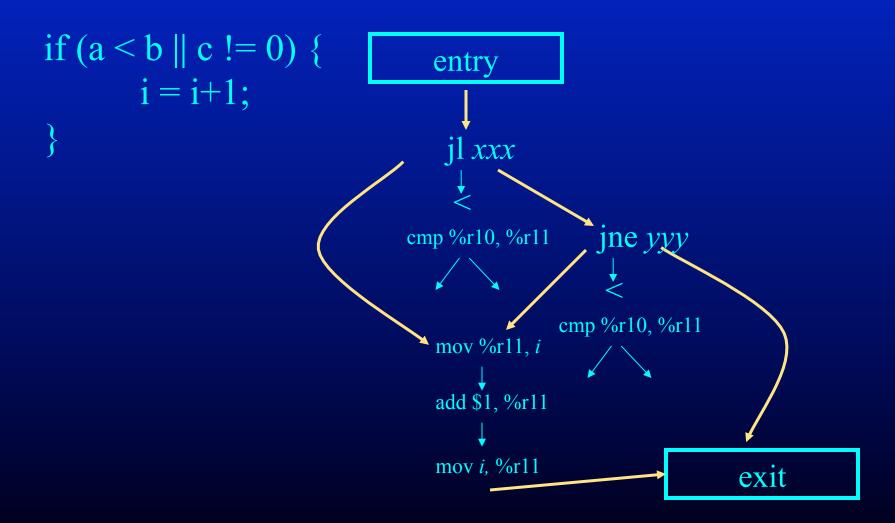
$$((i \le n) \&\& (v[i] != 0)) || (i \ge k)$$

- Semantics say should execute only as much as required to determine condition
 - Evaluate (v[i] != 0) only if (i < n) is true
 - Evaluate i > k only if ((i < n) && (v[i] != 0)) is false
- Use control-flow graph to represent this shortcircuit evaluation

Short-Circuit Conditionals



More Short-Circuit Conditionals



Routines for Destructuring Program Representation

destruct(n)

generates lowered form of structured code represented by n returns (b,e) - b is begin node, e is end node in destructed form

shortcircuit(c, t, f)

generates short-circuit form of conditional represented by c if c is true, control flows to t node if c is false, control flows to f node returns b - b is begin node for condition evaluation

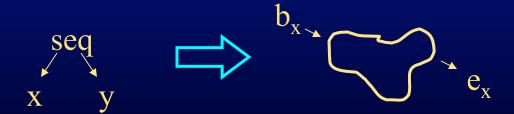
new kind of node - nop node

destruct(n)



destruct(n)

1:
$$(b_x, e_x) = destruct(x);$$



destruct(n)

1:
$$(b_x,e_x) = destruct(x)$$
; 2: $(b_y,e_y) = destruct(y)$;

destruct(n)

1:
$$(b_x,e_x) = destruct(x)$$
; 2: $(b_y,e_y) = destruct(y)$;

3:
$$next(e_x) = b_y$$
;



destruct(n)

1:
$$(b_x,e_x) = destruct(x)$$
; 2: $(b_y,e_y) = destruct(y)$;

3:
$$next(e_x) = b_y$$
; 4: $return(b_x, e_y)$;

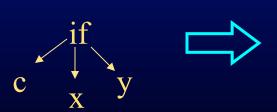


destruct(n)



destruct(n)

1:
$$(b_x, e_x) = destruct(x)$$
;





destruct(n)

1:
$$(b_x,e_x) = destruct(x)$$
; 2: $(b_y,e_y) = destruct(y)$;



$$b_{x} \xrightarrow{} e_{x}$$

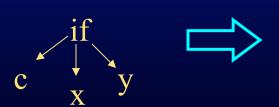
$$b_{y} \xrightarrow{} e_{y}$$

destruct(n)

generates lowered form of structured code represented by n returns (b,e) - b is begin node, e is end node in destructed form if n is of the form if c x y

1:
$$(b_x,e_x) = destruct(x)$$
; 2: $(b_y,e_y) = destruct(y)$;

3: e = new nop;



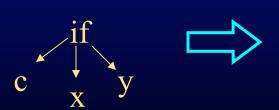
$$b_{x} \xrightarrow{} e_{x}$$

$$b_{y} \xrightarrow{} e_{y}$$

destruct(n)

1:
$$(b_x,e_x) = destruct(x)$$
; 2: $(b_y,e_y) = destruct(y)$;

3:
$$e = new nop;$$
 4: $next(e_x) = e;$ 5: $next(e_y) = e;$

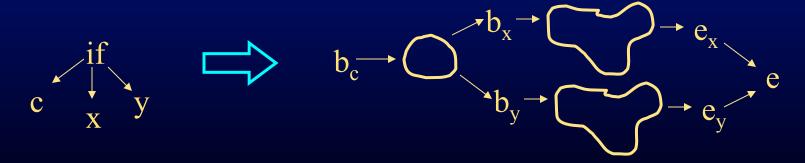


$$b_{x} \xrightarrow{} e_{x}$$

$$b_{y} \xrightarrow{} e_{y}$$

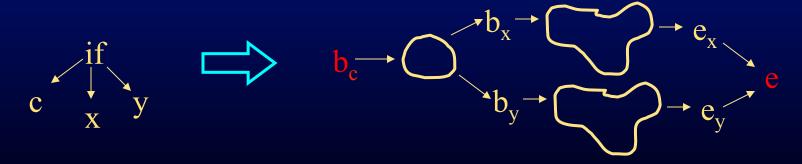
destruct(n)

- 1: $(b_x,e_x) = destruct(x)$; 2: $(b_y,e_y) = destruct(y)$;
- 3: $e = new nop; 4: next(e_x) = e; 5: next(e_y) = e;$
- 6: $b_c = \text{shortcircuit}(c, b_x, b_y);$



destruct(n)

- 1: $(b_x,e_x) = destruct(x)$; 2: $(b_y,e_y) = destruct(y)$;
- 3: e = new nop; 4: $next(e_x) = e;$ 5: $next(e_y) = e;$
- 6: $b_c = \text{shortcircuit}(c, b_x, b_y)$; 7: return (b_c, e) ;



Destructuring While Nodes

destruct(n)



destruct(n)

1:
$$e = new nop$$
;



destruct(n)

1:
$$e = new nop;$$
 2: $(b_x, e_x) = destruct(x);$

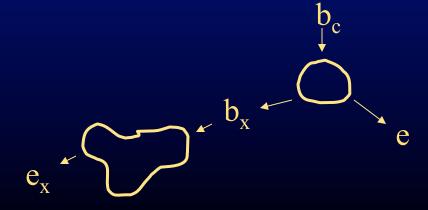


$$e_x$$
 b_x e

destruct(n)

- 1: e = new nop; 2: $(b_x, e_x) = destruct(x)$;
- 3: $b_c = \text{shortcircuit}(c, b_x, e);$

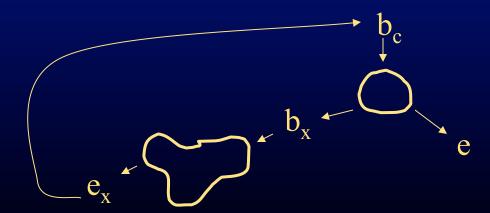




destruct(n)

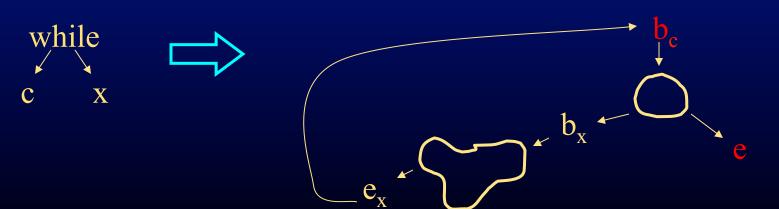
- 1: e = new nop; 2: $(b_x, e_x) = destruct(x)$;
- 3: $b_c = \text{shortcircuit}(c, b_x, e)$; 4: $\text{next}(e_x) = b_c$;





destruct(n)

- 1: e = new nop; 2: $(b_x, e_x) = destruct(x)$;
- 3: $b_c = \text{shortcircuit}(c, b_x, e)$; 4: $\text{next}(e_x) = b_c$; 5: $\text{return } (b_c, e)$;



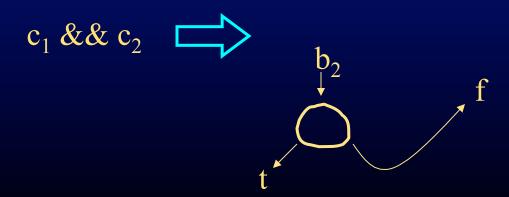
shortcircuit(c, t, f)

generates shortcircuit form of conditional represented by c returns b - b is begin node of shortcircuit form if c is of the form $c_1 \&\& c_2$

shortcircuit(c, t, f)

generates shortcircuit form of conditional represented by c returns b - b is begin node of shortcircuit form if c is of the form c_1 && c_2

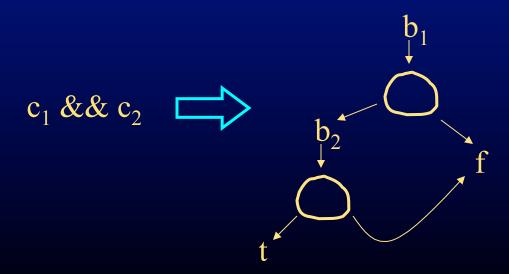
1: $b_2 = \text{shortcircuit}(c_2, t, f);$



shortcircuit(c, t, f)

generates shortcircuit form of conditional represented by c returns b - b is begin node of shortcircuit form if c is of the form $c_1 \&\& c_2$

1: $b_2 = \text{shortcircuit}(c_2, t, f)$; 2: $b_1 = \text{shortcircuit}(c_1, b_2, f)$;



```
shortcircuit(c, t, f)
   generates shortcircuit form of conditional represented by c
   returns b - b is begin node of shortcircuit form
   if c is of the form c_1 \&\& c_2
        1: b_2 = shortcircuit(c_2, t, f); 2: b_1 = shortcircuit(c_1, b_2, f);
        3: return (b_1);
```

shortcircuit(c, t, f)

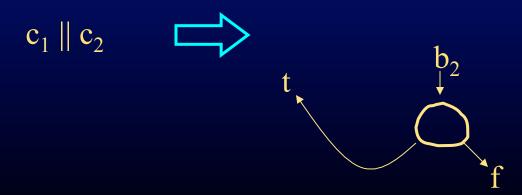
generates shortcircuit form of conditional represented by \mathbf{c} returns \mathbf{b} - \mathbf{b} is begin node of shortcircuit form if \mathbf{c} is of the form $\mathbf{c}_1 \parallel \mathbf{c}_2$

$$c_1 \parallel c_2$$

```
shortcircuit(c, t, f)
```

generates shortcircuit form of conditional represented by ${\bf c}$ returns ${\bf b}$ - ${\bf b}$ is begin node of shortcircuit form if ${\bf c}$ is of the form ${\bf c}_1 \parallel {\bf c}_2$

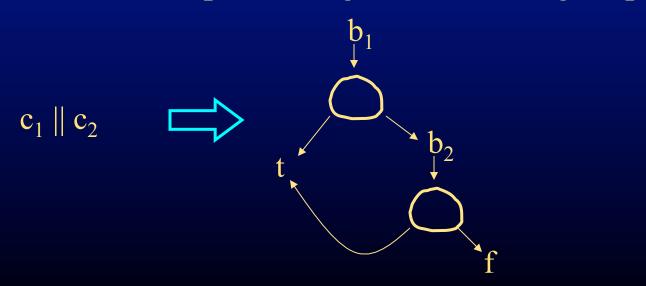
1: $b_2 = \text{shortcircuit}(c_2, t, f)$;



```
shortcircuit(c, t, f)
```

generates shortcircuit form of conditional represented by \mathbf{c} returns \mathbf{b} - \mathbf{b} is begin node of shortcircuit form if \mathbf{c} is of the form $\mathbf{c}_1 \parallel \mathbf{c}_2$

1: b_2 = shortcircuit(c_2 , t, f); 2: b_1 = shortcircuit(c_1 , t, b_2);



```
shortcircuit(c, t, f)
   generates shortcircuit form of conditional represented by c
   returns b - b is begin node of shortcircuit form
   if c is of the form c_1 \parallel c_2
         1: b_2 = shortcircuit(c_2, t, f); 2: b_1 = shortcircuit(c_1, t, b_2);
        3: return (b_1);
```

```
shortcircuit(c, t, f)
```

generates shortcircuit form of conditional represented by ${\bf c}$ returns ${\bf b}$ - ${\bf b}$ is begin node of shortcircuit form if ${\bf c}$ is of the form ! ${\bf c}_1$

1: $b = \text{shortcircuit}(c_1, f, t); \text{return}(b);$

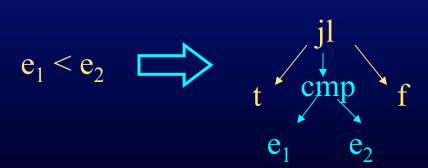


Computed Conditions

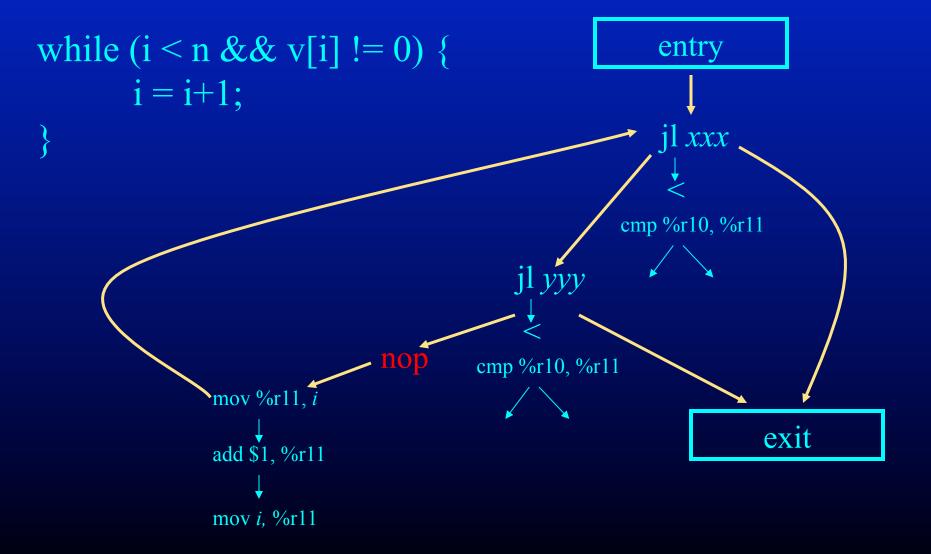
shortcircuit(c, t, f)

generates shortcircuit form of conditional represented by ${\bf c}$ returns ${\bf b}$ - ${\bf b}$ is begin node of shortcircuit form if ${\bf c}$ is of the form ${\bf e}_1 < {\bf e}_2$

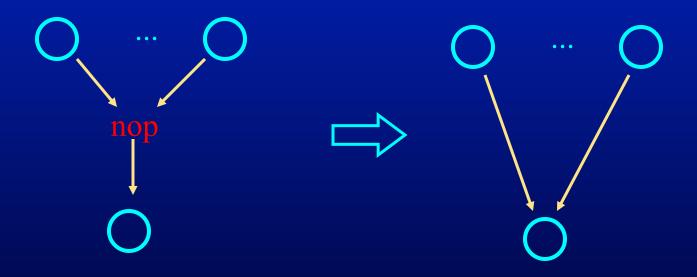
1: $b = \text{new cbr}(e_1 < e_2, t, f)$; 2: return (b);



Nops In Destructured Representation



Eliminating Nops Via Peephole Optimization



Linearizing CFG to Assembler

- Generate labels for edge targets at branches
 - Labels will correspond to branch targets
 - Can use patterns for this
- Generate code for statements/conditional expressions
- Generate code for procedure entry/exit

Outline

- Generation of statements
- Generation of control flow
- x86-64 Processor
- Guidelines in writing a code generator

Guidelines for the code generator

- Lower the abstraction level slowly
 - Do many passes, that do few things (or one thing)
 - Easier to break the project down, generate and debug
- Keep the abstraction level consistent
 - IR should have 'correct' semantics at all time
 - At least you should know the semantics
 - You may want to run some of the optimizations between the passes.
- Write sanity checks, consistency checks, use often

Guidelines for the code generator

- Do the simplest but dumb thing
 - it is ok to generate 0 + 1*x + 0*y
 - Code is painful to look at; let optimizations improve it

- Make sure you know want can be done at...
 - Compile time in the compiler
 - Runtime using generated code

Guidelines for the code generator

- Remember that optimizations will come later
 - Let the optimizer do the optimizations
 - Think about what optimizer will need and structure your code accordingly
 - Example: Register allocation, algebraic simplification, constant propagation
- Setup a good testing infrastructure
 - regression tests
 - If a input program creates a bug, use it as a regression test
 - Learn good bug hunting procedures
 - Example: binary search, delta debugging