

Supplement for Sections 4.8 - 4.10 of the textbook

Summary of the MARIE Assembly Language

Type of Instructions	Mnemonic	Hex Opcode	Description
Arithmetic	ADD X	3	Add the contents of address X to AC
	SUBT X	4	Subtract the contents of address X from the AC
	ADDI X	B	Add Indirect: Use the value at X as the actual address of the data operand to add to AC
	CLEAR	A	Put all zeros in the AC
Data Transfer	LOAD X	1	Load the contents of address X into AC
	STORE X	2	Store the contents of AC at address X
	LOADI X	D	Load Indirect: Use the value of X as the actual address of the data operand to load into the AC
	STOREI X	E	Store Indirect: Use the value of X as the actual address where the AC value is stored.
I/O	INPUT	5	Input a value from the keyboard into AC
	OUTPUT	6	Output the value in AC to the display
Branch	JUMP X	9	Unconditional branch to X by loading the value of X into PC
	SKIPCOND C	8	Skip the next instruction based on the condition, C: C = 000 ₁₆ : skip if AC is negative (b ₁₁ b ₁₀ = 00 ₂) C = 400 ₁₆ : skip if the AC = 0 (b ₁₁ b ₁₀ = 01 ₂) C = 800 ₁₆ : skip if the AC is positive (b ₁₁ b ₁₀ = 10 ₂)
Subroutine call and return	JNS X	0	Jump-and-Store: Store the PC at address X and jump to X+1
	JUMPI X	C	Use the value at X as the address to jump to
	HALT	7	Terminate the program

MARIE

Machine-language
Instruction Format

15

12 11 10

0

Opcode	Address (or Condition)
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A simple MARIE program can be written to perform the high-level language statements:

RESULT = X + Y - Z
print RESULT

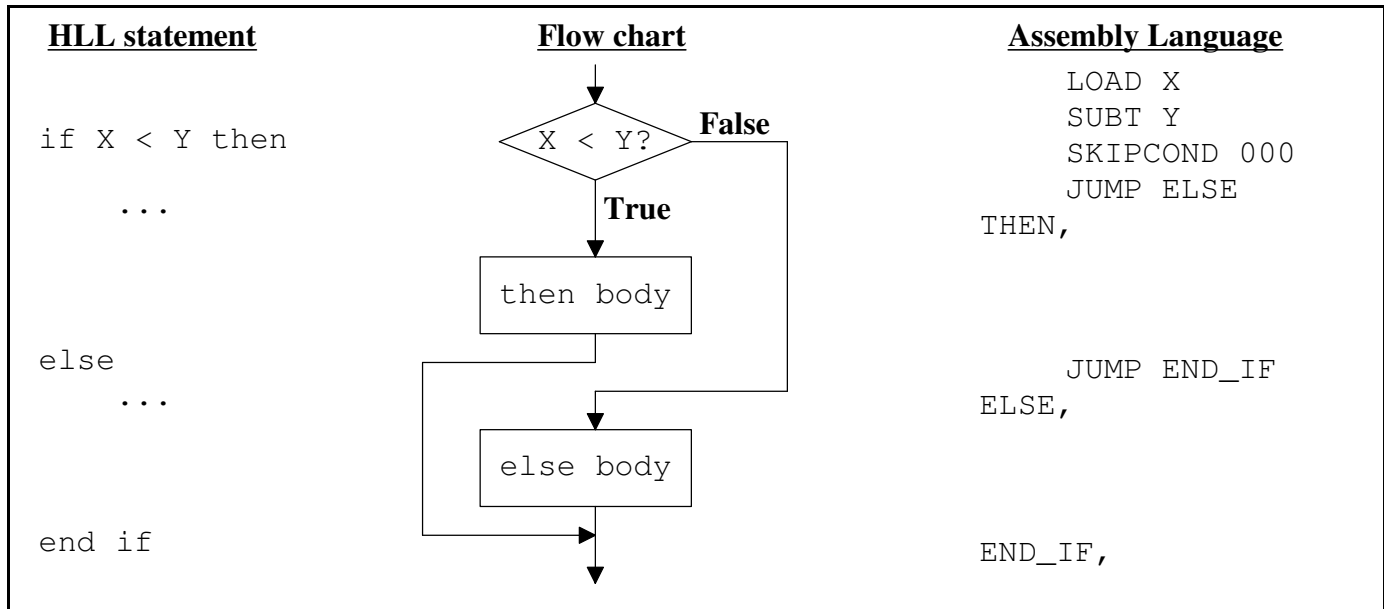
Address	Label	Assembly Language	Machine Language
0		LOAD X	1006 ₁₆
1		ADD Y	3007 ₁₆
2		SUBT Z	4008 ₁₆
3		STORE RESULT	2009 ₁₆
4		OUTPUT	6000 ₁₆
5		HALT	7000 ₁₆
6	X,	DEC 10	000A ₁₆
7	Y,	DEC 20	0014 ₁₆
8	Z,	DEC 5	0005 ₁₆
9	RESULT,	DEC 0	0000 ₁₆

The lines at address 6 to 9 are *assembler directives* (directions to the assembler) to initialize the memory location associated with X (address 6) to DECimal 10, the memory location associated with Y (address 7) to 20, etc. Lines at address 0 to 5 are the actual machine-language MARIE program. If the PC = 0 (program counter), the program execution would start at address 0 which contains 1006₁₆. This instruction would be

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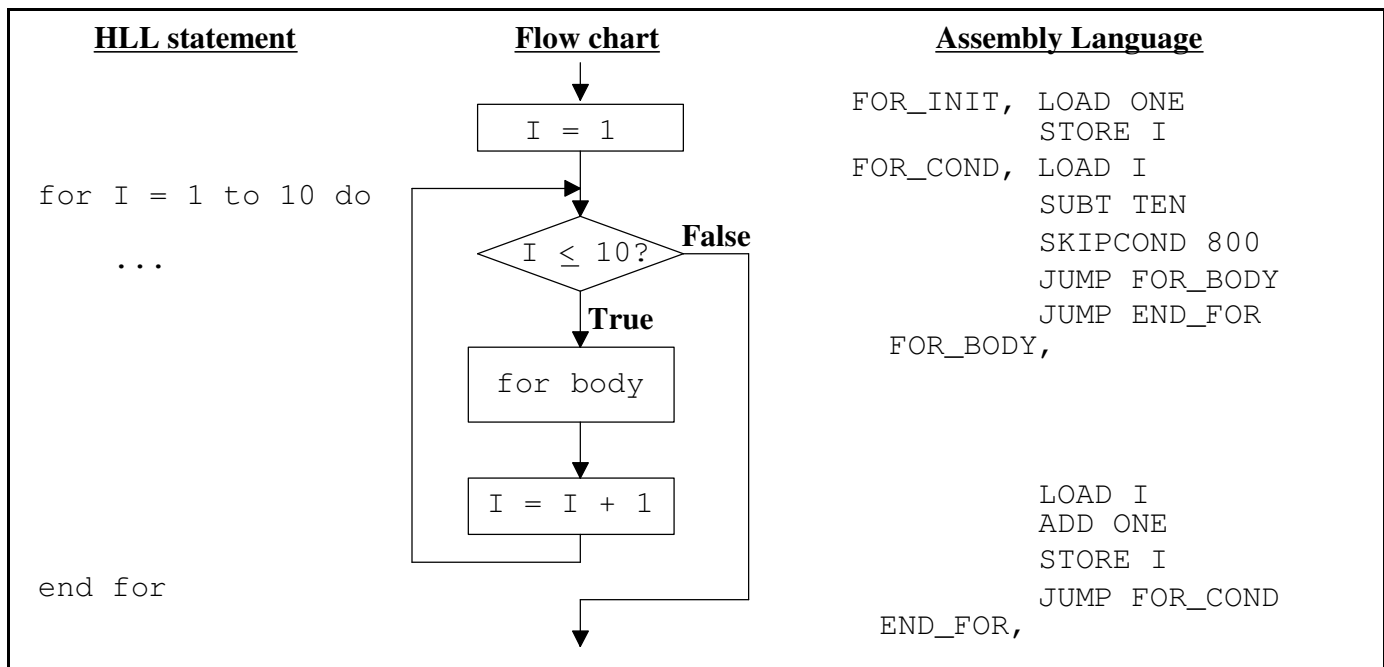
fetches into the CPU's IR (instruction register), bits 15-12 contain the operations code of 1_{16} would be decoded to determine that it is a LOAD instruction. Execution of the LOAD causes the specified memory address's (006_{16} in bits 11-0) content to be loaded into the accumulator (AC) register (i.e., the value 10_{10} would be loaded into the AC). During the fetch-decode-execute cycle, the PC would get incremented to the next instruction. The program instructions are executed sequentially until the HALT instruction which stops the program.

The branch instructions, JUMP and SKIPCOND, potentially cause the PC to “jump” (i.e., alter the *flow of control* in the program). These instructions are useful for implementing high-level language selection (IF, IF-THEN-ELSE, SWITCH, etc.) and looping statements (FOR, WHILE, REPEAT, etc.). For example, consider the following IF-THEN-ELSE statement and corresponding flow-chart:



If $X < Y$ is True, then the value of $(X - Y)$ in the AC is negative. The “SKIPCOND 000” cause the JUMP ELSE instruction to be jumped over if the AC is negative. Since the then-part code follows the JUMP ELSE instruction, it is only executed if $X < Y$. After the then-part code is executed, the JUMP END_IF causes the else-body to be skipped. If $X < Y$ is False, then the value of $(X - Y)$ in the AC will not be negative the SKIPCOND 000 instruction will not jump over the JUMP ELSE instruction.

For a loop example, consider the following FOR-loop and corresponding flow-chart:



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If $I \leq 10$ is False, then $(I - 10)$ is positive, so the SKIPCOND 800 skips to JUMP END_FOR. Thus, dropping out of the FOR loop. Otherwise, the JUMP FOR_BODY is not skipped. After the for-body executes and the loop-control variable I is incremented, the JUMP FOR_COND loops back to recheck the loop control variable.

The simplicity of the MARIE instruction set make writing assembly-language programs difficult. So, we'll only write small toy programs in MARIE, and later learn to write realistic assembly-language programs in the slightly more complex MIPS instruction set. However, the simplicity of the MARIE architecture is a huge benefit as we turn our attention to the hardware of implementing the CPU datapath and control unit.

MARIE Registers and Buses:

The revised Figure 4.9 (below) has moved the Memory from the CPU chip and hence the internal CPU Datapath. Thus, memory can only be accessed via the MAR (Memory-Address Register) and the MBR (Memory-Buffer Register) which is much more realistic. This has some impact on the microoperations that access memory. For example, fetching the instruction pointed at by the PC into the IR would require the following microoperations:

$MAR \leftarrow PC$

$MBR \leftarrow M[MAR]$ (read from memory into the MBR instead of directly into the IR as described on page 199)

$IR \leftarrow MBR$

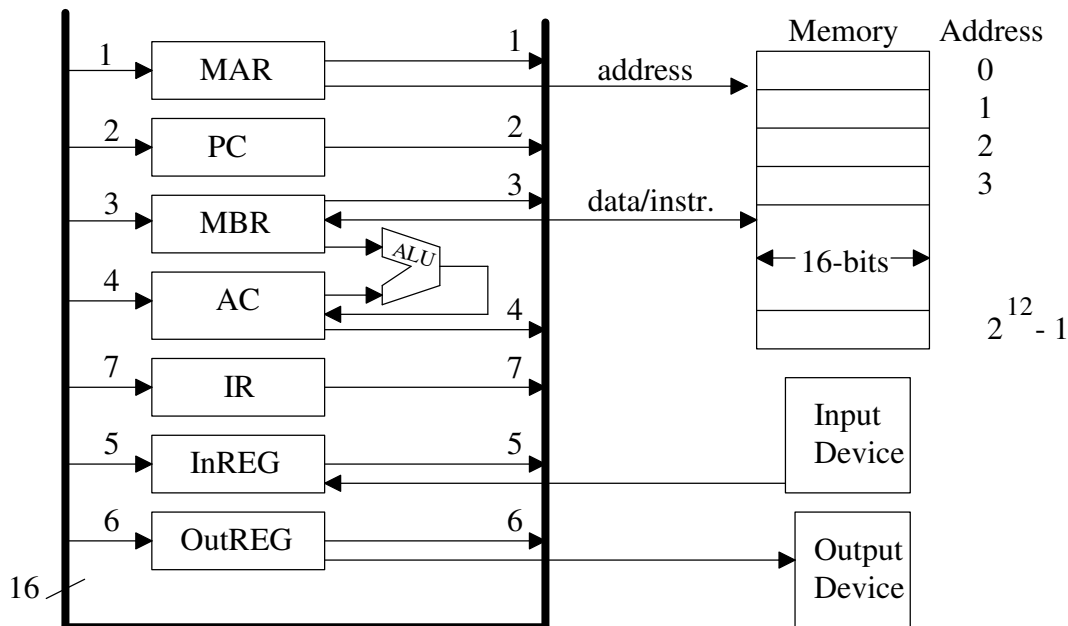
However, the authors seem to understand this since their microoperations to execute the Load X (on page 196) use the MBR correctly:

$MAR \leftarrow X$ (X is the address part of the IR, so this should technically be $MAR \leftarrow IR_{11-0}$)

$MBR \leftarrow M[MAR]$ (read from memory into the MBR instead of directly into the AC)

$AC \leftarrow MBR$

Revised Figure 4.9 Datapath in MARIE



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The text discusses the microoperations of the fetch-decode-execute machine cycle in the execution of the “Simple Program” below that calculates $RESULT = X + Y$.

<u>Address</u>	<u>Label</u>	<u>Assembly Language</u>	<u>Machine Language</u>
100		LOAD X	1104 ₁₆
101		ADD Y	3105 ₁₆
102		STORE RESULT	2106 ₁₆
103		HALT	7000 ₁₆
104	X,	DEC 35	0023 ₁₆
105	Y,	DEC -23	FFE9 ₁₆
106	RESULT,	DEC 0	0000 ₁₆

Revised Figure 4.14 (a) LOAD X (1104₁₆ in ML)

Step	Step #	RTN	PC	IR	MAR	MBR	AC
(initial values)			100				
Fetch	T ₀	MAR ← PC	100		100		
	T ₁	MBR ← M[MAR]	100		100	1104	
	T ₂	IR ← MBR	100	1104	100	1104	
	T ₃	PC ← PC + 1	101	1104	100	1104	
Decode IR[15-12]	T ₄	MAR ← IR[11-0]	101	1104	104	1104	
Get operand	T ₅	MBR ← M[MAR]	101	1104	104	0023	
Execute	T ₆	AC ← MBR	101	1104	104	0023	0023

Revised Figure 4.14 (b) ADD Y (3105₁₆ in ML)

Step	Step #	RTN	PC	IR	MAR	MBR	AC
(initial values AFTER LOAD X)			101	1104	104	0023	0023
Fetch	T ₀	MAR ← PC	101	1104	101	0023	0023
	T ₁	MBR ← M[MAR]	101	1104	101	3105	0023
	T ₂	IR ← MBR	101	3105	101	3105	0023
	T ₃	PC ← PC + 1	102	3105	101	3105	0023
Decode IR[15-12]	T ₄	MAR ← IR[11-0]	102	3105	105	3105	0023
Get operand	T ₅	MBR ← M[MAR]	102	3105	105	FFE9	0023
Execute	T ₆	AC ← AC + MBR	102	3105	105	FFE9	000C

Revised Figure 4.14 (c) STORE RESULT (2106₁₆ in ML)
(YOU COMPLETE THIS AS PART OF AN ASSIGNMENT)

Step	Step #	RTN	PC	IR	MAR	MBR	AC
(initial values AFTER ADD Y)			102	3105	105	FFE9	000C
Fetch	T ₀						
	T ₁						
	T ₂						
	T ₃						
Decode IR[15-12]	T ₄						
Execute*	T ₅						

* “Get Operand” step is not necessary for STORE instructions

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Advanced MARIE Assembly Language Example: Print null terminated string to output “HELLO WORLD”

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HLL: index = 0
    while str[index] != 0 do
        output str[index]
        index = index + 1
    end while

```

Address	Label	Assembly Language	Machine Language
0		CLEAR	A000 ₁₆
1		STORE INDEX	2010 ₁₆
2	WHILE,	LOAD STR_BASE	1012 ₁₆
3		ADD INDEX	3010 ₁₆
4		STORE ADDR	2011 ₁₆
5		LOADI ADDR	D011 ₁₆
6		SKIPCOND 400	8400 ₁₆
7		JUMP DO	9009 ₁₆
8		JUMP END_WHILE	900E ₁₆
9	DO,	OUTPUT	6000 ₁₆
A		LOAD INDEX	1010 ₁₆
B		ADD ONE	300F ₁₆
C		STORE INDEX	2010 ₁₆
D		JUMP WHILE	9002 ₁₆
E	END_WHILE,	HALT	7000 ₁₆
F	ONE,	DEC 1	0001 ₁₆
10	INDEX,	DEC 0	0000 ₁₆
11	ADDR,	HEX 0	0000 ₁₆
12	STR_BASE,	HEX 13	0013 ₁₆
13	STR,	DEC 72 / H	0048 ₁₆
14		DEC 69 / E	0045 ₁₆
15		DEC 76 / L	004C ₁₆
16		DEC 76 / L	004C ₁₆
17		DEC 79 / O	004F ₁₆
18		DEC 13 /carriage return	000D ₁₆
19		DEC 87 / W	0057 ₁₆
1A		DEC 79 / O	004F ₁₆
1B		DEC 82 / R	0052 ₁₆
1C		DEC 76 / L	004C ₁₆
1D		DEC 68 / D	0044 ₁₆
1E	NULL,	DEC 0 / NULL CHAR	0000 ₁₆
1F			