

Министерство науки и высшего образования Российской Федерации

Федеральное государственное бюджетное образовательное учреждение высшего образования «МОСКОВСКИЙ ГОСУДАРСТВЕННЫЙ ТЕХНИЧЕСКИЙ УНИВЕРСИТЕТ имени Н.Э.БАУМАНА

(национальный исследовательский университет)»

Факультет: Информатика и системы управления

Кафедра: Теоретическая информатика и компьютерные технологии

Лабораторная работа №2

«Методы оптимизации нейронных сетей»

По дисциплине «Теория искусственных нейронных сетей»

Работу выполнил

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```
import json
import random
import math
import pickle
from copy import deepcopy
import time
import numpy as np
import matplotlib.pyplot as plt
FILE NAME = 'model.json'
class Sample:
    def init (self, input, expected):
        self.input = input
        self.expected = expected
    def show(self):
        plt.imshow(self.input.reshape(28, 28), cmap='gray')
        plt.show()
def combine samples(samples):
    inpt = np.array([x.input for x in samples]).transpose()
    expect = np.array([x.expected for x in samples]).transpose()
    return Sample(inpt, expect)
def get samples(train):
    samples = []
    x train, t train, x test, t test = mnist load()
    if train:
        data = zip(x train, t train)
    else:
        data = zip(x test, t test)
    for x, y in data:
        one hot = np.array([int(i == y) for i in range(10)])
        samples.append(Sample(np.vectorize(lambda x : x / 255)(x),
one hot))
    return samples
def mnist load():
    with open("../datasets/mnist/mnist.pkl", "rb") as f:
        mnist = pickle.load(f)
    return (
        mnist["training images"],
        mnist["training labels"],
```

```
mnist["test images"],
        mnist["test labels"],
    )
def show random wrong sample(score):
    wrong = []
    for pred in score.predictions:
        if pred.sample.expected.argmax() != pred.prediction.argmax():
            wrong.append(pred)
    w = wrong[random.randint(0, len(wrong))]
    print('Expected: ', w.sample.expected.argmax())
    print('Got: ', w.prediction.argmax())
    w.sample.show()
class Prediction:
    def __init__(self, sample, prediction):
        self.sample = sample
        self.prediction = prediction
class ScoreResult:
    def init (self, accuracy, loss, predictions):
        self.accuracy = accuracy
        self.loss = loss
        self.predictions = predictions
    def str (self):
        return f"accuracy: {self.accuracy * 100}%, loss: {self.loss}"
class RunResult:
    def init (self, activations, weighted inputs):
        self.activations = activations
        self.weighted inputs = weighted inputs
train data = get samples(True)
test data = get samples(False)
class SGD():
    def __init__(self, lr=0.01):
        \overline{self.lr} = lr
    def init params(self, model):
        self.model = model
    def step(self, grad w, grad b, batch):
        for i in range(1, len(self.model.layers)):
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self.model.weights[i] -= self.lr * grad_w[i]
            self.model.biases[i] -= self.lr * grad b[i]
class Momentum():
    def __init__(self, lr=0.01, momentum=0.6):
        self.m = momentum
        self.lr = lr
    def init params(self, model):
        self.model = model
        self.velocity_w = [None]
        self.velocity b = [None]
        for i in range(1, len(self.model.layers)):
self.velocity w.append(np.zeros like(self.model.weights[i]))
self.velocity_b.append(np.zeros_like(self.model.biases[i]))
    def step(self, grad_w, grad_b, batch):
        for i in range(1, len(self.model.layers)):
            self.velocity w[i] = self.m * self.velocity w[i] + self.lr
* grad w[i]
            self.velocity_b[i] = self.m * self.velocity_b[i] + self.lr
* grad b[i]
            self.model.weights[i] -= self.velocity_w[i]
            self.model.biases[i] -= self.velocity b[i]
class Nesterov():
    def __init__(self, lr=0.01, momentum=0.6):
        \overline{\text{self.m}} = \text{momentum}
        self.lr = lr
    def init params(self, model):
        self.model = model
        self.velocity w = [None]
        self.velocity b = [None]
        for i in range(1, len(self.model.layers)):
self.velocity w.append(np.zeros like(self.model.weights[i]))
self.velocity_b.append(np.zeros_like(self.model.biases[i]))
    def step(self, grad w, grad b, batch):
        model ahead = deepcopy(self.model)
        for i in range(1, len(model ahead.layers)):
            model_ahead.weights[i] -= self.m * self.velocity_w[i]
            model ahead.biases[i] -= self.m * self.velocity b[i]
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result = model ahead.run(batch)
        errors = model ahead.backprop(batch, result)
        grad ahead w, grad ahead b =
model ahead.calculate grad(result.activations, errors)
        for i in range(1, len(model ahead.layers)):
            self.velocity_w[i] = self.m * self.velocity_w[i] + self.lr
* grad ahead w[i]
            self.velocity_b[i] = self.m * self.velocity_b[i] + self.lr
* grad ahead b[i]
            self.model.weights[i] -= self.velocity w[i]
            self.model.biases[i] -= self.velocity b[i]
class AdaGrad():
    def init (self, lr=1):
        self.lr = lr
        self.eps = 1e-10
    def init params(self, model):
        self.model = model
        self.N w = [None]
        self.N b = [None]
        for i in range(1, len(self.model.layers)):
            self.N w.append(np.zeros like(self.model.weights[i]))
            self.N b.append(np.zeros like(self.model.biases[i]))
    def step(self, grad w, grad b, batch):
        for i in range(\overline{1}, len(self.model.layers)):
            self.N w[i] += grad w[i] ** 2
            self.N b[i] += grad b[i] ** 2
            self.model.weights[i] -= self.lr * grad w[i] /
(np.sqrt(self.N_w[i]) + self.eps)
            self.model.biases[i] -= self.lr * grad_b[i] /
(np.sqrt(self.N b[i]) + self.eps)
class RMSprop():
    def __init__(self, lr=0.01, decay=0.9):
        self.lr = lr
        self.decay = decay
        self.eps = 1e-10
    def init params(self, model):
        self.model = model
        self.N w = [None]
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self.N b = [None]
        for i in range(1, len(self.model.layers)):
            self.N_w.append(np.zeros_like(self.model.weights[i]))
            self.N b.append(np.zeros like(self.model.biases[i]))
    def step(self, grad_w, grad_b, batch):
        for i in range(\overline{1}, len(\overline{\text{self}}.model.layers)):
            self.N w[i] = self.decay * self.N w[i] + (1-self.decay) *
grad w[i] ** 2
            self.N b[i] = self.decay * self.N b[i] + (1-self.decay) *
grad b[i] ** 2
            self.model.weights[i] -= self.lr * grad w[i] /
(np.sqrt(self.N w[i]) + self.eps)
            self.model.biases[i] -= self.lr * grad_b[i] /
(np.sqrt(self.N b[i]) + self.eps)
class AdaDelta():
    def __init__(self, lr=0.01, decay=0.9):
        self.lr = lr
        self.decay = decay
        self.eps = 1e-10
    def init params(self, model):
        self.model = model
        self.N w = [None]
        self.N b = [None]
        self.P w = [None]
        self.P_b = [None]
        for i in range(1, len(self.model.layers)):
            self.N w.append(np.zeros like(self.model.weights[i]))
            self.N b.append(np.zeros like(self.model.biases[i]))
            self.P w.append(np.zeros like(self.model.weights[i]))
            self.P b.append(np.zeros like(self.model.biases[i]))
    def step(self, grad_w, grad_b, batch):
        for i in range(1, len(self.model.layers)):
            self.N w[i] = self.decay * self.N w[i] + (1-
self.decay)*grad w[i] ** 2
            self.N b[i] = self.decay * self.N b[i] + (1-
self.decay)*grad b[i] ** 2
            d w = grad w[i] * np.sqrt(self.P w[i] + self.eps) /
np.sqrt(self.N w[i] + self.eps)
            d_b = grad_b[i] * np.sqrt(self.P_b[i] + self.eps) /
np.sqrt(self.N b[i] + self.eps)
```

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self.P_w[i] = self.decay * self.P_w[i] + (1 - self.decay)
* d w ** 2
            self.P b[i] = self.decay * self.P b[i] + (1 - self.decay)
* d b ** 2
            self.model.weights[i] -= self.lr * d w
            self.model.biases[i] -= self.lr * d b
class Adam():
    def init (self, lr=0.01, beta1=0.9, beta2=0.999):
        self.lr = lr
        self.beta1 = beta1
        self.beta2 = beta2
        self.eps = 1e-10
    def init_params(self, model):
        self.model = model
        self.M w = [None]
        self.M b = [None]
        self.N w = [None]
        self.Nb = [None]
        for i in range(1, len(self.model.layers)):
            self.M w.append(np.zeros like(self.model.weights[i]))
            self.M b.append(np.zeros like(self.model.biases[i]))
            self.N_w.append(np.zeros_like(self.model.weights[i]))
            self.N b.append(np.zeros like(self.model.biases[i]))
    def step(self, grad w, grad b, batch):
        t = self.model.current epoch + 1
        for i in range(1, len(self.model.layers)):
            self.M w[i] = self.beta1 * self.M w[i] + (1 - self.beta1)
* grad w[i]
            self.M b[i] = self.beta1 * self.M b[i] + (1 - self.beta1)
* grad b[i]
            self.N_w[i] = self.beta2 * self.N_w[i] + (1 - self.beta2)
* grad_w[i] ** 2
            self.N b[i] = self.beta2 * self.N b[i] + (1 - self.beta2)
* grad b[i] ** 2
            m w hat = self.M w[i] / (1 - self.beta1 ** t)
            m b hat = self.M b[i] / (1 - self.beta1 ** t)
            n w hat = self.N w[i] / (1 - self.beta2 ** t)
            n b hat = self.N b[i] / (1 - self.beta2 ** t)
            self.model.weights[i] -= self.lr * m w hat /
```

```
(np.sqrt(n_w hat) + self.eps)
            self.model.biases[i] -= self.lr * m b hat /
(np.sqrt(n b hat) + self.eps)
class Network:
    def __init__(self, layers, optimizer, batch size):
        \overline{\text{self.current epoch}} = 0
        self.layers = layers
        self.weights = [None]
        self.biases = [None]
        self.batch size = batch size
        for i in range(1, len(layers)):
            self.weights.append(np.random.uniform(-1, -1, (layers[i],
layers[i - 1])) * np.sqrt(1/layers[i - 1]))
            self.biases.append(np.random.uniform(-1, 1, layers[i]))
        self.optimizer = optimizer
        optimizer.init params(self)
    def dump(self, path):
        d = {
            "layers": self.layers,
            "weights": [x.tolist() for x in self.weights[1:]],
            "biases": [x.tolist() for x in self.biases[1:]],
        with open(path, 'w') as f:
            json.dump(d, f)
    def load(self, path):
        with open(path, 'r') as f:
            d = json.load(f)
        self.layers = d["layers"]
        self.weights = [None] + [np.array(x) for x in d["weights"]]
        self.biases = [None] + [np.array(x) for x in d["biases"]]
    def train(self, samples, epochs, monitor dataset=None):
        samples_copy = samples[:]
        res = []
        for epoch in range(epochs):
            self.current epoch += 1
            random.shuffle(samples copy)
            for i in range(0, len(samples_copy), self.batch_size):
                batch =
combine samples(samples copy[i:i+self.batch size])
                result = self.run(batch)
                errors = self.backprop(batch, result)
                grad w, grad b =
self.calculate grad(result.activations, errors)
                self.optimizer.step(grad w, grad b, batch)
            if monitor dataset is not None:
                score = self.score(monitor dataset)
```

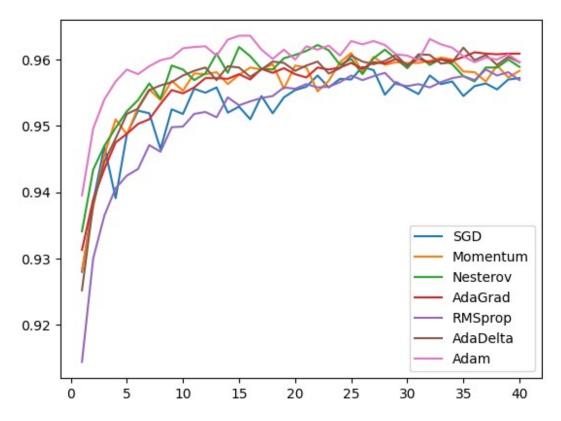
```
res.append(score)
        return res
    def run(self, sample):
        activations = [None for _ in self.layers]
        activations[0] = sample.\overline{i}nput
        weighted inputs = [None for in self.layers]
        for i in range(1, len(self.layers)):
            weighted inputs[i] = self.weights[i] @ activations[i - 1]
+ self.biases[i].reshape(self.layers[i], 1)
            activations[i] = self.calc activation(weighted inputs[i])
        return RunResult(activations, weighted inputs)
    def backprop(self, sample, result):
        errors = [None for in self.layers]
        errors[-1] = self.calc delta(sample.expected,
result.activations[-1])
        for i in reversed(range(1, len(self.layers) - 1)):
            errors[i] = (
                (np.transpose(self.weights[i + 1]) @ errors[i + 1])
self.calc activation derivative(result.weighted inputs[i])
        return errors
    def calculate grad(self, activations, errors):
        grad w = [None]
        grad b = [None]
        for i in range(1, len(self.layers)):
            grad w.append(errors[i] @ activations[i - 1].transpose() /
self.batch size)
            grad b.append(errors[i].sum(axis=1) / self.batch size)
        return grad w, grad b
    def score(self, samples):
        cost = 0
        accurate = 0
        predictions = []
        for sample in samples:
            res = self.run(combine samples([sample]))
            out = res.activations[-1][:, 0]
            pred = Prediction(sample, out)
            predictions.append(pred)
            cost += self.calc_cost(sample.expected, out)
            if out.argmax() == sample.expected.argmax():
                accurate += 1
        return ScoreResult(accurate / len(samples), cost /
len(samples), predictions)
    def calc cost(self, expected, out):
```

```
return np.sum(np.nan to num(-expected*np.log(out)) - (1 -
expected) * np.log(1 - out))
    def calc delta(self, expected, activations):
        return (activations - expected)
    def calc activation(self, x):
        return 1 / (1 + np.exp(-x))
    def calc activation derivative(self, x):
        return self.calc activation(x) * (1 - self.calc activation(x))
optimizers = [
    SGD(1),
    Momentum(0.1, 0.8),
    Nesterov(0.1, 0.8),
    AdaGrad(0.1),
    RMSprop(0.001, 0.9),
    AdaDelta(100),
    Adam(0.01, 0.9, 0.999),
1
EPOCHS = 40
scores = []
labels = ["SGD", "Momentum", "Nesterov", "AdaGrad", "RMSprop",
"AdaDelta", "Adam"]
for i, optimizer in enumerate(optimizers):
    start time = time.time()
    network = Network(layers=[784, 30, 10], optimizer=optimizer,
batch size=10)
    score = network.train(train data, EPOCHS,
monitor dataset=test data)
    print(f"{labels[i]}: {score[-1]}")
    print(f"{time.time() - start time}")
    scores.append(score)
SGD: accuracy: 95.72%, loss: 0.33273904947070304
42.52070593833923
Momentum: accuracy: 95.83%, loss: 0.32346239906508806
47.275773763656616
Nesterov: accuracy: 95.89%, loss: 0.32140317102912935
77.97539782524109
AdaGrad: accuracy: 96.09%, loss: 0.2666548896643032
49.052425146102905
RMSprop: accuracy: 95.69%, loss: 0.4622452222234267
55.96908211708069
AdaDelta: accuracy: 95.9600000000001%, loss: 0.4471318212923637
69.02415299415588
```

```
Adam: accuracy: 95.9600000000001%, loss: 0.34356949469522235 68.53807091712952
```

```
xs = list(range(1, EPOCHS + 1))
for i in range(len(optimizers)):
    ys = [x.accuracy for x in scores[i]]
    plt.plot(xs, ys)
plt.legend(labels)
```

<matplotlib.legend.Legend at 0x2eaec2880>



```
xs = list(range(1, EPOCHS + 1))
for i in range(len(optimizers)):
    ys = [x.loss for x in scores[i]]
    plt.plot(xs, ys)
plt.legend(labels)
```

<matplotlib.legend.Legend at 0x2b5c24be0>

