Last time

Value Iteration Converge asymtotically

Discrete state and Actions

LQR

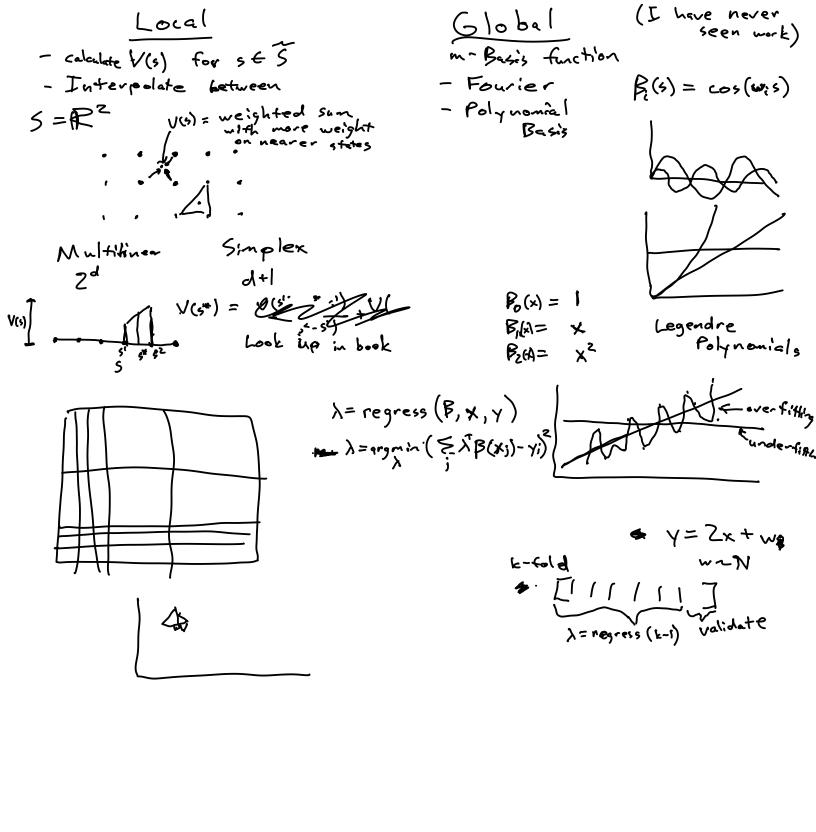
S=Pⁿ A=P^m

S+11 ~ N(As++Ba+, E) 5++1 ~ N (As+ + Ba+, E) $R(s,a) = s^TOs + a^T Ra$ $V^* \rightarrow \pi^*$ Easy $\pi^*(s) = angmax R(s,a) + \gamma E[V(s')]$ TX -> V* Easy MDP -> V* Hard MDP -> 7 Hand What if S is continuous L'Discretize Curse of Dimensionality

Function Approximation (5) = Ld

Approximate Dynamic Programming

Value Function Approx 100 $V(s) = \sum_{i} \lambda_{i} \beta_{i}(s) = \lambda^{T} \beta(s)$ Local



Global/Local Approximation Value Iteration 1=0 Irandom bop until convergence for in 1 ton Si=sample from S $V_i = \max_{a} \left(R(s_i a) + \gamma E \tilde{V}(s') \right)$ regress $\left(\beta, s_{i:n}, V_{i:n} \right)$ $\sum_{i} T_{i:n}$ $\lambda = regress (\beta, s_{i:n}, v_{i:n})$ $\sum_{s'} T(s' | s, a) \tilde{V}(s')$ The Shape (G(si,a,we))

Monte (arlo Things to Worry about - Gibb's Phenomenon & Fix this > <</p> for si in grid points

vi = maxR(si,a) + y E [x B(si)] Q(s,a) = A B(s,a) ★ TC(5) = arguex Q(5,5) **λ= ν**: - Features have to approximate V well at every ; taration

Direct Policy Search $\pi(s) = f_{\Theta}(s)$ e.g. $\pi(s) = Ks$

Derivative - free optimization

Genetic Alg Simulated Annecling (ross-Entropy

evaluate for