

# Applied Data-Science Capstone Project

Treasure Okafor 24th October, 2022





## OUTLINE



- Executive Summary
- Introduction
- Methology
- Results
  - Visualization Charts
  - Dashboard
- Discussion
  - Findings & Implications
- Conclusion
- Appendix

#### **EXECUTIVE SUMMARY**



• Data Science journey:

Data collection, wrangling, exploratory data analysis with sequel and python, interactive visual analytics and predictive analytics.

Summary of all results.

#### INTRODUCTION



A Data Science project is a project that provides the basis for performing subsequent analysis and processing of data.

In this report, I'll help you understand my Data science journey so far with the little skills I covered.

Let get started!

### **METHODOLOGY**



- Executive Summary
- Data collection
- Data wrangling
- Exploratory data analysis
- Data visualization
- Model Development
- Reporting

## Data Collection

Space X advertises Falcon 9 rocket launches on its website with a cost of 62 million dollars; other providers cost upward of 165 million dollars each, much of the savings is because Space X can reuse the first stage. Therefore if we can determine if the first stage will land, we can determine the cost of a launch. This information can be used if an alternate company wants to bid against space X for a rocket launch.

#### Data Collection API

#### Now let's start requesting rocket launch data from SpaceX API with the following URL: spacex url="https://api.spacexdata.com/v4/launches/past" response = requests.get(spacex\_url) Check the content of the response print(response.content) b'[{"fairings":{"reused":false, "recovery\_attempt":false, "recovered":false, "ships":[]}, "links":{"patch":{"sm h45r\_o.png", "large": "https://images2.imgbox.com/5b/02/QcxHUbSV\_o.png"}, "reddit": {"campaign":null, "launch": {"small":[], "original":[]}, "presskit":null, "webcast": "https://www.youtube.com/watch?v=0a\_00nJ\_Y88", "youtube pace.com/2196-spacex-inaugural-falcon-1-rocket-lost-launch.html", "wikipedia": "https://en.wikipedia.org/wiki 17700:00:00.000Z", "static\_fire\_date\_unix":1142553600, "net":false, "window":0, "rocket":"5e9d0d95eda69955f709d1 3, "altitude":null, "reason": "merlin engine failure"}], "details": "Engine failure at 33 seconds and loss of ve [],"payloads":["5eb0e4b5b6c3bb0006eeb1e1"],"launchpad":"5e9e4502f5090995de566f86","flight\_number":1,"name" 0.000Z", "date\_unix":1143239400, "date\_local":"2006-03-25T10:30:00+12:00", "date\_precision":"hour", "upcoming" b2623", "flight":1, "gridfins":false, "legs":false, "reused":false, "landing attempt":false, "landing success":nu to\_update":true, "tbd":false, "launch\_library\_id":null, "id":"5eb87cd9ffd86e000604b32a"}, {"fairings":{"reused" d":false, "ships":[]}, "links": {"patch": {"small": "https://images2.imgbox.com/f9/4a/ZboXReNb\_o.png", "large": " png"},"reddit":{"campaign":null,"launch":null,"media":null,"recovery":null},"flickr":{"small":[],"original"

#### Data Collection with webscraping with beautiful soup

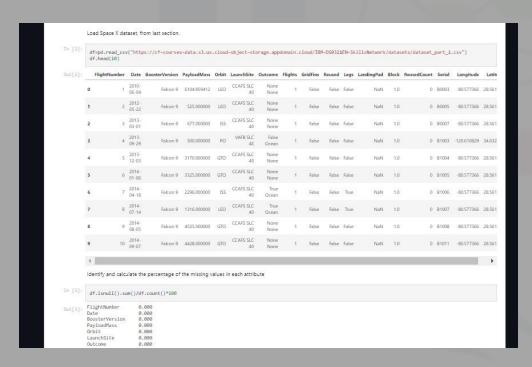
```
static_url = "https://en.wikipedia.org/w/index.php?title=List_of_Falcon_9_and_Falcon_Heavy_launches&oldid=1027686922"
Next, request the HTML page from the above URL and get a response object
First, let's perform an HTTP GET method to request the Falcon9 Launch HTML page, as an HTTP response
 # use requests.get() method with the provided static url
 response = requests.get(static_url)
 # assign the response to a object
Create a BeautifulSoup object from the HTML response
 # Use BeautifulSoup() to create a BeautifulSoup object from a response text content
 soup = BeautifulSoup(response.text, "html.parser")
Print the page title to verify if the BeautifulSoup object was created properly
# Use soup.title attribute
 print(html_file.prettify())
<html class="client-nojs" dir="ltr" lang="en">
  <title>
  List of Falcon 9 and Falcon Heavy launches - Wikipedia
   document.documentElement.className="client-js";RLCONF={"wgBreakFrames":false,"wgSeparatorTransformTable":["",""],"wgDigitTransform
gDefaultDateFormat":"dmy","wgMonthNames":["","January","February","March","April","May","June","July","August","September","October"
```

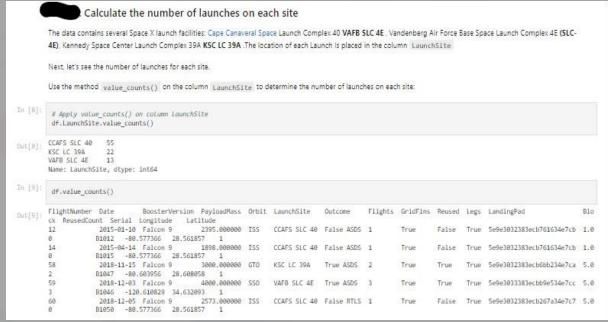




## Data wrangling

- Calculate the number of launches on each site.
- Calculate the number and occurrence of each orbit.
- https://github.com/Teekafy/Treasure\_proj/blob/97cce462a14e1bd6bc35d7f05705b941e0acf056/Data%2 0Wrangling.ipynb





#### EDA and interactive visual analytics

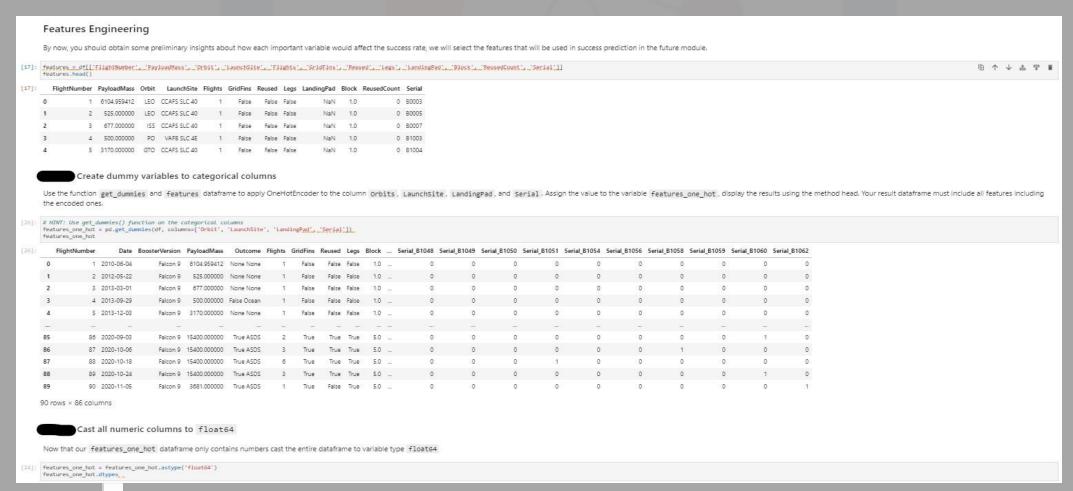
https://github.com/Teekafy/Treasure\_proj/blob/c1fba45b132d661b31ac248b66a5355003838975/eda%20visualization.ipynb

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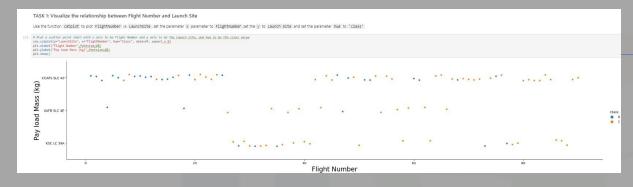
## Predictive analysis

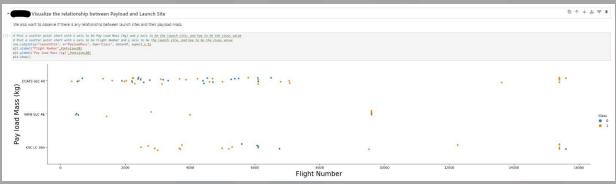


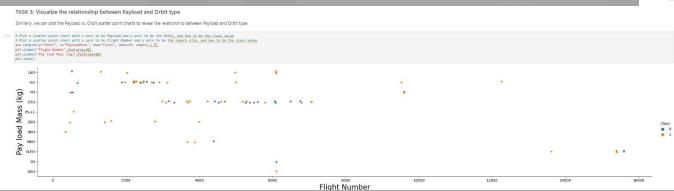




### EDA with Visualization





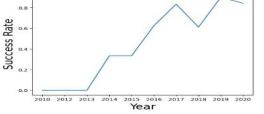


### IBM Developer



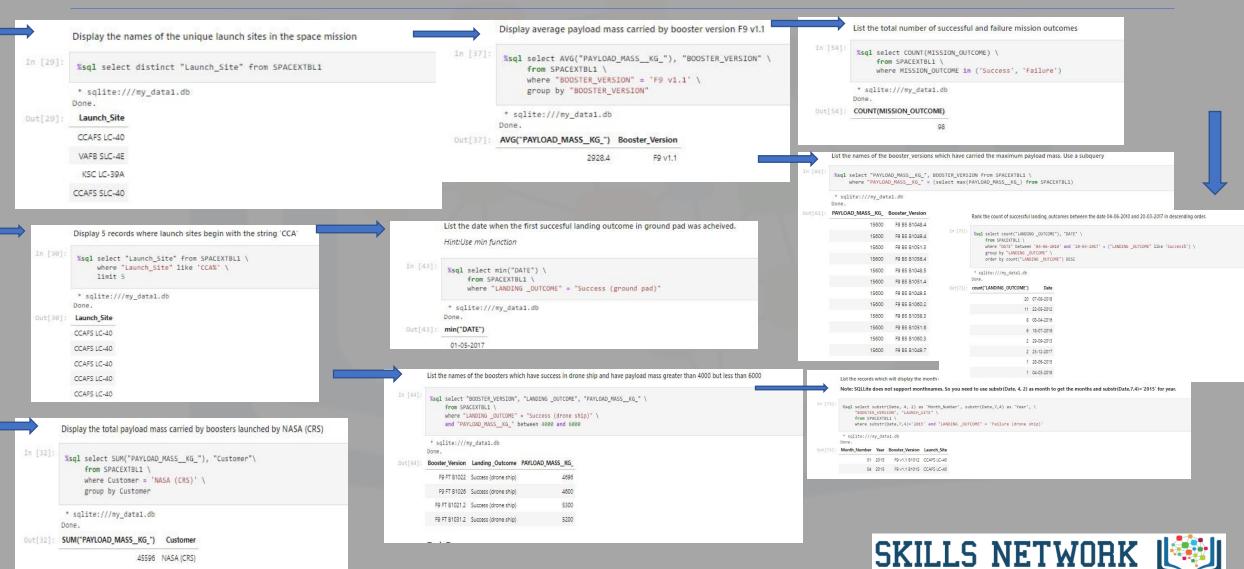






# EDA with Sequel (SQL)

45596 NASA (CRS)

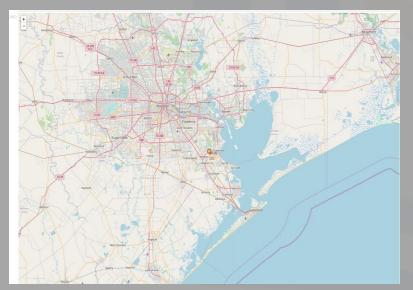


## Interactive map with Folium

```
TODO: For each launch result in spacex_df data frame, add a folium.Marker to marker_cluster
151: #Add marker cluster to current site map
    site_map.add_child(marker_cluster)
    # for each row in spacex_df data frame
    # create a Marker object with its coordinate
    # and customize the Marker's icon property to indicate if this Launch was successed or failed.
    # e.g., icon=folium.Icon(color='white', icon_color=row['marker_color']
     for index, record in spacex df.iterrows():
        # TODO: Create and add a Marker cluster to the site map
        lat = record['Lat']
        long = record['Long']
        coordinate = [lat, long]
        marker = folium.Marker(
           coordinate.
            icon=folium.Icon(color='white', icon_color=record['marker_color'])
        marker cluster.add child(marker)
```

```
TODO: Draw a PolyLine between a launch site to the selected coastline point

| # Create a 'folium.PolyLine' object using the coastline coordinates and Launch site coordinate
    # Lines=folium.PolyLine(Locations=coordinates, weight=1)
    # Create a 'folium.PolyLine' object using the coastline coordinates and Launch site coordinate
    # Lines=folium.PolyLine(Locations=coordinates, weight=1)
    coast_coordinate = [coastline_lat, coastline_lon]
    launch_coordinate = [launch_site_lat, launch_site_lon]
    coordinates = [coast_coordinate, launch_coordinate]
    lines = folium.PolyLine(locations=coordinates, weight=1)
    site_map.add_child(lines)
    site_map.add_child(lines)
```







## Plotly Dash dashboard

Link to Code:

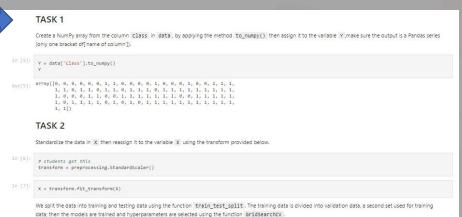
https://github.com/Teekafy/Treasure\_proj/blob/c1fba45b132d661b31ac248b66a5355003838975/spacex\_dash\_app.py



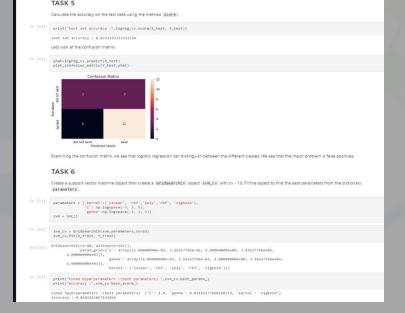
IBM **Developer** 

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## Predictive Analysis











#### continued

#### TASK 9 Calculate the accuracy of tree\_cv on the test data using the method score : print("test set accuracy :",tree\_cv.score(X\_test, Y\_test)) test set accuracy : 0.833333333333333334 We can plot the confusion matrix yhat = svm\_cv.predict(X\_test) plot\_confusion\_matrix(Y\_test,yhat) Confusion Matrix TASK 10 Create a kinearest neighbors object then create a GridSearchCV object knn\_cv with cv = 10. Fit the object to find the best parameters from the dictionary parameters. parameters = {'n\_neighbors': [1, 2, 3, 4, 5, 6, 7, 8, 9, 10], 'algorithm': ['auto', 'ball\_tree', 'kd\_tree', 'brute'], KNN = KNeighborsClassifier() In [26]: knn\_cv = GridSearchCV(KNN,parameters,cv=10) knn\_cv.fit(X\_train, Y\_train) GridSearchCV(cv=10, estimator=KNeighborsClassifier(), param\_grid={'algorithm': ['auto', 'ball\_tree', 'kd\_tree', 'brute'], 'n\_neighbors': [1, 2, 3, 4, 5, 6, 7, 8, 9, 10], 'p': [1, 2]}) In [27]: print("tuned hpyerparameters :(best parameters) ",knn\_cv.best\_params\_) print("accuracy :",knn\_cv.best\_score\_)

```
TASK 12
Find the method performs best:
 models = {'KNeighbors':knn_cv.best_score_,
               'DecisionTree':tree_cv.best_score_
               'LogisticRegression':logreg_cv.best_score_,
               'SupportVector': svm_cv.best_score_}
 bestalgorithm = max(models, key=models.get)
 print('Best model is', bestalgorithm,'with a score of', models[bestalgorithm])
 if bestalgorithm == 'DecisionTree'
    print('Best params is :', tree_cv.best_params_)
 if bestalgorithm == 'KNeighbors'
    print('Best params is :', knn_cv.best_params_)
 if bestalgorithm == 'LogisticRegression
    print('Best params is :', logreg_cv.best_params_)
 if bestalgorithm == 'SupportVector
    print('Best params is :', svm_cv.best_params_)
Best model is DecisionTree with a score of 0.8732142857142856
Best params is : {'criterion': 'gini', 'max_depth': 6, 'max_features': 'auto', 'min_samples_leaf': 2, 'min_samples_split': 5, 'splitter': 'random'}
```

```
TASK 11
Calculate the accuracy of tree_cv on the test data using the method score :
 print("test set accuracy :",knn_cv.score(X_test, Y_test))
test set accuracy : 0.83333333333333334
We can plot the confusion matrix
 yhat = knn_cv.predict(X_test)
 plot_confusion_matrix(Y_test,yhat)
                 Confusion Matrix
```

did not land

Predicted labels



tuned hpyerparameters :(best parameters) {'algorithm': 'auto', 'n\_neighbors': 10, 'p': 1}



## Conclusion and Insights

- The SVM, KNN and Logistic Regression models are the best in terms of prediction accuracy for this dataset.
- Low weighted payloads perform better than heavier payloads.
- KSC LC 39A had the most successful launches from all the sites.
- Orbit GEO, HEO, SSO, ES I1 have the best success rate.

#### **APPENDICES**



<a href="https://en.wikipedia.org/wiki/SpaceX">https://en.wikipedia.org/wiki/SpaceX</a>
<a href="https://www.youtube.com/c/spacex">https://www.youtube.com/c/spacex</a>