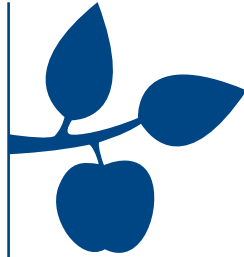


BACHELOR



UNIVERSITY OF SOUTHERN DENMARK

EXTENDED USER INTERFACE AND SIMPLIFICATION OF THE
INTERACTIONS WITH ROBWORK

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Course code: RB-BAP6-U1
Project title: Extended user interface and simplification of the interactions with RobWork
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Project period: 1. of february – Sometime in 2017
Number of pages: 2 pages
Character count: 48,000 (excl. references, appendices etc.)
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Abstract

Your abstract goes here... ...

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Foreword

- The foreword page should describe the aim of the thesis, and its various research stages, and present the partners, funding and circumstances involved in the thesis project. The forewords should also include words of gratitude, addressed to people who have been incremental in your thesis-writing process. The supervisor, the second examiner, and the technical supervisor can be mentioned as well.

List of Abbreviations and Symbols

RW	RobWork
RWS	RobWorkStudio
Diller	Greger

1 Introduction

- Describe the background and motivation of your thesis
- Describe in detail the objectives of your thesis (i.e. what is your aim to achieve), and on what basis the scope of your research area has been chosen
- At the end of the introduction, you might want to give an overview about the structure of your thesis

RobWork is a collection of C++ libraries for simulation and control of robot systems. RobWork is used for research and education as well as for practical robot applications. It has been noted that there exists different tedious processes of editing the environment of the RobWork simulation, involving reconfiguring files, unintuitive user interaction or reloading software. If some of these processes can be shortened or made more intuitive, the user experience of RobWork would greatly benefit from it. An example of an above-mentioned process: Adding a specific object to the environment of a simulated robot requires altering an .XML file and reloading RobWork. To specify goals for this bachelor project, the following features to implement is stated in order of importance:

- A user interface to initialize and load objects into the environment of RobWork with a simple drag and drop-like feature.
- Changing the configurations of the simulated robot in an intuitive matter, involving cursor interaction pulling the robot into the desired position.
- Adding tools or end effector to a simulated robot in a drag and drop-like feature. The tool should then be able to snap unto various parts of the robot.

With skills and experience within software development, object oriented C++ and various programming oriented skills, the authors of this project will try to solve and implement the goals stated. The first step of the project would be to become familiar with RobWork and learn how the source code works. The next step is to design the software for the first feature and disclose a possible solution. The third step is to implement the first feature and test it. The success criteria for the project is a finished, tested and working feature for RobWork of the before mentioned first goal set for this project. If this criterion is met early, the project would continue in similar manner with the second and third feature.

2 Chapter 1

2.1 We write shit

shit shit shit shit