# Multiresolution Analysis and Fast Wavelet Transform

Fondamenti di elaborazione del segnale multi-dimensionale

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#### **Motivations**

- ► CWT has valuable properties for signal processing.
- ► However, the use of CWT requires some approximations:
  - inner product computation;
  - scale and translation parameters sampling.
- ▶ A discrete version of wavelet transform (i.e., a wavelet transform that operates with only a dyadic set of wavelets and on a discrete set of samples of the signal) is possible: the Discrete Wavelet Transform (DWT).
- ► The theory that allows to obtain such a transform is better explained starting from the Multi-Resolution Analysis (MRA).
- ▶ A fundamental result of the MRA theory is that, under some conditions, the DWT can be obtained through a digital filtering operation.
- ► This transform is computationally very efficient and, for this reason, it is called Fast Wavelet Transform (FWT).



# Multiresolution Analysis — Overview

▶ A Multiresolution Analysis (MRA) defines a sequence of nested spaces of functions, {V<sub>j</sub>}:

$$\cdots \subset V_{-1} \subset V_0 \subset V_1 \subset \cdots \subset V_j \subset V_{j+1} \subset \cdots$$

such that lower the index, smoother the functions that belong to the space.

- ▶ This sequence will, at the end, cover the space of the finite energy functions,  $L^2(\mathbb{R})$ .
- ▶ For each function  $f \in L^2(\mathbb{R})$ , the best approximation,  $P_j[f]$ , in each space,  $V_j$ , can be defined by projecting the function onto this space.
- ▶ Hence, a sequence of approximating functions,  $\{P_j[f]\}$ , is obtained, such that:

$$\lim_{j\to\infty} P_j[f] = f$$



# Multiresolution Analysis — Overview (2)

► The difference between two consecutive approximations represents the details that are added:

$$Q_{j}[f] = P_{j+1}[f] - P_{j}[f]$$

and can be obtained as the projection of the function f onto an appropriate detail space,  $W_j$ .

► Hence, the function *f* can be represented by summing the sequence of the detail projections:

$$f = \sum_{j} Q_{j}[f]$$

▶ The basis of the  $W_j$ 's spaces are the wavelets.



# Scaling functions — Approximation spaces

A Multiresolution Analysis (MRA) of  $L^2(\mathbb{R})$  is defined as the sequence of closed subspaces  $V_j \in L^2(\mathbb{R})$ ,  $j \in \mathbb{Z}$ , which have the following properties:

- 1.  $V_i \subset V_{i+1}$
- 2.  $v(x) \in V_i \Leftrightarrow v(2x) \in V_{i+1}$
- 3.  $v(x) \in V_0 \Leftrightarrow v(x+1) \in V_0$
- 4.  $\bigcup_{j=-\infty}^{\infty} V_j$  is dense in  $L^2(\mathbb{R})$  and  $\bigcap_{j=-\infty}^{\infty} V_j = \{0\}$
- 5. There is a function  $\varphi(x) \in V_0$ , having non null integral, such that the set  $\{(\varphi(x-k)|k \in \mathbb{Z})\}$  is a Riesz basis for  $V_0$ .

The function  $\varphi(\cdot)$  is called *scaling function*.



# Scaling functions — Approximation spaces (2)

There is a sequence  $\{h_k\} \in I^2(\mathbb{Z})$  for which the scaling function satisfies:

$$\varphi(x) = 2\sum_{k} h_{k} \, \varphi(2x - k)$$

- ▶ The relation is called the *refinement equation*;
  - ▶ aka dilation equation or two-scale difference equation
- Defining

$$\varphi_{j,k}(x) = \sqrt{2^j}\,\varphi(2^j x - k)$$

it can be shown that  $\{ \varphi_{j,k}(x) \, | \, k \in \mathbb{Z} \}$  is a Riesz basis for  $V_j$ 

▶ Hence,  $\{\varphi_{j,k}(x) | j, k \in \mathbb{Z}\}$  is a Riesz basis for  $L^2(\mathbb{R})$ 



# Scaling functions — Approximation spaces (3)

Hence there are at least three ways to build or identify a MRA:

- ▶ through the description of the V<sub>i</sub>s spaces;
- by means of the scaling function,  $\varphi$ ;
- ▶ through the coefficients  $\{h_k\}$  of the refinement equation.

As it will be shown, in order to obtain an approximation, the coefficients  $\{h_k\}$  can be used directly.

- ▶ It is efficient.
- ▶ There is no need of using the scaling function.

However, a more detailed characterization of these coefficients is required.



# Properties of the scaling functions

▶ It can be shown that:

$$\sum_k h_k = 1$$

▶ The normalization is a condition usually required:

$$\int_{-\infty}^{\infty} \varphi(x) \, \mathrm{d}x = 1$$

▶ In the frequency domain, this condition is equivalent to:

$$\hat{\varphi}(0) = 1$$

From the refinement equation and the normalization condition, the scaling function is uniquely determined.



# Properties of the scaling functions (2)

► In order to be able to approximate simple function (e.g., constants), it is useful to assume that:

$$\forall x \in \mathbb{R}, \ \sum_{k} \varphi(x-k) = 1$$

- the scaling function and its integer translates partition the unit.
- ► This condition is equivalent to:

$$\hat{\varphi}(2\pi k) = 0, \ k \in \mathbb{Z}, \ k \neq 0$$

• or  $\hat{\varphi}(2\pi k) = \delta$ ,  $k \in \mathbb{Z}$ , due to  $\hat{\varphi}(0) = 1$ .



# Properties of the scaling functions (3)

▶ From the refinement equation,  $\varphi(x) = 2 \sum_k h_k \varphi(2x - k)$ :

$$\hat{\varphi}(\nu) = H(\nu/2)\hat{\varphi}(\nu/2)$$

where H is a  $2\pi$ -periodic function defined as:

$$H(\nu) = \sum_{k} h_{k} e^{-\iota k \nu}$$

• Since  $\hat{\varphi}(0) = 1$ , the recursion on the above property produces:

$$\hat{\varphi}(\nu) = \prod_{j=1}^{\infty} H(2^{-j}\nu)$$

This relation can be used for obtaining  $\varphi$  from  $\{h_k\}$ .



# Properties of the scaling functions (4)

- ▶ It can be shown that H(0) = 1.
  - E.g., from  $\hat{\varphi}(\nu) = H(\nu/2)\hat{\varphi}(\nu/2)$ .
- ► It can also be shown that a condition for the partition of the unity is:

$$H(\pi) = 0$$
 or  $\sum_{k} (-1)^{k} h_{k} = 0$ 



# Approximation at the j-th scale

For each function, its approximation can be obtained projecting it onto an approximation space:

$$\forall f(\cdot) \in L^2(\mathbb{R}), \lim_{j \to \infty} P_j[f(\cdot)] = f(\cdot)$$

$$P_{j}[f(x)] = \sum_{k} \lambda_{j,k} \, \varphi_{j,k}(x)$$

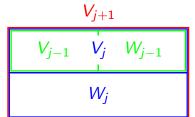
for some  $\{\lambda_{j,k}\}$ .



# Wavelets — Detail spaces

Let  $W_j$  be the complementary space of  $V_j$  in  $V_{j+1}$ , i.e., the space that satisfies:

$$V_{j+1} = V_j \oplus W_j$$
  
=  $\{v_j + w_j \mid v_j \in V_j, w_j \in W_j\}$ 



The space  $W_j$  contains the information about the "details" required for moving from a j-resolution approximation to the j+1-resolution one. As a consequence:

$$\bigoplus_{j} W_{j} = L^{2}(\mathbb{R})$$



#### Wavelets — Details space (2)

A function  $\psi(\cdot)$  is a wavelet if the set of functions  $\{\psi(x-k) \mid k \in \mathbb{Z}\}$  is a Riesz basis for the wavelet space  $W_0$ .

$$\{\psi_{j,k}(x) \mid j,k \in \mathbb{Z}\}$$
, where  $\psi_{j,k}(x) = \sqrt{2^j} \, \psi(2^j x - k)$ , is a Riesz bases for  $L^2(\mathbb{R})$ .

Since  $\psi \in V_1$ , there is a sequence  $\{g_k\} \in l^2(\mathbb{Z})$  such that:

$$\psi_{0,0}(x) = \psi(x) = 2\sum_{k} g_{k} \varphi(2x - k)$$

The function  $\psi(\cdot)$  is called *mother wavelet*.



# Properties of the wavelets

▶ The Fourier transform of the wavelet is:

$$\hat{\psi}(\nu) = G(\nu/2)\,\hat{\psi}(\nu/2)$$

where G is a  $2\pi$ -periodic function given by:

$$G(\nu) = \sum_{k} g_{k} e^{-\iota k \nu}$$



# Detail at the *j*-th scale

As for the approximation, the detail at a given scale can be obtained by projecting the function onto a proper wavelet space:

$$\forall f(x) \in L^2(\mathbb{R})$$
:

$$f(x) = \sum_{j} Q_{j}[f(x)] = \sum_{j,k} \gamma_{j,k} \psi_{j,k}(x)$$

#### Notes:

- ► The above equation is a "discrete" (in the scale and position parameters) inverse wavelet transform.
- ▶ The computational cost for computing the coefficients  $\{\gamma_{j,k}\}$  depends by the properties of the wavelets and scaling functions.



#### Orthogonal wavelets

- ► The use of an orthogonal basis is particularly interesting as it allows to decompose a function in uncorrelated elements.
- ▶ In this case, the coefficient  $\lambda_{j,k}$  are obtained by the orthogonal projection of the function f onto the basis element  $\varphi_{j,k}$ :

$$P_{j}[f(x)] = \sum_{k} \langle f, \varphi_{j,k} \rangle \varphi_{j,k}(x)$$

▶  $P_j[f(\cdot)]$  is the best representation of  $f(\cdot)$  in  $V_j$ , as:

$$\forall g \in V_j, ||g - f|| \ge ||P_j[f] - f||$$

▶ Similarly, if the wavelets  $\{\psi_{j,k}\}$  form an orthogonal basis for  $W_j$ , the projection  $Q_j$  is an orthogonal projection and the coefficient  $\gamma_{j,k}$  can be obtained by orthogonally projecting f onto  $\psi_{j,k}$ :

$$Q_{j}[f(x)] = \sum_{k} \langle f, \psi_{j,k} \rangle \, \psi_{j,k}(x)$$



# Orthogonal wavelets (2)

- ▶ A MRA where the wavelet spaces  $W_j$  are defined as the orthogonal complement of  $V_i$  in  $V_{i+1}$ .
  - As a consequence, the wavelet spaces,  $\{W_j\}$ , are mutually orthogonal,
  - $\triangleright$  the above defined projections  $P_i$  and  $Q_i$  are orthogonal, and
  - the expansion

$$f(x) = \sum_{j} Q_{j}[f(x)]$$

is an expansion of orthogonal functions.

▶ If the above mentioned conditions on the scaling function are satisfied, a sufficient condition for the orthogonality of a MRA is:

$$W_0 \perp V_0$$

or

$$\langle \psi(x), \varphi(x-k) \rangle = 0$$



#### Orthogonal wavelets (3)

▶ Under mild conditions,  $\langle \psi(x), \varphi(x-k) \rangle = 0$  is equivalent to:

$$orall 
u \in \mathbb{R}, \; \sum_{\mathbf{k}} \hat{\psi}(
u + 2k\pi) \overline{\hat{\varphi}}(
u + 2k\pi) = 0$$

In order to investigate on the properties of the orthogonal wavelets and scaling functions, the following  $2\pi$ -periodic function is introduced:

$$F(\nu) = \sum_{k} |\hat{\varphi}(\nu + 2k\pi)|^2$$

▶ Since  $\{\varphi(x-k) \mid k \in \mathbb{Z}\}$  is a Riesz basis, there are two constants A and B such that:

$$0 < A \le F(\nu) \le B < \infty$$

i.e.,  $F(\cdot)$  is bounded (and the bounds do not depend on  $\nu$ ).



#### Orthogonal wavelets (4)

▶ Since  $\hat{\varphi}(\nu) = H(\nu/2) \, \hat{\varphi}(\nu/2)$ , it derives:

$$F(2\nu) = |H(\nu)|^2 F(\nu) + |H(\nu + \pi)|^2 F(\nu + \pi)$$

which shows that F is actually  $\pi$ -periodic.

▶ The scaling function is orthogonal when

$$\langle \varphi(x), \varphi(x-k) \rangle = \delta_k, \ k \in \mathbb{Z}$$

In this case,  $\{\varphi_{j,k} \mid k \in \mathbb{Z}\}$  is an orthonormal basis for  $V_j$ .

Under mild conditions, the above relation is equivalent to:

$$\forall \nu \in \mathbb{R}, \; \sum_{k} |\hat{\varphi}(\nu + 2k\pi)|^2 = F(\nu) = 1$$

Hence

$$\forall \nu \in \mathbb{R}, \ |H(\nu)|^2 + |H(\nu + \pi)|^2 = 1$$

which is equivalent to

$$\forall k \in \mathbb{Z}, \ \sum_{j} h_{j} h_{j-2k} = \frac{\delta_{k}}{2}$$

#### Orthogonal wavelets (5)

- ▶  $\sum_{j} h_{j} h_{j-2k} = \frac{\delta_{k}}{2}$  and  $\langle \varphi(x), \varphi(x-k) \rangle = \delta_{k}$  describe the orthogonality necessary conditions in the time domain;
- ▶  $\sum_{k} |\hat{\varphi}(x+2k\pi)|^2 = 1$  and  $|H(\nu)|^2 + |H(\nu+\pi)|^2 = 1$  describes the orthogonality necessary conditions in the frequency domain.
- These conditions can be used to build orthogonal scaling functions.
- ▶ Similarly, the basis  $\{\psi_{j,k} \,|\, k \in \mathbb{Z}\}$  is an orthonormal basis for  $W_0$  if

$$\langle \psi(\mathbf{x}), \psi(\mathbf{x} - \mathbf{k}) \rangle = \delta_{\mathbf{k}}$$

or, equivalently

$$\sum_{\nu} |\hat{\psi}(\nu + 2k\pi)|^2 = 1$$

from which results the necessary condition:

$$|G(\nu)|^2 + |G(\nu + \pi)|^2 = 1$$



# Orthogonal wavelets (6)

- ► The *G* function (and, hence the *g* coefficients), can be better characterized.
- ▶ It can be shown that

$$\forall \nu \in \mathbb{R}, \ G(\nu) \, \overline{H}(\nu) + G(\nu + \pi) \, \overline{H}(\nu + \pi) = 0$$

▶ An important result [Mallat, 1989] show that

$$G(\nu) = A(\nu)\bar{H}(\nu + \pi)$$

where A is a  $2\pi$  periodic function such that:

$$A(\nu + \pi) = -A(\nu)$$

With the above conditions.

$$|A(\nu)| = 1$$

▶ Hence, the above relations allow to build an orthogonal wavelet given the orthogonal scaling function, for a chosen A.

# Orthogonal wavelets (7)

- ► For practical uses, the compactness of the wavelet and scaling function is very important.
- ▶ It can be shown that this can be obtained for

$$A(\nu) = Ce^{-(2k+1)\nu}$$
, for  $|C| = 1$  and  $k \in \mathbb{Z}$ 

The standard choice is

$$A(\nu) = e^{-\iota\nu}$$

for which G and H are the transfer functions of a pair of quadrature mirror filters:

$$g_k = (-1)^k \, \bar{h}_k$$

▶ This choice has also the advantage of yielding real coefficients  $g_k$ s, provided that also  $h_k$ s are reals.



# Biorthogonal wavelets

- ► The orthogonality puts strong limitation on the construction of the wavelets (e.g., on compactness of the wavelets).
- More flexibility can be achieved by using biorthogonal wavelets.
- ► The definition on a compact domain allows for an accurate implementation of the transform.
- ► In this case, the wavelet and the scaling function are represented by FIR filters,
  - $ightharpoonup h_k$  and  $g_k$  have a finite number of non-null coefficients.



# Biorthogonal wavelets — Dual spaces

- ▶ The biorthogonal MRA requires the existence of a *dual scaling* function,  $\tilde{\varphi}$ , and a *dual wavelet*,  $\tilde{\psi}$ .
- ▶ They generate a dual multiresolution analysis with subspaces  $\tilde{V}_i$  and  $\tilde{W}_i$  such that:

$$ilde{V}_j \perp W_j$$
 and  $V_j \perp ilde{W}_j$ 

► Hence

$$\tilde{W}_j \perp W_{j'}$$
 for  $j' \neq j$ 

► The above orthogonality relations imply:

$$\langle \tilde{\varphi}(x), \psi(x-k) \rangle = \langle \tilde{\psi}(x), \varphi(x-k) \rangle = 0$$



# Biorthogonal wavelets — Dual spaces (2)

Moreover:

$$\langle \tilde{\varphi}_{j,l}, \, \varphi_{j,k} \rangle = \delta_{l-k} \quad j, k, l \in \mathbb{Z}$$
$$\langle \tilde{\psi}_{j,l}, \, \psi_{i,k} \rangle = \delta_{j-i} \delta_{l-k} \quad j, k, l \in \mathbb{Z}$$

► In particular

$$\langle \tilde{\varphi}(x), \, \varphi(x-k) \rangle = \delta_k \quad k \in \mathbb{Z}$$

$$\langle \tilde{\psi}(\mathsf{x}), \, \psi(\mathsf{x} - \mathsf{k}) \rangle = \delta_{\mathsf{k}} \quad \mathsf{k} \in \mathbb{Z}$$

➤ The properties of the dual wavelet and scaling function, are similar to those of the wavelet and scaling function, respectively.



#### Biorthogonal wavelets — Dual spaces (3)

- ▶ The role of primal and dual MRA is interchangeable:
  - both can have the role of the primal or the dual MRA;
  - the effects on the transform and the inverse will depend on the characteristics of the primal and the dual.
- ► However, the biorthogonal MRA maintains the main advantage of the orthogonal MRA:
  - the coefficients can be computed by means of orthogonal projections;
  - the dual MRA is used for computing the transform (analysis MRA);
  - ▶ the primal MRA is used reconstructing the signal from the transform coefficients (synthesis).
- ▶ The projection operator  $P_i$  and  $Q_i$  are here defined as:

$$P_{j}[f(x)] = \sum_{k} \langle f, \tilde{\varphi}_{j,k} \rangle \varphi_{j,k}(x)$$

and

$$Q_{j}[f(x)] = \sum_{k} \langle f, \tilde{\psi}_{j,k} \rangle \, \psi_{j,k}(x)$$



# Biorthogonal wavelets — Dual spaces (4)

► Hence, the discrete wavelet transform is:

$$f(x) = \sum_{j,k} \langle f, \tilde{\psi}_{j,k} \rangle \psi_{j,k}(x)$$

Properties and conditions similar to those obtained to the orthogonal MRA can be obtained. In particular:

$$ilde{arphi}(x)=2\sum_{k} ilde{h}_{k} ilde{arphi}(2x-k) ext{ and } ilde{\psi}(x)=2\sum_{k} ilde{g}_{k} ilde{\psi}(2x-k)$$

from which can be obtained

$$\tilde{h}_{k-2l} = \langle \tilde{\varphi}(x-l), \varphi(2x-k) \rangle$$
 and  $\tilde{g}_{k-2l} = \langle \tilde{\psi}(x-l), \varphi(2x-k) \rangle$ 



#### Biorthogonal wavelets — Dual spaces (5)

▶ In particular, by writing  $\varphi(2x - k) \in V_1$  as element of  $V_0$  and  $W_0$ :

$$\varphi(2x-k) = \sum_{l} \tilde{h}_{k-2l} \varphi(x-l) + \sum_{l} \tilde{g}_{k-2l} \psi(x-l)$$

▶ By imposing that  $h_k$ ,  $g_k$ ,  $\tilde{h}_k$ ,  $\tilde{g}_k$  have finite components, it can be shown that, under mild conditions:

$$ilde{G}(
u)=e^{-\iota
u}ar{H}(
u+\pi) ext{ and } G(
u)=e^{-\iota
u}ar{ ilde{H}}(
u+\pi)$$

The properties of the orthogonal and biorthogonal MRA can be used to formulate an efficient algorithm for computing the wavelet transform and its inverse.



#### Fast Wavelet Transform

As  $V_j = V_{j-1} \oplus W_{j-1}$ ,  $v_j \in V_j$  can be uniquely write as sum of a function  $v_{j-1} \in V_{j-1}$  and a function  $w_{j-1} \in W_{j-1}$ :

$$v_{j}(x) = \sum_{k} \lambda_{j,k} \varphi_{j,k}(x) = v_{j-1}(x) + w_{j-1}(x)$$
$$= \sum_{k} \lambda_{j-1,k} \varphi_{j-1,k}(x) + \sum_{k} \gamma_{j-1,k} \psi_{j-1,k}(t)$$

for proper coefficients  $\{\lambda_{j,k}\}$ ,  $\{\lambda_{j-1,k}\}$ ,  $\{\gamma_{j-1,k}\}$ .

- ▶ Hence the same function  $v_j$  can be represented either by means the sequence  $\{\lambda_{j,k}\}$ , and by the sequences  $\{\lambda_{j-1,k}\}$   $\{\gamma_{j-1,k}\}$ .
- ► This is a key relation for obtaining an efficient algorithm for the analysis and synthesis.



# Fast Wavelet Transform (2)

► In fact:

$$\lambda_{j-1,l} = \langle v_j, \tilde{\varphi}_{j-1,l} \rangle = \sqrt{(2)} \langle v_j, \sum_k \tilde{h}_{k-2l} \tilde{\varphi}_{j-1,l} \rangle$$
$$= \sqrt{2} \sum_k \tilde{h}_{k-2l} \lambda_{k-2l}$$

and, similarly,

$$\gamma_{j-1,l} = \sqrt{2} \sum_{k} \tilde{g}_{k-2l} \, \lambda_{k-2l}$$

The refinement equations allow to obtain the inverse transform:

$$\lambda_{j,k} = \sqrt{2} \sum_{l} h_{k-2l} \lambda_{j-1,l} + g_{k-2l} \gamma_{j-1,l}$$

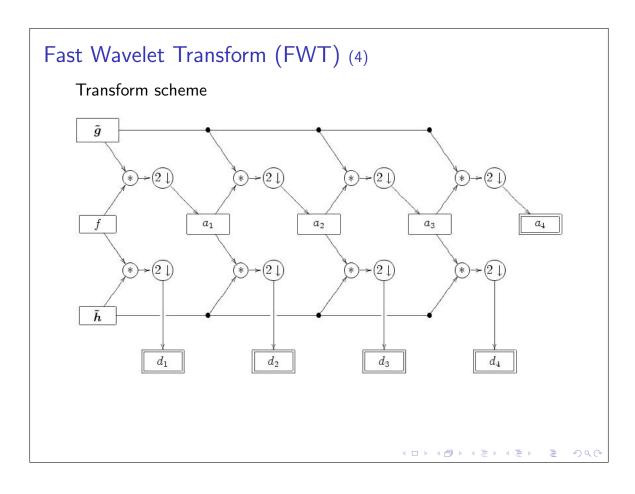
► The recursive application of these formulas provide the Fast Wavelet Transform (FWT) or cascade algorithm.

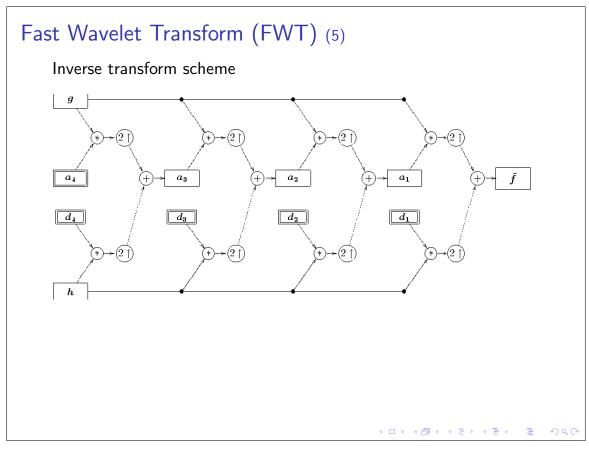


#### Fast Wavelet Transform (3)

- It should be noticed that the filters  $\tilde{h}$  and  $\tilde{g}$  are translated by two positions.
- ▶ Hence the  $\lambda_{j-1,l} = \sqrt{2} \sum_{k} \tilde{h}_{k-2l} \lambda_{k-2l}$  do not describe a convolution.
- ► However, they can be computed as a convolution followed by a subsampling.
- ▶ If the signal is defined over an interval, the number of  $\lambda_{j,k}$  coefficients will be the double of that of  $\lambda_{j-1,k}$  and  $\gamma_{j-1,k}$ .
- ► The number of coefficients to represent the signal does not change.
- ▶ The inverse transform can be obtained by upsampling the coefficients  $\lambda_{j-1,k}$  and  $\gamma_{j-1,k}$ , putting zeros between the coefficients.







#### Fast Wavelet Transform (6)

- ▶ A problem is the estimate of the initial coefficients  $\lambda_0$ .
- ► They should be the inner product of the (mother) scaling function and the signal itself.
- ► A simple choice is using a sampling of the signal for the starting level, *n*:

$$\lambda_{n,l} = f\left(\frac{l}{2^n}\right)$$

- It is equivalent to suppose that the initial scaling function is an approximation of the Dirac's  $\delta$ .
- It is important to notice that the FWT allows to obtain an *exact* inner product of the signal with the basis functions of the successive levels, by using only the  $\lambda_{n,l}$  coefficients.



#### Plotting the basis functions

- ► The basis functions (wavelet and scaling function) sometimes cannot be expressed analytically.
- ▶ In this case, the cascade algorithm can be used to obtain an approximation of them.
- ▶ In fact,  $f \in L^2(\mathbb{R})$  can be represented as:

$$f(x) = \sum_{k} \lambda_{j,k} \varphi_{j,k}(x) + \sum_{l \geq j} \sum_{k} \gamma_{l,k} \psi_{l,k}(x)$$

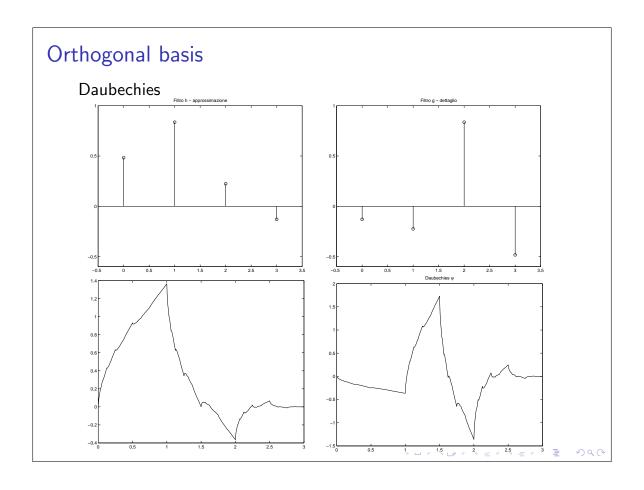
- ▶ From proper coefficients  $\{\lambda\}$  and  $\{\gamma\}$ , the function f can be reconstructed.
- ▶ The scaling function  $\varphi_{j,k}$  is characterized by having only the coefficient  $\lambda_{j,k}$  set to 1; all the others are null.
- ▶ Hence, starting from such a sequence, after few iterations of the cascade algorithm a good sampling of the scaling function is obtained.
  - ▶ The number of coefficients doubles at each iteration.

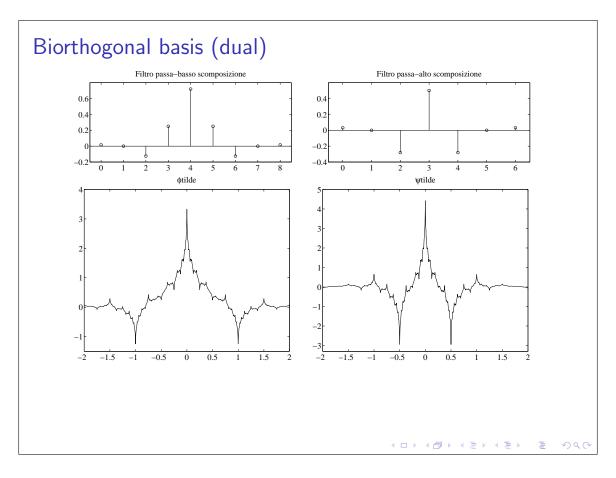


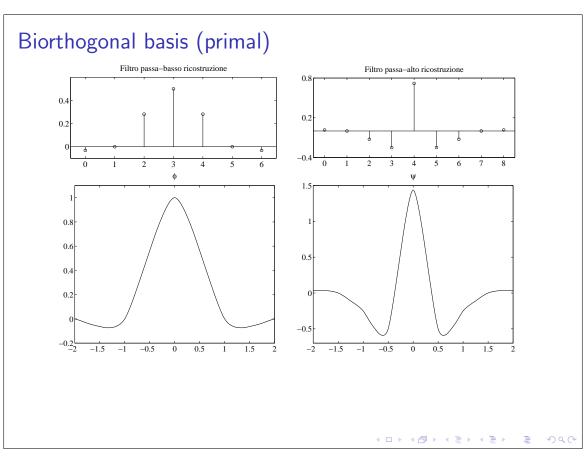
# Plotting the basis functions (2)

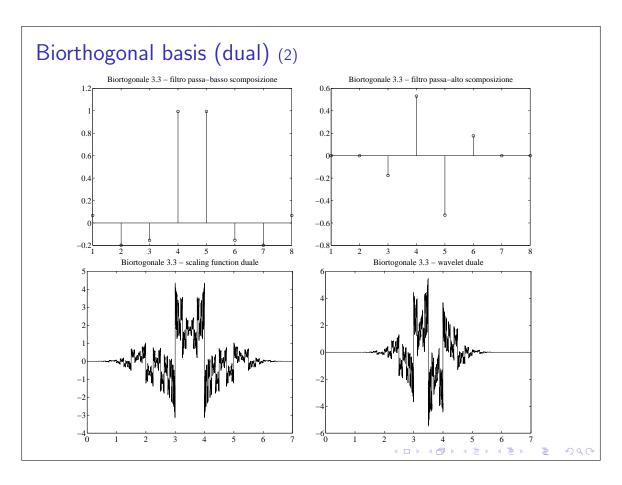
- ► Similarly, the wavelet can be obtained.
  - ▶ All the  $\lambda$  and  $\gamma$  are set to 0, but one of  $\gamma$  is set to 1.
- ► The Fourier transforms of wavelet and scaling functions can also be obtained.

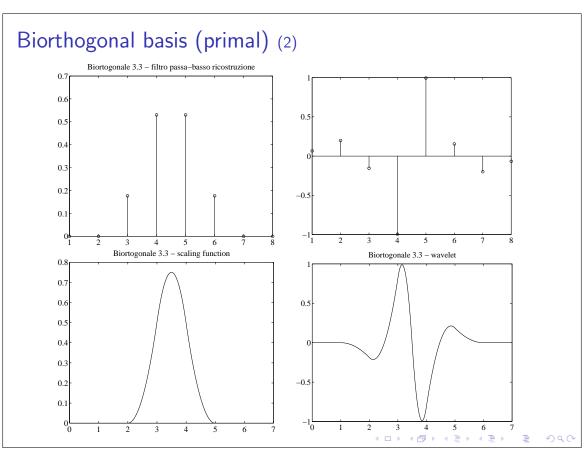


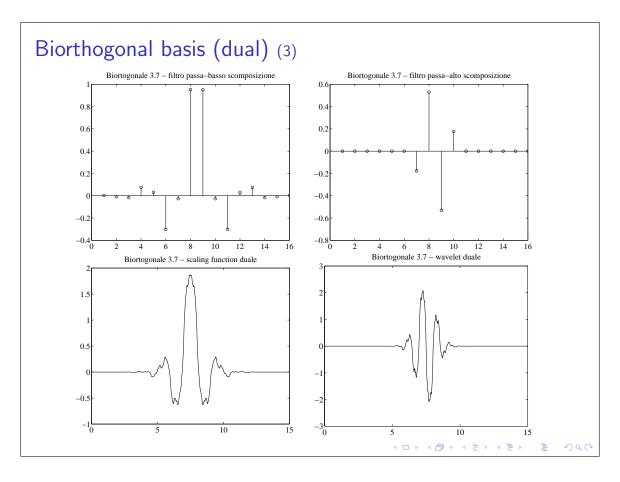


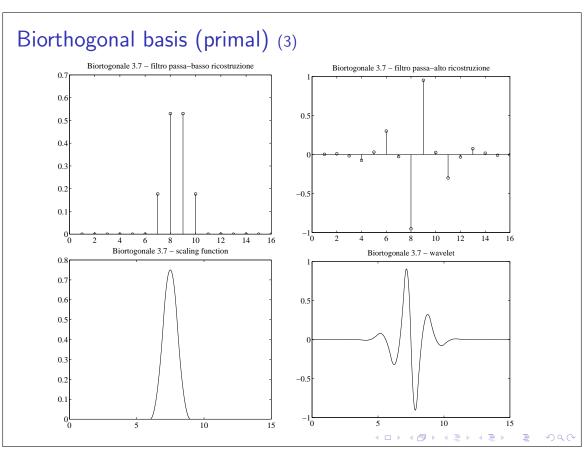












# Fast Wavelet Transform (FWT)

orthogonality or biorthogonality

fast algorithm for wavelet transform computation

function projection

 $\rightarrow$ 

FIR filters filtering

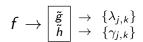
$$f \to \begin{bmatrix} \mathsf{g} \\ \mathsf{h} \end{bmatrix} \to \begin{bmatrix} \lambda_{j,k} \\ \gamma_{j,k} \end{bmatrix}$$

transform

$$\begin{cases} \lambda_{j,k} \} & \rightarrow \boxed{g} \\ \{\gamma_{j,k} \} & \rightarrow \boxed{h} \end{cases} \rightarrow f$$

inverse transform

orthogonal MRA



transform

$$\begin{array}{ccc} \{\lambda_{j,k}\} & \to & \texttt{g} \\ \{\gamma_{j,k}\} & \to & \texttt{h} \end{array} \right] \to f$$

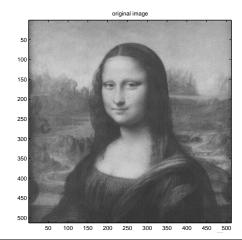
inverse transform

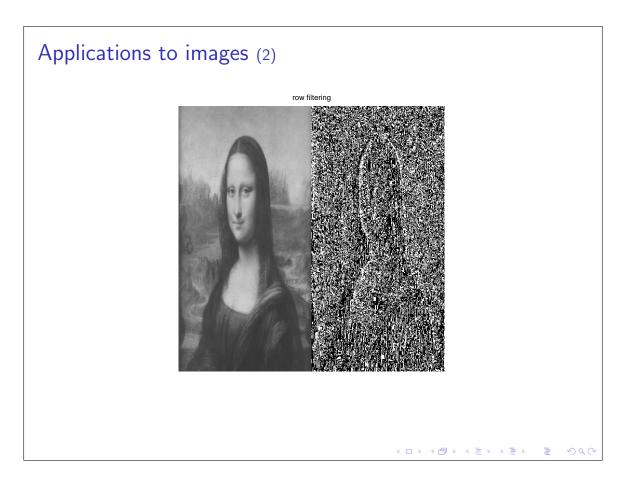
biorthogonal MRA

# Applications to images

- Wavelet and scaling function can be defined also on a bidimensional domain, by using the tensor product.
  - ▶ They are defined as the product over the two dimensions.
- Hence they can be applied to the two dimensions independently.
  - Like the Fourier transform.

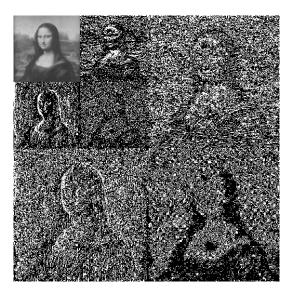
#### Example:







# Applications to images (4)





# **Applications**

- ► Signal representation (e.g., compression)
- ► Signal processing (e.g., filtering, anomalies detection)
- ▶ Pattern recognition (e.g., for feature selection)
- ► Hybrid models (e.g., Wavelet neural networks)



#### Image compression

Wavelet based image compression algorithms are based on some considerations:

- small detail coefficients (probably) carry unimportant information or noise;
  - ▶ if a detail occurs, the coefficients of all the levels corresponding to its position should be meaningful;
  - thresholding is used to set to zero unimportant coefficients;
  - quantization and encoding (e.g. Huffman) can then be realized.
- ▶ the shorter the wavelet support, the smaller the number of non-zero coefficients generated by an edge;
- orthogonality (and biorthogonality) decorrelates the coefficients.



# Image compression (2)

- $f_M = \sum_{j,k} b_{j,k} \psi_{j,k}(x)$  with M non-zero coefficients,  $b_{j,k}$
- ▶ From the orthogonality, the reconstruction error is:

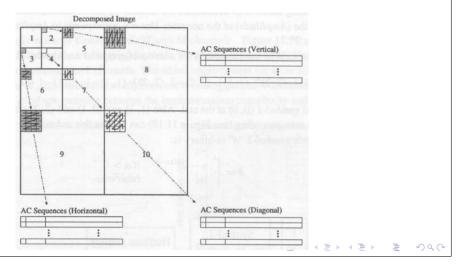
$$||f-f_{\mathcal{M}}||_{L^2}=\left(\sum_{j,k}|\langle f,\,\psi_{j,k}
angle-b_{j,k}|^2
ight)^{rac{1}{2}}$$

- ▶ Hence, the larger the  $b_{i,k}$ 's, the smallest the error.
- ▶ Besov space characterization allows a better estimate of the compression rate wrt. *M*.



# Image compression (3)

- ▶ Encoding can take advantage of long sequences of zeros.
- ► The scanning order of the coefficients is critical for maximizing the length of zeros sequences.
- ▶ If a coefficient is zero, also the corresponding coefficients at the higher scales are probably zero.



# Image compression (4)

- ► Compression of image sequences can be realized using the 3D wavelet transform.
- Quality can be improved by considering not only a single coefficients, but the value of the coefficients in a neighborhood of each position.



# Image denoising

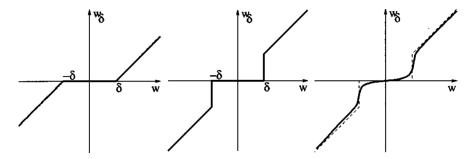
Wavelet denoising is based on three assumptions.

- ► Additive, stationary, and zero-mean noise affects the coefficients of all resolution levels.
- ► Large coefficients describe a good approximation of the original image.
- ▶ Noise should be relatively small.
  - ► Small influence on the large coefficients.



# Image denoising - shrinking

- ▶ Shrinking is the approach generally used for denoising:
  - ▶ a threshold for each level and component is chosen;
  - ▶ the coefficients under threshold are set to zero.



- Soft and hard thresholding, and a sophisticated shrinking function.
- ► Soft thresholding is often used.



# Image denoising - threshold selection

► For a given level and component (horizontal, vertical, diagonal), the optimal threshold should optimize (MSE):

$$\frac{1}{N}||w_{\delta}-v||^2$$

where:

- $w_{\delta}$  are the coefficients after shrinking
- v are the unknown noise-free coefficients
- ▶ The Donoho and Johnstone threshold:

$$\delta = \sqrt{2\log(N)}\sigma$$

where:

- N is the number of coefficients
- $ightharpoonup \sigma$  is the noise standard deviation



# Image denoising – threshold selection (2)

► Generalized cross validation can be used for estimating the threshold, by minimizing:

$$\mathsf{GCV}(\delta) = rac{rac{1}{N}||w - w_{\delta}||^2}{\left(rac{N_0}{N}
ight)^2}$$

where:

- $ightharpoonup N_0$  is the number of zero coefficients
- ▶ It mimics the MSE criterion.
- ▶ No estimate for the noise energy,  $\sigma$ , is needed.
- Adaptive techniques for estimating  $\delta$  from the data can be found in literature.



# Image denoising - neighboring

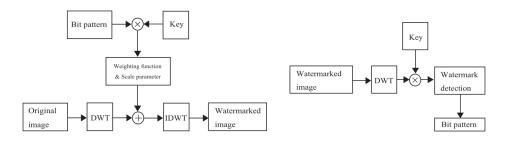
- ► Correlation between neighboring coefficients can be exploited:
  - 1. compute  $s_{j,k} = \sum_{t \in \mathcal{N}(k)} w_{j,t}$
  - 2. shrink  $w_{i,k}$ :

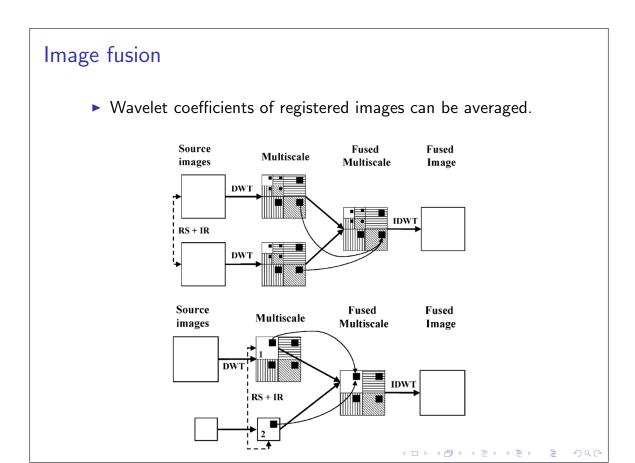
$$w_{j,k} = \left\{ egin{array}{ll} 0, & s_{j,k} < \delta \ w_{j,k} (1 - \delta/s_{j,k}), & ext{otherwise} \end{array} 
ight.$$

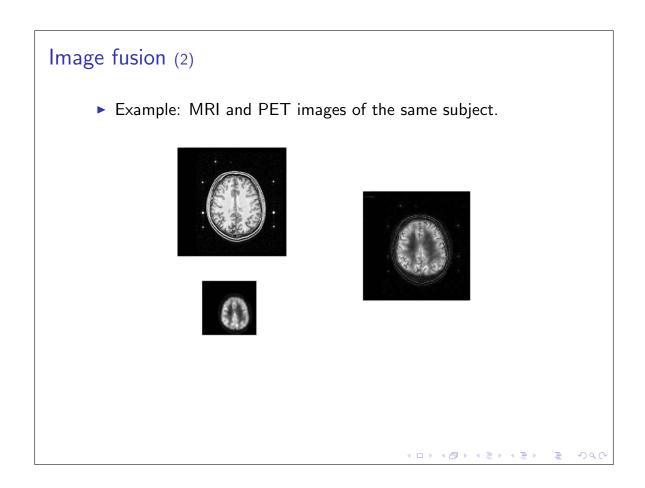


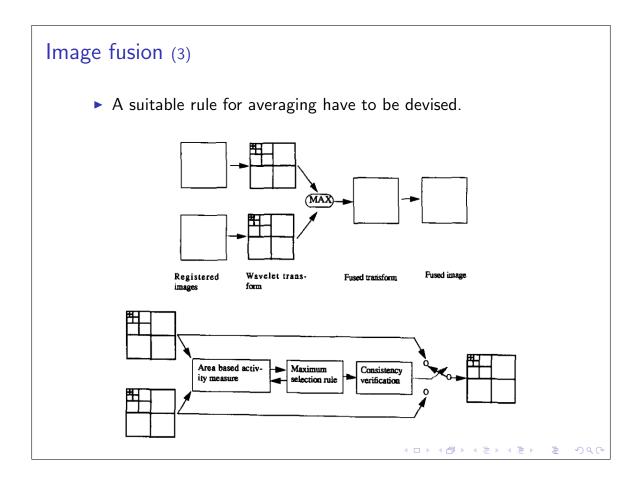
# Image watermarking

- Wavelet coefficients can be perturbed in order to insert a watermark.
- ► The key can than be used in detecting the presence of the watermark.









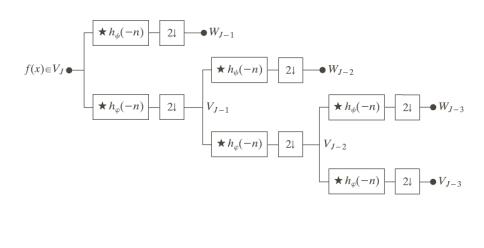
#### Modern wavelets

- ▶ Wavelets packets
- ▶ Lifting schema

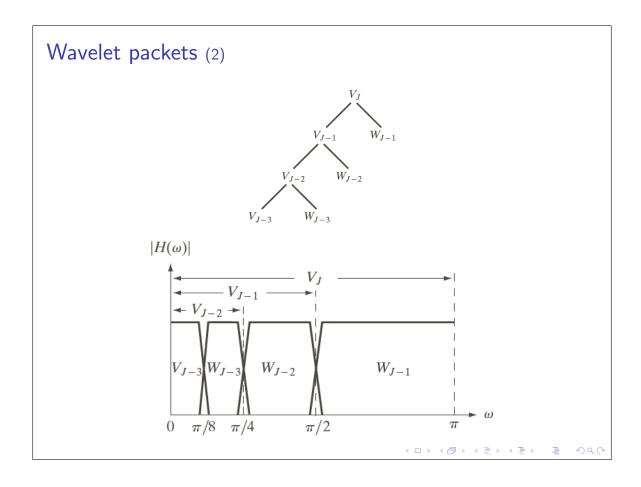
Stefano Ferrari— Fondamenti di elaborazione del segnale multi-dimensionale— a.a. 2011/12

# Wavelet packets

FWT provides a decomposition of a signal f in element of several subspaces (with O(N) computational cost).

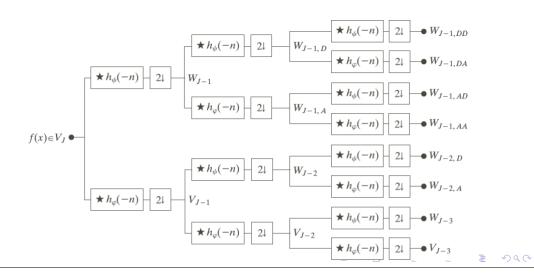


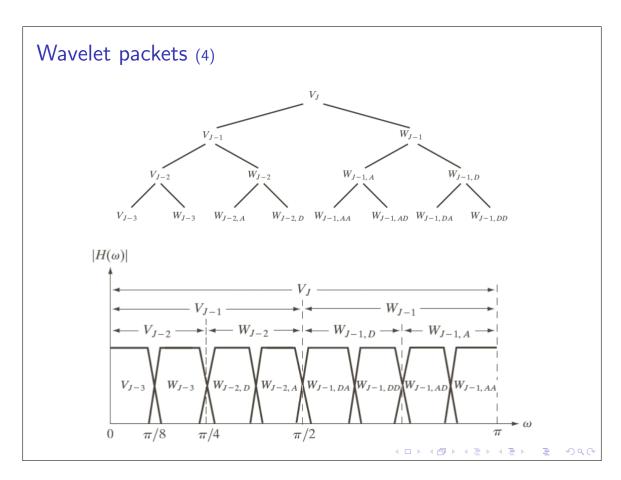


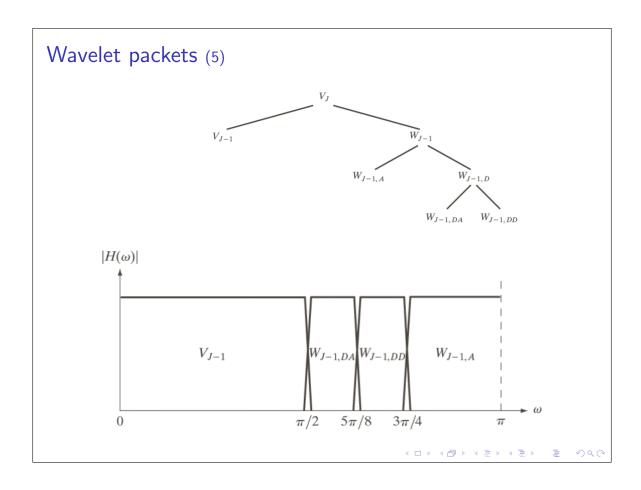


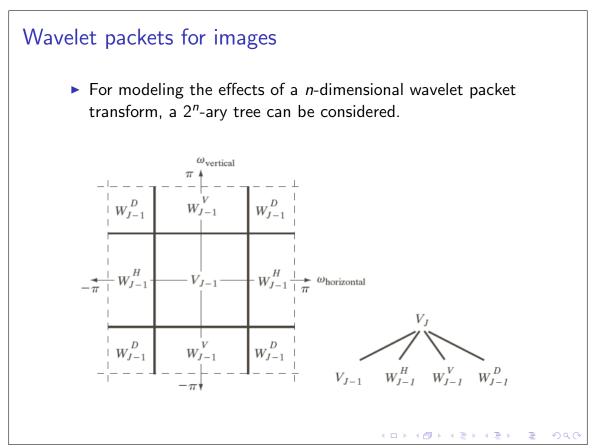
# Wavelet packets (3)

- ► FWT machinery can be extended for decomposing also the detail coefficients.
- ► This transforms is called *wavelet packet* (and have an  $O(N \log(N))$  cost).





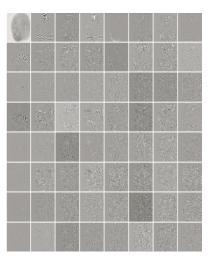




# Wavelet packets - optimal decomposition

- ► For the FBI fingerprint archive, a three scales wavelet packets based compression is used.
  - ▶ The complete decomposition yields to 64 coefficients sets.



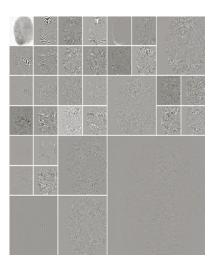




# Wavelet packets – optimal decomposition (2)

▶ In order to optimize the storage requirement, the optimal decomposition (best basis selection) can be considered.





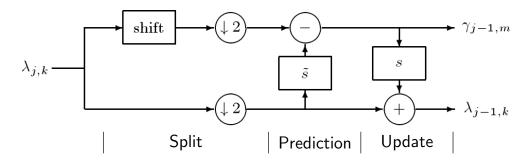
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#### Lifting scheme

- ► The lifting scheme is a method for constructing the so-called second generation wavelets (orthogonal and biorthogonal):
  - they do not make use of Fourier transform (no regularly spaced samples are required);
  - they are not necessarily translates and dilates of the same function.
- ▶ Lifting scheme (LS) has the following advantages:
  - Faster implementation of the wavelet transform
    - ► FWT processes the same sequence with two filters and then subsample both the sequences;
    - ▶ LS splits the sequence before processing.
  - ▶ In-place processing (no additional memory requirement).
  - ▶ Inverse transform is realized inverting the transform operations.



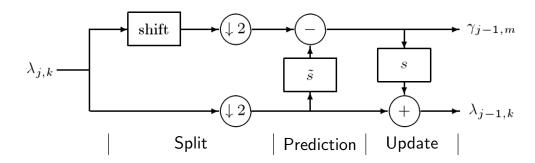
# Lifting scheme – analysis



- ▶ Split:  $\{\lambda_{j,k}\}$  is split in  $\{\lambda_{j-1,k}\}$  and  $\{\gamma_{j-1,k}\}$ ;
  - ▶ the split can be done with any rule, but even and odd samples partition is a sensible choice.
- ▶ Prediction:  $\{\lambda_{j-1,k}\}$  is used to predict  $\{\gamma_{j-1,k}\}$  through  $\tilde{s}$ :
  - the value in the two sequence should be correlated;
  - ▶ this information is used to change the values of  $\{\gamma_{i-1,k}\}$ .



# Lifting scheme – analysis (2)

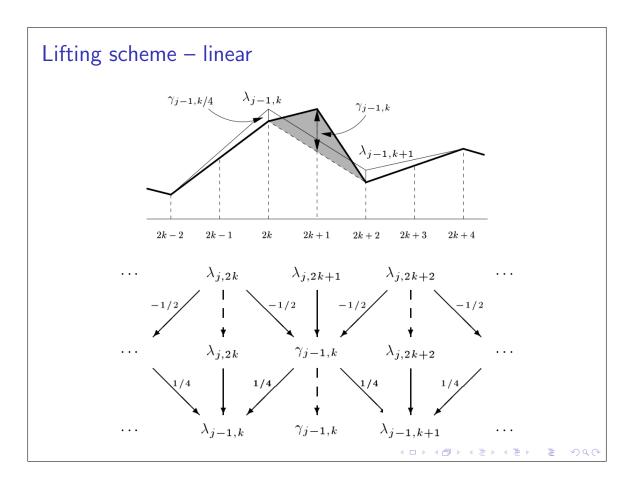


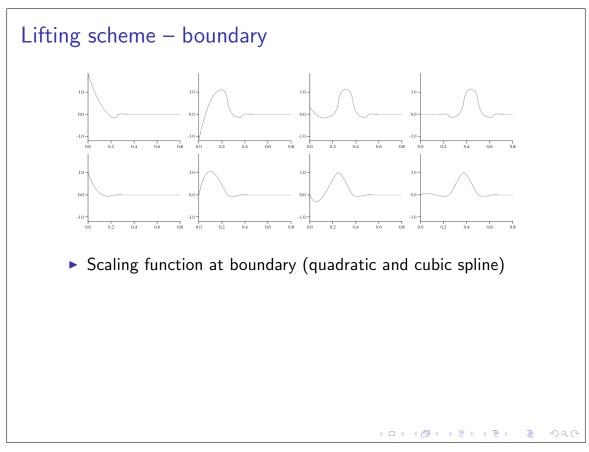
- ▶ Update: information in the original  $\{\gamma_{j-1,k}\}$  that cannot be predicted by  $\{\lambda_{j-1,k}\}$  is now in  $\{\gamma_{j-1,k}\}$ ; this can be used for update the value of  $\{\lambda_{j-1,k}\}$  through s:
  - downsampling can suffer of aliasing;
  - $\{\lambda_{j-1,k}\}$  can now preserve some features of  $\{\lambda_{j,k}\}$  (e.g., the mean);
  - an ad-hoc operator could be hardly invertible.



# Lifting scheme – synthesis

- Since the analysis stage can be realized as:
  - 1.  $[\{\lambda_{j-1,k}\}, \{\gamma_{j-1,k}\}] := \text{split}(\{\lambda_{j,k}\})$
  - 2.  $\{\gamma_{j-1,k}\} := \{\gamma_{j-1,k}\} \tilde{s}(\{\lambda_{j-1,k}\})$
  - 3.  $\{\lambda_{j-1,k}\} := \{\lambda_{j-1,k}\} + s(\{\gamma_{j-1,k}\})$
- the synthesis stage can be obtained as:
  - 1.  $\{\lambda_{j-1,k}\} := \{\lambda_{j-1,k}\} s(\{\gamma_{j-1,k}\})$
  - 2.  $\{\gamma_{j-1,k}\} := \{\gamma_{j-1,k}\} + \tilde{s}(\{\lambda_{j-1,k}\})$ 3.  $\{\lambda_{j,k}\} := \text{join}(\{\lambda_{j-1,k}\}, \{\gamma_{j-1,k}\})$





# Lifting scheme – irregular sampling



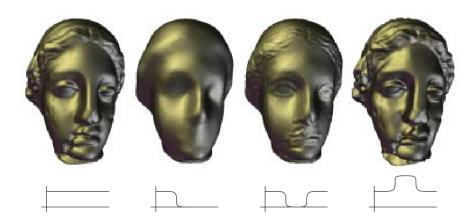




- Second generation wavelets can be applied on irregular sampled data.
- ▶ Low scale approximation of mesh produce a coarsification.



# Lifting scheme – mesh processing



- Typical signal processing techniques are possible also on meshes:
  - original, smoothed, stop-banded, enhanced.



# Other multiscale approaches

- Curvelets
- ▶ Beamlets
- Tetrolets
- Ridgelets



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