

RobWork EasyInsert-plugin Survey

Name:

Title:

Occupation:

Questions:

1. Relationship regarding RW:
2. Do you recognize the problem that EasyInsert seeks to resolve?
3. How do you expect to use the plugin?
 - a. Access to the loadable objects? (browser, pop-up.. etc.) (draw)
 - i. layout for the browser? (in detail)
 - b. Drag and drop, load button.. etc?
 - c. Selection description? (images, text.. etc.)
 - d. Extending the library? (if one)
 - i. Standard objects?
4. Remove objects from the workcell?
 - a. Undo button?

Changing the configurations of the simulated robot in an intuitive matter, involving cursor interaction pulling the robot into the desired position.

Adding tools or end effector to a simulated robot in a drag and drop-like feature. The tool should then be able to snap onto various parts of the robot.