

PS 3000 C register list for devices with KE firmware from V2.02 (check the installed version in your device's MENU in item INFO HW, SW)												
Modbus address	Read coils (0x01)	Read holding registers	Write single coil (0x05)	Write single register (0x06)	Write multiple registers		Access	Data type	Data length in bytes	Number of registers		
						Description					Data	Example
0	x			x		Device class	R	uint(16)	2	1		57 = PS 3000 C Series
1		x			x	Device type	R	char	40	20	ASCII	PS 3080-05 C
21		x			x	Manufacturer	R	char	40	20	ASCII	
41		x				Manufacturer address	R	char	40	20	ASCII	
61		x			x	Manufacturer ZIP code	R	char	40	20	ASCII	
81		x			x	Manufacturer phone number	R	char	40	20	ASCII	
101		x			x	Manufacturer website	R	char	40	20	ASCII	
121		x			x	Nominal voltage	R	float	4	2	Floating point number IEEE754	80
123		x			x	Nominal current	R	float	4	2	Floating point number IEEE754	5
125		x			x	Nominal power	R	float	4	2	Floating point number IEEE754	160
131		x			x	Article no.	R	char	40	20	ASCII	35320209
151		x			x	Serial no.	R	char	40	20	ASCII	1234567890
171		x			x	User text	RW	char	40	20	ASCII	
191		x			x	Firmware version (KE)	R	char	40	20	ASCII	V2.02
211		x			x	Firmware version (HMI)	R	char	40	20	ASCII	V2.02
231		x			x	Firmware version (DR)	R	char	40	20	ASCII	V2.0.1
402	x		x			Remote mode	RW	uint(16)	2	1	Coils : Remote	0x0000 = off; 0xFF00 = on
405	x		x			DC output	RW	uint(16)	2	1	Coils : Converter	0x0000 = off; 0xFF00 = active
407	x		x			Condition of DC output after power fail alarm	RW	uint(16)	2	1	Coils : Auto-On	0x0000 = off; 0xFF00 = auto-on
408		x		x		Condition of DC output after powering the device	RW	uint(16)	2	1	Coils : Power-On	0xFFFF = off; 0xFFFE = Restore
410	x		x			Restart of the device (warm start)	W	uint(16)	2	1	Coils : Restart	0xFF00 = execute
411	x		x			Acknowledge alarms	W	uint(16)	2	1	Coils : Alarms	0xFF00 = acknowledge
416	x		x			Analog interface: Reference voltage (pin VREF)	RW	uint(16)	2	1	Coils : VREF	0x0000 = 10V; 0xFF00 = 5V
417	x		x			Analog interface: REM-SB level	RW	uint(16)	2	1	Coils : REM-SB Level	0x0000 = normal; 0xFF00 = inverted
418	x		x			Analog interface: REM-SB action	RW	uint(16)	2	1	Coils : REM-SB Action	0x0000 = DC off; 0xFF00 = DC auto
425	x		x			DC output after leaving remote	RW	uint(16)	2	1	Coils : Condition	0x0000 = off (default); 0xFF00 = unchanged
500		x		x		Set voltage value	RW	uint(16)	2	1	0x0000 - 0xD0E5 (0 - 102%)	Voltage value (for translation see programming guide)
501		x		x		Set current value	RW	uint(16)	2	1	0x0000 - 0xD0E5 (0 - 102%)	Current value (for translation see programming guide)
502		x		x		Set power value	RW	uint(16)	2	1	0x0000 - 0xD0E5 (0 - 102%)	Power value (for translation see programming guide)
505			x			Device state	R	uint(32)	4	2	Bit 0- 4: Control location Bit 7 : DC output Bit 9-10 : Regulation mode Bit 11 : Remote control Bit 14 : External sense Bit 15 : Alarms Bit 16 : OVP Bit 17 : OCP Bit 18 : OPP Bit 19 : OT Bit 21 : Power fail Bit 30 : REM-SB	0x00 = frei; 0x01 = lokal; 0x02 = fern; 0x03 = USB; 0x04 = analog; 0x06 = Ethernet 0 = off; 1 = on 00 = CV; 01 = CR; 10 = CC; 11 = CP 0 = off; 1 = on 0 = off; 1 = on 0 = none; 1 = active