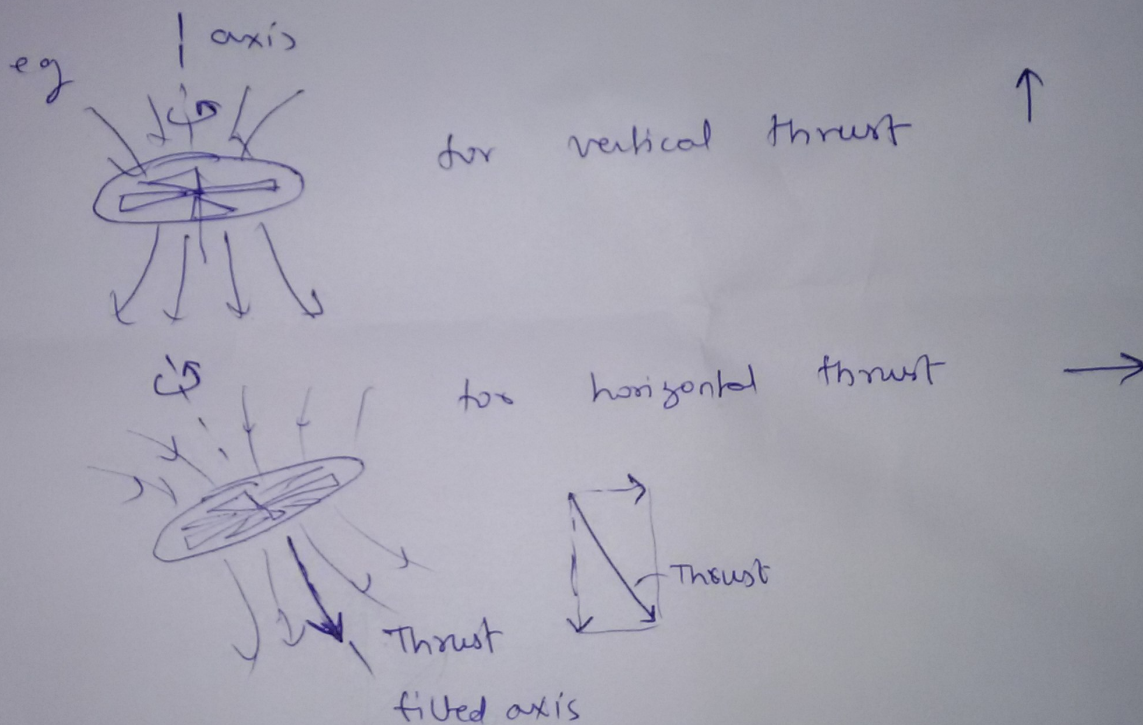


- * In our designs axis of rotor will adjustable.
- * ~~It~~ i.e we will control it by remote control
- * Initially axis will be vertical. \Rightarrow from which we will get vertical thrust.

\therefore According to the direction in which we have to fly our machine we will tilt axis accordingly.



- * Our hoverbike will carry payload like camera for ~~test~~ field monitoring & surveillances

