Machine LearningMSE FTP MachLe

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V11 Dimensionality Reduction (TSM_MachLE)

Comparison of different methods

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- MSE TSM_MachLe

based on a Jupyter notebook by Aurelien Géron

Setup

First, let's make sure this notebook works well in both python 2 and 3, import a few common modules, ensure MatplotLib plots figures inline and prepare a function to save the figures:

```
In [1]: # To support both python 2 and python 3
    from __future__ import division, print_function, unicode_literals

# Common imports
    import numpy as np
    import os

# to make this notebook's output stable across runs
    np.random.seed(42)

# To plot pretty figures
%matplotlib inline
    import matplotlib
    import matplotlib.pyplot as plt
    plt.rcParams['axes.labelsize'] = 14
    plt.rcParams['xtick.labelsize'] = 12
    plt.rcParams['ytick.labelsize'] = 12
```

Generate a 3D dataset:

```
X[:, 1] = np.sin(angles) * 0.7 + noise * np.random.randn(m) / 2
X[:, 2] = X[:, 0] * w1 + X[:, 1] * w2 + noise * np.random.randn(m)
```

PCA using Scikit-Learn

With Scikit-Learn, PCA is really trivial. It even takes care of mean centering for you:

```
In [3]: from sklearn.decomposition import PCA
          pca = PCA(n\_components = 2)
          X2D = pca.fit_transform(X)
         X2D[:5]
 In [4]:
          array([[ 1.26203346, 0.42067648],
 Out[4]:
                 [-0.08001485, -0.35272239],
                 [ 1.17545763, 0.36085729],
                 [0.89305601, -0.30862856],
                 [ 0.73016287, -0.25404049]])
          X3D_inv = pca.inverse_transform(X2D)
 In [5]:
          Of course, there was some loss of information during the projection step, so the recovered
          3D points are not exactly equal to the original 3D points:
          np.allclose(X3D_inv, X)
 In [6]:
          False
 Out[6]:
          We can compute the reconstruction error:
          np.mean(np.sum(np.square(X3D_inv - X), axis=1))
 In [7]:
          0.010170337792848549
 Out[7]:
          The PCA object gives access to the principal components that it computed:
          pca.components
 In [8]:
          array([[-0.93636116, -0.29854881, -0.18465208],
 Out[8]:
                 [ 0.34027485, -0.90119108, -0.2684542 ]])
          Now let's look at the explained variance ratio:
 In [9]:
          pca.explained_variance_ratio_
          array([0.84248607, 0.14631839])
 Out[9]:
          The first dimension explains 84.2% of the variance, while the second explains 14.6%.
          By projecting down to 2D, we lost about 1.1% of the variance:
          1 - pca.explained_variance_ratio_.sum()
In [10]:
          0.011195535570688975
Out[10]:
```

Next, let's generate some nice figures! :)

Utility class to draw 3D arrows (copied from http://stackoverflow.com/questions/11140163)

```
In [11]: from matplotlib.patches import FancyArrowPatch
    from mpl_toolkits.mplot3d import proj3d

class Arrow3D(FancyArrowPatch):
    def __init__(self, xs, ys, zs, *args, **kwargs):
        super().__init__((0,0), (0,0), *args, **kwargs)
        self._verts3d = xs, ys, zs

def do_3d_projection(self, renderer=None):
        xs3d, ys3d, zs3d = self._verts3d
        xs, ys, zs = proj3d.proj_transform(xs3d, ys3d, zs3d, self.axes.M)
        self.set_positions((xs[0],ys[0]),(xs[1],ys[1]))

        return np.min(zs)
```

Express the plane as a function of x and y.

```
In [12]: axes = [-1.8, 1.8, -1.3, 1.3, -1.0, 1.0]

x1s = np.linspace(axes[0], axes[1], 10)
x2s = np.linspace(axes[2], axes[3], 10)
x1, x2 = np.meshgrid(x1s, x2s)

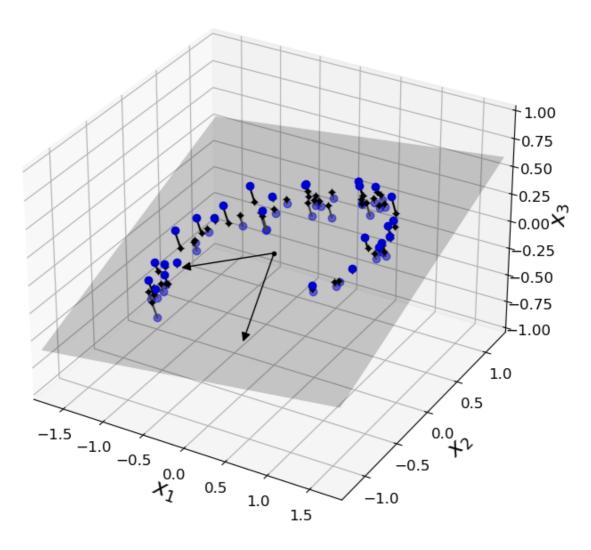
C = pca.components_
R = C.T.dot(C)
z = (R[0, 2] * x1 + R[1, 2] * x2) / (1 - R[2, 2])
```

Plot the 3D dataset, the plane and the projections on that plane.

```
In [13]: from mpl_toolkits.mplot3d import Axes3D
                            fig = plt.figure(figsize=(8, 8))
                            ax = fig.add_subplot(111, projection='3d')
                            X3D_above = X[X[:, 2] > X3D_inv[:, 2]]
                            X3D\_below = X[X[:, 2] \leftarrow X3D\_inv[:, 2]]
                            ax.plot(X3D_below[:, 0], X3D_below[:, 1], X3D_below[:, 2], "bo", alpha=0.5)
                            ax.plot surface(x1, x2, z, alpha=0.2, color="k")
                            np.linalg.norm(C, axis=0)
                            ax.add_artist(Arrow3D([0, C[0, 0]], [0, C[0, 1]], [0, C[0, 2]], mutation_scale=15, leading to the context of 
                            ax.add_artist(Arrow3D([0, C[1, 0]],[0, C[1, 1]],[0, C[1, 2]], mutation_scale=15, li
                            ax.plot([0], [0], [0], "k.")
                            for i in range(m):
                                        if X[i, 2] > X3D_inv[i, 2]:
                                                   ax.plot([X[i][0], X3D_inv[i][0]], [X[i][1], X3D_inv[i][1]], [X[i][2], X3D_inv[i][1]]
                                                   ax.plot([X[i][0], X3D_inv[i][0]], [X[i][1], X3D_inv[i][1]], [X[i][2], X3D_inv[i][1]]
                            ax.plot(X3D_inv[:, 0], X3D_inv[:, 1], X3D_inv[:, 2], "k+")
                            ax.plot(X3D_inv[:, 0], X3D_inv[:, 1], X3D_inv[:, 2], "k.")
                            ax.plot(X3D_above[:, 0], X3D_above[:, 1], X3D_above[:, 2], "bo")
                            ax.set_xlabel("$x_1$", fontsize=18)
                            ax.set_ylabel("$x_2$", fontsize=18)
                            ax.set zlabel("$x 3$", fontsize=18)
```

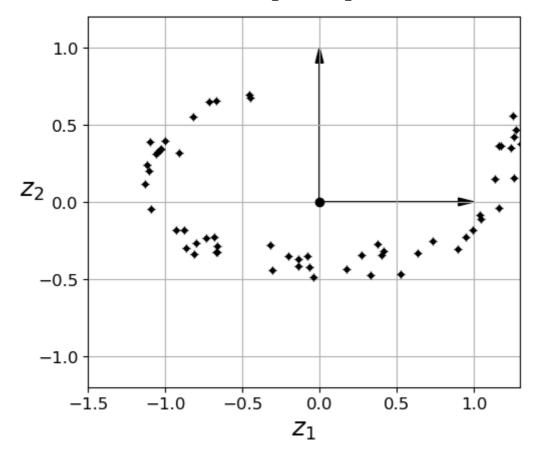
```
ax.set_xlim(axes[0:2])
ax.set_ylim(axes[2:4])
ax.set_zlim(axes[4:6])
plt.show()
plt.savefig('PCA-demo.pdf')
```

C:\Users\christoph.wuersch\AppData\Local\Temp\ipykernel_20592\3871663956.py:21: Us erWarning: color is redundantly defined by the 'color' keyword argument and the fm t string "k-" (-> color='k'). The keyword argument will take precedence. ax.plot([X[i][0], X3D_inv[i][0]], [X[i][1], X3D_inv[i][1]], [X[i][2], X3D_inv[i] [2]], "k-", color="#505050")



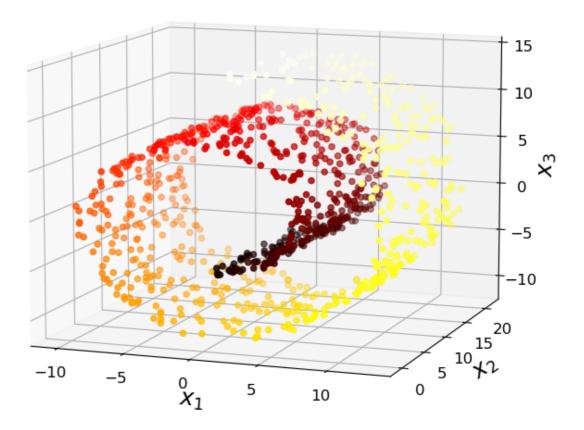
<Figure size 640x480 with 0 Axes>

```
In [14]: fig = plt.figure()
         ax = fig.add_subplot(111, aspect='equal')
         ax.plot(X2D[:, 0], X2D[:, 1], "k+")
         ax.plot(X2D[:, 0], X2D[:, 1], "k.")
         ax.plot([0], [0], "ko")
         ax.arrow(0, 0, 0, 1, head_width=0.05, length_includes_head=True, head_length=0.1,
         ax.arrow(0, 0, 1, 0, head width=0.05, length includes head=True, head length=0.1,
         ax.set_xlabel("$z_1$", fontsize=18)
         ax.set_ylabel("$z_2$", fontsize=18, rotation=0)
         ax.axis([-1.5, 1.3, -1.2, 1.2])
         ax.grid(True)
         plt.savefig('PCA-demo_2D.pdf')
```



Manifold learning

Swiss roll:

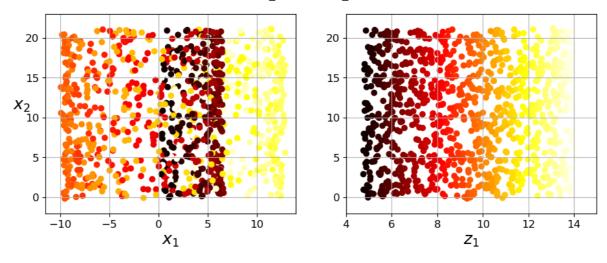


```
In [17]: plt.figure(figsize=(11, 4))

plt.subplot(121)
plt.scatter(X[:, 0], X[:, 1], c=t, cmap=plt.cm.hot)
plt.axis(axes[:4])
plt.xlabel("$x_1$", fontsize=18)
plt.ylabel("$x_2$", fontsize=18, rotation=0)
plt.grid(True)

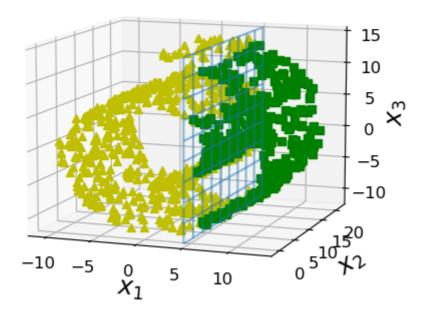
plt.subplot(122)
plt.scatter(t, X[:, 1], c=t, cmap=plt.cm.hot)
plt.axis([4, 15, axes[2], axes[3]])
plt.xlabel("$z_1$", fontsize=18)
plt.grid(True)

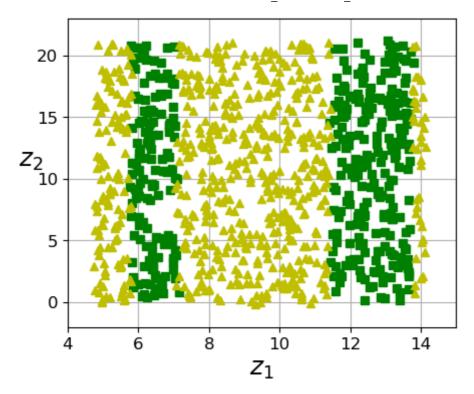
plt.savefig('squished_swiss_roll_plot.pdf')
plt.show()
```

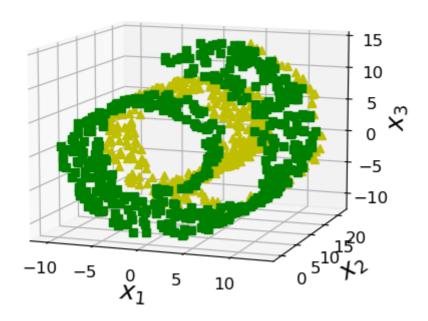


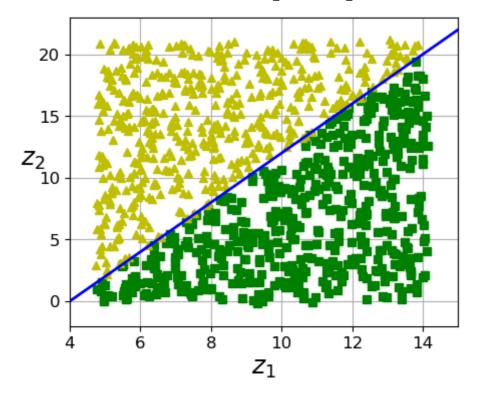
```
In [18]: from matplotlib import gridspec
         axes = [-11.5, 14, -2, 23, -12, 15]
         x2s = np.linspace(axes[2], axes[3], 10)
         x3s = np.linspace(axes[4], axes[5], 10)
         x2, x3 = np.meshgrid(x2s, x3s)
         fig = plt.figure(figsize=(6, 5))
         ax = plt.subplot(111, projection='3d')
         positive_class = X[:, 0] > 5
         X_pos = X[positive_class]
         X_neg = X[~positive_class]
         ax.view_init(10, -70)
         ax.plot(X_neg[:, 0], X_neg[:, 1], X_neg[:, 2], "y^")
         ax.plot_wireframe(5, x2, x3, alpha=0.5)
         ax.plot(X_pos[:, 0], X_pos[:, 1], X_pos[:, 2], "gs")
         ax.set_xlabel("$x_1$", fontsize=18)
         ax.set_ylabel("$x_2$", fontsize=18)
         ax.set_zlabel("$x_3$", fontsize=18)
         ax.set xlim(axes[0:2])
         ax.set_ylim(axes[2:4])
         ax.set_zlim(axes[4:6])
         plt.savefig('manifold_decision_boundary_1.pdf')
         plt.show()
         fig = plt.figure(figsize=(5, 4))
         ax = plt.subplot(111)
         plt.plot(t[positive_class], X[positive_class, 1], "gs")
         plt.plot(t[~positive_class], X[~positive_class, 1], "y^")
         plt.axis([4, 15, axes[2], axes[3]])
         plt.xlabel("$z_1$", fontsize=18)
         plt.ylabel("$z_2$", fontsize=18, rotation=0)
         plt.grid(True)
         plt.savefig('manifold decision boundary 2.pdf')
         plt.show()
         fig = plt.figure(figsize=(6, 5))
         ax = plt.subplot(111, projection='3d')
         positive class = 2 * (t[:] - 4) > X[:, 1]
         X_pos = X[positive_class]
         X_neg = X[~positive_class]
```

```
ax.view_init(10, -70)
ax.plot(X_neg[:, 0], X_neg[:, 1], X_neg[:, 2], "y^")
ax.plot(X_pos[:, 0], X_pos[:, 1], X_pos[:, 2], "gs")
ax.set_xlabel("$x_1$", fontsize=18)
ax.set_ylabel("$x_2$", fontsize=18)
ax.set_zlabel("$x_3$", fontsize=18)
ax.set_xlim(axes[0:2])
ax.set_ylim(axes[2:4])
ax.set_zlim(axes[4:6])
plt.savefig('manifold_decision_boundary_3.pdf')
plt.show()
fig = plt.figure(figsize=(5, 4))
ax = plt.subplot(111)
plt.plot(t[positive_class], X[positive_class, 1], "gs")
plt.plot(t[~positive_class], X[~positive_class, 1], "y^")
plt.plot([4, 15], [0, 22], "b-", linewidth=2)
plt.axis([4, 15, axes[2], axes[3]])
plt.xlabel("$z_1$", fontsize=18)
plt.ylabel("$z_2$", fontsize=18, rotation=0)
plt.grid(True)
plt.savefig('manifold_decision_boundary_4.pdf')
plt.show()
```





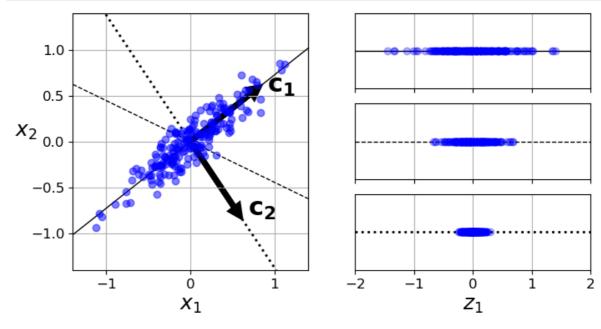




PCA

```
In [19]:
         angle = np.pi / 5
         stretch = 5
         m = 200
         np.random.seed(3)
         X = np.random.randn(m, 2) / 10
         X = X.dot(np.array([[stretch, 0],[0, 1]])) # stretch
         X = X.dot([[np.cos(angle), np.sin(angle)], [-np.sin(angle), np.cos(angle)]]) # rote
         u1 = np.array([np.cos(angle), np.sin(angle)])
         u2 = np.array([np.cos(angle - 2 * np.pi/6), np.sin(angle - 2 * np.pi/6)])
         u3 = np.array([np.cos(angle - np.pi/2), np.sin(angle - np.pi/2)])
         X_{proj1} = X.dot(u1.reshape(-1, 1))
         X_{proj2} = X.dot(u2.reshape(-1, 1))
         X_{proj3} = X.dot(u3.reshape(-1, 1))
         plt.figure(figsize=(8,4))
         plt.subplot2grid((3,2), (0, 0), rowspan=3)
         plt.plot([-1.4, 1.4], [-1.4*u1[1]/u1[0], 1.4*u1[1]/u1[0]], "k-", linewidth=1)
         plt.plot([-1.4, 1.4], [-1.4*u2[1]/u2[0], 1.4*u2[1]/u2[0]], "k--", linewidth=1)
         plt.plot([-1.4, 1.4], [-1.4*u3[1]/u3[0], 1.4*u3[1]/u3[0]], "k:", linewidth=2)
         plt.plot(X[:, 0], X[:, 1], "bo", alpha=0.5)
         plt.axis([-1.4, 1.4, -1.4, 1.4])
         plt.arrow(0, 0, u1[0], u1[1], head_width=0.1, linewidth=5, length_includes_head=Tr
         plt.arrow(0, 0, u3[0], u3[1], head_width=0.1, linewidth=5, length_includes_head=Tr
         plt.text(u1[0] + 0.1, u1[1] - 0.05, r"$\mathbb{c_1}$", fontsize=22)
         plt.text(u3[0] + 0.1, u3[1], r"\mbox{mathbf}{c_2}", fontsize=22)
         plt.xlabel("$x_1$", fontsize=18)
         plt.ylabel("$x_2$", fontsize=18, rotation=0)
         plt.grid(True)
         plt.subplot2grid((3,2), (0, 1))
         plt.plot([-2, 2], [0, 0], "k-", linewidth=1)
         plt.plot(X_proj1[:, 0], np.zeros(m), "bo", alpha=0.3)
```

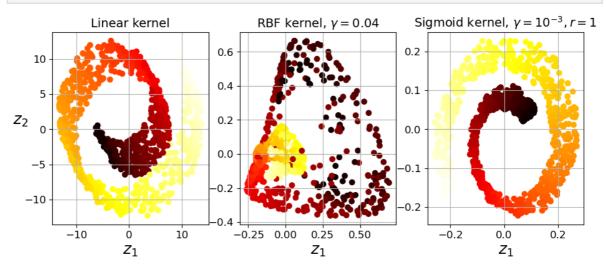
```
plt.gca().get_yaxis().set_ticks([])
plt.gca().get_xaxis().set_ticklabels([])
plt.axis([-2, 2, -1, 1])
plt.grid(True)
plt.subplot2grid((3,2), (1, 1))
plt.plot([-2, 2], [0, 0], "k--", linewidth=1)
plt.plot(X_proj2[:, 0], np.zeros(m), "bo", alpha=0.3)
plt.gca().get_yaxis().set_ticks([])
plt.gca().get_xaxis().set_ticklabels([])
plt.axis([-2, 2, -1, 1])
plt.grid(True)
plt.subplot2grid((3,2), (2, 1))
plt.plot([-2, 2], [0, 0], "k:", linewidth=2)
plt.plot(X_proj3[:, 0], np.zeros(m), "bo", alpha=0.3)
plt.gca().get_yaxis().set_ticks([])
plt.axis([-2, 2, -1, 1])
plt.xlabel("$z_1$", fontsize=18)
plt.grid(True)
plt.savefig('pca_best_projection.pdf')
plt.show()
```



Kernel PCA

```
In [20]: X, t = make swiss roll(n samples=1000, noise=0.2, random state=42)
In [21]: from sklearn.decomposition import KernelPCA
         rbf_pca = KernelPCA(n_components = 2, kernel="rbf", gamma=0.04)
         X_reduced = rbf_pca.fit_transform(X)
In [22]: from sklearn.decomposition import KernelPCA
         lin_pca = KernelPCA(n_components = 2, kernel="linear", fit_inverse_transform=True)
         rbf pca = KernelPCA(n components = 2, kernel="rbf", gamma=0.0433, fit inverse trans
         sig_pca = KernelPCA(n_components = 2, kernel="sigmoid", gamma=0.001, coef0=1, fit_
         y = t > 6.9
```

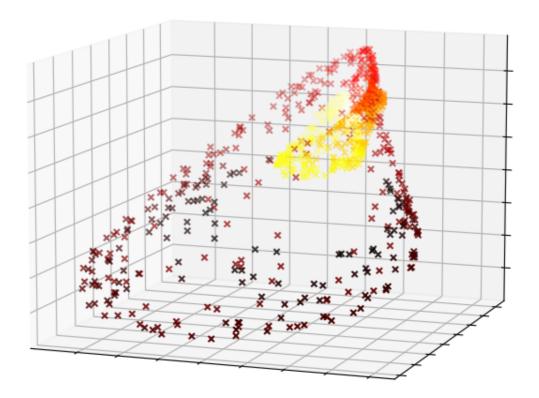
```
plt.figure(figsize=(11, 4))
for subplot, pca, title in ((131, lin_pca, "Linear kernel"), (132, rbf_pca, "RBF ke
    X_reduced = pca.fit_transform(X)
    if subplot == 132:
        X_reduced_rbf = X_reduced
    plt.subplot(subplot)
    #plt.plot(X_reduced[y, 0], X_reduced[y, 1], "gs")
    #plt.plot(X_reduced[~y, 0], X_reduced[~y, 1], "y^")
    plt.title(title, fontsize=14)
    plt.scatter(X_reduced[:, 0], X_reduced[:, 1], c=t, cmap=plt.cm.hot)
    plt.xlabel("$z_1$", fontsize=18)
    if subplot == 131:
        plt.ylabel("$z_2$", fontsize=18, rotation=0)
    plt.grid(True)
plt.savefig('kernel_pca_plot.pdf')
plt.show()
```



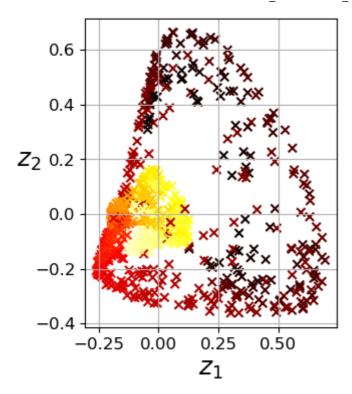
```
In [23]: plt.figure(figsize=(8,8))

X_inverse = pca.inverse_transform(X_reduced_rbf)

ax = plt.subplot(111, projection='3d')
ax.view_init(10, -70)
ax.scatter(X_inverse[:, 0], X_inverse[:, 1], X_inverse[:, 2], c=t, cmap=plt.cm.hot
ax.set_xlabel("")
ax.set_ylabel("")
ax.set_ylabel("")
ax.set_zlabel("")
ax.set_zlabels([])
ax.set_yticklabels([])
ax.set_yticklabels([])
plt.savefig('preimage_plot.pdf')
plt.show()
```



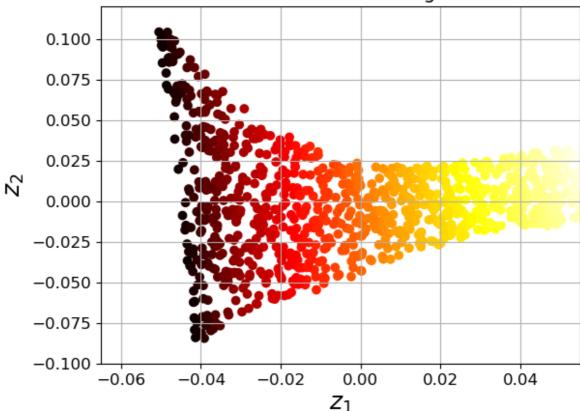
```
In [24]: X_reduced = rbf_pca.fit_transform(X)
         plt.figure(figsize=(11, 4))
         plt.subplot(132)
         plt.scatter(X_reduced[:, 0], X_reduced[:, 1], c=t, cmap=plt.cm.hot, marker="x")
         plt.xlabel("$z_1$", fontsize=18)
         plt.ylabel("$z_2$", fontsize=18, rotation=0)
         plt.grid(True)
```



```
In [25]:
         from sklearn.model_selection import GridSearchCV
         from sklearn.linear_model import LogisticRegression
         from sklearn.pipeline import Pipeline
         clf = Pipeline([
                  ("kpca", KernelPCA(n_components=2)),
                  ("log_reg", LogisticRegression(solver='lbfgs'))
             1)
         param_grid = [{
                  "kpca__gamma": np.linspace(0.03, 0.05, 10),
                  "kpca__kernel": ["rbf", "sigmoid"]
             }]
         grid_search = GridSearchCV(clf, param_grid, cv=3)
         grid_search.fit(X, y)
         GridSearchCV(cv=3,
Out[25]:
                      estimator=Pipeline(steps=[('kpca', KernelPCA(n_components=2)),
                                                 ('log_reg', LogisticRegression())]),
                      param_grid=[{'kpca__gamma': array([0.03])
                                                                    , 0.03222222, 0.0344444
         4, 0.03666667, 0.03888889,
                0.04111111, 0.04333333, 0.04555556, 0.04777778, 0.05
                                                                           ]),
                                    'kpca__kernel': ['rbf', 'sigmoid']}])
In [26]: print(grid_search.best_params_)
         {'kpca__gamma': 0.0433333333333335, 'kpca__kernel': 'rbf'}
In [27]: rbf_pca = KernelPCA(n_components = 2, kernel="rbf", gamma=0.0433,
                              fit inverse transform=True)
         X_reduced = rbf_pca.fit_transform(X)
         X_preimage = rbf_pca.inverse_transform(X_reduced)
In [28]: from sklearn.metrics import mean_squared_error
         mean_squared_error(X, X_preimage)
         32.78630879576608
Out[28]:
```

LLE





MDS, Isomap and t-SNE

```
In [32]: from sklearn.manifold import MDS
    mds = MDS(n_components=2, random_state=42)
    X_reduced_mds = mds.fit_transform(X)

In [33]: from sklearn.manifold import Isomap
```

```
isomap = Isomap(n_components=2)
X_reduced_isomap = isomap.fit_transform(X)
```

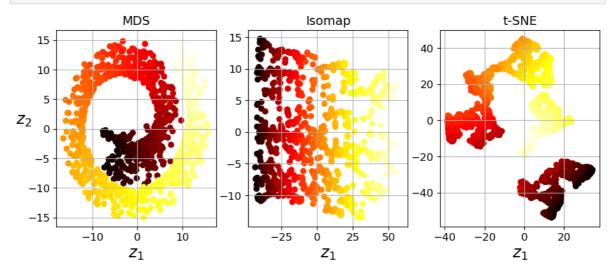
```
In [34]: from sklearn.manifold import TSNE
    tsne = TSNE(n_components=2, random_state=42)
    X_reduced_tsne = tsne.fit_transform(X)
```

C:\Users\christoph.wuersch\.conda\envs\ML\lib\site-packages\sklearn\manifold_t_sn e.py:780: FutureWarning: The default initialization in TSNE will change from 'rand om' to 'pca' in 1.2.

warnings.warn(

C:\Users\christoph.wuersch\.conda\envs\ML\lib\site-packages\sklearn\manifold_t_sn e.py:790: FutureWarning: The default learning rate in TSNE will change from 200.0 to 'auto' in 1.2.

warnings.warn(



```
In [ ]:
```