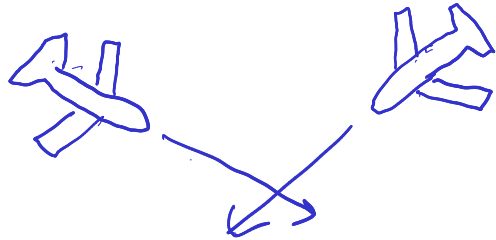


ASEN 5264

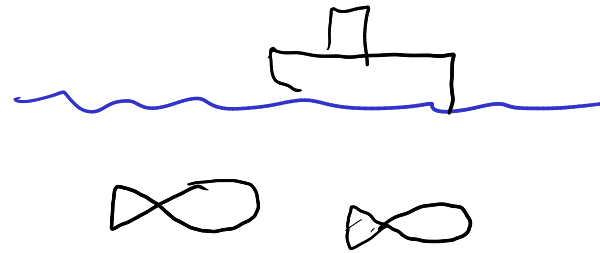
Decision Making under Uncertainty

3 Example Problems

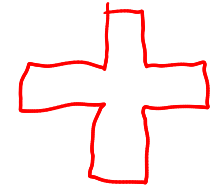
A/C Collision Avoidance



Fishery Management



Health Screening



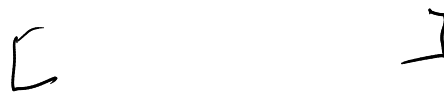
FAA: Collision Avoidance

Quantify Uncertainty in States

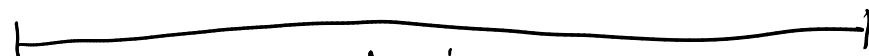
$$[x_1, y_1, h_1, v_x, v_y]$$



$$\begin{matrix} \text{---} \Delta h \text{---} \\ \text{---} \Delta h \text{---} \end{matrix}$$

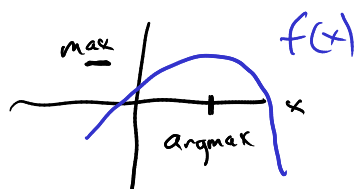


~~$\pi(a|s)$~~



$d \quad d$ MDP

$\pi: S \rightarrow A$
 ~~$\pi(s) = \operatorname{argmax}_{a \in A} R(s, a)$~~



1) States:

2) Actions

3) Dynamics

4) Reward

Set of variables describe the environment at the current time $[d, d, \Delta h, \Delta h]$

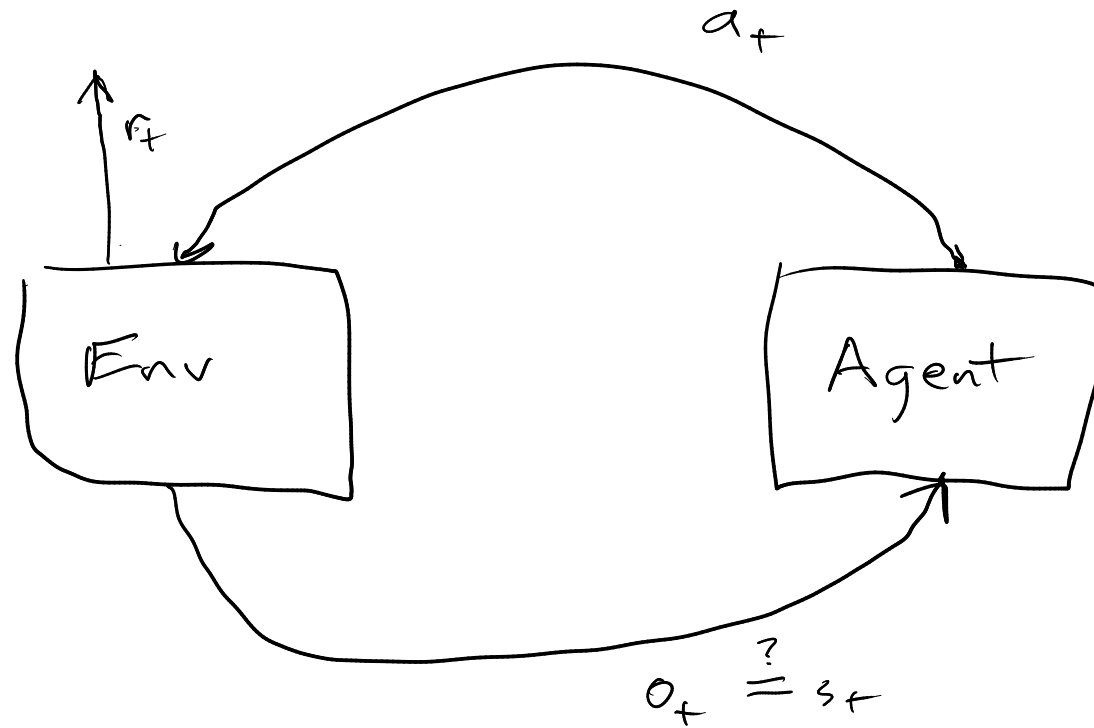
$\{\text{up, down}\}^2$

how state changes over time given an action

Designation of which states/actions are "good"

$$R(s, a) = -1 \mathbb{I}(a = \text{up}) - 1000 \mathbb{I}(d < 1000)$$

Sense-Plan-Act Loop



Four Big Challenges in DMU

1. Immediate + Future Rewards
2. Unknown Models
3. Imperfect Observations
4. Other Agents

MDP
Reinforcement Learning
POMDP
Game Theory

Reinforcement Learning from ML perspective

Four Types of Uncertainty in DMU

1. Outcome
2. Model
3. State
4. Interaction

Probabilistic

Allegoric

Epistemic Static

Epistemic Dynamic

Coinflip

Loaded Die

Blackjack

Rock-Paper-Scissors

Break

Break

- Engineering is a team sport!

Break

- Engineering is a team sport!
- Groups of 2-4:
 - Name
 - Department
 - Sequential decision making problem

Course Materials/Logistics

Course Materials/Logistics

- Ed

Course Materials/Logistics

- Ed
- Syllabus

Course Materials/Logistics

- Ed
- Syllabus
- Book

Course Materials/Logistics

- Ed
- Syllabus
- Book
- Homework

Course Materials/Logistics

Julia
1

Python
All

MATLAB
All

C++
1/2

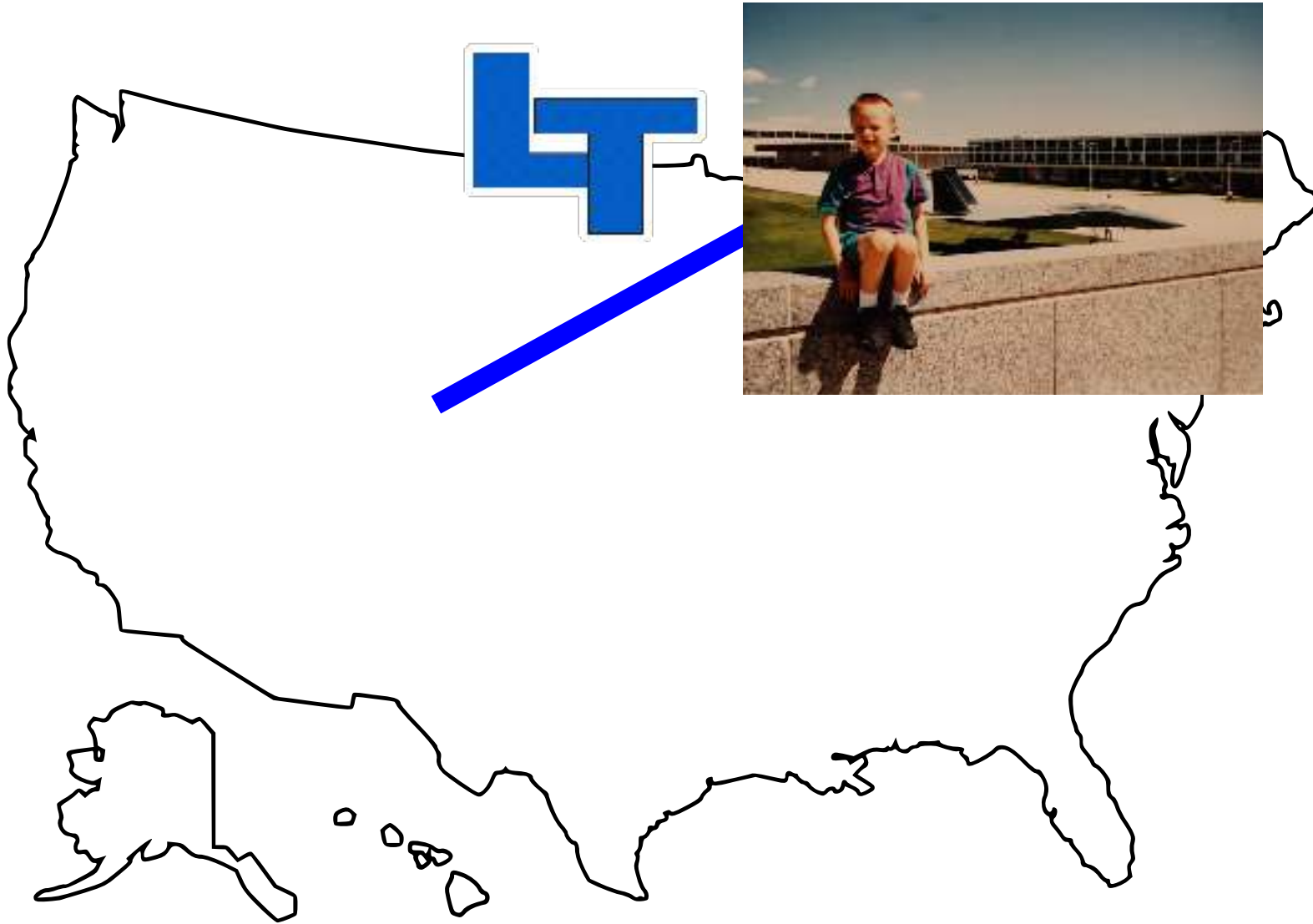
- Ed
- Syllabus
- Book
- Homework
- Julia

A bit about me

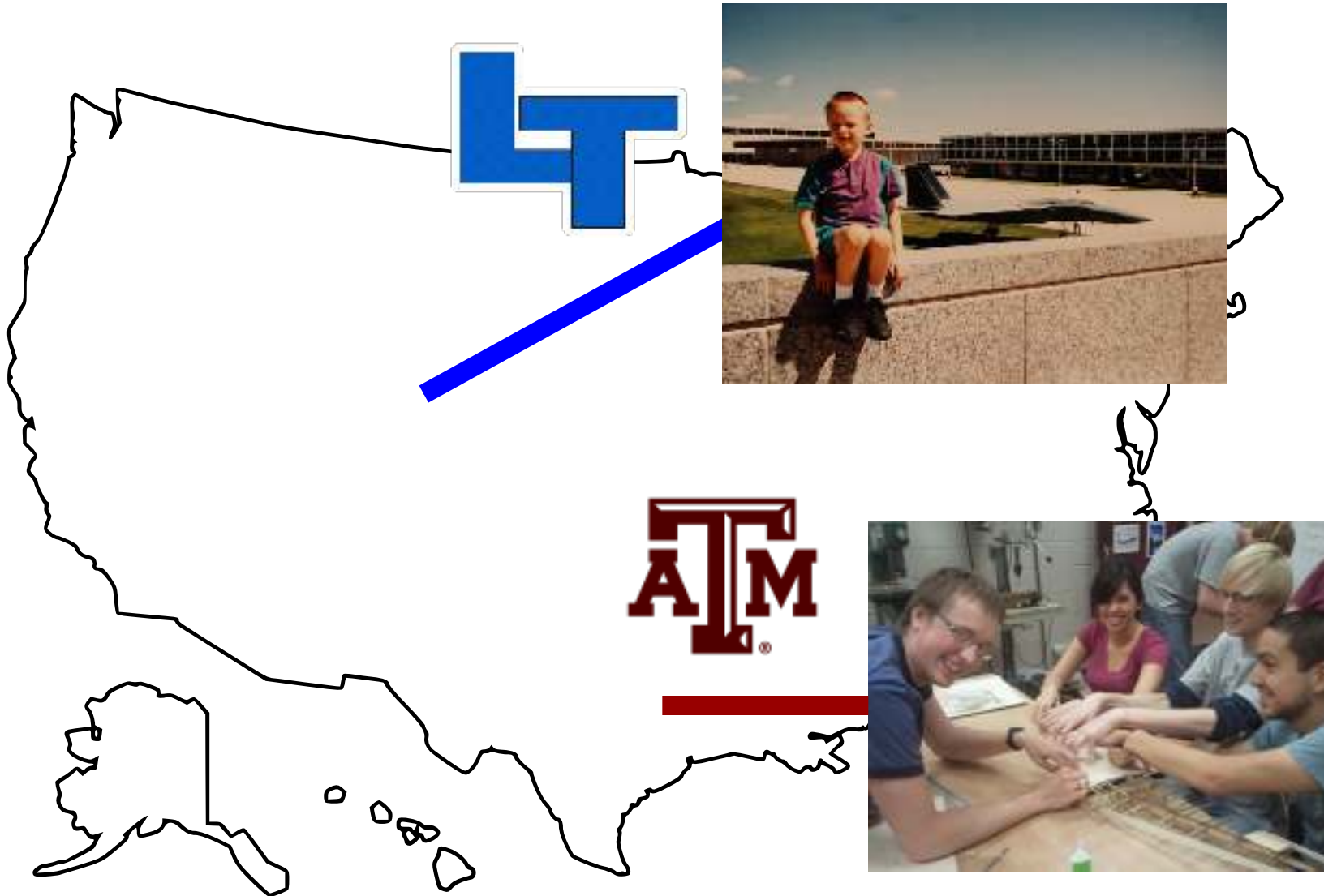
A bit about me



A bit about me



A bit about me



A bit about me



A bit about me



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A bit about me



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