

▼ Zadatak - dan 2

Prikažite na videu:

- Redni broj frame-a
- Broj objekata po klasi za svaki frame (barem 2 klase)
- Broj svih objekata

▼ Priprema paketa

```
from IPython.display import clear_output
```

```
!pip3 install torch torchvision torchaudio --index-url https://download.pytorch.  
clear_output(wait=False)
```

```
!pip3 install ultralytics  
clear_output()
```

```
import torch  
from ultralytics import YOLO  
from PIL import Image  
import cv2  
import matplotlib.pyplot as plt  
import colorsys  
from IPython.display import HTML  
from base64 import b64encode  
import os  
import shutil
```

```
if torch.cuda.is_available():  
    # Get the default CUDA device  
    device = torch.device('cuda')  
    print(f'Device name: {torch.cuda.get_device_name(device)}')  
    print(f'Total memory available: {torch.cuda.get_device_properties(device).total_memory}')  
    print(f'CUDA version: {torch.version.cuda}')  
else:  
    print('CUDA is not available on this system.')  
  
Device name: Tesla T4  
Total memory available: 15.84 GB  
CUDA version: 11.8
```

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Looking in indexes: <https://pypi.org/simple>, <https://us-python.pkg.dev/colab-repository-us/python/pkgs>

✓ Os completed at 12:31 PM ● X

Requirement already satisfied: filelock in /usr/local/lib/python3.10/dist-packages
 Requirement already satisfied: requests[socks] in /usr/local/lib/python3.10/dist-packages
 Requirement already satisfied: six in /usr/local/lib/python3.10/dist-packages
 Requirement already satisfied: tqdm in /usr/local/lib/python3.10/dist-packages
 Requirement already satisfied: beautifulsoup4 in /usr/local/lib/python3.10/dist-packages
 Requirement already satisfied: soupsieve>1.2 in /usr/local/lib/python3.10/dist-packages
 Requirement already satisfied: urllib3<1.27,>=1.21.1 in /usr/local/lib/python3.10/dist-packages
 Requirement already satisfied: certifi>=2017.4.17 in /usr/local/lib/python3.10/dist-packages
 Requirement already satisfied: charset-normalizer~=2.0.0 in /usr/local/lib/python3.10/dist-packages
 Requirement already satisfied: idna<4,>=2.5 in /usr/local/lib/python3.10/dist-packages
 Requirement already satisfied: PySocks!=1.5.7,>=1.5.6 in /usr/local/lib/python3.10/dist-packages

```
import gdown
```

```
# Download the video file
file_id = '1Fd9Yq2LqEcLNjxfLr1RCxFV1lWAI4Af0'
url = f'https://drive.google.com/uc?id={file_id}'
output = '/content/test_vid.mp4' # Provide the desired output path and filename
gdown.download(url, output, quiet=False)
```

```
Downloading...
From: https://drive.google.com/uc?id=1Fd9Yq2LqEcLNjxfLr1RCxFV1lWAI4Af0
To: /content/test_vid.mp4
100%|██████████| 15.2M/15.2M [00:00<00:00, 127MB/s]
'/content/test_vid.mp4'
```

```
class Colors:
    # Ultralytics color palette https://ultralytics.com/
    def __init__(self):
        # hex = matplotlib.colors.TABLEAU_COLORS.values()
        hexs = ('FF3838', 'FF9D97', 'FF701F', 'FFB21D', 'CFD231', '48F90A', '92D050',
                '2C99A8', '00C2FF', '344593', '6473FF', '0018EC', '8438FF', '520082',
                'FF9966', 'FF3333', 'FF0000', '000000', 'FFFFFF', 'CCCCFF', '0000FF')
        self.palette = [self.hex2rgb(f'#{c}') for c in hexs]
        self.n = len(self.palette)

    def __call__(self, i, bgr=False):
        c = self.palette[int(i) % self.n]
        return (c[2], c[1], c[0]) if bgr else c

    @staticmethod
    def hex2rgb(h): # rgb order (PIL)
        return tuple(int(h[1 + i:1 + i + 2], 16) for i in (0, 2, 4))

colors = Colors()
```

YouTube video download

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Looking in indexes: <https://pypi.org/simple> <https://us-python-nk.dev/colab>

```
from pytube import YouTube
import os

def downloadYouTube(videourl, path, resolution="720p"):

    yt = YouTube(videourl)
    yt = yt.streams.filter(progressive=True, file_extension='mp4', resolution=resolution)
    if not os.path.exists(path):
        os.makedirs(path)
    yt.download(path, filename="smallcat.mp4")

#TODO stavite odgovarajući YouTube link te želejni filename
downloadYouTube('https://www.youtube.com/watch?v=W86cTIoMv2U', '/content', '720p')

# extract seconds worth of video frames of it
from IPython.display import clear_output
!yes Y | ffmpeg -ss 00:00:33 -i "/content/smallcat.mp4" -t 00:00:56 -c copy catcropped.avi
clear_output()

!yes Y | ffmpeg -i "/content/catcropped.avi" cropped_test.mp4
clear_output()
```

Model

```
# load model
model = YOLO("yolov8n.pt")
# set model parameters
model.conf = 0.25 # NMS confidence threshold
model.iou = 0.45 # NMS IoU threshold
model.agnostic = False # NMS class-agnostic
model.multi_label = False # NMS multiple labels per box
model.max_det = 1000 # maximum number of detections per image

classes = model.names
list(classes.values())[:10]
```

```
Downloading https://github.com/ultralytics/assets/releases/download/v0.0.0,
100%|██████████| 6.23M/6.23M [00:00<00:00, 151MB/s]
['person',
 'bicycle',
 'car',
 'motorcycle',
 'airplane',
 'bus',
 'train',
```

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Pomoćna dokumentacija

[cv2.putText\(\)](#)

Video inference

```
red = (255, 0, 0)
green = (0, 255, 0)
blue = (0, 0, 255)
yellow = (255, 255, 0)
orange = (0, 165, 255)
purple = (178, 102, 155)
```

```
classes = model.names
list(classes.values()) [15:30]
```

```
['cat',
 'dog',
 'horse',
 'sheep',
 'cow',
 'elephant',
 'bear',
 'zebra',
 'giraffe',
 'backpack',
 'umbrella',
 'handbag',
 'tie',
 'suitcase',
 'frisbee']
```

```
def draw_boxes(image, results):
    # TODO: variables init
    countercat = 0
    countertree = 0

    for result in results[0].boxes.data.to("cpu"):
        # unpacking model output
        x1, y1, x2, y2 = int(result[0]), int(result[1]), int(result[2]), int(result[3])
        conf = result[4]
        class_id = int(result[5])
        class_name = classes[class_id]

        # TODO: count by class
        for class_id in classes:
```

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```
        elif (class_name == 'tree'):
```

```
        countertree +=1

#drawing
cv2.rectangle(image, (x1,y1), (x2, y2), colors(class_id), 2)
label = f'{class_name} {conf:.2f}'
(w, h), _ = cv2.getTextSize(label, cv2.FONT_HERSHEY_SIMPLEX, 0.5, 2)
cv2.rectangle(image, (x1, y1-h-15), (x1+w, y1), colors(class_id), -1)
cv2.putText(image, label, (x1,y1-10), cv2.FONT_HERSHEY_SIMPLEX, 0.5, (255,255,255))

# TODO: drawing counts

    cv2.putText(image, countercat, (x1, y1), cv2.FONT_HERSHEY_SIMPLEX, 0.5, (255,255,255))

return image

# labels dir
labels_dir = 'labels'
if not os.path.exists(labels_dir):
    os.makedirs(labels_dir)
else:
    shutil.rmtree(labels_dir)

# Load the video
# TODO: put valid path
cap = cv2.VideoCapture('/content/cropped_test.mp4')

# Get the video properties
fps = cap.get(cv2.CAP_PROP_FPS)
width = int(cap.get(cv2.CAP_PROP_FRAME_WIDTH))
height = int(cap.get(cv2.CAP_PROP_FRAME_HEIGHT))

# Define the video writer
fourcc = cv2.VideoWriter_fourcc(*'MJPG')
out = cv2.VideoWriter('output.avi', fourcc, fps, (width, height))

# Loop through the frames of the video
frame_n = 0

while cap.isOpened():
    ret, frame = cap.read()

    if ret:
        frame_n += 1
        # TODO: put frame number on frame
        #.se
        # Process the frame here
        result = model(frame, verbose=False)
        frame = draw_boxes(frame, result)
        out.write(frame)
```

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```
#cv2.imshow(frame)

# Wait for the user to press a key (optional)
if cv2.waitKey(1) & 0xFF == ord('q'):
    break
else:
    break

# Release the video capture object and close all windows
cap.release()
cv2.destroyAllWindows()
```

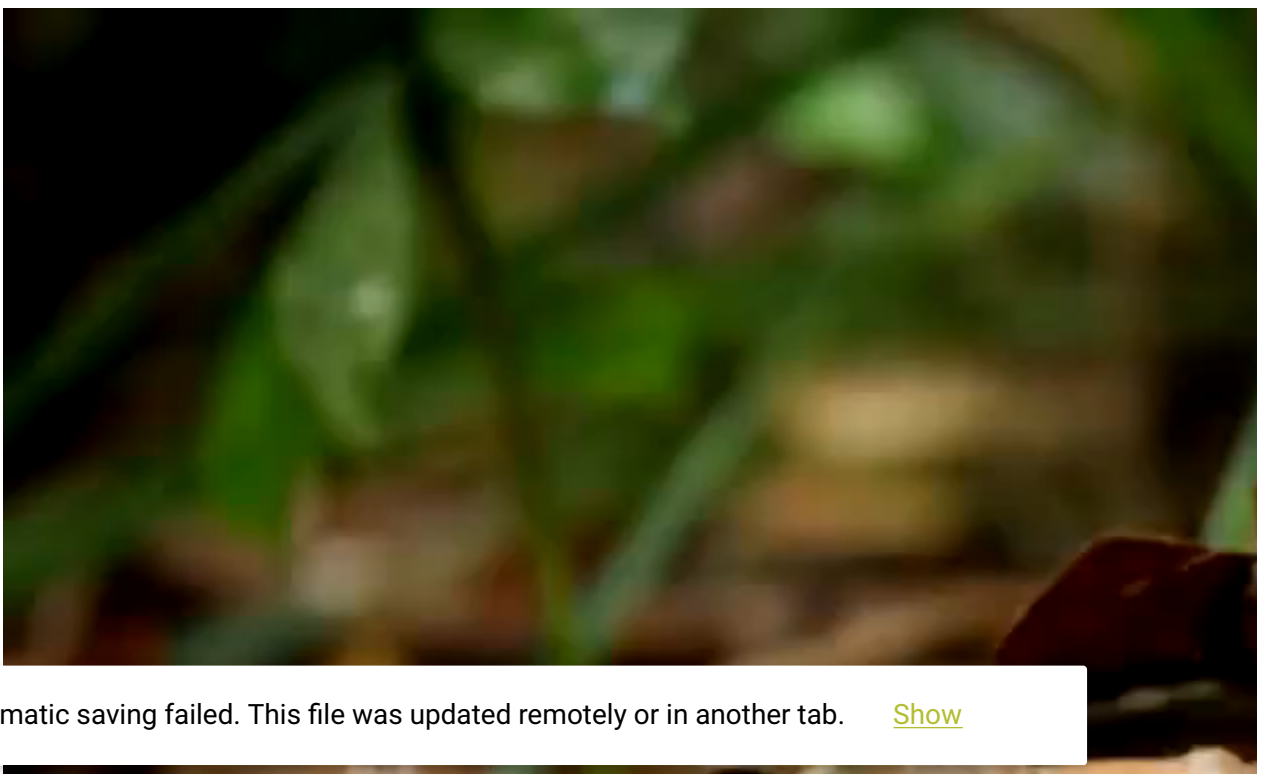
Double-click (or enter) to edit

Prikaz rezultata

```
# TODO: put valid path
!yes Y | ffmpeg -i "/content/output.avi" final.mp4
clear_output()

mp4 = open('/content/final.mp4','rb').read()
data_url = "data:video/mp4;base64," + b64encode(mp4).decode()

HTML("""
<video controls>
  <source src="%s" type="video/mp4">
</video>
""" % data_url)
```



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Zadatak 2 - detekcija određenog područja

Alat za pregled koordinata na slici: [pixspy](#)

- Dohvatite prvi frame pomoću ćelije koda ispod te pomoću pixspy provjerite željene točke za pravokutnik (x1, y1), (x2, y2)
- Spremite točke u **globalnu** varijablu npr. rectangle = (x1, y1, x2, y2)
- Iscrtajte pravokutnik na svakom učitanoj frame-u videa
- Odredite centar objekta i iscrtajte ga funkcijom [cv2.circle](#)(frame, (x,y), radius, color, thickness)
- Pripremite funkciju koja će provjeravati nalazi li se centar objekta unutar pravokutnika
- Provjerite detektiraju li se objekti zaista samo u području pravokutnika

```
# TODO: put valid path
cap = cv2.VideoCapture("path_to_vid")
ret, frame = cap.read()
if ret:
    cv2.imwrite("fframe.jpg", frame)
cap.release()
cv2.destroyAllWindows()
```

```
rectangle = (0,0,0,0)
```

```
# TODO: Additional functions (optional)
```

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```
def draw_boxes(image, results):
    # TODO:variables initialization

    for result in results[0].boxes.data.to("cpu"):
        # unpacking model output
        x1, y1, x2, y2 = int(result[0]), int(result[1]), int(result[2]), int(r
        conf = result[4]
        class_id = int(result[5])
        class_name = classes[class_id]

        # TODO: check if is in area

        #drawing
        cv2.rectangle(image, (x1,y1), (x2, y2), colors(class_id), 2)
        label = f'{class_name} {conf:.2f}'
        (w, h), _ = cv2.getTextSize(label, cv2.FONT_HERSHEY_SIMPLEX, 0.5, 2)
        cv2.rectangle(image, (x1, y1-h-15), (x1+w, y1), colors(class_id), -1)
        cv2.putText(image, label, (x1,y1-10), cv2.FONT_HERSHEY_SIMPLEX, 0.5, (

    # TODO:drawing counts

    return image

# Rectangle coordinates as a global variable
# rect = (600,395,1230,969)

# labels dir
labels_dir = 'labels'
if not os.path.exists(labels_dir):
    os.makedirs(labels_dir)
else:
    shutil.rmtree(labels_dir)

# Load the video
# TODO: put valid path
cap = cv2.VideoCapture('/content/test_vid.mp4')

# Get the video properties
fps = cap.get(cv2.CAP_PROP_FPS)
width = int(cap.get(cv2.CAP_PROP_FRAME_WIDTH))
height = int(cap.get(cv2.CAP_PROP_FRAME_HEIGHT))

# Define the video writer
fourcc = cv2.VideoWriter_fourcc(*'MJPG')
out = cv2.VideoWriter('output_area.avi', fourcc, fps, (width, height))

# Loop through the frames of the video
frame n = 0
```

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```
if ret:
    frame_n += 1
    # TODO: draw rectangle on each frame

    # Process the frame here
    result = model(frame, verbose=False)
    frame = draw_boxes(frame, result)
    out.write(frame)

    # save results
    # result[0].save_txt(f'{labels_dir}/{frame_n}.txt')
    # Show the frame
    # cv2_imshow(frame)

    # Wait for the user to press a key (optional)
    if cv2.waitKey(1) & 0xFF == ord('q'):
        break
else:
    break

# Release the video capture object and close all windows
cap.release()
cv2.destroyAllWindows()

# TODO: put valid path
!yes Y | ffmpeg -i "/content/output_area.avi" final_area.mp4
clear_output()

# TODO: put valid path
mp4 = open('/content/final_area.mp4', 'rb').read()
data_url = "data:video/mp4;base64," + b64encode(mp4).decode()

HTML("""
<video controls>
    <source src="%s" type="video/mp4">
</video>
""") % data_url)
```

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