Simple Games

• Games: a mathematical formalism for rational interaction

Simple Games

- Games: a mathematical formalism for rational interaction
- What is the best solution concept? (Nash Equilibrium)

Alleatory

Alleatory



Markov Decision Process

Alleatory



Markov Decision Process

Epistemic (Static)

Alleatory

Epistemic (Static)



Markov Decision Process



Reinforcement Learning

Alleatory

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Markov Decision Process

Epistemic (Static)



Reinforcement Learning

Epistemic (Dynamic)



POMDP

Alleatory

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Markov Decision Process

Epistemic (Static)



Reinforcement Learning

Epistemic (Dynamic)



POMDP

Interaction

Alleatory

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Markov Decision Process

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POMDP

Interaction



Game

 Alice and Bob are working on a homework assignment.

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- They can either share or withhold their knowledge.

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Alice's Payoffs

_
_
_
_

	S	W
S	4	2
W	3	1

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Alice's Payoffs

В

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Bob's Payoffs

В

	S	W
S	4	3
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W	3	1

Bob's Payoffs

В

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S	4	3
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Bob

Alice

	S	W
S	4, 4	2, 3
W	3, 2	1, 1

Α

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Alice's Payoffs

Bob's Payoffs

В

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Alice

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Called a **Normal Form**, **Simple**, or **Bimatrix** Game

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Bob's Payoffs

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Bob

W

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Alice

Called a Normal Form, Simple, or Bimatrix Game

Question for today: What **solution concept** should we use for games?

Bob

Alice

	S	W
S	3, 3	2, 2
W	2, 2	1, 1

Bob

	S	W
S	3, 3	2, 2
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Alice

Definitions

- Action $a^i \in A^i$
- Joint Action $a=(a^1,\ldots,a^k)$
- All Other Actions $a^{-i}=(a^1,\ldots,a^{i-1},a^{i+1},\ldots,a^k)$
- Reward $R^i(a)$
- Joint Reward $R(a) = (R^1(a), \dots, R^k(a))$

Bob

S W 3, 3 2, 2 2, 2 1, 1 W

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Deterministic Best Response:

Action a^i is a deterministic best response

to
$$a^{-i}$$
 if $R^i(a^i,a^{-i}) \geq R^i({a^i}',a^{-i}) \quad orall {a^i}'$

Bob

Alice

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Is the dominant strategy equilibrium always the best outcome for the players?

• 2 criminals are captured

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- Each can either keep silent or testify
 - other keeps silent -> minor conviction (1 year)
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Player 1

Player 2

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Т	0, -4	-3, -3

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S	-1, -1	-4, 0
-	0 1	2 2

Player 2

Dominant strategy for both players is to testify

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Player 1

P	layer	2
	•	

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- Dominant strategy for both players is to testify
- Dominant strategy equilibrium is a very bad social result (for the criminals)

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Player 1

Player	2
--------	---

	S	T
S	-1, -1	-4, 0
T	0, -4	-3, -3

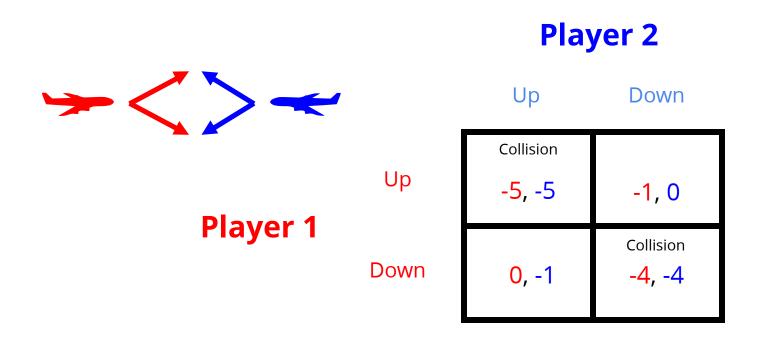
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Do all games have a dominant strategy equilibrium?

Collision Avoidance Game

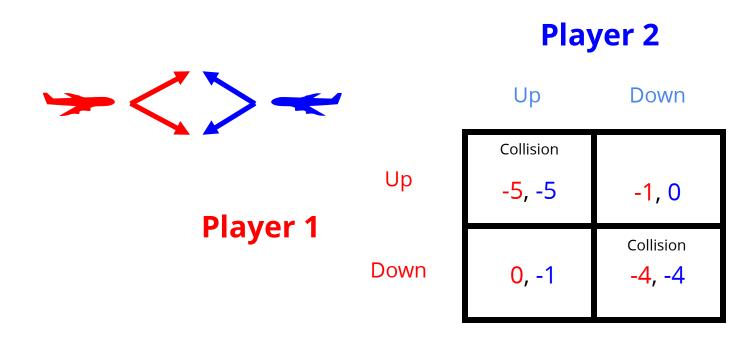
Collision Avoidance Game

Example: Airborne Collision Avoidance



Collision Avoidance Game

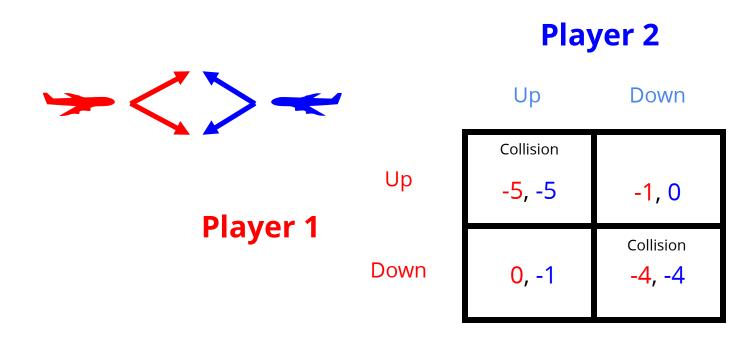
Example: Airborne Collision Avoidance



Pure Nash Equilibrium: All players play a deterministic best response.

Collision Avoidance Game

Example: Airborne Collision Avoidance



Pure Nash Equilibrium: All players play a deterministic best response.

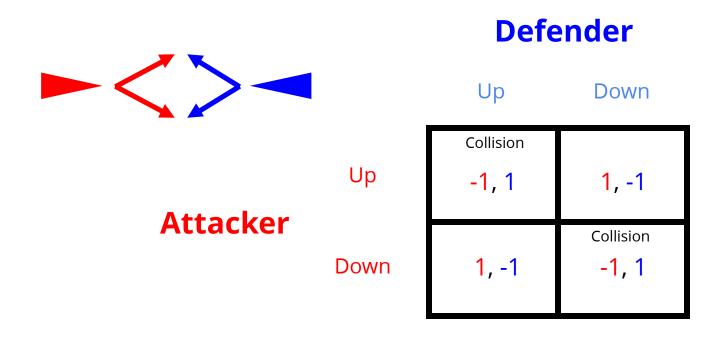
Which equilibrium is better?

Do all simple games have a pure Nash equilibrium?

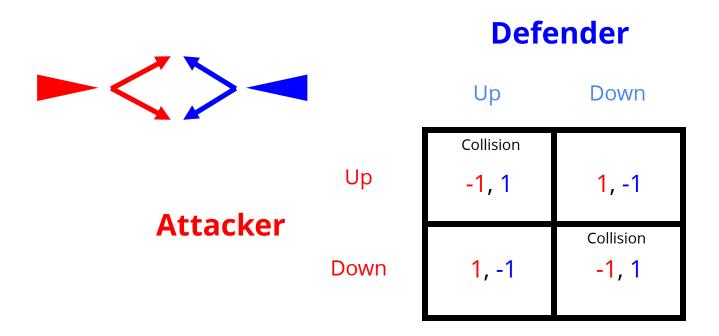
Practice: Find Pure Nash Equilibria

	Player 2			
		a	b	c
Playor 1	a	4,4	2,5	0,0
Player 1	b	5,2	3,3	0,0
•	С	0,0	0,0	10,10

Missile Defense (simplified)

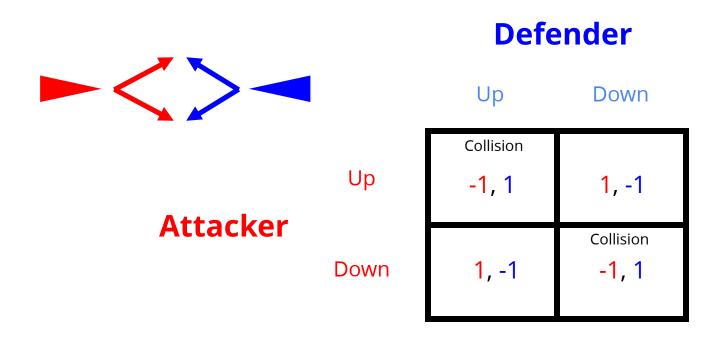


Missile Defense (simplified)



No Pure Nash Equilibrium!

Missile Defense (simplified)



No Pure Nash Equilibrium!

Need a broader solution concept: Mixed Nash equilibrium.

Single Player

Single Player

Joint

Action

 $a^i \in A^i$

 $a \in A$

Single Player

$$a^i \in A^i$$

$$a \in A$$

$$\pi^i(a^i)$$

$$\pi(a) = \prod_i \pi^i(a^i)$$

Single Player

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$$R^i(a)$$

Single Player

$$a^i \in A^i$$

$$a \in A$$

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$$\pi(a) = \prod_i \pi^i(a^i)$$

$$R^i(a)$$

$$U^i(\pi) = \sum_a R^i(a)\pi(a)$$
 $U(\pi) = \sum_a R(a)\pi(a)$

$$U(\pi) = \sum_{a} R(a)\pi(a)$$

Single Player

Joint

$$a^i \in A^i$$

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Two Player Zero Sum:

$$R^1(a) + R^2(a) = 0 \quad \forall a$$

Single Player

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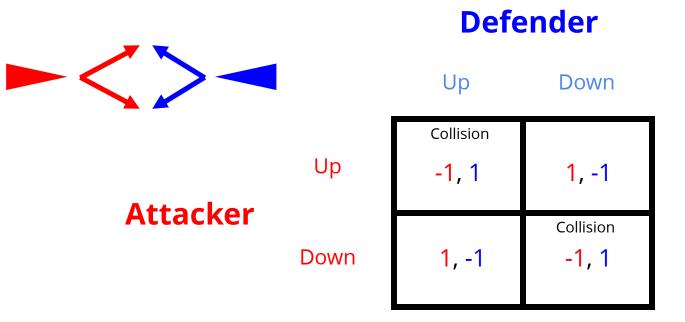
$$R^1(a) + R^2(a) = 0 \quad orall a$$

Best Response: Given a joint policy of all other agents, π^{-i} , a best response is a policy π^i that satisfies

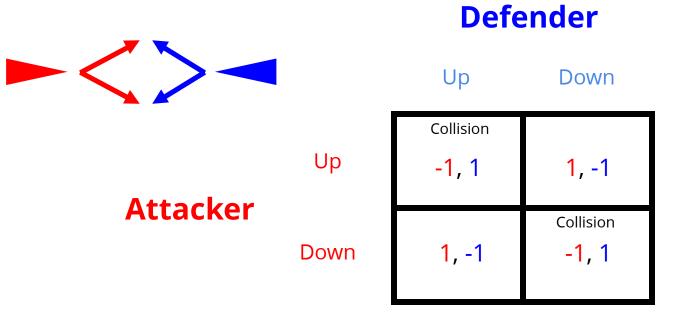
$$U^{i}\left(\pi^{i},\pi^{-i}
ight)\geq U^{i}\left({\pi^{i}}',\pi^{-i}
ight)$$

for all other $\pi^{i'}$.

Missile Defense (simplified)



Missile Defense (simplified)



 A Nash equilibrium is a joint policy in which all agents are following a best response

Rock-paper scissors

- 1. Guess the Nash Equilibrium argument
- 2. Make a qualitative argument that this is an NE based on best responses

	agent 2		
	rock	paper	scissors
rock	0,0	-1,1	1,-1
agent 1 paper	1, -1	0,0	-1,1
scissors	-1,1	1, -1	0,0

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EQUILIBRIUM POINTS IN N-PERSON GAMES

By John F. Nash, Jr.*

PRINCETON UNIVERSITY

Communicated by S. Lefschetz, November 16, 1949

One may define a concept of an *n*-person game in which each player has a finite set of pure strategies and in which a definite set of payments to the *n* players corresponds to each *n*-tuple of pure strategies, one strategy being taken for each player. For mixed strategies, which are probability distributions over the pure strategies, the pay-off functions are the expectations of the players, thus becoming polylinear forms in the probabilities with which the various players play their various pure strategies.

Any n-tuple of strategies, one for each player, may be regarded as a point in the product space obtained by multiplying the n strategy spaces of the players. One such n-tuple counters another if the strategy of each player in the countering n-tuple yields the highest obtainable expectation for its player against the n-1 strategies of the other players in the countered n-tuple. A self-countering n-tuple is called an equilibrium point.

The correspondence of each n-tuple with its set of countering n-tuples gives a one-to-many mapping of the product space into itself. From the definition of countering we see that the set of countering points of a point is convex. By using the continuity of the pay-off functions we see that the graph of the mapping is closed. The closedness is equivalent to saying: if P_1, P_2, \ldots and $Q_1, Q_2, \ldots, Q_n, \ldots$ are sequences of points in the product space where $Q_n \to Q$, $P_n \to P$ and Q_n counters P_n then Q counters P.

Since the graph is closed and since the image of each point under the mapping is convex, we infer from Kakutani's theorem¹ that the mapping has a fixed point (i.e., point contained in its image). Hence there is an equilibrium point.

In the two-person zero-sum case the "main theorem" and the existence of an equilibrium point are equivalent. In this case any two equilibrium points lead to the same expectations for the players, but this need not occur in general.

^{*} The author is indebted to Dr. David Gale for suggesting the use of Kakutani's theorem to simplify the proof and to the A. E. C. for financial support.

¹ Kakutani, S., Duke Math. J., 8, 457-459 (1941).

² Von Neumann, J., and Morgenstern, O., The Theory of Games and Economic Behaviour, Chap. 3, Princeton University Press, Princeton, 1947.

Kakutani's fixed-point theorem

- (1) X is a non-empty, closed, bounded, and convex set.
- (2) $f(\mathbf{x})$ is non-empty for any \mathbf{x} .
- (3) f(x) is convex for any x.
- (4) The set $\{(\mathbf{x}, \mathbf{y}) \mid \mathbf{y} \in f(\mathbf{x})\}$ is closed.

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- The BR operator and policy space for finite games meet the conditions above

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- The BR operator and policy space for finite games meet the conditions above
- ullet BR has a fixed point for every finite game, i.e. every finite game has a Nash Equilibrium

General approach to find Nash Equilibria

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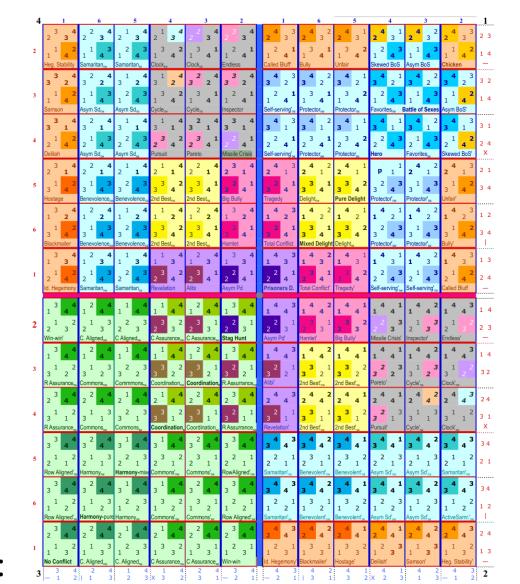
$$\begin{aligned} & \underset{\boldsymbol{\pi}, U}{\text{minimize}} & & \sum_{i} \left(U^{i} - U^{i}(\boldsymbol{\pi}) \right) \\ & \text{subject to} & & U^{i} \geq U^{i}(a^{i}, \boldsymbol{\pi}^{-i}) \text{ for all } i, a^{i} \\ & & \sum_{a^{i}} \pi^{i}(a^{i}) = 1 \text{ for all } i \\ & & & \pi^{i}(a^{i}) \geq 0 \text{ for all } i, a^{i} \end{aligned}$$

General approach to find Nash Equilibria

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$$\sum_{i} \left(U^{i} - U^{i}(\boldsymbol{\pi}) \right)$$
 subject to
$$U^{i} \geq U^{i}(a^{i}, \boldsymbol{\pi}^{-i}) \text{ for all } i, a^{i}$$

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$$\pi^{i}(a^{i}) \geq 0 \text{ for all } i, a^{i}$$



Algorithms that use best response

Iterated Best Response: randomly cycle between agents who play the best response for the current policy (converges to Nash for certain narrow classes of games)

Fictitious Play:

1. Estimate maximum likelihood policies for opponents:

$$\pi^j(a^j) \propto N(j,a^j)$$

2. Play best response to estimated policy

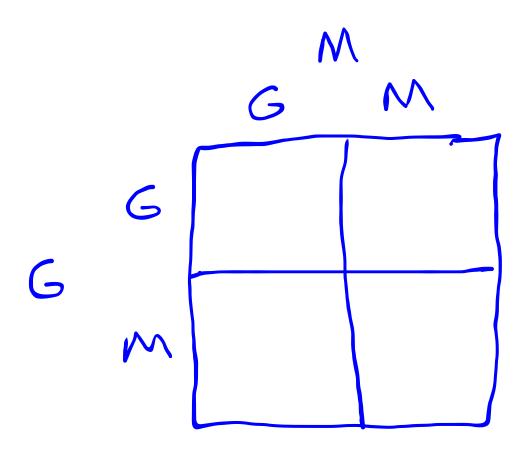
(converges to Nash for wider class of games, notably zero-sum)

• Gabby and Max are going on a date

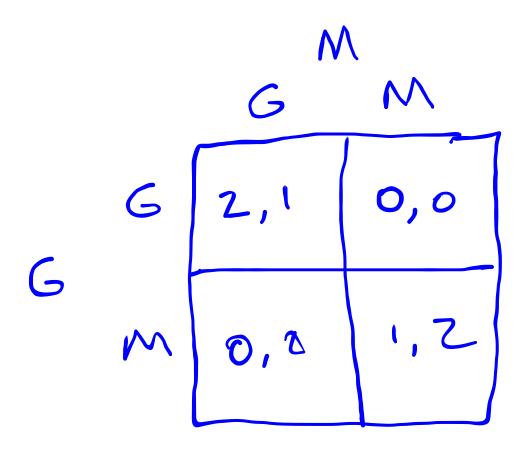
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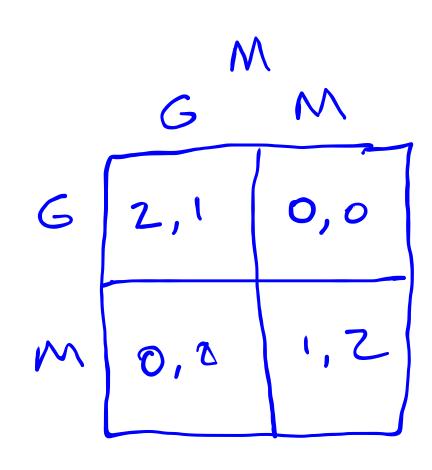
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Correlated Equilibrium

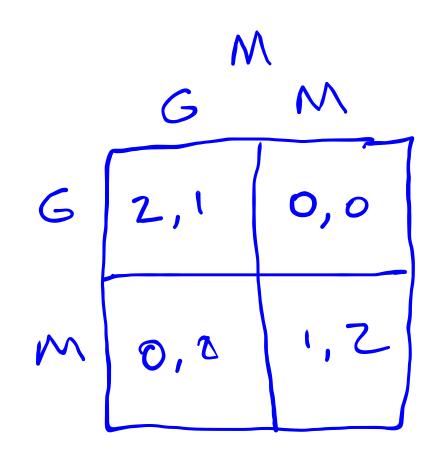
- A *correlated joint policy* is a single distribution over the joint actions of all agents.
- A *correlated equilibrium* is a correlated joint policy where no agent *i* can increase their expected utility by deviating from their current action to another.



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 Easier to find than Nash equilibrium (Linear Program)_{5.7}

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- Games may not have a single "optimal" solution; instead there are equilibria
- If every player is playing a best response, that joint policy is a Nash Equilibrium
- Every finite game has at least one Nash Equilibrium (pure or mixed)