

## Level 2

The velocity controller from Exercise 3 was used as controller. Following the first part of the task the chosen values can be seen in the following table.

$A_m$	500
$A_{o1}$	1000
$A_{o2}$	2000

### 1

Figure 1 shows the step responses for two different values of  $A_o$ . A force of 5000 N is applied at the time 0.03 seconds.

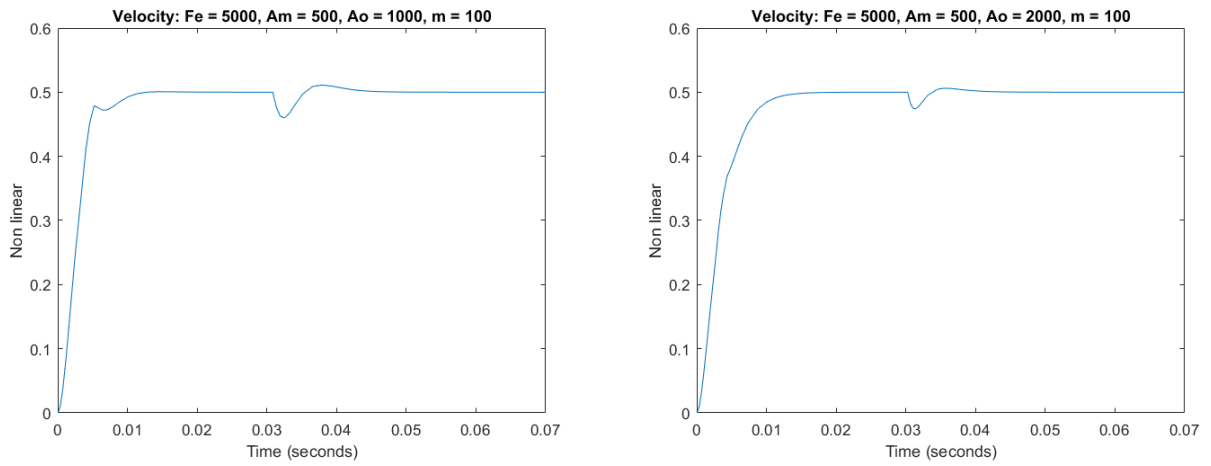


Figure 1: Comparison between the two different  $A_o$  values

### 2

Figure 2 shows the step responses for two different values of  $A_o$  and now with a mass of 200 kg instead of 100 kg. The system behaves more or less the same as with a mass of 100 kg.

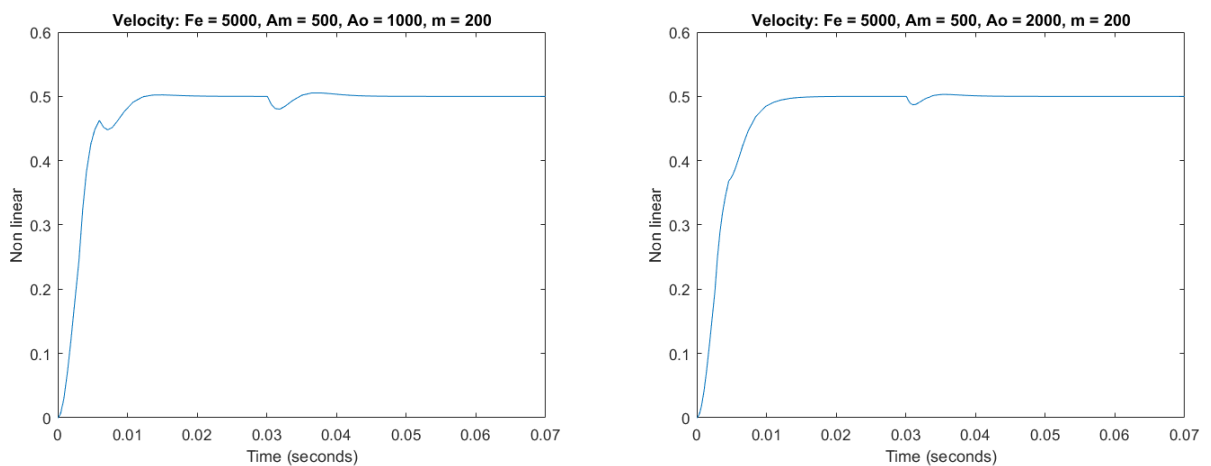


Figure 2: Comparison between the two different  $A_o$  values

### 3

Figure 3 shows the step responses for two different values of  $A_o$  with a sine wave as noise. The sine wave has a frequency of 1700 rad/s.

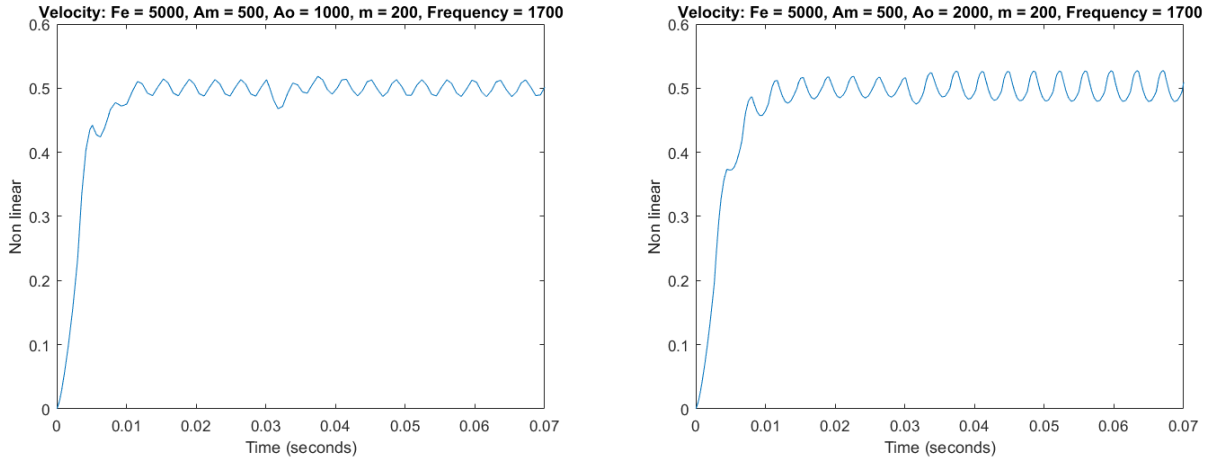


Figure 3: Comparison between the two different  $A_o$  values

Figure 4 shows the complementary sensitivity function for the two different  $A_o$  values. The magnitude when the frequency is 1700 rad/s is shown which shows that a lower  $A_o$  value dampens the noise more. It was hard to find a frequency where the noise dampening were very noticeable but the dampening can be seen in Figure 3 where the noise affects the system less when  $A_o=1000$  compared to  $A_o=2000$ .

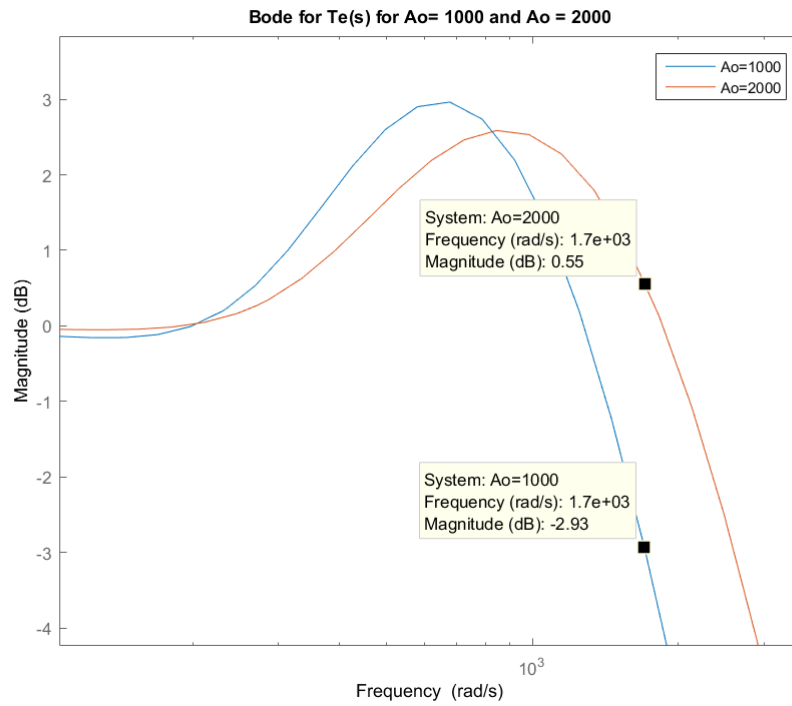


Figure 4: Comparison between the complementary sensitivity functions