Foundations of Machine Learning Ranking

Mehryar Mohri
Courant Institute and Google Research
mohri@cims.nyu.edu

Motivation

Very large data sets:

- too large to display or process.
- limited resources, need priorities.
- ranking more desirable than classification.

Applications:

- search engines, information extraction.
- decision making, auctions, fraud detection.
- Can we learn to predict ranking accurately?

Related Problem

- Rank aggregation: given n candidates and k voters each giving a ranking of the candidates, find ordering as close as possible to these.
 - closeness measured in number of pairwise misrankings.
 - problem NP-hard even for k=4 (Dwork et al., 2001).

This Talk

- Score-based ranking
- Preference-based ranking

Score-Based Setting

- Single stage: learning algorithm
 - receives labeled sample of pairwise preferences;
 - returns scoring function $h: U \to \mathbb{R}$.

Drawbacks:

- h induces a linear ordering for full set U.
- does not match a query-based scenario.

Advantages:

- efficient algorithms.
- good theory: VC bounds, margin bounds, stability bounds (FISS 03, RCMS 05, AN 05, AGHHR 05, CMR 07).

Score-Based Ranking

■ Training data: sample of i.i.d. labeled pairs drawn from $U \times U$ according to some distribution D,

$$S = \left((x_1, x_1', y_1), \dots, (x_m, x_m', y_m) \right) \in U \times U \times \{-1, 0, +1\},$$
with $y_i = \begin{cases} +1 & \text{if } x_i' >_{\text{pref}} x_i \\ 0 & \text{if } x_i =_{\text{pref}} x_i' \text{ or no information} \\ -1 & \text{if } x_i' <_{\text{pref}} x_i. \end{cases}$

■ Problem: find hypothesis $h:U \to \mathbb{R}$ in H with small generalization error

$$R(h) = \Pr_{(x,x') \sim D} \left[(f(x,x') \neq 0) \land (f(x,x')(h(x') - h(x)) \leq 0) \right].$$

Notes

Empirical error:

$$\widehat{R}(h) = \frac{1}{m} \sum_{i=1}^{m} 1_{(y_i \neq 0) \land (y_i(h(x_i') - h(x_i)) \leq 0)}.$$

- The relation $x \mathcal{R} x' \Leftrightarrow f(x, x') = 1$ may be nontransitive (needs not even be anti-symmetric).
- Problem different from classification.

Distributional Assumptions

- \blacksquare Distribution over points: m points (literature).
 - labels for pairs.

 - dependency issue.
- Distribution over pairs: m pairs.
 - label for each pair received.
 - independence assumption.
 - same (linear) number of examples.

Confidence Margin in Ranking

- \blacksquare Labels assumed to be in $\{+1, -1\}$.
- lacktriangle Empirical margin loss for ranking: for ho>0 ,

$$\widehat{R}_{\rho}(h) = \frac{1}{m} \sum_{i=1}^{m} \Phi_{\rho} \Big(y_i \big(h(x_i') - h(x_i) \big) \Big).$$

$$\widehat{R}_{\rho}(h) \leq \frac{1}{m} \sum_{i=1}^{m} 1_{y_i[h(x_i') - h(x_i)] \leq \rho}.$$

Marginal Rademacher Complexities

- Distributions:
 - D_1 marginal distribution with respect to the first element of the pairs;
 - D_2 marginal distribution with respect to second element of the pairs.
- Samples: $S_1 = ((x_1, y_1), \dots, (x_m, y_m))$ $S_2 = ((x'_1, y_1), \dots, (x'_m, y_m)).$
- Marginal Rademacher complexities:

$$\mathfrak{R}_m^{D_1}(H) = \mathrm{E}[\widehat{\mathfrak{R}}_{S_1}(H)] \quad \mathfrak{R}_m^{D_2}(H) = \mathrm{E}[\widehat{\mathfrak{R}}_{S_2}(H)].$$

Ranking Margin Bound

(Boyd, Cortes, MM, and Radovanovich 2012; MM, Rostamizadeh, and Talwalkar, 2012)

Theorem: let H be a family of real-valued functions. Fix $\rho > 0$, then, for any $\delta > 0$, with probability at least $1 - \delta$ over the choice of a sample of size m, the following holds for all $h \in H$:

$$R(h) \le \widehat{R}_{\rho}(h) + \frac{2}{\rho} (\mathfrak{R}_{m}^{D_{1}}(H) + \mathfrak{R}_{m}^{D_{2}}(H)) + \sqrt{\frac{\log \frac{1}{\delta}}{2m}}.$$

Ranking with SVMs

see for example (Joachims, 2002)

Optimization problem: application of SVMs.

$$\min_{\mathbf{w}, \boldsymbol{\xi}} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{i=1}^m \xi_i$$
subject to: $y_i \left[\mathbf{w} \cdot \left(\mathbf{\Phi}(x_i') - \mathbf{\Phi}(x_i) \right) \right] \ge 1 - \xi_i$

$$\xi_i \ge 0, \quad \forall i \in [1, m].$$

Decision function:

$$h: x \mapsto \mathbf{w} \cdot \mathbf{\Phi}(x) + b.$$

Notes

The algorithm coincides with SVMs using feature mapping

$$(x, x') \mapsto \Psi(x, x') = \Phi(x') - \Phi(x).$$

Can be used with kernels:

$$K'((x_i, x_i'), (x_j, x_j')) = \Psi(x_i, x_i') \cdot \Psi(x_j, x_j')$$

= $K(x_i, x_j) + K(x_i', x_j') - K(x_i', x_j) - K(x_i, x_j').$

Algorithm directly based on margin bound.

Boosting for Ranking

- Use weak ranking algorithm and create stronger ranking algorithm.
- Ensemble method: combine base rankers returned by weak ranking algorithm.
- Finding simple relatively accurate base rankers often not hard.
- How should base rankers be combined?

CD RankBoost

(Freund et al., 2003; Rudin et al., 2005)

$$\begin{split} &H \subseteq \{0,1\}^X. \epsilon_t^0 + \epsilon_t^+ + \epsilon_t^- = 1, \epsilon_t^s(h) = \Pr_{(x,x') \sim D_t} \left[\operatorname{sgn} \left(f(x,x') (h(x') - h(x)) \right) = s \right]. \\ &\operatorname{RANKBOOST}(S = \left((x_1, x_1', y_1) \dots, (x_m, x_m', y_m) \right)) \\ &1 \quad \text{for } i \leftarrow 1 \text{ to } m \text{ do} \\ &2 \quad D_1(x_i, x_i') \leftarrow \frac{1}{m} \\ &3 \quad \text{for } t \leftarrow 1 \text{ to } T \text{ do} \\ &4 \quad h_t \leftarrow \text{base ranker in } H \text{ with smallest } \epsilon_t^- - \epsilon_t^+ = -\operatorname{E}_{i \sim D_t} \left[y_i \left(h_t(x_i') - h_t(x_i) \right) \right] \\ &5 \quad \alpha_t \leftarrow \frac{1}{2} \log \frac{\epsilon_t^+}{\epsilon_t^-} \\ &6 \quad Z_t \leftarrow \epsilon_t^0 + 2 \left[\epsilon_t^+ \epsilon_t^- \right]^{\frac{1}{2}} \quad \triangleright \text{normalization factor} \\ &7 \quad \text{for } i \leftarrow 1 \text{ to } m \text{ do} \\ &8 \quad D_{t+1}(x_i, x_i') \leftarrow \frac{D_t(x_i, x_i') \exp \left[-\alpha_t y_i \left(h_t(x_i') - h_t(x_i) \right) \right]}{Z_t} \\ &9 \quad \varphi_T \leftarrow \sum_{t=1}^T \alpha_t h_t \\ &10 \quad \text{return } \varphi_T \end{split}$$

Notes

- \blacksquare Distributions D_t over pairs of sample points:
 - originally uniform.
 - at each round, the weight of a misclassified example is increased.
 - observation: $D_{t+1}(x,x') = \frac{e^{-y[\varphi_t(x')-\varphi_t(x)]}}{|S|\prod_{s=1}^t Z_s}$, since

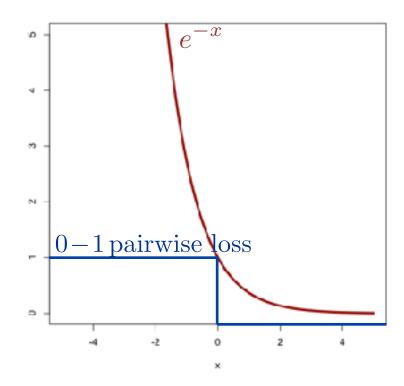
$$D_{t+1}(x,x') = \frac{D_t(x,x')e^{-y\alpha_t[h_t(x')-h_t(x)]}}{Z_t} = \frac{1}{|S|} \frac{e^{-y\sum_{s=1}^t \alpha_s[h_s(x')-h_s(x)]}}{\prod_{s=1}^t Z_s}.$$

weight assigned to base classifier h_t : α_t directly depends on the accuracy of h_t at round t.

Coordinate Descent RankBoost

Objective Function: convex and differentiable.

$$F(\alpha) = \sum_{(x,x',y)\in S} e^{-y[\varphi_T(x') - \varphi_T(x)]} = \sum_{(x,x',y)\in S} \exp\left(-y\sum_{t=1}^T \alpha_t[h_t(x') - h_t(x)]\right).$$



• Direction: unit vector \mathbf{e}_t with

$$\mathbf{e}_t = \underset{t}{\operatorname{argmin}} \frac{dF(\boldsymbol{\alpha} + \eta \mathbf{e}_t)}{d\eta} \bigg|_{\eta=0}.$$

• Since
$$F(\alpha + \eta \mathbf{e}_t) = \sum_{(x, x', y) \in S} e^{-y \sum_{s=1}^T \alpha_s [h_s(x') - h_s(x)]} e^{-y \eta [h_t(x') - h_t(x)]}$$
,

$$\frac{dF(\alpha + \eta e_t)}{d\eta} \Big|_{\eta=0} = -\sum_{(x,x',y)\in S} y[h_t(x') - h_t(x)] \exp\left[-y \sum_{s=1}^T \alpha_s [h_s(x') - h_s(x)]\right]
= -\sum_{(x,x',y)\in S} y[h_t(x') - h_t(x)] D_{T+1}(x,x') \Big[m \prod_{s=1}^T Z_s \Big]
= -[\epsilon_t^+ - \epsilon_t^-] \Big[m \prod_{s=1}^T Z_s \Big].$$

Thus, direction corresponding to base classifier selected by the algorithm.

Step size: obtained via

$$\frac{dF(\boldsymbol{\alpha} + \eta \mathbf{e}_t)}{d\eta} = 0$$

$$\Leftrightarrow -\sum_{(x,x',y)\in S} y[h_t(x') - h_t(x)] \exp\left[-y\sum_{s=1}^T \alpha_s[h_s(x') - h_s(x)]\right] e^{-y[h_t(x') - h_t(x)]\eta} = 0$$

$$\Leftrightarrow -\sum_{(x,x',y)\in S} y[h_t(x') - h_t(x)]D_{T+1}(x,x') \left[m\prod_{s=1}^T Z_s\right] e^{-y[h_t(x') - h_t(x)]\eta} = 0$$

$$\Leftrightarrow -\sum_{(x,x',y)\in S} y[h_t(x') - h_t(x)]D_{T+1}(x,x') e^{-y[h_t(x') - h_t(x)]\eta} = 0$$

$$\Leftrightarrow -[\epsilon_t^+ e^{-\eta} - \epsilon_t^- e^{\eta}] = 0$$

$$\Leftrightarrow \eta = \frac{1}{2} \log \frac{\epsilon_t^+}{\epsilon_t^-}.$$

Thus, step size matches base classifier weight used in algorithm.

Bipartite Ranking

- Training data:
 - sample of negative points drawn according to $D_ S_- = (x_1, \dots, x_m) \in U$.
 - ullet sample of positive points drawn according to D_+

$$S_+ = (x'_1, \dots, x'_{m'}) \in U.$$

Problem: find hypothesis $h\colon U\to \mathbb{R}$ in H with small generalization error

$$R_D(h) = \Pr_{x \sim D_-, x' \sim D_+} [h(x') < h(x)].$$

Notes

- Connection between AdaBoost and RankBoost (Cortes & MM, 04; Rudin et al., 05).
 - if constant base ranker used.
 - relationship between objective functions.
- More efficient algorithm in this special case (Freund et al., 2003).
- Bipartite ranking results typically reported in terms of AUC.

AdaBoost and CD RankBoost

Objective functions: comparison.

$$F_{\text{Ada}}(\boldsymbol{\alpha}) = \sum_{x_i \in S_- \cup S_+} \exp(-y_i f(x_i))$$

$$= \sum_{x_i \in S_-} \exp(+f(x_i)) + \sum_{x_i \in S_+} \exp(-f(x_i))$$

$$= F_-(\alpha) + F_+(\alpha).$$

$$F_{\text{Rank}}(\boldsymbol{\alpha}) = \sum_{(i,j) \in S_- \times S_+} \exp(-[f(x_j) - f(x_i)])$$

$$= \sum_{(i,j) \in S_- \times S_+} \exp(+f(x_i)) \exp(-f(x_i))$$

$$= F_-(\alpha) F_+(\alpha).$$

AdaBoost and CD RankBoost

(Rudin et al., 2005)

- Property: AdaBoost (non-separable case).
 - constant base learner $h=1 \longrightarrow$ equal contribution of positive and negative points (in the limit).
 - consequence: AdaBoost asymptotically achieves optimum of CD RankBoost objective.
- lacksquare Observations: if $F_+(\alpha) = F_-(\alpha)$,

$$d(F_{\text{Rank}}) = F_{+}d(F_{-}) + F_{-}d(F_{+})$$
$$= F_{+}(d(F_{-}) + d(F_{+}))$$
$$= F_{+}d(F_{\text{Ada}}).$$

Bipartite RankBoost - Efficiency

lacktriangle Decomposition of distribution: for $(x,x') \in (S_-,S_+)$,

$$D(x, x') = D_{-}(x)D_{+}(x').$$

Thus,

$$D_{t+1}(x,x') = \frac{D_t(x,x')e^{-\alpha_t[h_t(x')-h_t(x)]}}{Z_t}$$

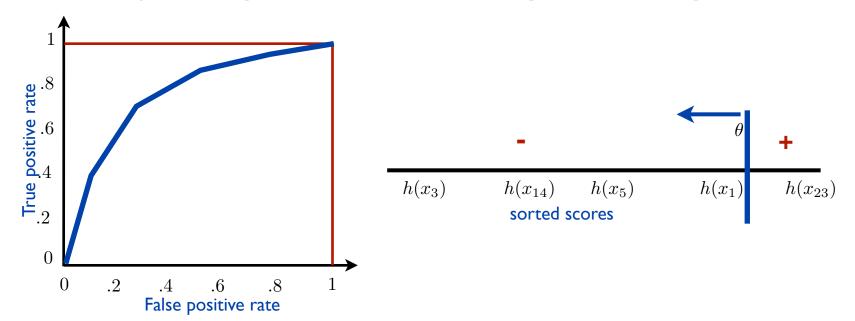
$$= \frac{D_{t,-}(x)e^{\alpha_t h_t(x)}}{Z_{t,-}} \frac{D_{t,+}(x')e^{-\alpha_t h_t(x')}}{Z_{t,+}},$$

with
$$Z_{t,-} = \sum_{x \in S_{-}} D_{t,-}(x) e^{\alpha_t h_t(x)}$$
 $Z_{t,+} = \sum_{x' \in S_{+}} D_{t,+}(x') e^{-\alpha_t h_t(x')}$.

ROC Curve

(Egan, 1975)

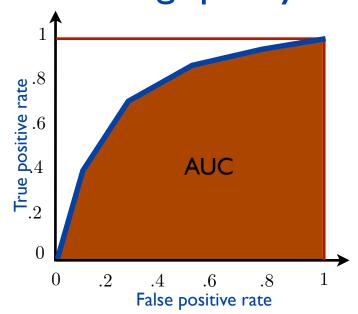
- Definition: the receiver operating characteristic (ROC) curve is a plot of the true positive rate (TP) vs. false positive rate (FP).
 - TP: % positive points correctly labeled positive.
 - FP: % negative points incorrectly labeled positive.



Area under the ROC Curve (AUC)

(Hanley and McNeil, 1982)

Definition: the AUC is the area under the ROC curve. Measure of ranking quality.



Equivalently,

$$AUC(h) = \frac{1}{mm'} \sum_{i=1}^{m} \sum_{j=1}^{m'} 1_{h(x'_j) > h(x_i)} = \Pr_{\substack{x \sim \widehat{D}_- \\ x' \sim \widehat{D}_+}} [h(x') > h(x)]$$
$$= 1 - \widehat{R}(h).$$

This Talk

- Score-based ranking
- Preference-based ranking

Preference-Based Setting

Definitions:

- U: universe, full set of objects.
- V: finite query subset to rank, $V \subseteq U$.
- τ^* : target ranking for V (random variable).
- Two stages: can be viewed as a reduction.
 - learn preference function $h: U \times U \rightarrow [0, 1]$.
 - given V, use h to determine ranking σ of V.
- \blacksquare Running-time: measured in terms of |calls to h|.

Preference-Based Ranking Problem

Training data: pairs (V, τ^*) sampled i.i.d. according to D:

$$(V_1,\tau_1^*),(V_2,\tau_2^*),\dots,(V_m,\tau_m^*) \qquad V_i\subseteq U.$$
 subsets ranked by different labelers.

preference function $h: U \times U \rightarrow [0, 1]$.

Problem: for any query set $V \subseteq U$, use h to return ranking $\sigma_{h,V}$ close to target τ^* with small average error

$$R(h,\sigma) = \mathop{\mathbf{E}}_{(V,\tau^*)\sim D}[L(\sigma_{h,V},\tau^*)].$$

Preference Function

- h(u, v) close to 1 when u preferred to v, close to 0 otherwise. For the analysis, $h(u, v) \in \{0, 1\}$.
- Assumed pairwise consistent:

$$h(u,v) + h(v,u) = 1.$$

May be non-transitive, e.g., we may have

$$h(u, v) = h(v, w) = h(w, u) = 1.$$

Output of classifier or 'black-box'.

Loss Functions

(for fixed (V, τ^*))

Preference loss:

$$L(h, \tau^*) = \frac{2}{n(n-1)} \sum_{u \neq v} h(u, v) \tau^*(v, u).$$

Ranking loss:

$$L(\sigma, \tau^*) = \frac{2}{n(n-1)} \sum_{u \neq v} \sigma(u, v) \tau^*(v, u).$$

(Weak) Regret

Preference regret:

$$\mathcal{R}'_{class}(h) = \underset{V,\tau^*}{\mathrm{E}}[L(h_{|V},\tau^*)] - \underset{V}{\mathrm{E}} \min_{\tilde{h}} \underset{\tau^*|V}{\mathrm{E}}[L(\tilde{h},\tau^*)].$$

Ranking regret:

$$\mathcal{R}'_{rank}(A) = \underset{V,\tau^*,s}{\mathrm{E}}[L(A_s(V),\tau^*)] - \underset{V}{\mathrm{E}} \underset{\tilde{\sigma} \in S(V)}{\min} \underset{\tau^* \mid V}{\mathrm{E}}[L(\tilde{\sigma},\tau^*)].$$

Deterministic Algorithm

(Balcan et al., 07)

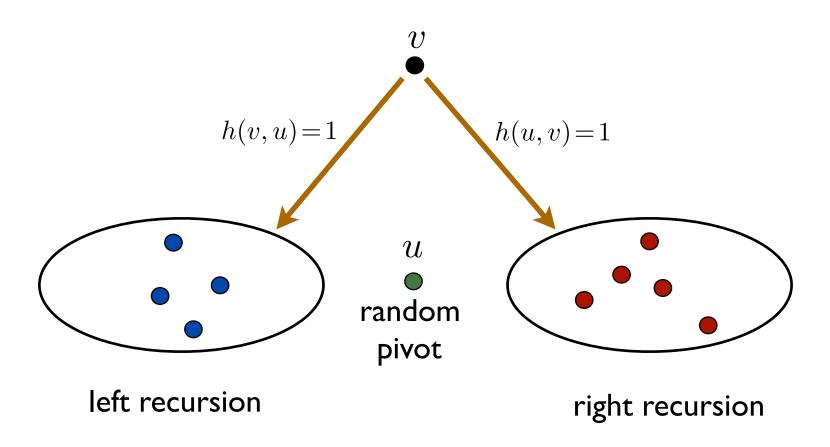
- Stage one: standard classification. Learn preference function $h: U \times U \rightarrow [0,1]$.
- Stage two: sort-by-degree using comparison function h.
 - sort by number of points ranked below.
 - quadratic time complexity $O(n^2)$.

Randomized Algorithm

(Ailon & MM, 08)

- Stage one: standard classification. Learn preference function $h: U \times U \rightarrow [0,1]$.
- Stage two: randomized QuickSort (Hoare, 61) using h as comparison function.
 - comparison function non-transitive unlike textbook description.
 - but, time complexity shown to be $O(n \log n)$ in general.

Randomized QS



Deterministic Algo. - Bipartite Case

$$(V = V_{+} \cup V_{-})$$
 (Balcan et al., 07)

- Bounds: for deterministic sort-by-degree algorithm
 - expected loss:

$$E_{V,\tau^*}[L(A(V),\tau^*)] \le 2 E_{V,\tau^*}[L(h,\tau^*)].$$

regret:

$$\mathcal{R}'_{rank}(A(V)) \le 2 \mathcal{R}'_{class}(h).$$

■ Time complexity: $\Omega(|V|^2)$.

Randomized Algo. - Bipartite Case

$$(V = V_+ \cup V_-)$$

(Ailon & MM, 08)

- Bounds: for randomized QuickSort (Hoare, 61).
 - expected loss (equality):

$$\mathop{\mathbf{E}}_{V,\tau^*,s}[L(Q_s^h(V),\tau^*)] = \mathop{\mathbf{E}}_{V,\tau^*}[L(h,\tau^*)].$$

regret:

$$\mathcal{R}'_{rank}(Q_s^h(\cdot)) \le \mathcal{R}'_{class}(h)$$
.

- Time complexity:
 - full set: $O(n \log n)$.
 - top k: $O(n + k \log k)$.

Proof Ideas

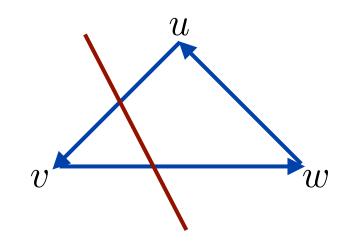
QuickSort decomposition:

$$p_{uv} + \frac{1}{3} \sum_{w \notin \{u,v\}} p_{uvw} \Big(h(u,w)h(w,v) + h(v,w)h(w,u) \Big) = 1.$$

Bipartite property:

$$\tau^*(u,v) + \tau^*(v,w) + \tau^*(w,u) =$$

$$\tau^*(v,u) + \tau^*(w,v) + \tau^*(u,w).$$



Lower Bound

■ Theorem: for any deterministic algorithm A, there is a bipartite distribution for which

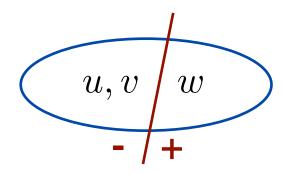
$$\mathcal{R}_{rank}(A) \geq 2 \mathcal{R}_{class}(h).$$

- thus, factor of 2 = best in deterministic case.
- randomization necessary for better bound.
- Proof: take simple case $U = V = \{u, v, w\}$ and assume that h induces a cycle. u
 - ullet up to symmetry, A returns

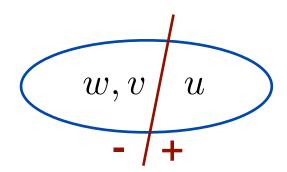
$$u, v, w$$
 or w, v, u .

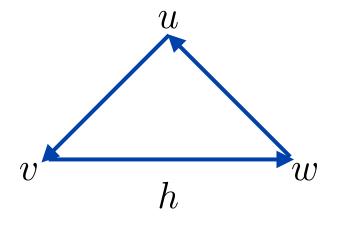
Lower Bound

If A returns u, v, w, then choose τ^* as:



If A returns w, v, u, then choose τ^* as:





$$L[h,\tau^*] = \frac{1}{3};$$

$$L[A, \tau^*] = \frac{2}{3}.$$

Guarantees - General Case

Loss bound for QuickSort:

$$\mathop{\mathbf{E}}_{V,\tau^*,s}[L(Q_s^h(V),\tau^*)] \le 2 \mathop{\mathbf{E}}_{V,\tau^*}[L(h,\tau^*)].$$

Comparison with optimal ranking (see (CSS 99)):

$$E_s[L(Q_s^h(V), \sigma_{optimal})] \le 2L(h, \sigma_{optimal})$$
$$E_s[L(h, Q_s^h(V))] \le 3L(h, \sigma_{optimal}),$$

where
$$\sigma_{optimal} = \underset{\sigma}{\operatorname{argmin}} L(h, \sigma)$$
.

Weight Function

Generalization:

$$\tau^*(u,v) = \sigma^*(u,v)\,\omega(\sigma^*(u),\sigma^*(v)).$$

- Properties: needed for all previous results to hold,
 - symmetry: $\omega(i,j) = \omega(j,i)$ for all i,j.
 - monotonicity: $\omega(i,j), \omega(j,k) \leq \omega(i,k)$ for i < j < k .
 - triangle inequality: $\omega(i,j) \leq \omega(i,k) + \omega(k,j)$ for all triplets i,j,k.

Weight Function - Examples

- **Kemeny:** $w(i,j) = 1, \ \forall i,j.$
- Top-k: $w(i,j) = \begin{cases} 1 & \text{if } i \leq k \text{ or } j \leq k; \\ 0 & \text{otherwise.} \end{cases}$
- Bipartite: $w(i,j) = \begin{cases} 1 & \text{if } i \leq k \text{ and } j > k; \\ 0 & \text{otherwise.} \end{cases}$
- k-partite: can be defined similarly.

(Strong) Regret Definitions

Ranking regret:

$$\mathcal{R}_{rank}(A) = \underset{V,\tau^*,s}{\text{E}}[L(A_s(V),\tau^*)] - \underset{\tilde{\sigma}}{\text{min}} \underset{V,\tau^*}{\text{E}}[L(\tilde{\sigma}_{|V},\tau^*)].$$

Preference regret:

$$\mathcal{R}_{class}(h) = \mathop{\mathbf{E}}_{V,\tau^*}[L(h_{|V},\tau^*)] - \min_{\tilde{h}} \mathop{\mathbf{E}}_{V,\tau^*}[L(\tilde{h}_{|V},\tau^*)].$$

lacktriangle All previous regret results hold if for $V_1,V_2\supseteq\{u,v\}$,

$$\underset{\tau^*|V_1}{\mathrm{E}} [\tau^*(u,v)] = \underset{\tau^*|V_2}{\mathrm{E}} [\tau^*(u,v)]$$

for all u, v (pairwise independence on irrelevant alternatives).

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