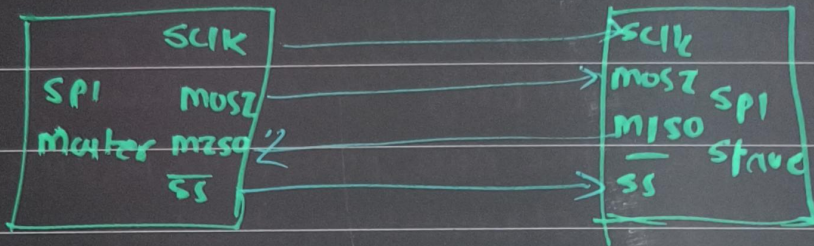


SPI (Serial peripheral Interface)

MOSI = SDI serial data in
MISO = SDO serial data out

master always initiates transaction.

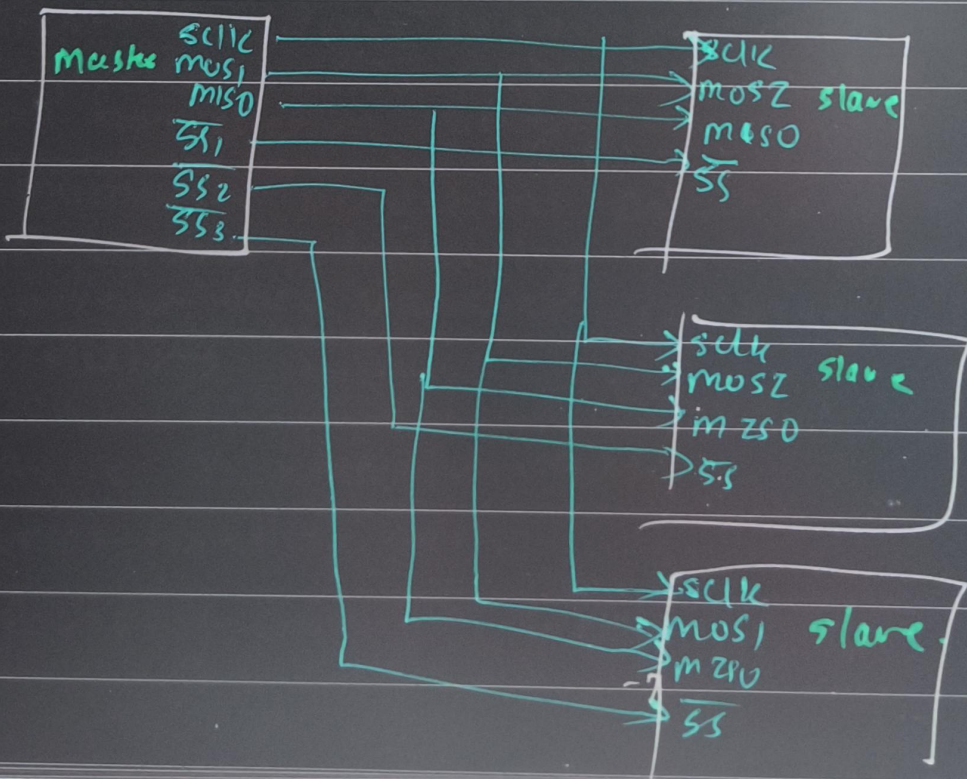


SCLK → serial clock

MOSI → master out slave in

MISO → master in slave out

\overline{SS} → slave select (chip select, active low)



Advantages / Disadvantages.

→ Full duplex

→ Higher speed than

UART + I2C

→ ubiquitous

more pins than UART+I2C

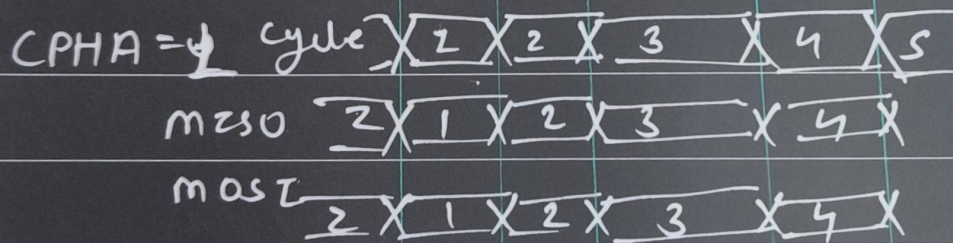
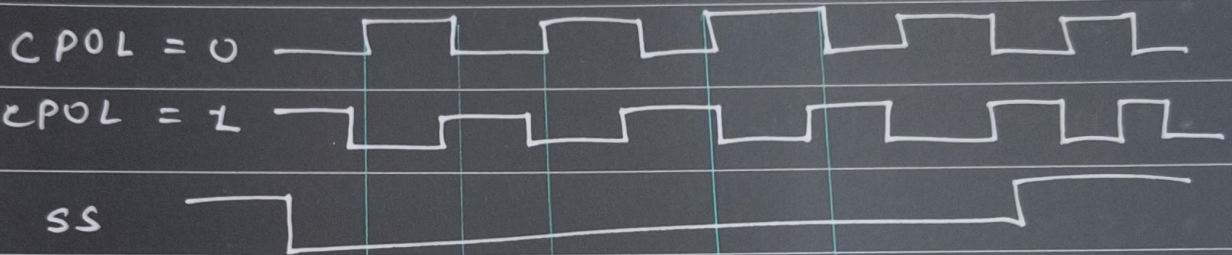
short distance vs.

RS485 / RS232

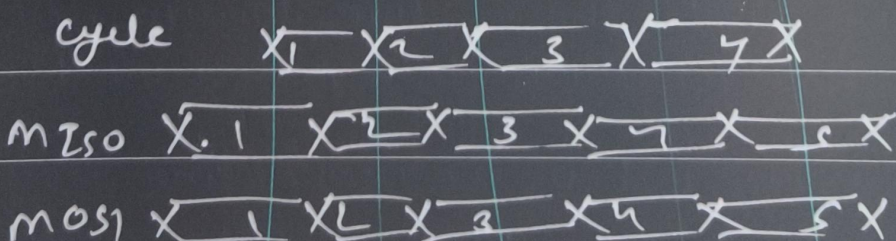
Lots of variants

CPOL → clock polarity

CPHA → clock phase.



CPHA = 0



Key features of SPI:-

1] Full-Duplex communication

SPI supports simultaneous data transmission and reception.

2] Master slave architecture:-

~~SPI supp~~ There is typically one master device and one or more slave

3] Four-wire interface

- MOSI (Master out Slave In)

carries data from the master to the slave

- MISO (Master in Slave out)

carries data from the slave to the master

- SCLK (Serial clock)

Generated by the master to synchronize data transfer

- SS (Slave select)

Used by master to select which slave device to communicate with.

How SPI works:-

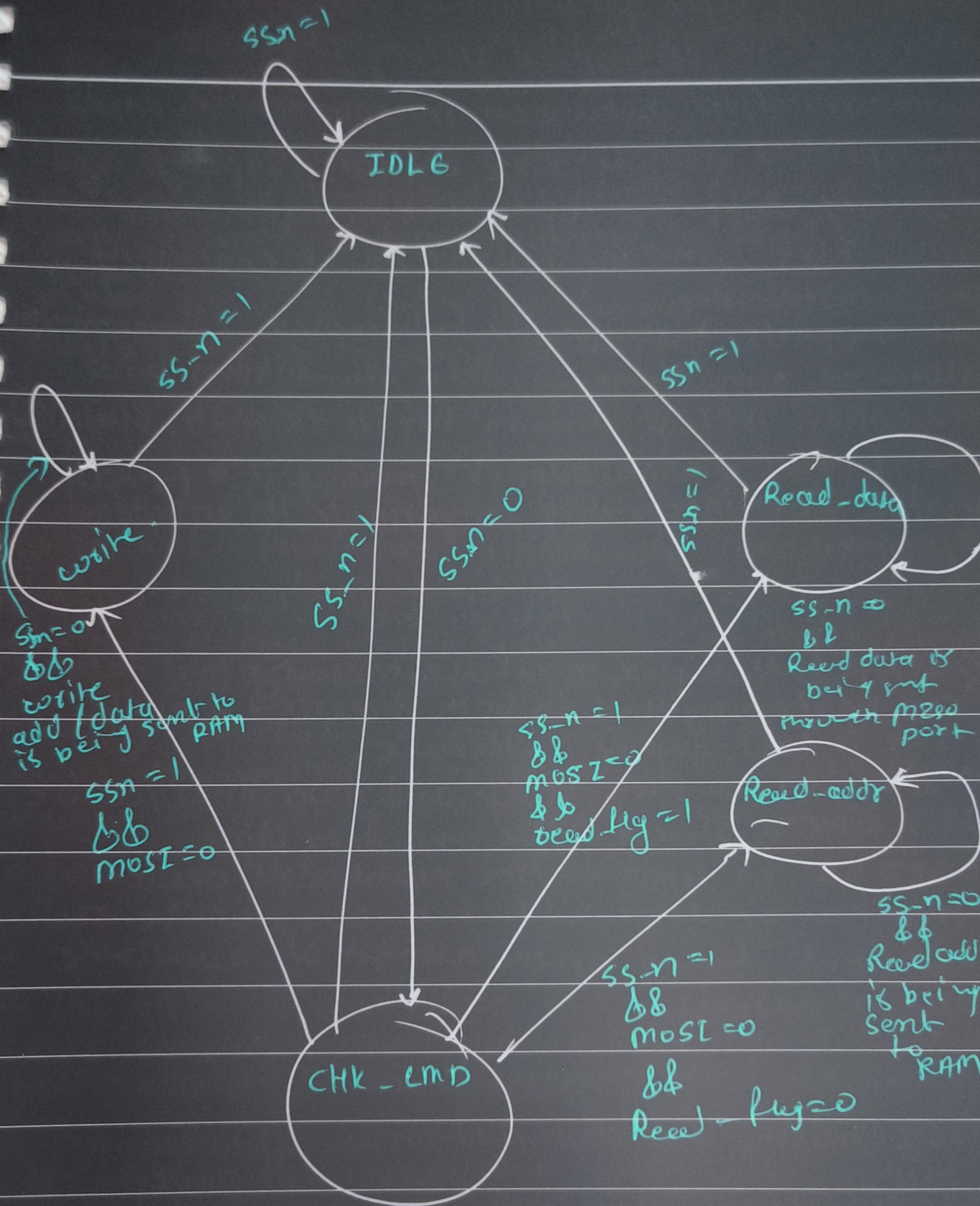
1] Initialization

master configures the clock polarity (CPOL) and clock phase (CPHA) settings. It also determines the clock frequency.

2] Data Transfer.

- The master pulls the SS line low to select slave.
- The master generates clock pulse on the SCLK line.
- Data is shifted out of the MOSI line from master and into the slave, while data from the slave is shifted out of the MISO line and into master.

slave state Transition Diagram FSM



Daisy chain in SPI

