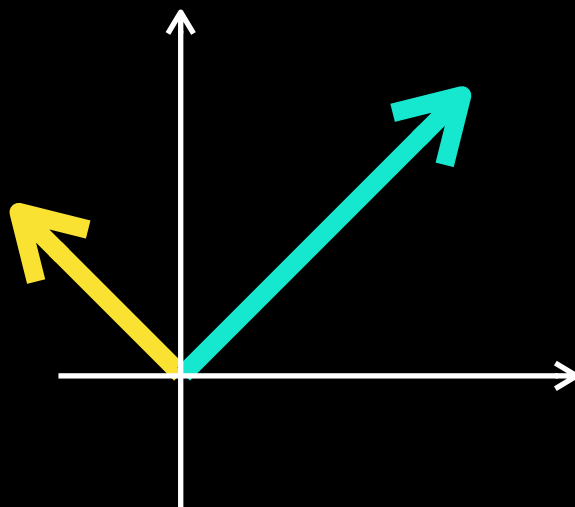


Changing reference frame

Linear Algebra Essentials



$$v = \begin{bmatrix} 4 \\ 5 \end{bmatrix} = 4 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 5 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = 4\vec{e}_1 + 5\vec{e}_2$$

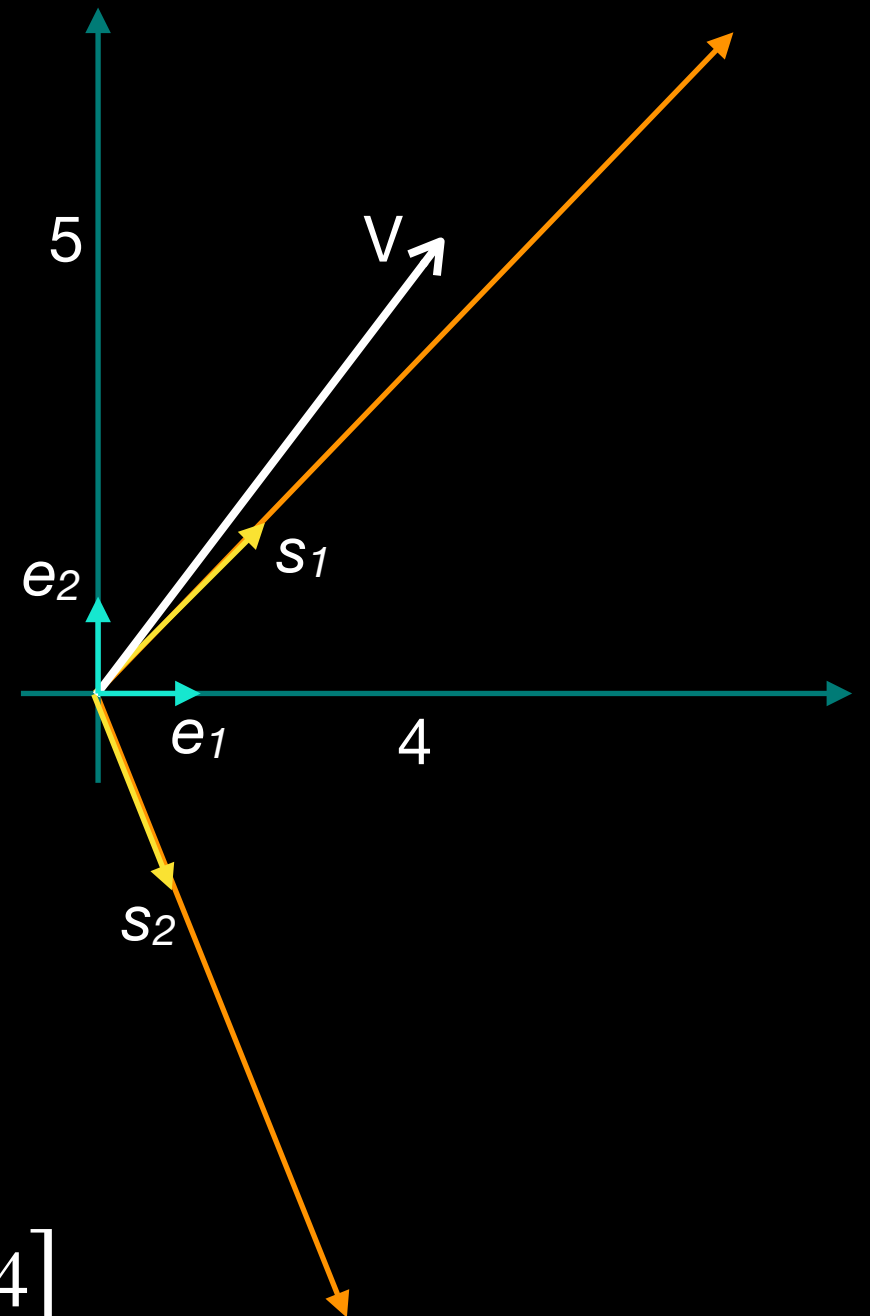
$$s_1 = \begin{bmatrix} 2 \\ 2 \end{bmatrix} \quad s_2 = \begin{bmatrix} 1 \\ -2 \end{bmatrix} \quad - \text{new basis}$$

$$v = a_1 \vec{s}_1 + a_2 \vec{s}_2$$

$$= \begin{bmatrix} 2 \\ 2 \end{bmatrix} a_1 + \begin{bmatrix} 1 \\ -2 \end{bmatrix} a_2 = \begin{bmatrix} 2 & 1 \\ 2 & -2 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \end{bmatrix}$$

$$S \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} = v \quad \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} = S^{-1}v = \begin{bmatrix} 1/3 & 1/6 \\ 1/3 & -1/3 \end{bmatrix} \begin{bmatrix} 4 \\ 5 \end{bmatrix}$$

$$v_{new} = \begin{bmatrix} 13/6 \\ -1/3 \end{bmatrix}$$



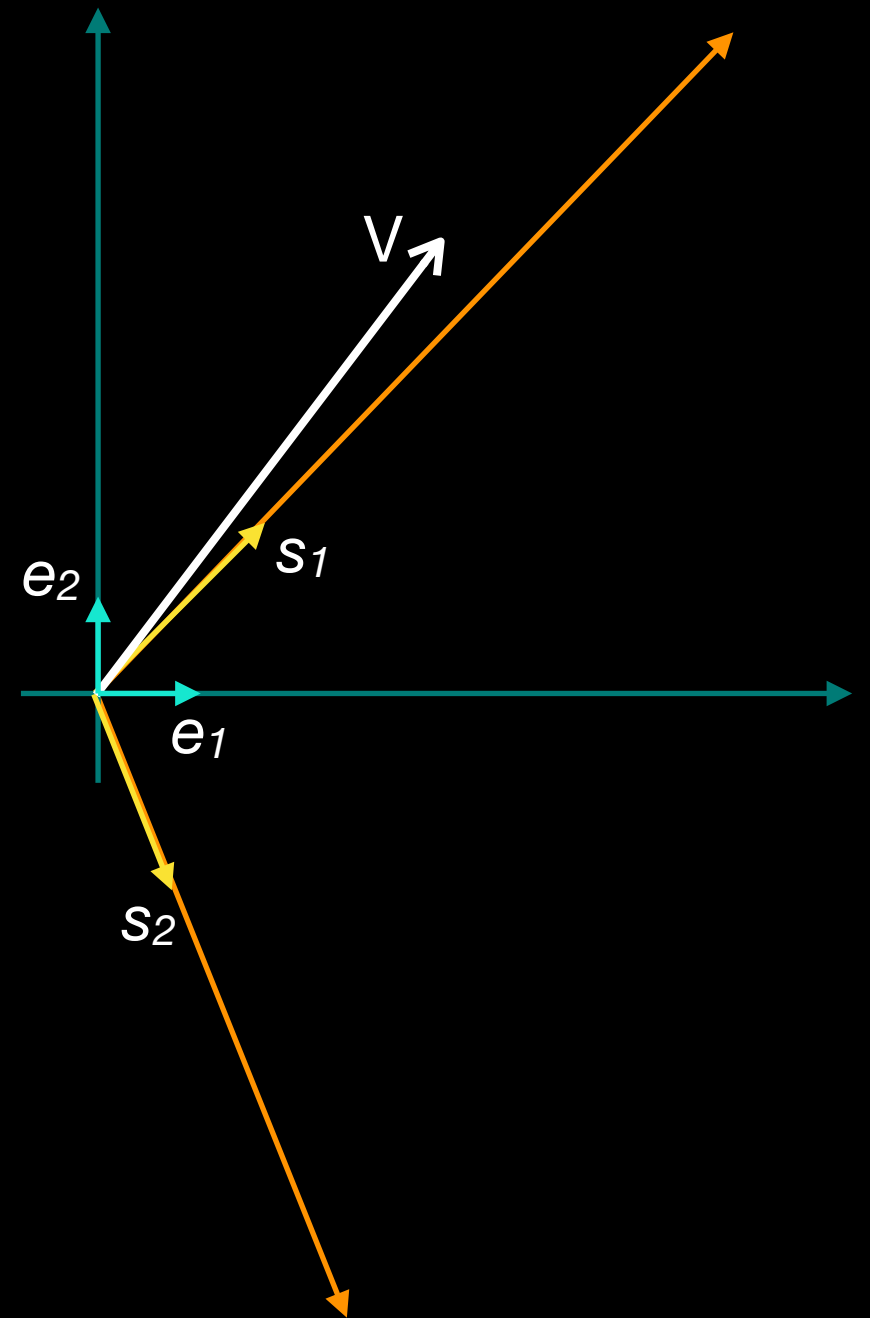
Old reference frame: $\{e_1, e_2, \dots, e_n\}$

New basis: $\{s_1, s_2, \dots, s_n\}$

$$S = \begin{bmatrix} s_1 & s_2 & \dots & s_n \end{bmatrix}$$

$$v_{old} = a_1 e_1 + \dots + a_n e_n = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix}$$

$$v_{new} = S^{-1} v_{old} = \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix}$$



$$s_1 = \begin{bmatrix} 2 \\ 2 \end{bmatrix} \quad s_2 = \begin{bmatrix} 1 \\ -2 \end{bmatrix} \quad - \text{new basis}$$

$$t = \begin{bmatrix} 2 \\ -3 \end{bmatrix} \quad V' = V - t \quad - \text{in the old ref. frame}$$

$$v'_{new} = S^{-1}v'_{old}$$

$$v'_{new} = S^{-1}v_{old} - S^{-1}t$$

$$v'_{new} = \begin{bmatrix} S^{-1} & -S^{-1}t \\ (2 \times 3) \end{bmatrix} \begin{bmatrix} v_{old} \\ 1 \end{bmatrix}$$

$$v'_{new} = \begin{bmatrix} 1/3 & 1/6 & -1/6 \\ 1/3 & -1/3 & -5/3 \end{bmatrix} \begin{bmatrix} 4 \\ 5 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ -2 \end{bmatrix}$$

