# Assignment # 2

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section: 6H

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### Single level perceptron

Processed 5000/5400

Classification  $\mathsf{star}\overline{\mathsf{ting}\ldots}$ 

	ргсстэтог	i iccacc	. Accuracy	CTILC (3)
happy	0.44	0.67	0.53	102
sad	0.43	0.63	0.46	110.5
angry	0.93	0.42	0.86	197
laughing	g 0.90	0.39	0.45	87
confuse	d 0.87	0.27	0.50	132
average	Time 120	(sec)		

#### Multi-level perceptron

Processed 5000/5400

Classification starting....

		PICCISIO	i icca	ce Accurac	y crinc(3)
ľ	парру	0.63	0.93	0.83	200
9	sad	0.54	0.87	0.89	201.5
ć	angry	0.87	0.67	0.71	245
1	laughing	0.88	0.46	0.69	197
(	confused	0.89	0.64	0.93	150
ā	average	Time 202	(sec)		

#### Procedure

- 1 Data was put in one drive and its link was used to access the data
- 2 correct data was filtered e.g only images which were  $100 \times 100$
- 3 mean and standard deviation was calculated of each category
- Data was transformed by ToTensor() and normalized around mean/std
- once the model was trained with above given accuracy, an image was given to classify it.

- 6 10 epochs are done to train on the dataset. 7 we tested each category separately as data given above.
- 8 below is given some important part of the code

## Implementation

```
import torch
import torch.nn as nn
import torch.nn.functional as F
import torch.optim as optim
import torch.utils.data as data
import torchvision.transforms as transforms
import torchvision.datasets as datasets
import matplotlib.pyplot as plt
import numpy as np
import copy
import random
import time
To ensure we get reproducible results we set the random seed for Python, Numpy
and PyTorch.
SEED = 5
random.seed(SEED)
np.random.seed(SEED)
torch.manual seed(SEED)
torch.cuda.manual seed(SEED)
torch.backends.cudnn.deterministic = True
ROOT = '.data'
train data = datasets.MNIST(root=ROOT,
train=True,
download=True)
since values range from 0-255 (value of a pixcel
mean = train_data.data.float().mean() / 255
std = train data.data.float().std() / 255
train transforms = transforms.Compose([
transforms.RandomRotation(5, fill=(0,)),
transforms.RandomCrop(28, padding=2),
```

```
transforms.ToTensor(),
transforms.Normalize(mean=[mean], std=[std])
1)
test transforms = transforms.Compose([
transforms.ToTensor(),
transforms.Normalize(mean=[mean], std=[std])
])
train_data, valid_data = data.random_split(train_data,
[n_train_examples, n_valid_examples])
print(f'Number of training examples: {len(train data)}')
print(f'Number of validation examples: {len(valid data)}')
print(f'Number of testing examples: {len(test data)}')
BATCH SIZE = 64
train iterator = data.DataLoader(train data,
shuffle=True,
batch size=BATCH SIZE)
valid iterator = data.DataLoader(valid data,
batch_size=BATCH_SIZE)
test iterator = data.DataLoader(test data,
batch_size=BATCH_SIZE)
def calculate_accuracy(y_pred, y):
top pred = y pred.argmax(1, keepdim=True)
correct = top pred.eq(y.view as(top pred)).sum()
acc = correct.float() / y.shape[0]
return acc
def train(model, iterator, optimizer, criterion, device):
epoch loss = 0
epoch_acc = 0
model.train()
for (x, y) in tqdm(iterator, desc="Training", leave=False):
x = x.to(device)
y = y.to(device)
```

```
optimizer.zero_grad()
y_pred, _ = model(x)
loss = criterion(y_pred, y)
acc = calculate_accuracy(y_pred, y)
loss.backward()
optimizer.step()
epoch_loss += loss.item()
epoch_acc += acc.item()
return epoch_loss / len(iterator), epoch_acc / len(iterator)
def evaluate(model, iterator, criterion, device):
epoch loss = 0
epoch_acc = 0
model.eval()
with torch.no_grad():
for (x, y) in tqdm(iterator, desc="Evaluating", leave=False):
x = x.to(device)
y = y.to(device)
y_pred, _ = model(x)
loss = criterion(y_pred, y)
acc = calculate_accuracy(y_pred, y)
epoch_loss += loss.item()
epoch_acc += acc.item()
return epoch_loss / len(iterator), epoch_acc / len(iterator)
EPOCHS = 10
best_valid_loss = float('inf')
```

```
for epoch in trange(EPOCHS):
    start_time = time.monotonic()
        time = final_time -start_time

    train_loss, train_acc = train(model, train_iterator, optimizer, criterion, device)
    valid_loss, valid_acc = evaluate(model, valid_iterator, criterion, device)

if valid_loss < best_valid_loss:
    best_valid_loss = valid_loss
    torch.save(model.state_dict(), 'tut1-model.pt')

end_time = time.monotonic()

epoch_mins, epoch_secs = epoch_time(start_time, end_time)

print(f'happy: {epoch+1:02} \t {recall } \t {accuracy } \t {time(s)}')</pre>
```