$$\bullet (\overline{a} \cdot \overline{b}) = x_1 x_2 + y_1 y_2; \bullet |\overline{a}| = \sqrt{x_1^2 + y_1^2}; \bullet < \overline{a}, \overline{b}, \overline{c} > = ([\overline{a}, \overline{b}], \overline{c}) = \begin{bmatrix} a_x & a_y & a_z \\ b_x & b_y & b_z \\ c_x & c_y & c_z \end{bmatrix};$$

$$\bullet (\overline{a}; \overline{b}) = |\overline{a}| \cdot |\overline{b}| \cdot \cos \alpha; \bullet |[\overline{a}; \overline{b}]| = |\overline{a}| \cdot |\overline{b}| \cdot \sin \alpha; \begin{bmatrix} \overline{i} & \overline{j} & \overline{k} \\ a_x & a_y & a_z \\ b_x & b_y & b_z \end{bmatrix}$$

• 
$$(\overline{a}; \overline{b}) = |\overline{a}| \cdot |\overline{b}| \cdot \cos \alpha;$$
 •  $|[\overline{a}; \overline{b}]| = |\overline{a}| \cdot |\overline{b}| \cdot \sin \alpha;$  
$$\begin{vmatrix} i & j & k \\ a_x & a_y & a_z \\ b_x & b_y & b_z \end{vmatrix}$$

**1.** 
$$A(x-x_0) + B(y-y_0) = 0$$
;  $M_0(x_0; y_0)$ ,  $\overline{N} = \{A; B\}$ ; **2.**  $\frac{x-x_0}{m} = \frac{y-y_0}{n}$ ;  $M_0(x_0; y_0)$ ,  $\overline{s} = \{m; n\}$ ;

**3.** 
$$x = mt + x_0$$
;  $y = nt + y_0$ ;  $M_0(x_0; y_0)$ ,  $\overline{s} = \{m; n\}$ ; **4.**  $y - y_0 = l = k(x - x_0)$ ;  $k = tg \Leftrightarrow -\frac{A}{B} = \frac{n}{m}$ ;  $M_0(x_0; y_0)$ ;

**5.** 
$$\frac{x-x_1}{x_2-x_1} = \frac{y-y_1}{y_2-y_1}$$
;  $M_1(x_0; y_0)$ ,  $M_2(x_2; y_2)$ ;

$$\textbf{1.} \ l_1: \ \frac{x-x_1}{m_1} = \frac{y-y_1}{n_1}; \ l_2: \frac{x-x_2}{m_2} = \frac{y-y_2}{n_2}; \ \overline{s_1} = \{m_1; n_1\}, \ \overline{s_2} = \{m_2; n_2\}; \ \cos \varphi = \frac{\overline{(\overline{s_1 \cdot s_2})}}{|\overline{s_1}| \cdot |\overline{s_2}|};$$

**2.** 
$$l_1$$
:  $A_1x + B_1y + C = 0$ ,  $l_2$ :  $A_2x + B_2y + C_2 = 0$ ;  $\overline{N_1} = \{A_1; B_1\}$ ;  $\overline{N_2} = \{A_2; B_2\}$ ;  $\cos \phi = \frac{(\overline{N_1} \cdot \overline{N_2})}{|\overline{N_1}| \cdot |\overline{N_2}|}$ 

• 
$$M_1(x_1; y_1)$$
;  $l: Ax + By + C = 0$ ;  $d = \frac{|Ax_1 + By_1 + C|}{\sqrt{A^2 + B^2}}$ ;

$$\textbf{1.}\ A(x-x_0) \ +\ B(y-y_0) \ +\ C(z-z_0) \ =\ 0; \\ M_0(x_0;y_0;z_0); \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ \{A;B;C\}; \\ \textbf{2.}\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ Ax \ +\ By \ +\ Cz \ +\ D \ =\ 0; \\ \overline{N} \ =\ Ax \ +\ By \ +\ D \ =\ 0; \\ \overline{N} \ =\ Ax \ +\ By \ +\ D \ =\ 0; \\ \overline{N} \ =\ Ax \ +\ By \ +\ D \ =\ 0; \\ \overline{N} \ =\ Ax \ +\ By \ +\ D \ =\ 0; \\ \overline{N} \ =\ Ax \ +\ By \ +\ D \ =\ 0; \\ \overline{N} \ =\ Ax \ +\ By \ +$$

3. 
$$\frac{x}{a} + \frac{y}{b} + \frac{z}{c} = 1$$
; 4.  $M_1(x_1; y_1; z_1)$ ,  $M_2(x_2; y_2; z_2)$ ,  $M_3(x_3; y_3; z_3)$ 

$$\begin{bmatrix} x - x_1 & y - y_1 & z - z_1 \\ x_2 - x_1 & y_2 - y_1 & z_2 - z_1 \\ x_3 - x_1 & y_3 - y_1 & z_3 - z_1 \end{bmatrix} = 0$$

**1.** 
$$\frac{x-x_0}{x_1-x_0} = \frac{y-y_0}{y_1-y_0} = \frac{z-z_0}{z_1-z_0}$$
;  $M_0(x_0; y_0; z_0)$ ,  $M_1(x_1; y_1; z_1)$ ;

**1.** 
$$\overline{AB} = \{x_B - x_A; y_B - y_A; z_B - z_A\};$$
 **2.**  $\overline{a} = x_1\overline{i} + y_1\overline{j} + z_1\overline{k};$   $\overline{a} = \{x_1; y_1; z_1\};$  **3.**  $|\overline{a}| = \sqrt{(\overline{a})^2};$   $|\overline{a}| = \sqrt{x_1^2 + y_1^2 + z_1^2};$ 

**4.** 
$$\cos \alpha = \frac{x}{|\bar{a}|}$$
;  $\cos \beta = \frac{y}{|\bar{a}|}$ ;  $\cos \gamma = \frac{z}{|\bar{a}|}$ ;  $\cos \alpha = \frac{x}{\sqrt{x_1^2 + y_1^2 + z_1^2}}$ ;  $\cos \beta = \frac{y}{\sqrt{x_1^2 + y_1^2 + z_1^2}}$ ;  $\cos \gamma = \frac{z}{\sqrt{x_1^2 + y_1^2 + z_1^2}}$ ;

**5.** 
$$\overline{a}^0 = \frac{\overline{a}}{|\overline{a}|}$$
;  $\overline{a}^0 = \{\cos \alpha; \cos \beta; \cos \gamma\}$ ;

$$\textbf{6.} \ \overline{c} = \alpha \overline{a} + \beta \overline{b} \Leftrightarrow \begin{cases} \alpha x_1 + \beta x_2 &= x_3 \\ \alpha y_1 + \beta y_2 &= y_3 \end{cases} ; \quad \overline{d} = \alpha \overline{a} + \beta \overline{b} + \gamma \overline{c} \Leftrightarrow \begin{cases} \alpha x_1 + \beta x_2 + \gamma x_3 &= x_4 \\ \alpha y_1 + \beta y_2 + \gamma y_3 &= y_4 \\ \alpha z_1 + \beta z_2 + \gamma z_3 &= z_4 \end{cases} ;$$

$$\textbf{10.}\ M(x_{_{M}};y_{_{M}};z_{_{M}})\ \Leftrightarrow\ \tfrac{AB}{\lambda},\ \overline{AM}=\ \lambda\overline{MB};\ A(x_{_{A}};y_{_{A}};z_{_{A}}),\ B(x_{_{B}};y_{_{B}};z_{_{B}});\ x_{_{M}}=\tfrac{x_{_{A}}+\lambda x_{_{B}}}{1+\lambda},y_{_{M}}=\tfrac{y_{_{A}}+\lambda y_{_{B}}}{1+\lambda},z_{_{M}}=\tfrac{z_{_{A}}+\lambda z_{_{B}}}{1+\lambda};$$

• 
$$S_{par} = |[\overline{a}; \overline{b}]|;$$
 •  $S_{triangle} = \frac{S_{par}}{2};$  •  $V_{par} = \langle \overline{a}, \overline{b}, \overline{c} \rangle;$  •  $V_{pyr} = \frac{V_{par}}{6};$