

# Bayesian Network Learning

- Last time:
- Today:

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  - Conditional independence in Bayesian Networks
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  - Conditional independence in Bayesian Networks
  - Sampling from Bayesian Networks
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  - Given a **Bayesian Network** and some **values**, how do we calculate the probability of **other values**?

# Bayesian Network Learning

- Last time:

- Conditional independence in Bayesian Networks
- Sampling from Bayesian Networks

- Today:

- Given a **Bayesian Network** and some **values**, how do we calculate the probability of **other values**?
- Given **data**, how do we **fit** a Bayesian network?

*Inference*

*Learning*

# Bayesian Network

# Bayesian Network

**Structure**

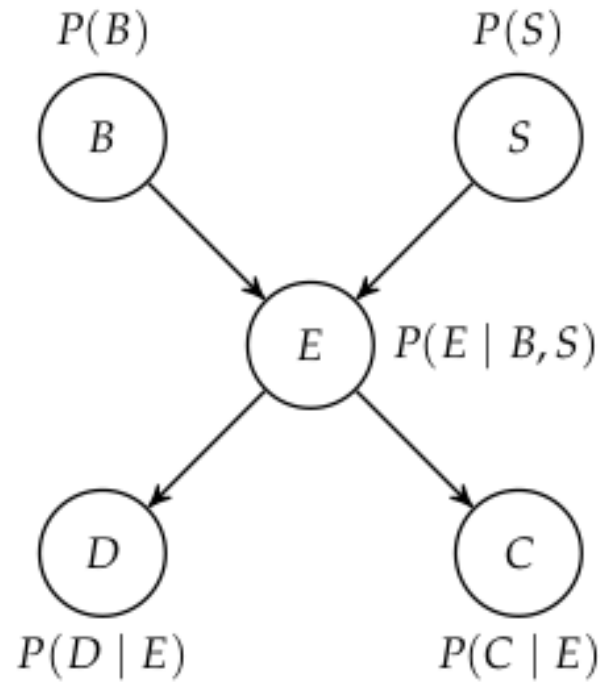
# Bayesian Network

**Structure**

**Parameters**

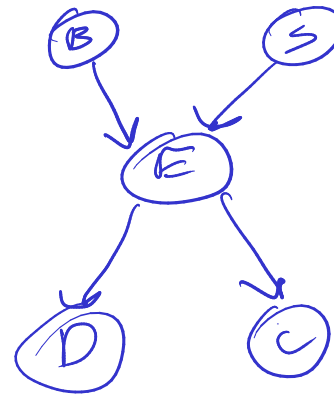


# Bayesian Network



$B$  battery failure  
 $S$  solar panel failure  
 $E$  electrical system failure  
 $D$  trajectory deviation  
 $C$  communication loss

Structure



Parameters

$P(B)$

$P(S)$

$P(E | B, S)$

$P(D | E)$

$P(C | E)$

# Inference

**Inputs**

**Outputs**

# Inference

## Inputs

- Bayesian network structure

## Outputs

# Inference

## Inputs

- Bayesian network structure
- Bayesian network parameters

## Outputs

# Inference

## Inputs

- Bayesian network structure
- Bayesian network parameters
- Values of *evidence variables*

## Outputs

# Inference

## Inputs

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## Outputs

- Posterior distribution of *query variables*

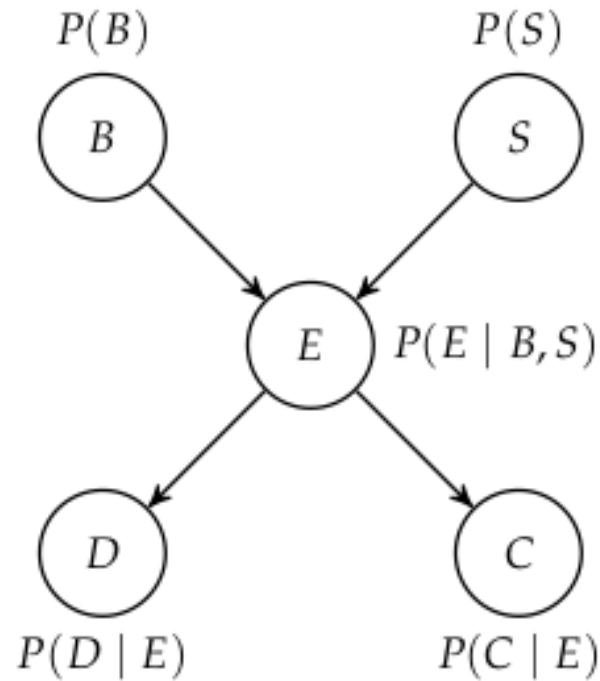
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## Inputs

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- Values of *evidence variables*

## Outputs

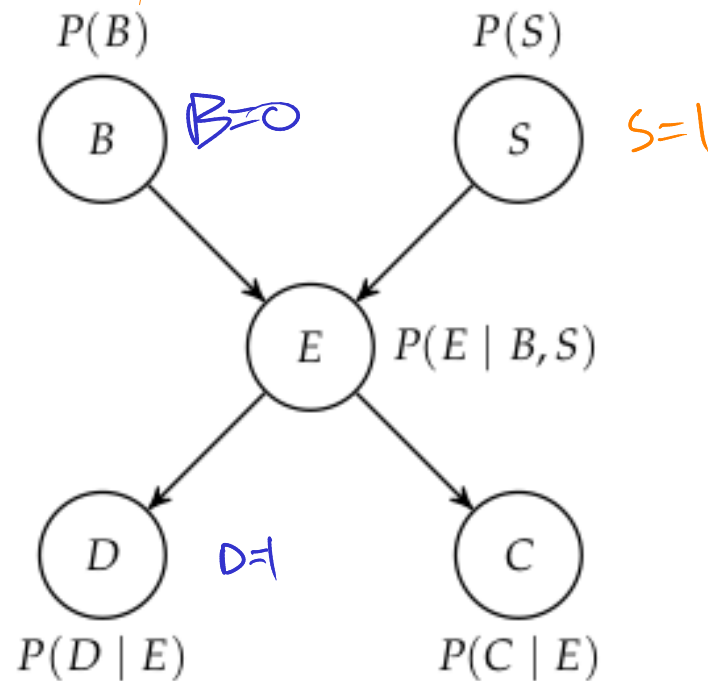
- Posterior distribution of *query variables*



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Evidence

Query



B battery failure  
S solar panel failure  
E electrical system failure  
D trajectory deviation  
C communication loss

# Inference

## Inputs

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## Outputs

- Posterior distribution of *query variables*

Given that you have detected a trajectory deviation, and the battery has not failed what is the probability of a solar panel failure?



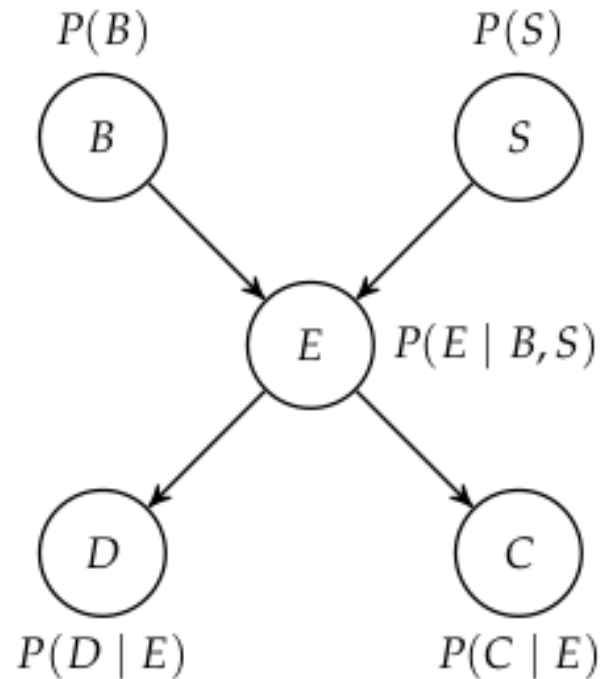
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## Outputs

- Posterior distribution of *query variables*



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$$P(S = 1 \mid D = 1, B = 0)$$

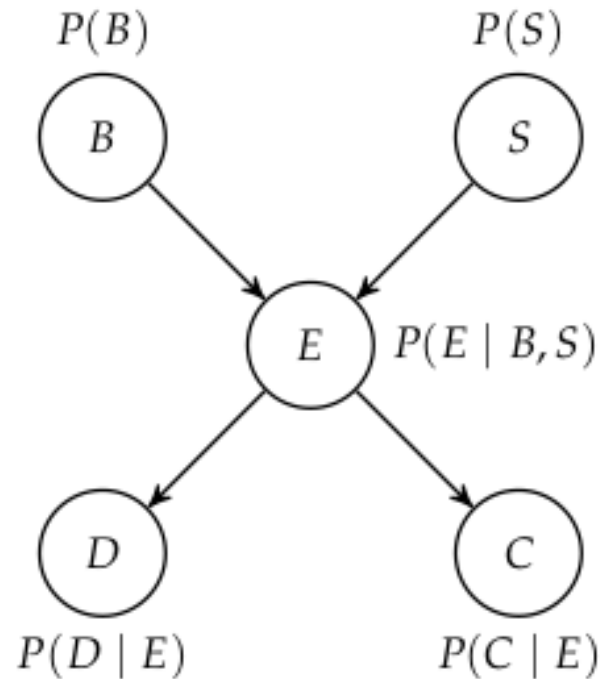
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Exact

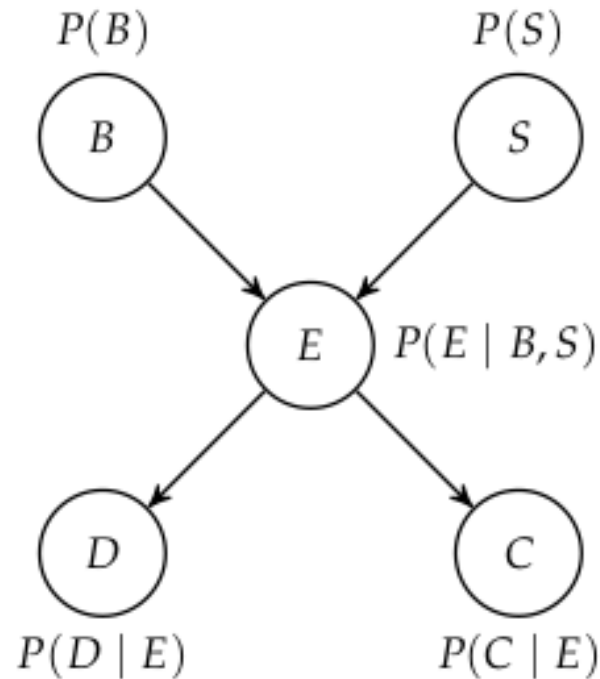
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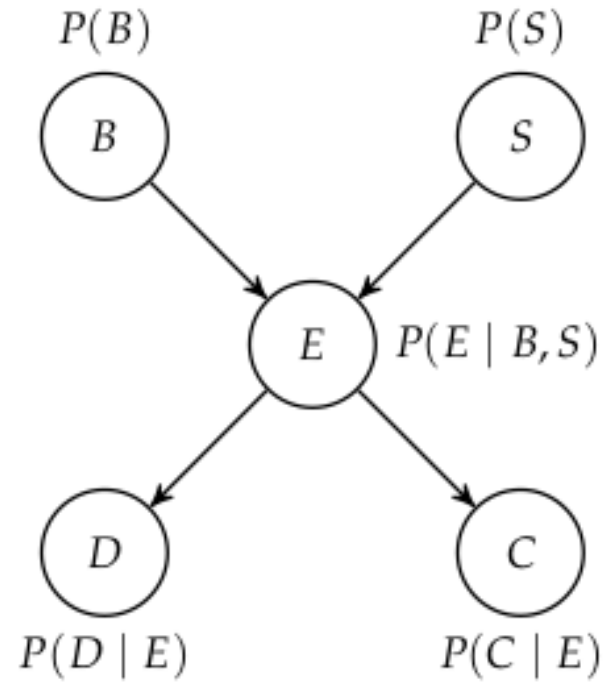
$$P(S = 1 \mid D = 1, B = 0)$$

Exact *NP-hard*

Approximate

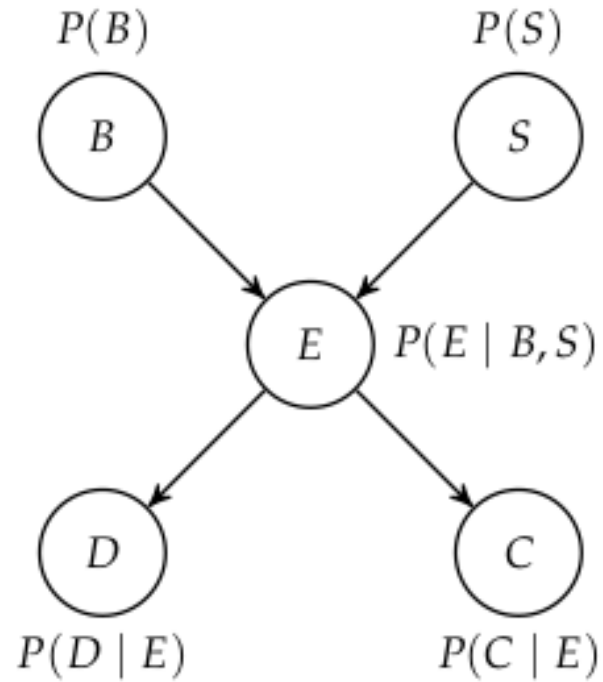
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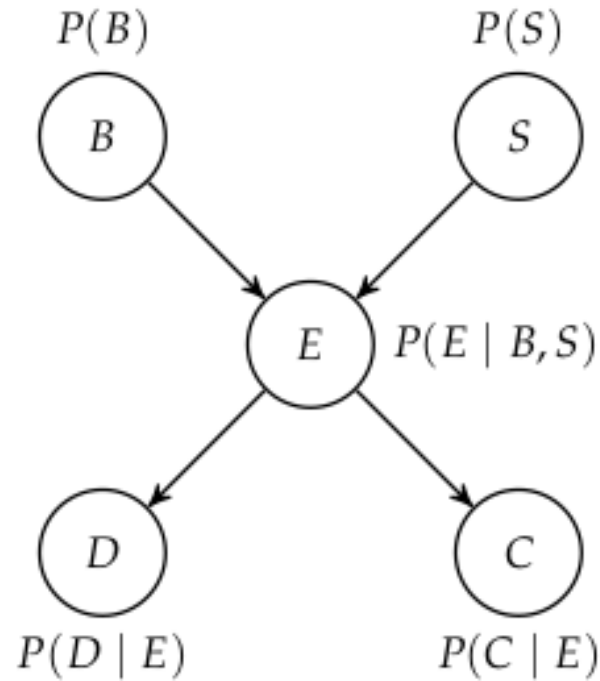
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$$P(S=1 \mid D=1, B=0)$$

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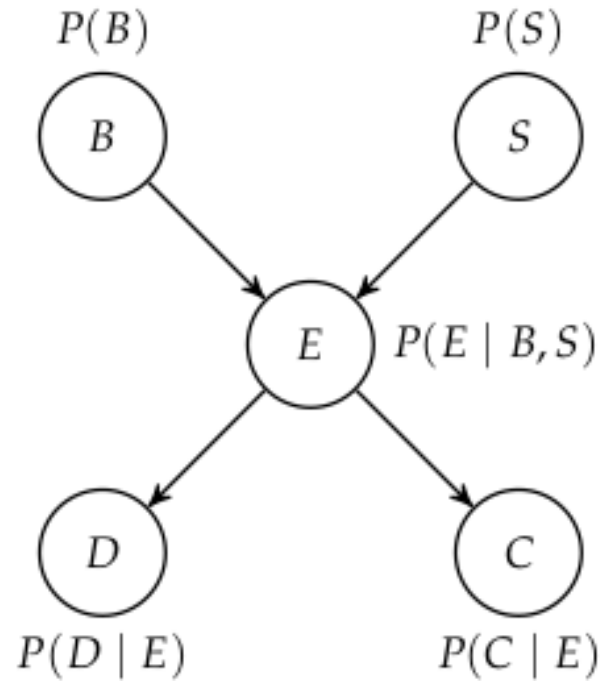
# Exact Inference



$$P(S=1 \mid D=1, B=0) = \frac{P(S=1, D=1, B=0)}{P(D=1, B=0)}$$

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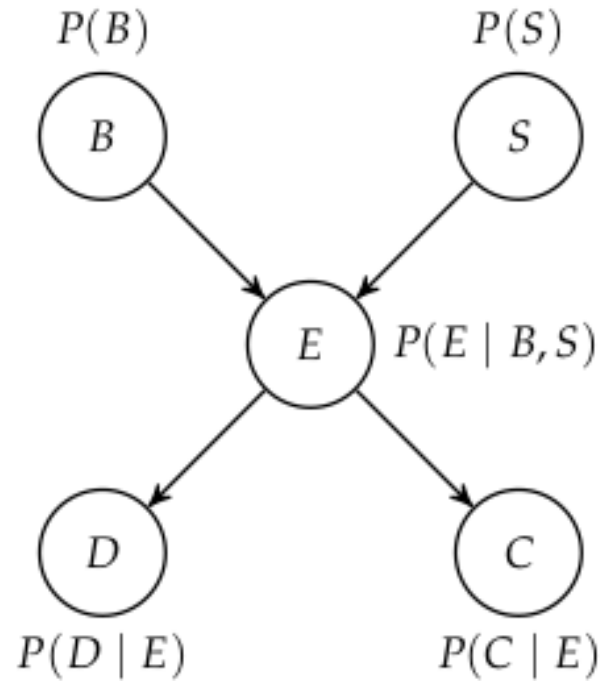
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$$P(S=1, D=1, B=0) = \sum_{e,c} P(\underline{B=0, S=1, E=e, D=1, C=c})$$



# Exact Inference



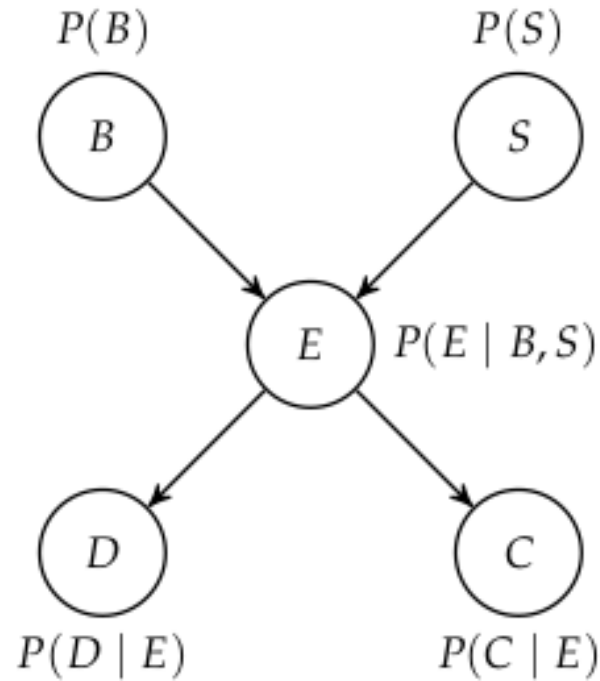
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$$P(B=0, S=1, E, D=1, C)$$

# Exact Inference



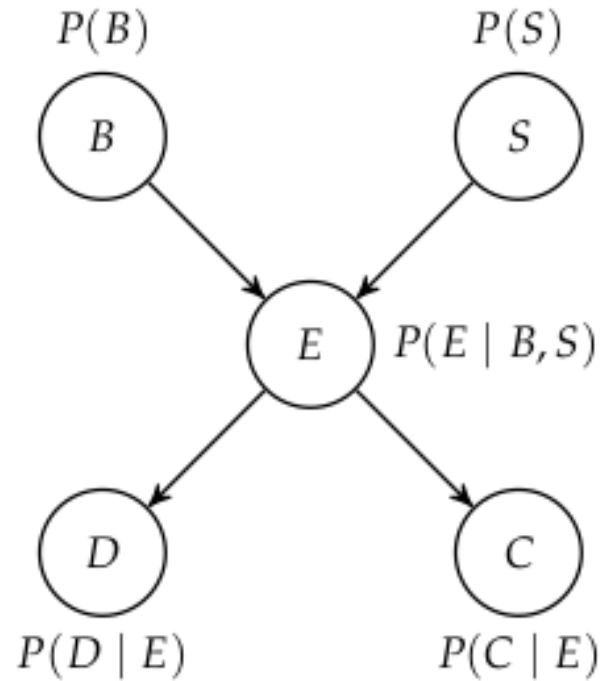
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$$P(B=0, S=1, E, D=1, C) = P(B=0) P(S=1) P(E \mid B=0, S=1) P(D=1 \mid E) P(C=1 \mid E)$$

# Exact Inference



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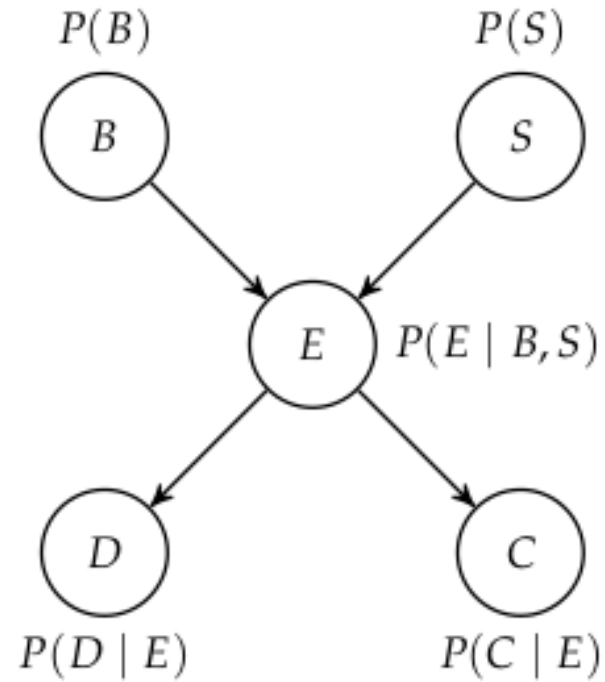
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$$\begin{aligned} &P(B=0, S=1, E, D=1, C) \\ &= P(B=0) P(S=1) P(E \mid B=0, S=1) P(D=1 \mid E) P(C=1 \mid E) \end{aligned}$$

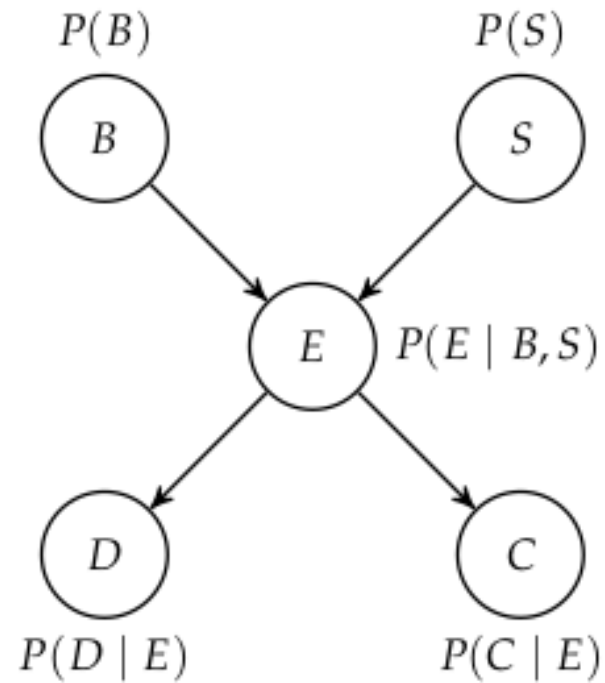
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Product

$X$	$Y$	$\phi_1(X, Y)$
0	0	0.3
0	1	0.4
1	0	0.2
1	1	0.1

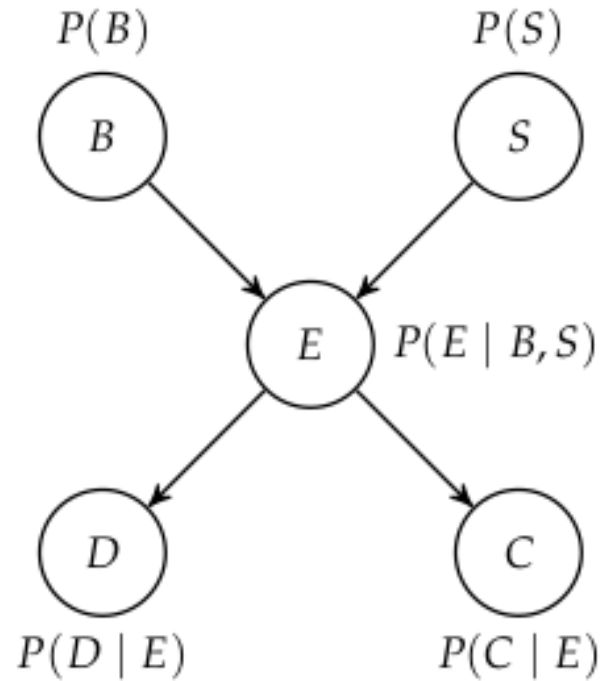
  

$Y$	$Z$	$\phi_2(Y, Z)$
0	0	0.2
0	1	0.0
1	0	0.3
1	1	0.5

$X$	$Y$	$Z$	$\phi_3(X, Y, Z)$
0	0	0	0.06
0	0	1	0.00
0	1	0	0.12
0	1	1	0.20
1	0	0	0.04
1	0	1	0.00
1	1	0	0.03
1	1	1	0.05

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## Condition

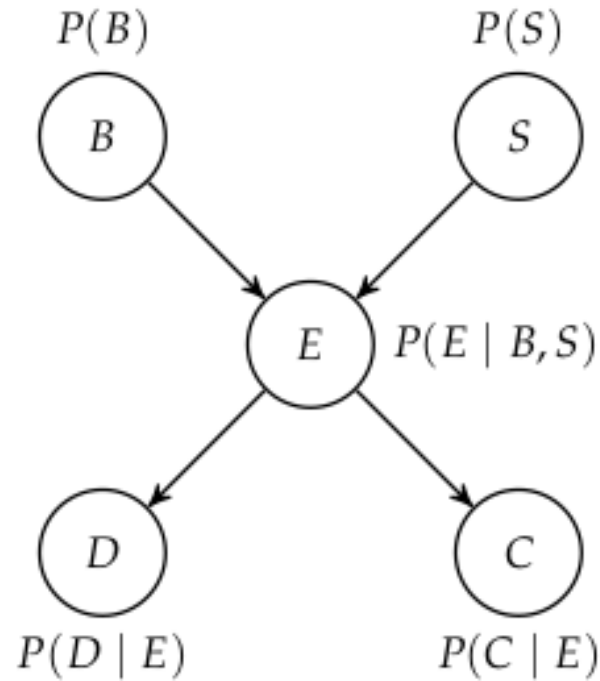
$X$	$Y$	$Z$	$\phi(X, Y, Z)$
0	0	0	0.08
0	0	1	0.31
0	1	0	0.09
0	1	1	0.37
1	0	0	0.01
1	0	1	0.05
1	1	0	0.02
1	1	1	0.07

$Y = 1$

$X$	$Z$	$\phi(X, Z)$
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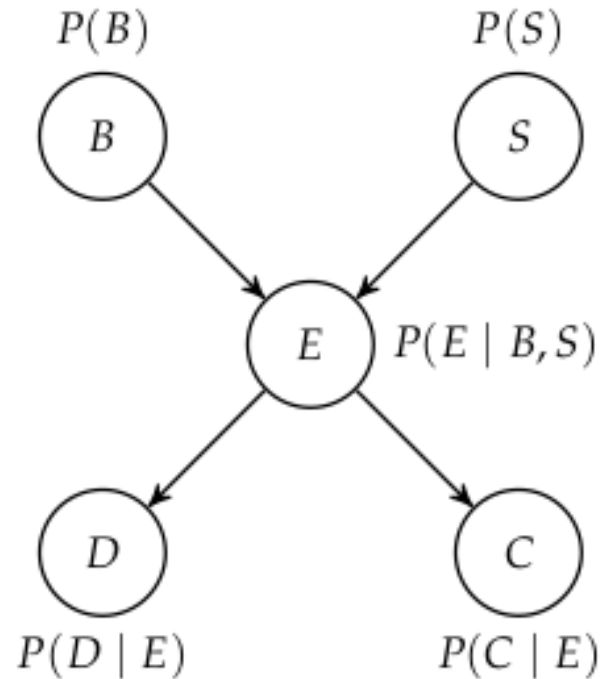
## Marginalize

$X$	$Y$	$Z$	$\phi(X, Y, Z)$
0	0	0	0.08
0	0	1	0.31
0	1	0	0.09
0	1	1	0.37
1	0	0	0.01
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$X$	$Z$	$\phi(X, Z)$
0	0	0.17
0	1	0.68
1	0	0.03
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```

struct ExactInference end
function infer(M::ExactInference, bn, query, evidence)
     $\phi$  = prod(bn.factors)
     $\phi$  = condition( $\phi$ , evidence)
    for name in setdiff(variablenames( $\phi$ ), query)
         $\phi$  = marginalize( $\phi$ , name)
    end
    return normalize!( $\phi$ )
end
  
```

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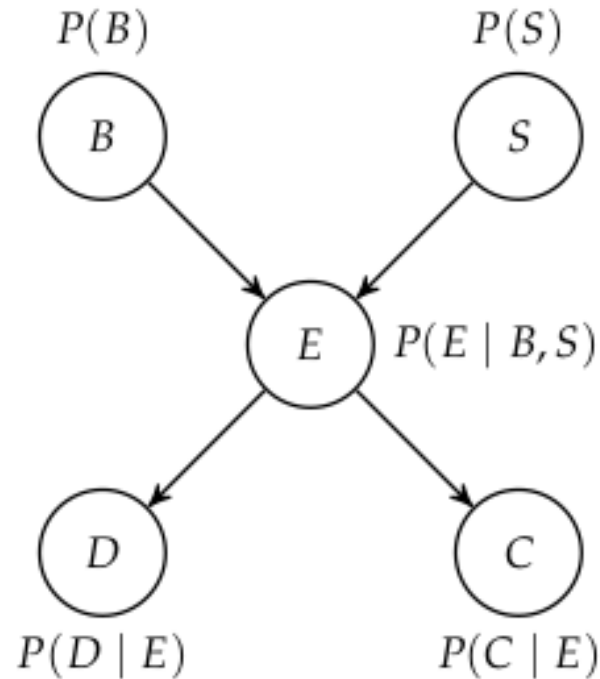
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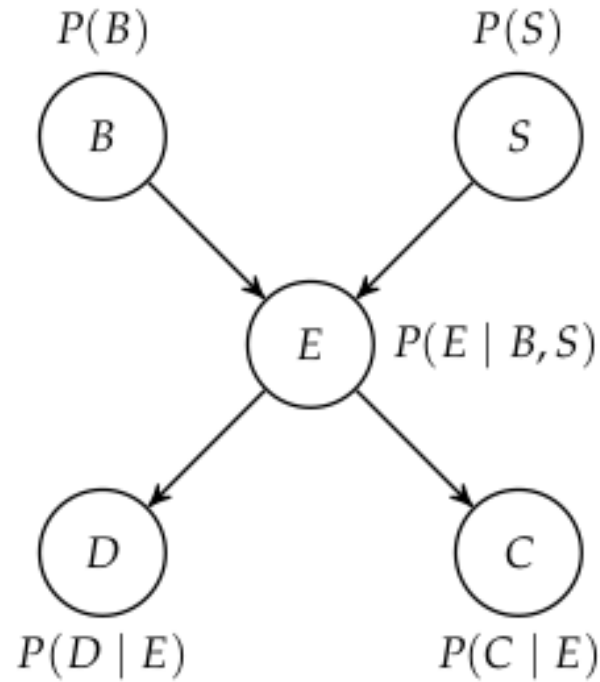
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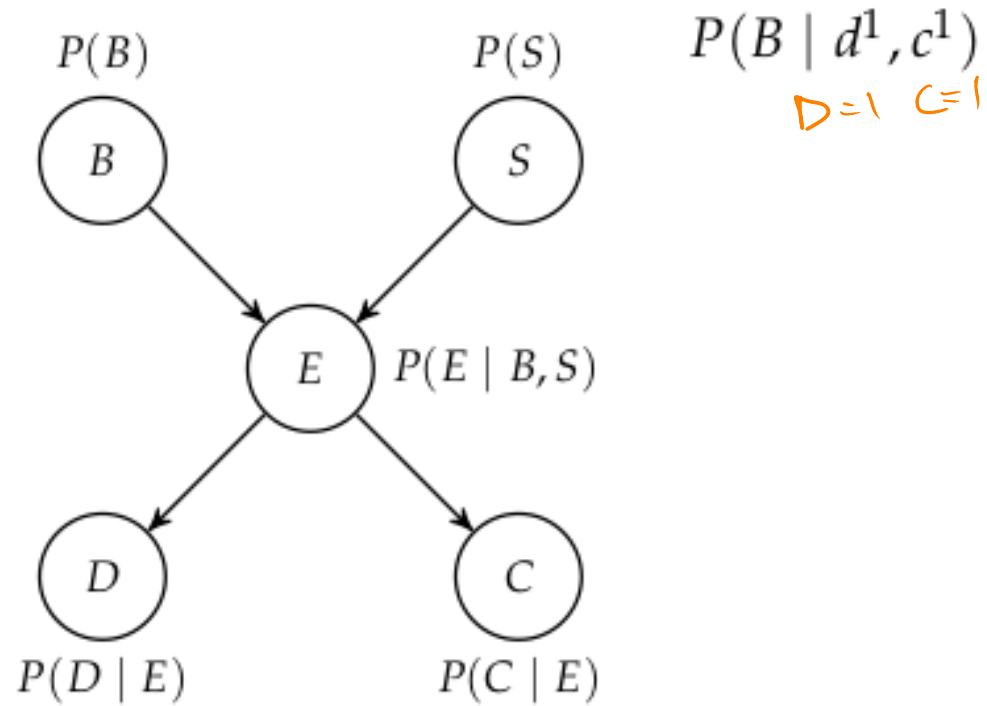
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# Exact Inference: Variable Elimination



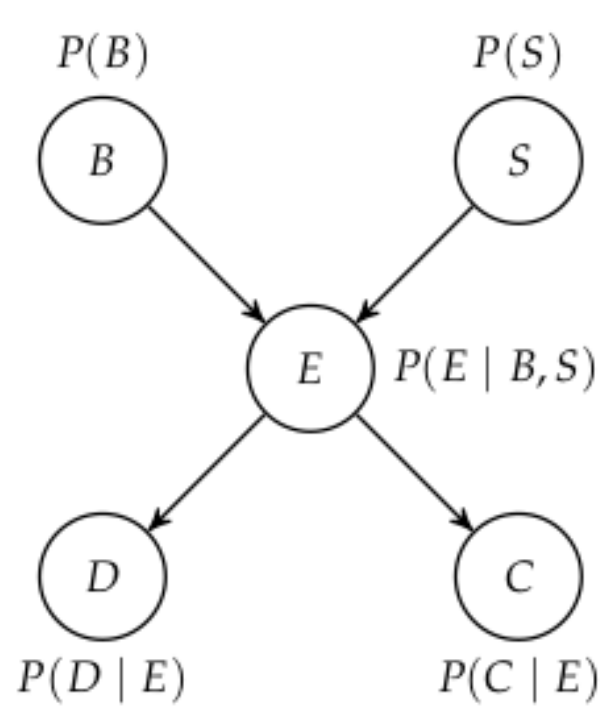
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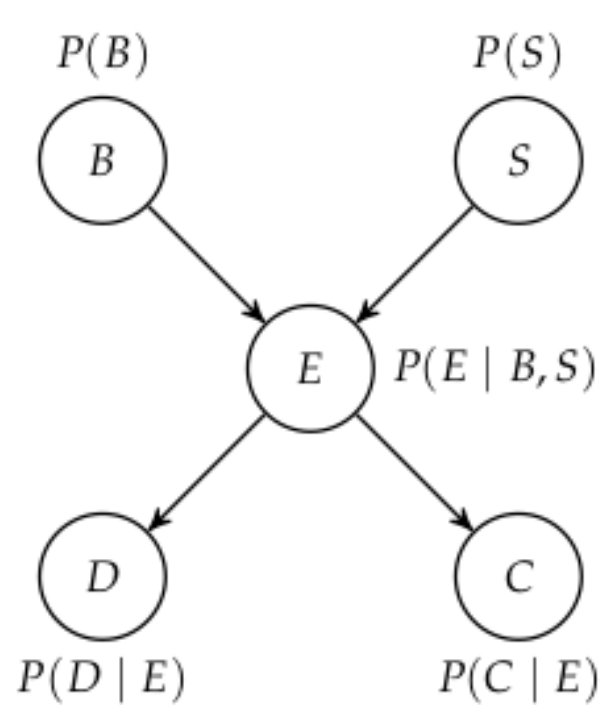
$$P(B | d^1, c^1)$$

Start with

$$\phi_1(B), \phi_2(S), \phi_3(E, B, S), \phi_4(D, E), \phi_5(C, E)$$

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# Exact Inference: Variable Elimination



$$P(B | \underline{d^1, c^1})$$

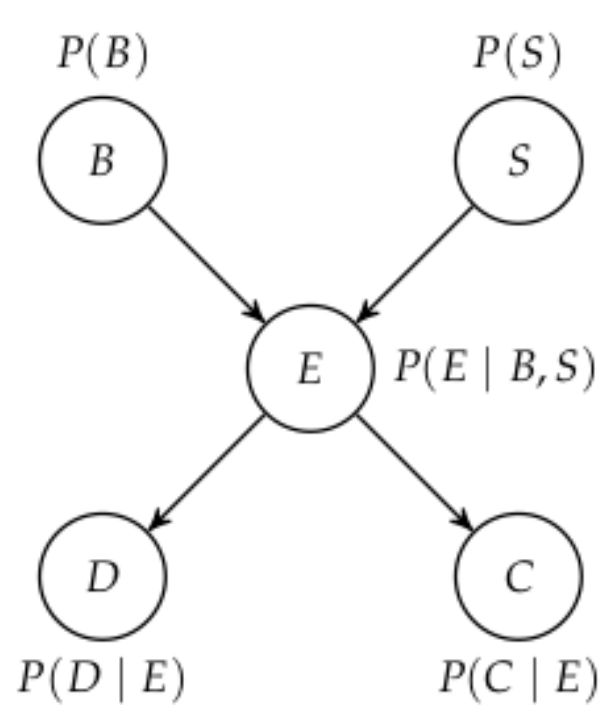
Start with

$$\phi_1(B), \phi_2(S), \phi_3(E, B, S), \phi_4(D, E), \phi_5(C, E)$$

Eliminate  $D$  and  $C$  (evidence) to get  $\phi_6(E)$  and  $\phi_7(E)$

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# Exact Inference: Variable Elimination



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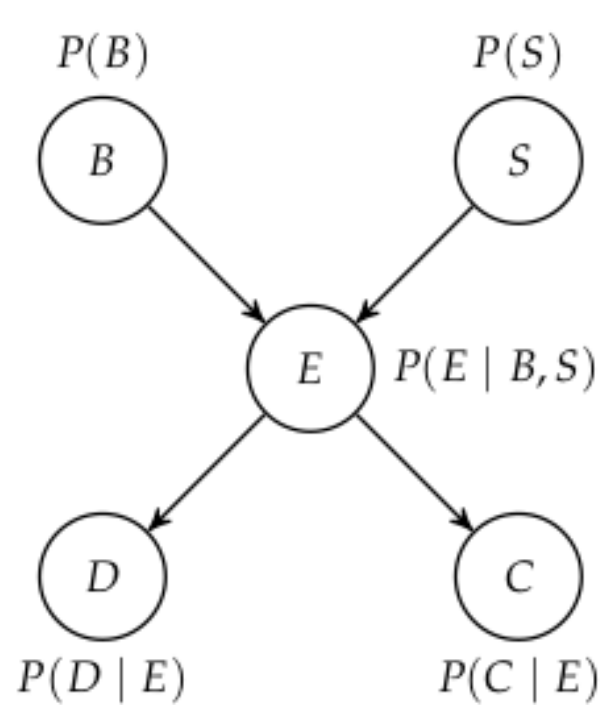
Eliminate  $D$  and  $C$  (evidence) to get  $\phi_6(E)$  and  $\phi_7(E)$

Eliminate  $E$

$$\underline{\phi_8(B, S)} = \sum_e \phi_3(e, B, S) \phi_6(e) \phi_7(e)$$

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$$P(B | d^1, c^1)$$

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$$\phi_1(B), \phi_2(S), \phi_3(E, B, S), \phi_4(D, E), \phi_5(C, E)$$

Eliminate  $D$  and  $C$  (evidence) to get  $\phi_6(E)$  and  $\phi_7(E)$

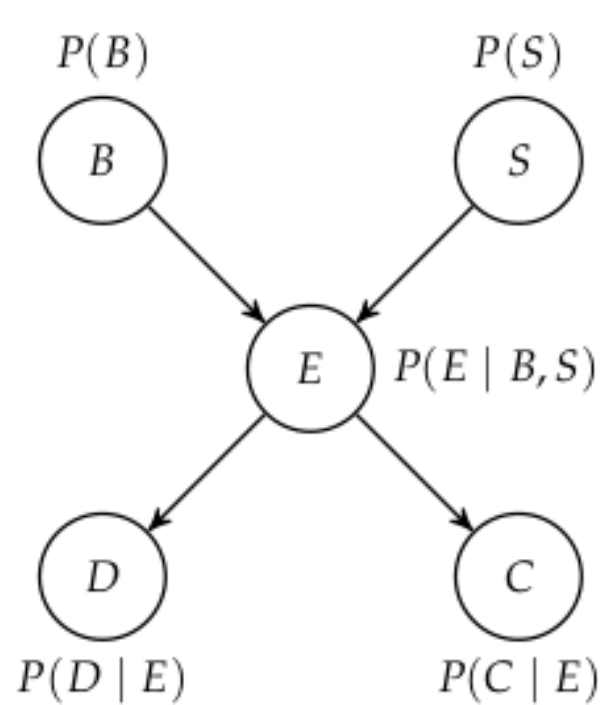
Eliminate  $E$

$$\phi_8(B, S) = \sum_e \phi_3(e, B, S) \phi_6(e) \phi_7(e)$$

Eliminate  $S$

$$\phi_9(B) = \sum_s \phi_2(s) \phi_8(B, s)$$

# Exact Inference: Variable Elimination



$B$  battery failure  
 $S$  solar panel failure  
 $E$  electrical system failure  
 $D$  trajectory deviation  
 $C$  communication loss

$$P(B | d^1, c^1)$$

Start with

$$\phi_1(B), \phi_2(S), \phi_3(E, B, S), \phi_4(D, E), \phi_5(C, E)$$

Eliminate  $D$  and  $C$  (evidence) to get  $\phi_6(E)$  and  $\phi_7(E)$

Eliminate  $E$

$$\phi_8(B, S) = \sum_e \phi_3(e, B, S) \phi_6(e) \phi_7(e)$$

Eliminate  $S$

$$\phi_9(B) = \sum_s \phi_2(s) \phi_8(B, s)$$

Variable Elimination

$$P(B | d^1, c^1) \propto \phi_1(B) \sum_s \left( \phi_2(s) \sum_e \left( \phi_3(e | B, s) \phi_4(d^1 | e) \phi_5(c^1 | e) \right) \right)$$

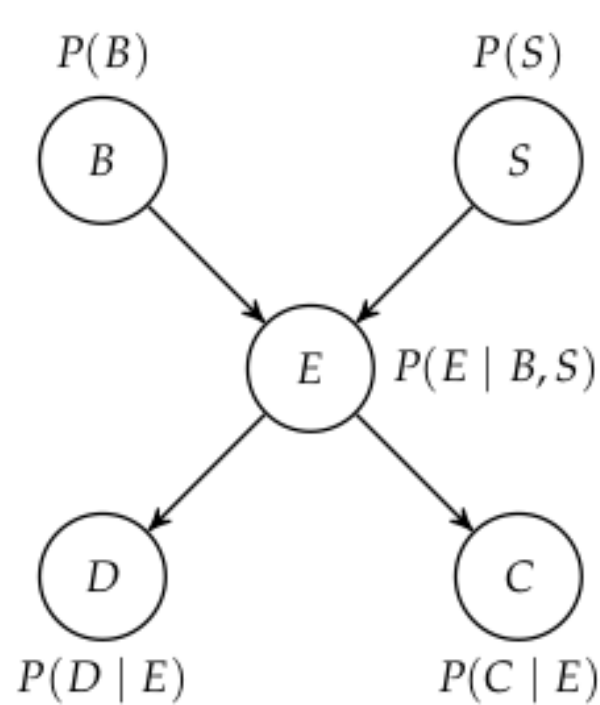
VS

Naive

$$P(B | d^1, c^1) \propto \sum_s \sum_e \phi_1(B) \phi_2(s) \phi_3(e | B, s) \phi_4(d^1 | e) \phi_5(c^1 | e)$$



# Exact Inference: Variable Elimination



$B$  battery failure  
 $S$  solar panel failure  
 $E$  electrical system failure  
 $D$  trajectory deviation  
 $C$  communication loss

$$P(B | d^1, c^1)$$

Start with

$$\phi_1(B), \phi_2(S), \phi_3(E, B, S), \phi_4(D, E), \phi_5(C, E)$$

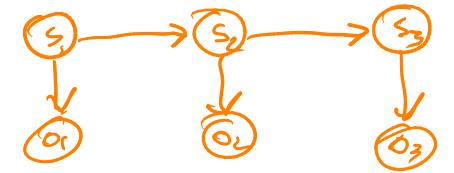
Eliminate  $D$  and  $C$  (evidence) to get  $\phi_6(E)$  and  $\phi_7(E)$

Eliminate  $E$

$$\phi_8(B, S) = \sum_e \phi_3(e, B, S) \phi_6(e) \phi_7(e)$$

Eliminate  $S$

$$\phi_9(B) = \sum_s \phi_2(s) \phi_8(B, s)$$



$$P(B | d^1, c^1) \propto \phi_1(B) \sum_s \left( \phi_2(s) \sum_e \left( \phi_3(e | B, s) \phi_4(d^1 | e) \phi_5(c^1 | e) \right) \right)$$

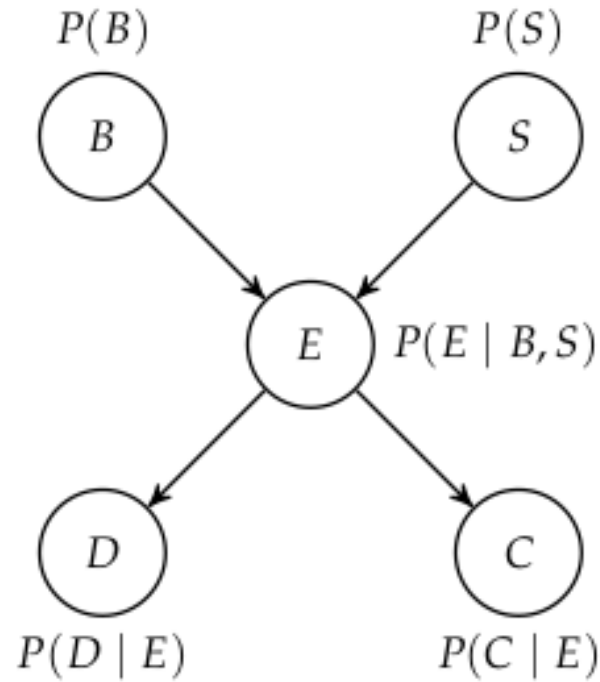
VS

$$P(B | d^1, c^1) \propto \sum_s \sum_e \phi_1(B) \phi_2(s) \phi_3(e | B, s) \phi_4(d^1 | e) \phi_5(c^1 | e)$$

Choosing  
optimal order  
is NP-hard

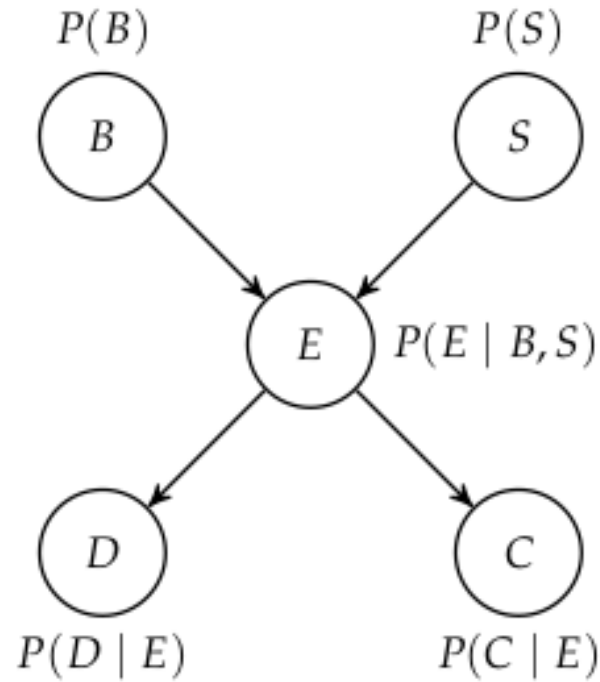
# Approximate Inference

# Approximate Inference: Direct Sampling



$B$  battery failure  
 $S$  solar panel failure  
 $E$  electrical system failure  
 $D$  trajectory deviation  
 $C$  communication loss

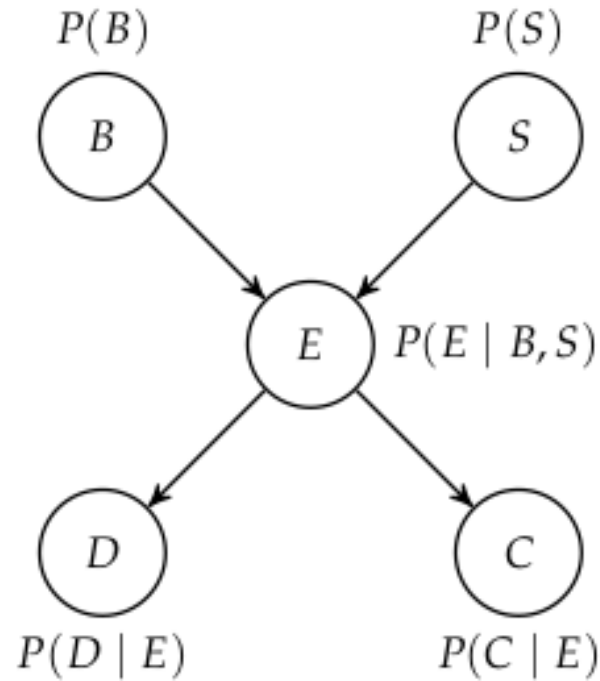
# Approximate Inference: Direct Sampling



$$P(b^1 | d^1, c^1) \approx \frac{\sum_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i (\underbrace{d^{(i)} = 1}_{\text{true}} \wedge \underbrace{c^{(i)} = 1}_{\text{true}})}$$

$B$  battery failure  
 $S$  solar panel failure  
 $E$  electrical system failure  
 $D$  trajectory deviation  
 $C$  communication loss

# Approximate Inference: Direct Sampling



B battery failure  
 S solar panel failure  
 E electrical system failure  
 D trajectory deviation  
 C communication loss

$$P(b^1 | d^1, c^1) \approx \frac{\sum_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i (d^{(i)} = 1 \wedge c^{(i)} = 1)}$$

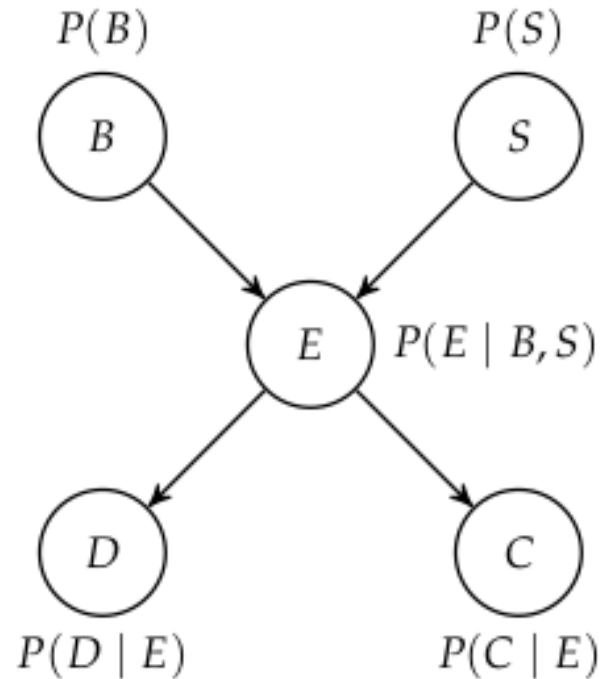
*Handwritten orange annotations: a '1/2' below the denominator and a double arrow pointing to the denominator.*

Sample 1 →

B	S	E	D	C
0	0	1	1	0
0	0	0	0	0
1	0	1	0	0
1	0	1	1	1
0	0	0	0	0
0	0	0	1	0
0	0	0	0	1
0	1	1	1	1
0	0	0	0	0
0	0	0	1	0

*Handwritten orange annotations: a horizontal line under the 4th row and the 9th row. Blue arrows point to the 5th column of the 4th and 9th rows.*

# Approximate Inference: Direct Sampling



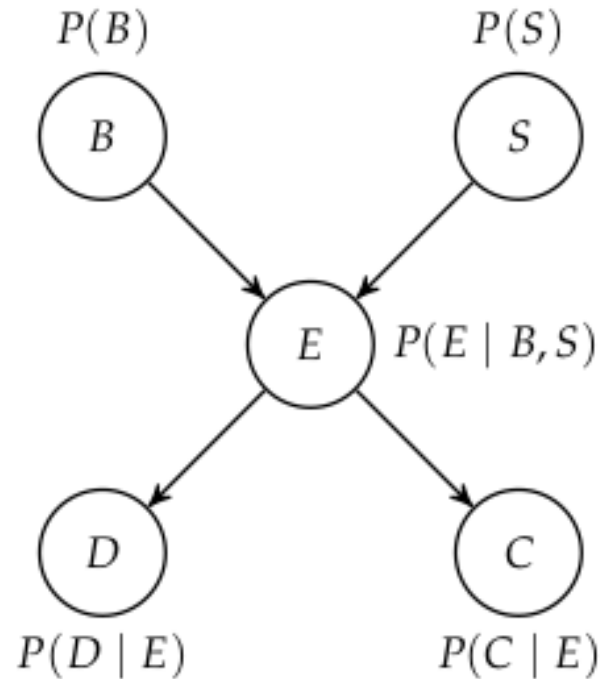
$B$  battery failure  
 $S$  solar panel failure  
 $E$  electrical system failure  
 $D$  trajectory deviation  
 $C$  communication loss

$$P(b^1 | d^1, c^1) \approx \frac{\sum_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i (d^{(i)} = 1 \wedge c^{(i)} = 1)}$$

$B$	$S$	$E$	$D$	$C$	
0	0	1	1	0	
0	0	0	0	0	
1	0	1	0	0	
1	0	1	1	1	←
0	0	0	0	0	
0	0	0	1	0	
0	0	0	0	1	
0	1	1	1	1	←
0	0	0	0	0	
0	0	0	1	0	

Analogous to

# Approximate Inference: Direct Sampling



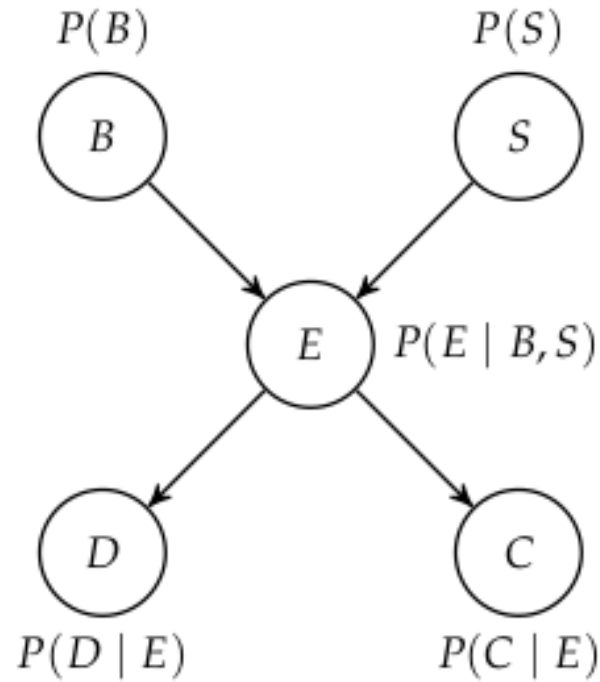
B battery failure  
S solar panel failure  
E electrical system failure  
D trajectory deviation  
C communication loss

$$P(b^1 | d^1, c^1) \approx \frac{\sum_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i (d^{(i)} = 1 \wedge c^{(i)} = 1)}$$

B	S	E	D	C
0	0	1	1	0
0	0	0	0	0
1	0	1	0	0
1	0	1	1	1
0	0	0	0	0
0	0	0	1	0
0	0	0	0	1
0	1	1	1	1
0	0	0	0	0
0	0	0	1	0

Analogous to **unweighted particle filtering**

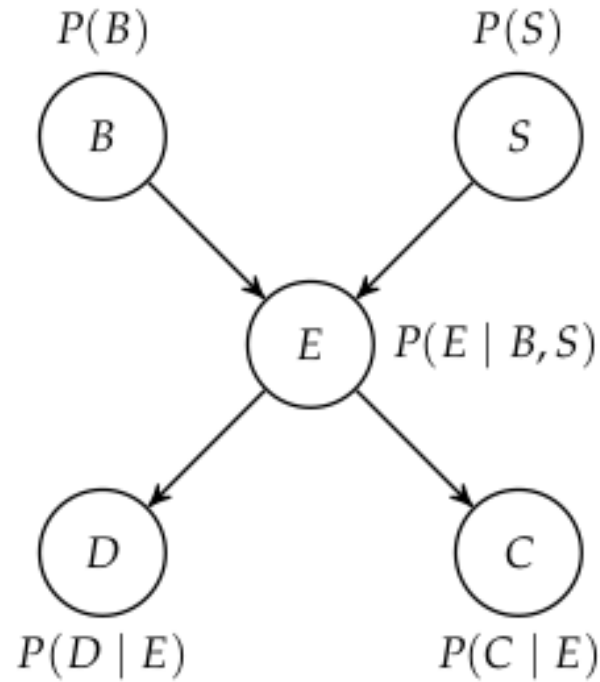
# Approximate Inference: Weighted Sampling



$B$  battery failure  
 $S$  solar panel failure  
 $E$  electrical system failure  
 $D$  trajectory deviation  
 $C$  communication loss



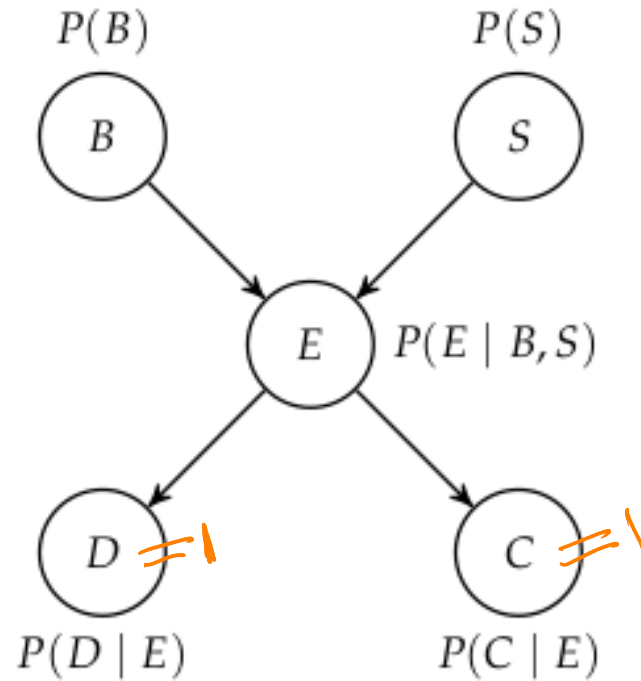
# Approximate Inference: Weighted Sampling



$B$  battery failure  
 $S$  solar panel failure  
 $E$  electrical system failure  
 $D$  trajectory deviation  
 $C$  communication loss

$$P(\textcolor{orange}{b}^1 | d^1, c^1) \approx \frac{\sum_i w_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i w_i (d^{(i)} = 1 \wedge c^{(i)} = 1)}$$
$$= \frac{\sum_i w_i (b^{(i)} = 1)}{\sum_i w_i}$$

# Approximate Inference: Weighted Sampling

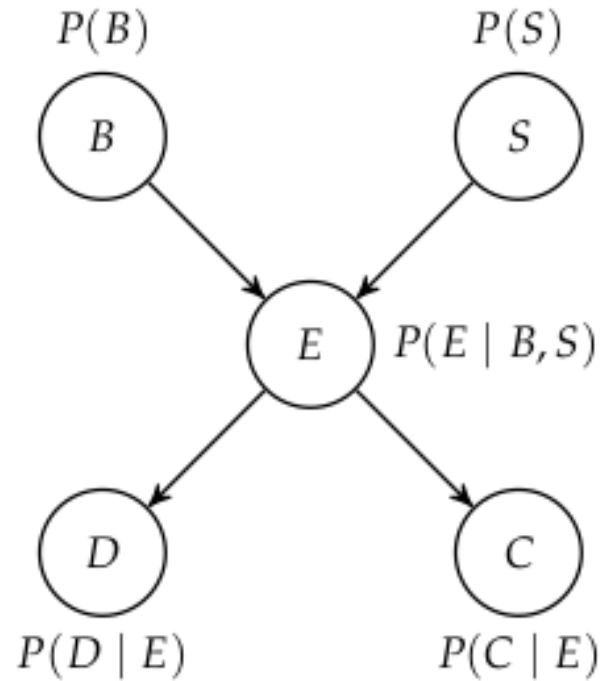


$B$  battery failure  
 $S$  solar panel failure  
 $E$  electrical system failure  
 $D$  trajectory deviation  
 $C$  communication loss

$$\begin{aligned}
 P(b^1 | \underbrace{d^1}, \underbrace{c^1}) &\approx \frac{\sum_i w_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i w_i (d^{(i)} = 1 \wedge c^{(i)} = 1)} \\
 &= \frac{\sum_i w_i (b^{(i)} = 1)}{\sum_i w_i}
 \end{aligned}$$

$B$	$S$	$E$	$D$	$C$	Weight
1	0	1	1	1	$P(d^1   e^1) P(c^1   e^1)$
0	1	1	1	1	$P(d^1   e^1) P(c^1   e^1)$
0	0	0	1	1	$P(d^1   e^0) P(c^1   e^0)$
0	0	0	1	1	$P(d^1   e^0) P(c^1   e^0)$
0	0	1	1	1	$P(d^1   e^1) P(c^1   e^1)$

# Approximate Inference: Weighted Sampling



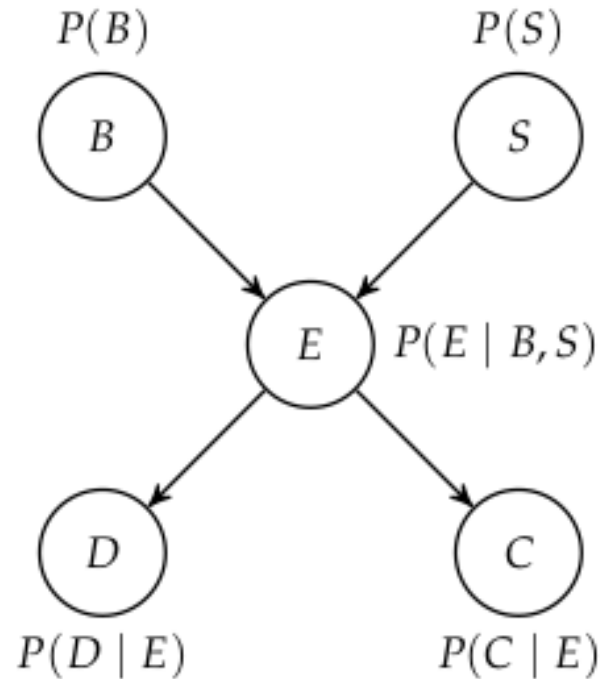
*B* battery failure  
*S* solar panel failure  
*E* electrical system failure  
*D* trajectory deviation  
*C* communication loss

$$\begin{aligned}
 P(b^1 | d^1, c^1) &\approx \frac{\sum_i w_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i w_i (d^{(i)} = 1 \wedge c^{(i)} = 1)} \\
 &= \frac{\sum_i w_i (b^{(i)} = 1)}{\sum_i w_i}
 \end{aligned}$$

<i>B</i>	<i>S</i>	<i>E</i>	<i>D</i>	<i>C</i>	Weight
1	0	1	1	1	$P(d^1   e^1)P(c^1   e^1)$
0	1	1	1	1	$P(d^1   e^1)P(c^1   e^1)$
0	0	0	1	1	$P(d^1   e^0)P(c^1   e^0)$
0	0	0	1	1	$P(d^1   e^0)P(c^1   e^0)$
0	0	1	1	1	$P(d^1   e^1)P(c^1   e^1)$

Analogous to

# Approximate Inference: Weighted Sampling



$B$  battery failure  
 $S$  solar panel failure  
 $E$  electrical system failure  
 $D$  trajectory deviation  
 $C$  communication loss

$$\begin{aligned}
 P(b^1 | d^1, c^1) &\approx \frac{\sum_i w_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i w_i (d^{(i)} = 1 \wedge c^{(i)} = 1)} \\
 &= \frac{\sum_i w_i (b^{(i)} = 1)}{\sum_i w_i}
 \end{aligned}$$

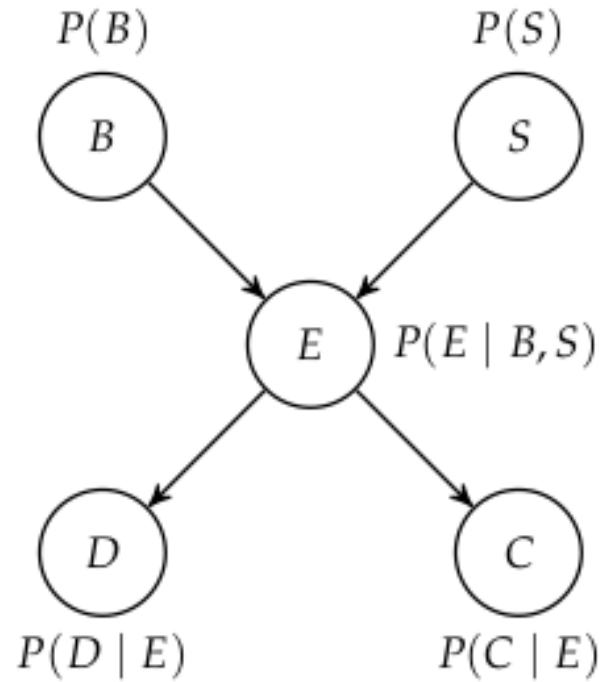
~~$P(d^1, c^1)$~~

$B$	$S$	$E$	$D$	$C$	Weight
1	0	1	1	1	$P(d^1   e^1)P(c^1   e^1)$
0	1	1	1	1	$P(d^1   e^1)P(c^1   e^1)$
0	0	0	1	1	$P(d^1   e^0)P(c^1   e^0)$
0	0	0	1	1	$P(d^1   e^0)P(c^1   e^0)$
0	0	1	1	1	$P(d^1   e^1)P(c^1   e^1)$



Analogous to **weighted particle filtering**

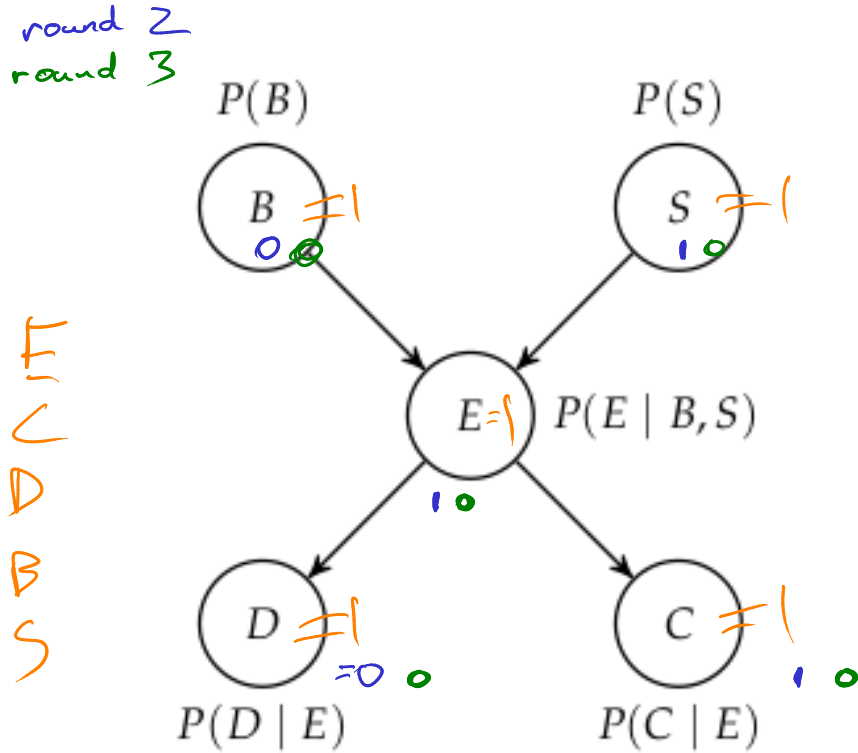
# Approximate Inference: Gibbs Sampling



$B$  battery failure  
 $S$  solar panel failure  
 $E$  electrical system failure  
 $D$  trajectory deviation  
 $C$  communication loss

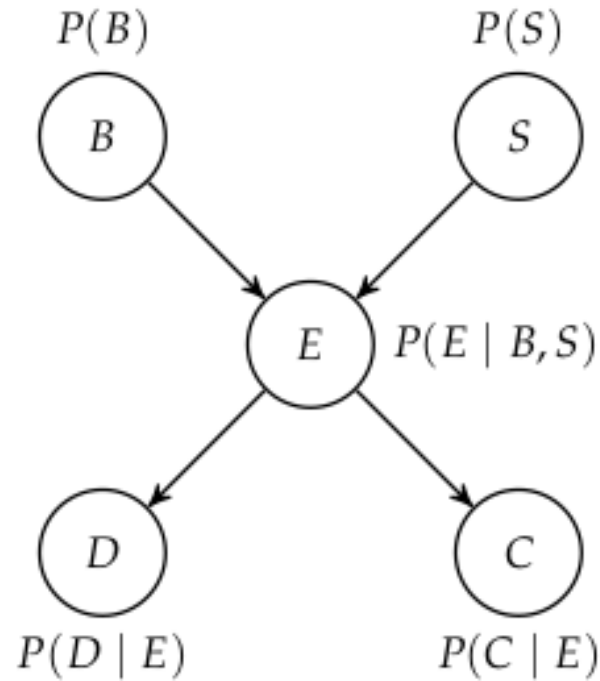
# Approximate Inference: Gibbs Sampling

Markov Chain Monte Carlo (MCMC)



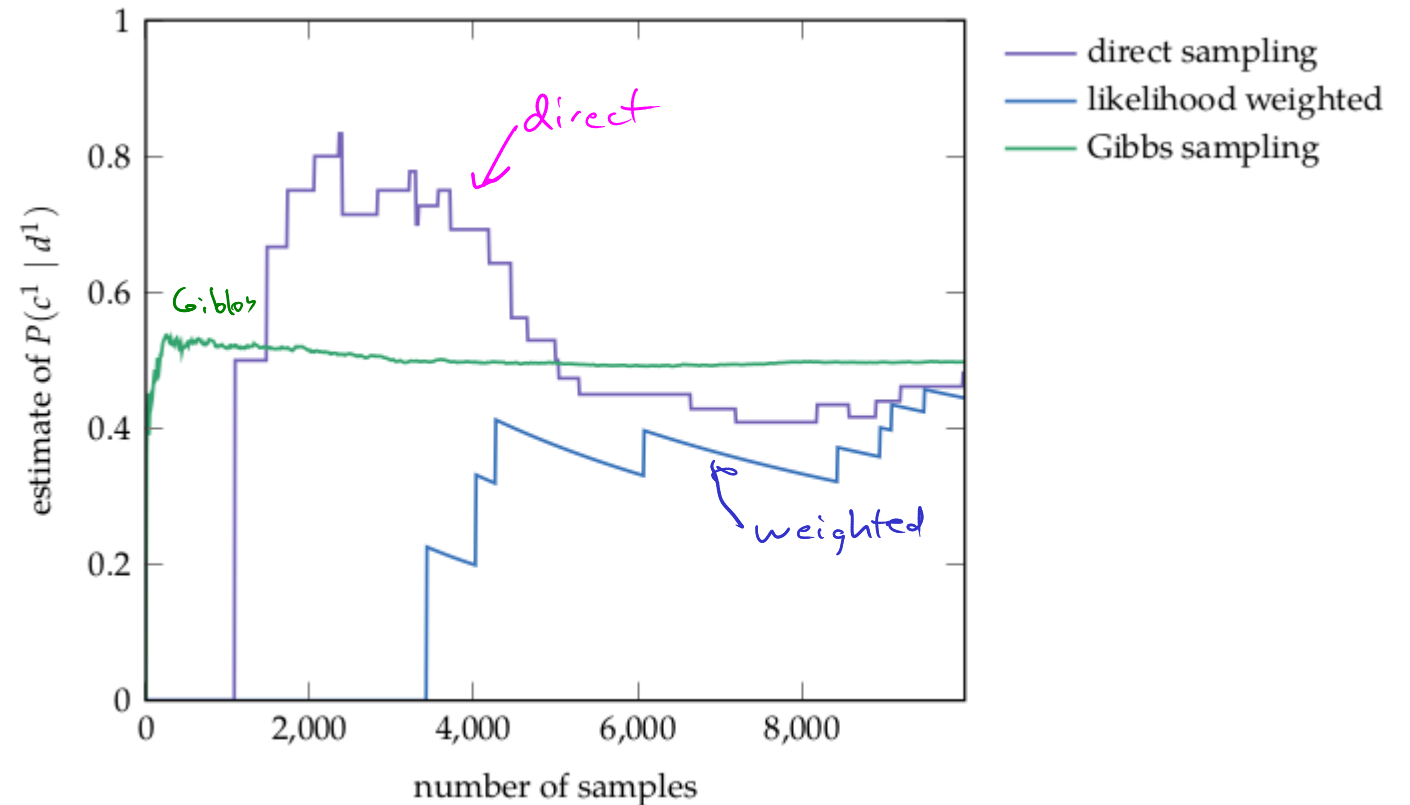
$B$  battery failure  
 $S$  solar panel failure  
 $E$  electrical system failure  
 $D$  trajectory deviation  
 $C$  communication loss

# Approximate Inference: Gibbs Sampling



$B$  battery failure  
 $S$  solar panel failure  
 $E$  electrical system failure  
 $D$  trajectory deviation  
 $C$  communication loss

## Markov Chain Monte Carlo (MCMC)



# Learning



# Bayesian Network Learning

**Inputs**

**Outputs**

# Bayesian Network Learning

## Inputs

- Data,  $D$

## Outputs

# Bayesian Network Learning

## Inputs

- Data,  $D$
- Priors (?)

## Outputs

# Bayesian Network Learning

## Inputs

- Data,  $D$
- Priors (?)

## Outputs

- Bayesian network structure,  $G$

# Bayesian Network Learning

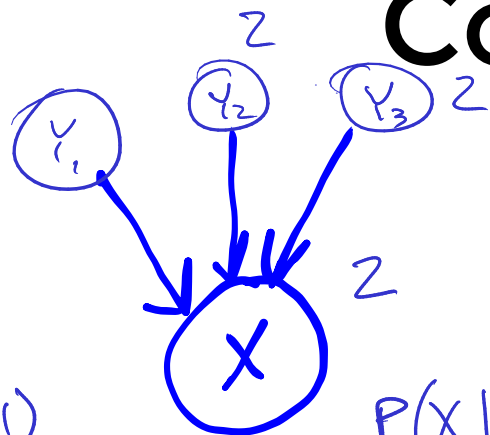
## Inputs

- Data,  $D$
- Priors (?)

## Outputs

- Bayesian network structure,  $G$
- Bayesian network parameters,  $\theta$

# Counting Parameters



For discrete R.V.s:

$$\dim(\theta_X) = (|\text{support}(X)| - 1) \prod_{Y \in \text{Pa}(X)} |\text{support}(Y)|$$

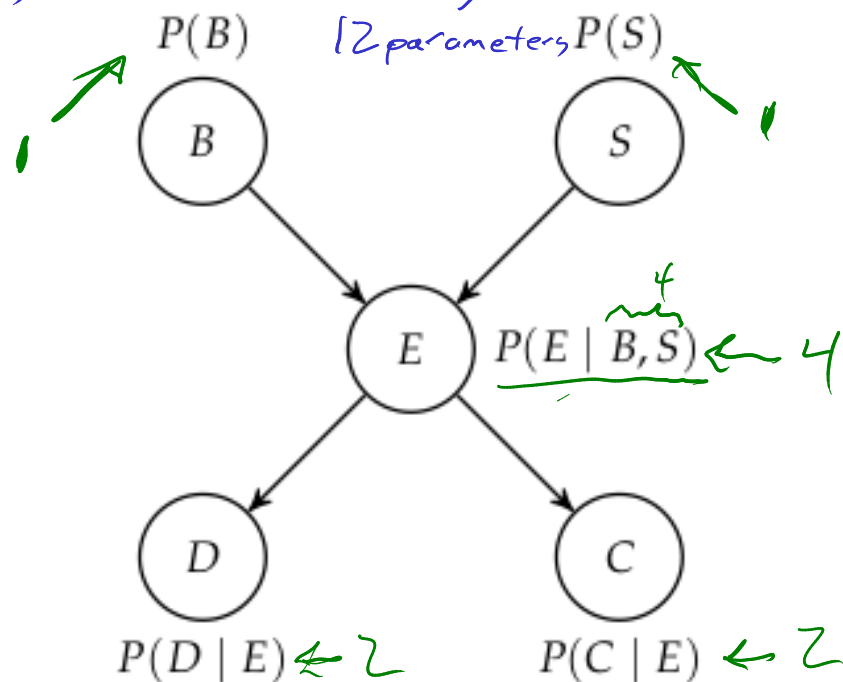
$$P(X | \text{Pa}(X)) = P(X | Y_1, Y_2, Y_3)$$

$$P(X | Y_1=1, Y_2=1, Y_3=1) : 1 \text{ parameter}$$

$$X \in \{1, 0\}$$

$$\theta_1 = P(X=1)$$

$$P(X=0) = 1 - \theta_1$$

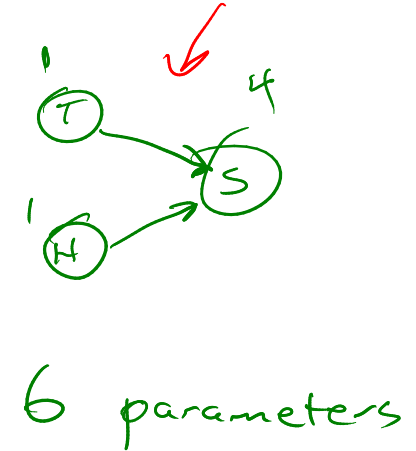
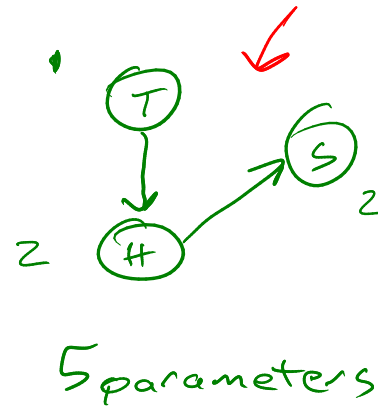
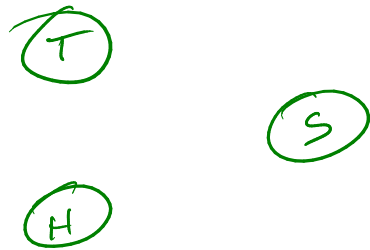


$$1 + 1 + 4 + 2 + 2 = 10 \text{ parameters}$$

$$C \sim N(\mu_C, \sigma_C)$$

$$C \sim N(aE + b, \sigma_C)$$

# Structure Learning Example



# Parameter Learning



# Parameter Learning

**Maximum Likelihood**

# Parameter Learning

**Maximum Likelihood**

**Bayesian**

# Parameter Learning

**Maximum Likelihood**

$$\hat{\theta} = \arg \max_{\theta} P(D \mid \theta)$$

**Bayesian**

# Parameter Learning

**Maximum Likelihood**

$$\hat{\theta} = \arg \max_{\theta} P(D \mid \theta)$$

$$P(D \mid \theta) = \prod_i P(o_i \mid \theta)$$


**Bayesian**

# Parameter Learning

## Maximum Likelihood

$$\hat{\theta} = \arg \max_{\theta} P(D \mid \theta)$$

$$P(D \mid \theta) = \prod_i P(o_i \mid \theta)$$

$$\hat{\theta} = \arg \max_{\theta} \sum_i \log P(o_i \mid \theta)$$


## Bayesian

# Parameter Learning

## Maximum Likelihood

## Bayesian

$$\hat{\theta} = \arg \max_{\theta} P(D \mid \theta)$$

$$P(D \mid \theta) = \prod_i P(o_i \mid \theta)$$

$$\hat{\theta} = \arg \max_{\theta} \sum_i \log P(o_i \mid \theta)$$

Multinomial:

$$P(B=i) = \frac{N \langle B=i \rangle}{N} \quad \hat{\theta}_i = \frac{n_i}{\sum_{j=1}^k n_j}$$

# Parameter Learning

## Maximum Likelihood

$$\hat{\theta} = \arg \max_{\theta} P(D \mid \theta)$$

$$P(D \mid \theta) = \prod_i P(o_i \mid \theta)$$

$$\hat{\theta} = \arg \max_{\theta} \sum_i \log P(o_i \mid \theta)$$

## Bayesian

$$\hat{\theta} = \mathbb{E}_{\theta \sim p(\cdot \mid D)}[\theta] = \int \theta p(\theta \mid D) \, d\theta$$

Multinomial:

$$\hat{\theta}_i = \frac{n_i}{\sum_{j=1}^k n_j}$$

# Parameter Learning

## Maximum Likelihood

$$\hat{\theta} = \arg \max_{\theta} P(D \mid \theta)$$

$$P(D \mid \theta) = \prod_i P(o_i \mid \theta)$$

$$\hat{\theta} = \arg \max_{\theta} \sum_i \log P(o_i \mid \theta)$$

Multinomial:

$$\hat{\theta}_i = \frac{n_i}{\sum_{j=1}^k n_j}$$

## Bayesian

$$\hat{\theta} = \mathbb{E}_{\theta \sim p(\cdot \mid D)}[\theta] = \int \theta p(\theta \mid D) d\theta$$

$$p(\theta \mid D) \propto P(D \mid \theta) P(\theta)$$

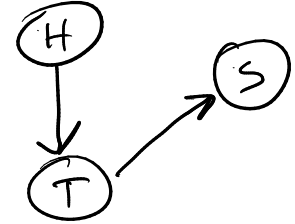
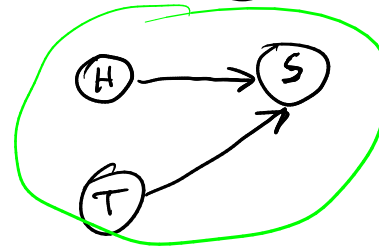
Multinomial:

$$p(\theta_{1:n} \mid \alpha_{1:n}, m_{1:n}) = \text{Dir}(\theta_{1:n} \mid \alpha_1 + m_1, \dots, \alpha_n + m_n)$$

$$\frac{\alpha_i}{\sum_{j=1}^n \alpha_j}$$



# Structure Learning



# Structure Learning

$$P(G \mid D)$$

# Structure Learning

$$\begin{aligned} P(G \mid D) &\propto P(G)P(D \mid G) \\ &= P(G) \int P(D \mid \theta, G) p(\theta \mid G) d\theta \end{aligned}$$

# Structure Learning

$$\begin{aligned} P(G \mid D) &\propto P(G)P(D \mid G) \\ &= P(G) \int P(D \mid \boldsymbol{\theta}, G) p(\boldsymbol{\theta} \mid G) d\boldsymbol{\theta} \end{aligned}$$

Dirichlet

$$P(G \mid D) = P(G) \prod_{i=1}^n \prod_{j=1}^{q_i} \frac{\Gamma(\alpha_{ij0})}{\Gamma(\alpha_{ij0} + m_{ij0})} \prod_{k=1}^{r_i} \frac{\Gamma(\alpha_{ijk} + m_{ijk})}{\Gamma(\alpha_{ijk})}$$

# Structure Learning

$$\begin{aligned} P(G \mid D) &\propto P(G)P(D \mid G) \\ &= P(G) \int P(D \mid \boldsymbol{\theta}, G) p(\boldsymbol{\theta} \mid G) d\boldsymbol{\theta} \end{aligned}$$

$$P(G \mid D) = P(G) \prod_{i=1}^n \prod_{j=1}^{q_i} \frac{\Gamma(\alpha_{ij0})}{\Gamma(\alpha_{ij0} + m_{ij0})} \prod_{k=1}^{r_i} \frac{\Gamma(\alpha_{ijk} + m_{ijk})}{\Gamma(\alpha_{ijk})}$$

$$\log P(G \mid D)$$

$$= \log P(G) + \sum_{i=1}^n \sum_{j=1}^{q_i} \left( \log \left( \frac{\Gamma(\alpha_{ij0})}{\Gamma(\alpha_{ij0} + m_{ij0})} \right) + \sum_{k=1}^{r_i} \log \left( \frac{\Gamma(\alpha_{ijk} + m_{ijk})}{\Gamma(\alpha_{ijk})} \right) \right)$$

# Structure Learning

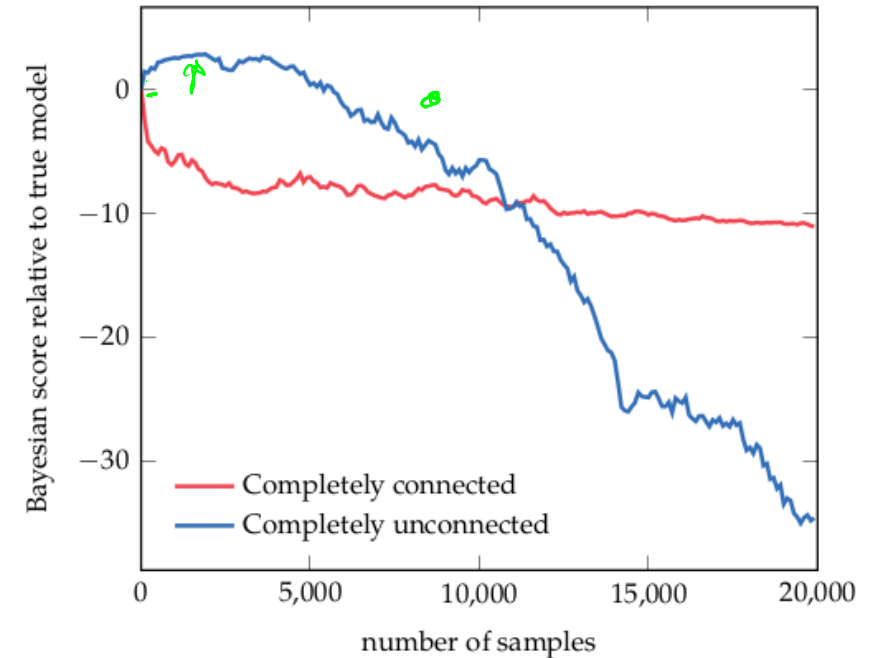
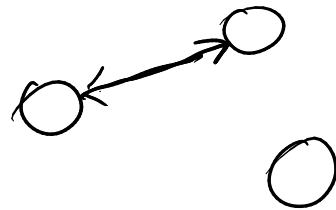
$$P(G | D) \propto P(G)P(D | G)$$

$$= P(G) \int P(D | \boldsymbol{\theta}, G) p(\boldsymbol{\theta} | G) d\boldsymbol{\theta}$$

$$P(G | D) = P(G) \prod_{i=1}^n \prod_{j=1}^{q_i} \frac{\Gamma(\alpha_{ij0})}{\Gamma(\alpha_{ij0} + m_{ij0})} \prod_{k=1}^{r_i} \frac{\Gamma(\alpha_{ijk} + m_{ijk})}{\Gamma(\alpha_{ijk})}$$

$$\log P(G | D) \quad \checkmark$$

$$= \log P(G) + \sum_{i=1}^n \sum_{j=1}^{q_i} \left( \log \left( \frac{\Gamma(\alpha_{ij0})}{\Gamma(\alpha_{ij0} + m_{ij0})} \right) + \sum_{k=1}^{r_i} \log \left( \frac{\Gamma(\alpha_{ijk} + m_{ijk})}{\Gamma(\alpha_{ijk})} \right) \right)$$



# Structure Learning

$$\begin{aligned} P(G \mid D) &\propto P(G)P(D \mid G) \\ &= P(G) \int P(D \mid \boldsymbol{\theta}, G) p(\boldsymbol{\theta} \mid G) d\boldsymbol{\theta} \end{aligned}$$

$$P(G \mid D) = P(G) \prod_{i=1}^n \prod_{j=1}^{q_i} \frac{\Gamma(\alpha_{ij0})}{\Gamma(\alpha_{ij0} + m_{ij0})} \prod_{k=1}^{r_i} \frac{\Gamma(\alpha_{ijk} + m_{ijk})}{\Gamma(\alpha_{ijk})}$$

$$\log P(G \mid D)$$

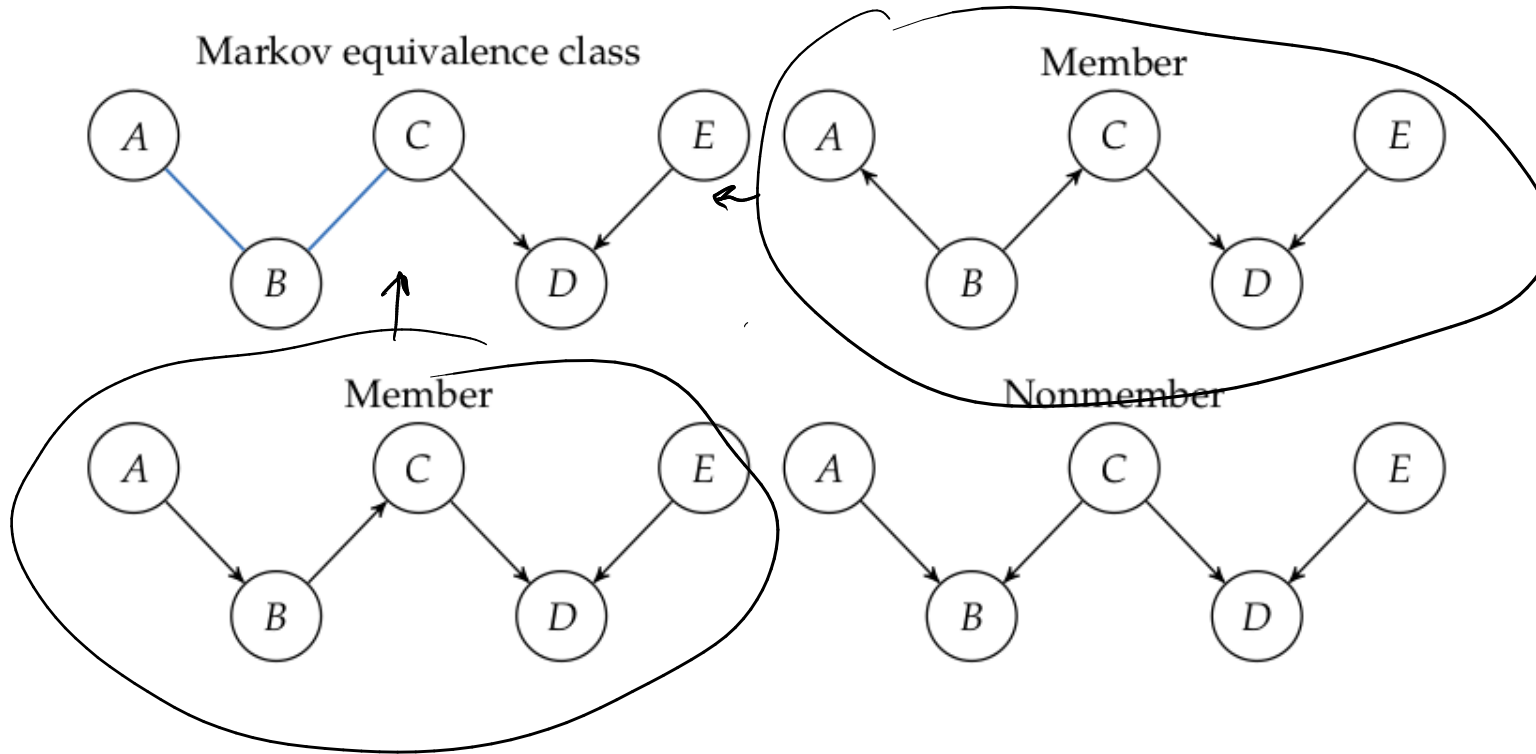
$$= \log P(G) + \sum_{i=1}^n \sum_{j=1}^{q_i} \left( \log \left( \frac{\Gamma(\alpha_{ij0})}{\Gamma(\alpha_{ij0} + m_{ij0})} \right) + \sum_{k=1}^{r_i} \log \left( \frac{\Gamma(\alpha_{ijk} + m_{ijk})}{\Gamma(\alpha_{ijk})} \right) \right)$$

NP-Hard

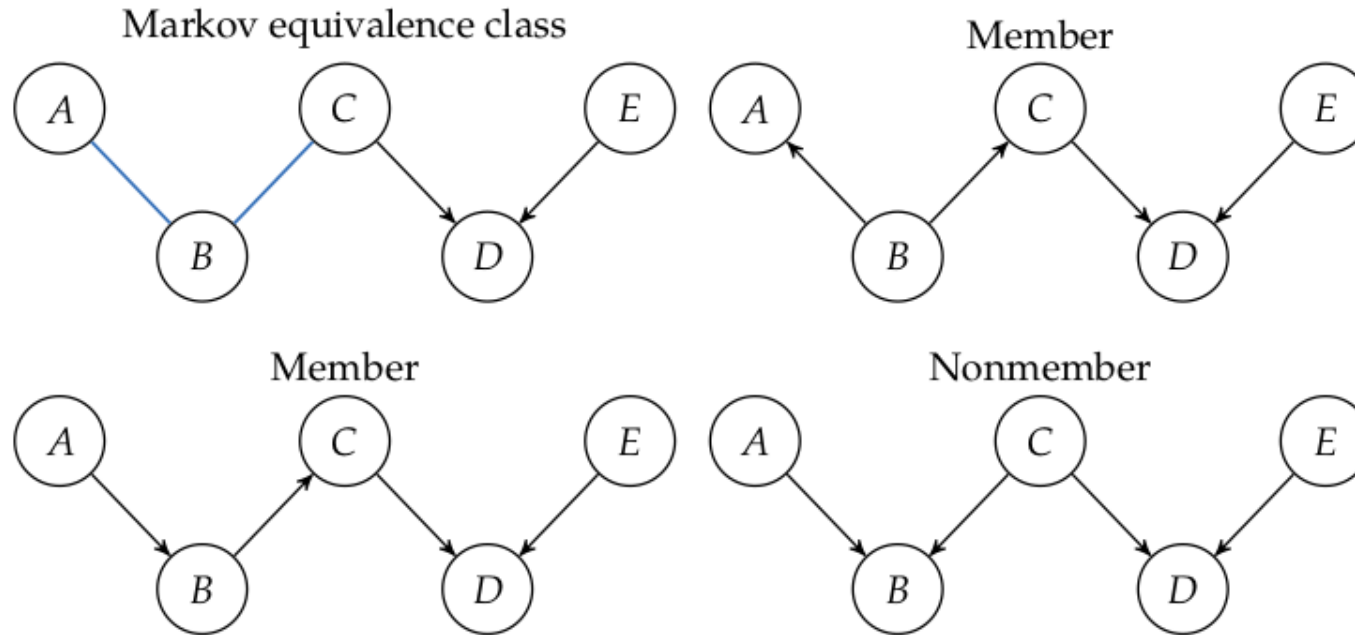
# Markov Equivalence Class



# Markov Equivalence Class

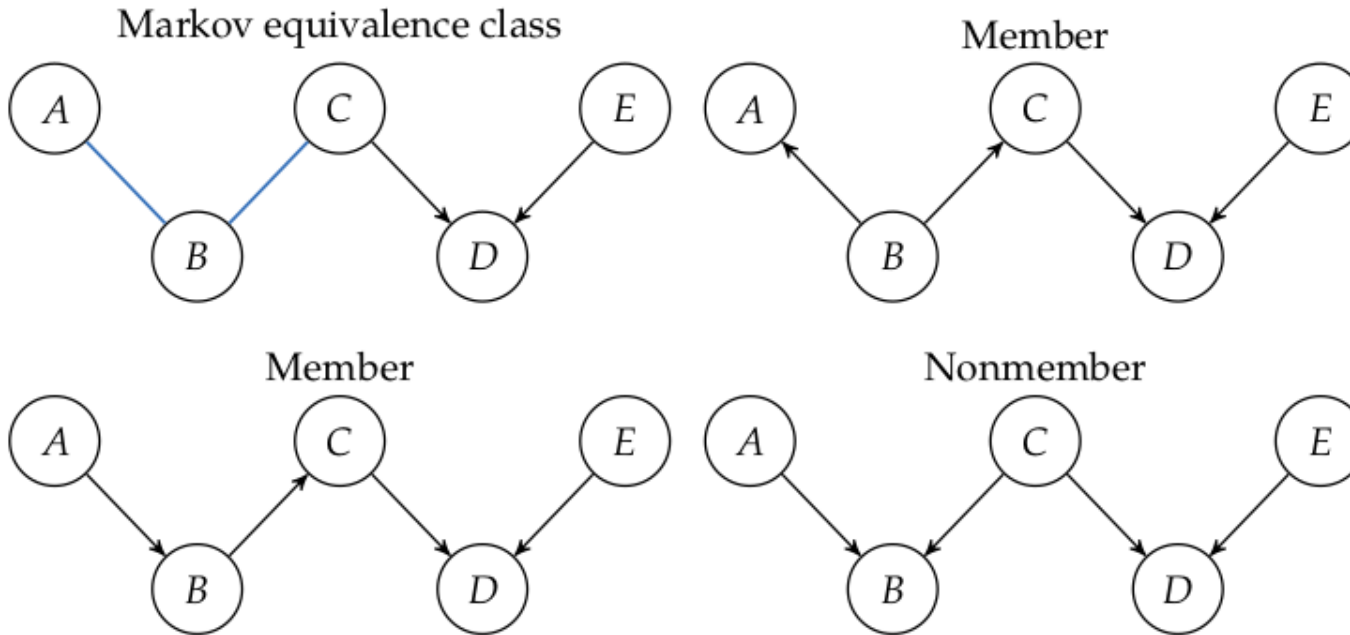


# Markov Equivalence Class



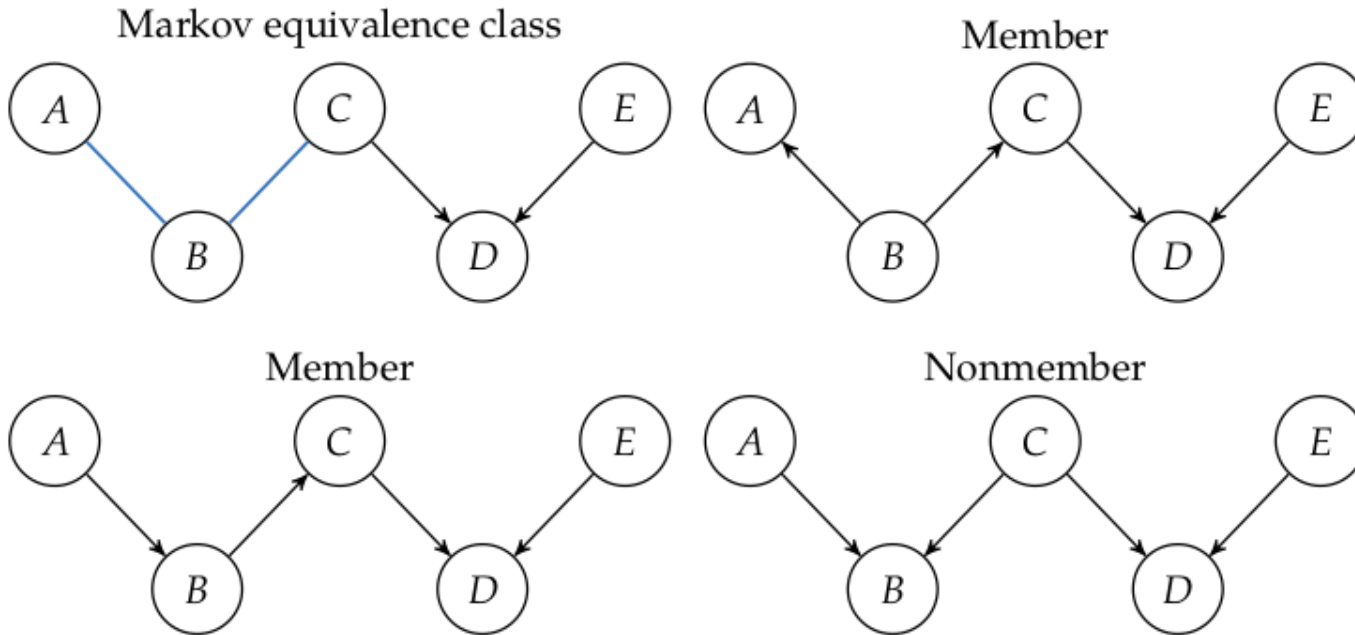
Markov Equivalent iff

# Markov Equivalence Class



Markov Equivalent iff  
1. Same undirected edges

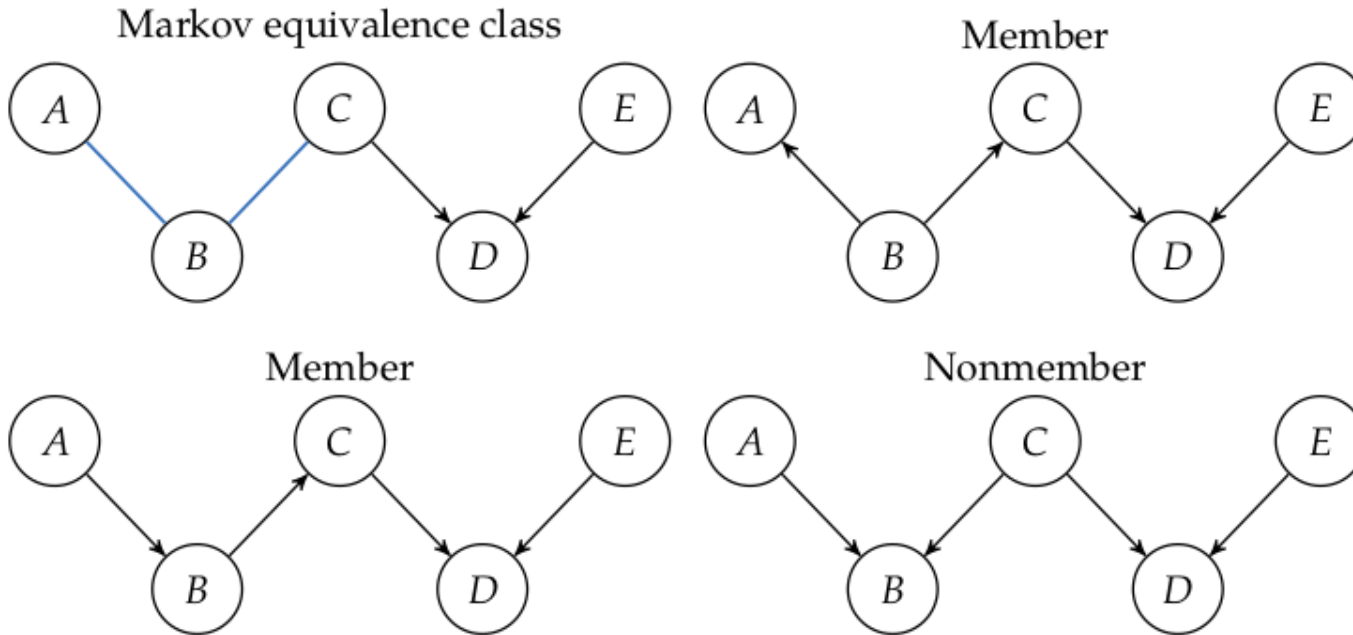
# Markov Equivalence Class



Markov Equivalent iff

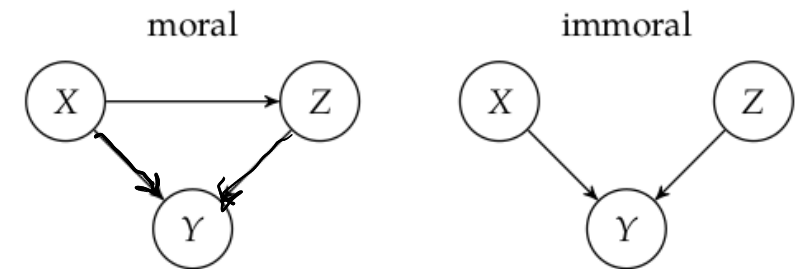
1. Same undirected edges
2. Same set of immoral v-structures

# Markov Equivalence Class



Markov Equivalent iff

1. Same undirected edges
2. Same set of immoral v-structures



# Recap

## Inference

Inputs

$G, \theta$ , evidence

Output

Probability of query variables  
given evidence

## Learning

Inputs

Data, Prior

Output

$G, \theta$