Formalising Groth16 in Lean 4

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1 Introduction

In this document, we describe the Groth16 soundness formalisation in Lean 4. The text contains the protocol description as well as some comments to its implementation.

Groth16 is a kind of ZK-SNARK protocol introduced in [1]. The latter means that:

- It is *zero-knowledge*. In other words, a prover has only a particular piece of information.
- It is *non-interactive* in order to make secret parameters reusable.

Protocols of this kind have the core characteristics such as:

- *Soundness*, i.e., if a statement does not hold, then the prover cannot convince the verifier.
- *Completeness*, i.e., the verifier is convinced whenever a statement is true.
- *Zero-knowledge*, i.e., the only thing is needed is the truth of a statement.

Generally, non-interactive zero-knowledge proofs relies on the *common reference string* model, that is, a model where a public string is generated in a trusted way and all parties have an access to it.

Let us describe the commond scheme that non-interactive zero-knowledge protocols obey, see [2] and [3] to have more details. Before that, we need a bit of terminology.

Let $p \in F[X]$ be a polynomial, a prover is going to convince a verifier that they know p. In turn, knowing p means that a prover knows some of its roots. As it is well-known, any polynomial might be decomposed as follows whenever it has roots (since fields we consider are finite and they are not algebraically closed):

$$p(x) = \prod_{i=0}^{\deg(p)} (x - a_i) \tag{1}$$

for some a_i, $i < \deg(p)$.

Assume that a prover has some values $\{r_i \mid i < n\}$ where each $r_i \in F$ for some $n \leq \deg(p)$. A prover wants to convince a verifier that $p(r_i)$ for each a_i from that set.

If there a_i's are really roots of p, then the polynomial p can be rewritten as:

$$p(x) = \left(\prod_{i=0}^{n}(x - r_i)\right) \cdot h(x) \tag{2}$$

for some $h \in F[X]$.

Denote $\prod_{i=0}^{n}(x - r_i)$ as $t(x)$. We shall call $t(x)$ further a *target polynomial*. So, a verifier accepts only if a target polynomial t divides p, in particular, that means that all those r_i's are roots of p.

*This document may be updated frequently.

The next notion we need is a square span program (see [4]) for verification of which the target polynomial is used. Originally, it has been introduced as a simpler version of quadratic span programs for an alternative characterisation of NP.

A square span program is defined rigorously as:

Definition 1.1. Let F be a field and m a natural number. A *square span program* Q over F is a collection of polynomials $t_0, \dots, t_m \in F[X]$ and a target polynomial t such that:

$$\forall i \leq m \ \deg(t_i) \leq \deg(t)$$

Let $1 \leq l \leq m$, then a square span program Q accepts a tuple $(a_1, \dots, a_l) \in F^l$ iff

$$\exists a_{l+1}, \dots, a_m \in F \ \left(t(x) \mid \left(t_0(x) + \sum_{i=1}^{m} a_i t_i(x) \right)^2 - 1 \right)$$

Square span programs are NP-complete and it is proved by reducing them to the Boolean satisfiability problem. We focus on their application in non-interactive zero-knowledge arguments.

TODO: describe in more detail

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Now we discuss specific aspects of Groth16 in addition the aforedescribed general ZK-SNARK scheme. We emphasise such properties of Groth16 as:

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2 Preliminary definitions

We have a fixed finite field F, and $F[X]$ stands for the polynomial ring over F as usual. The corresponding listing written in Lean:

```
variable {F : Type u} [field : Field F]
```

In Groth16, we have random values $\alpha, \beta, \gamma, \delta \in F$ that we introduce separately as a data type:

```
inductive Vars : Type
  | alpha : Vars
  | beta : Vars
  | gamma : Vars
  | delta : Vars
```

We also introduce the following parameters:

- $n_{stmt} \in \mathbb{N}$ — the statement size;
- $n_{wit} \in \mathbb{N}$ — the witness size;
- $n_{var} \in \mathbb{N}$ — the number of variables.

where n_{wit} is the degree of the target polynomial

In Lean 4, we introduce those parameters as variables in the following way:

```
variable {n_stmt n_wit n_var : Nat}
```

We also define several finite collections of polynomials from the square span program:

- $u_{stmt} = \{f_i \in F[X] \mid i < n_{stmt}\}$
- $u_{wit} = \{f_i \in F[X] \mid i < n_{wit}\}$
- $v_{stmt} = \{f_i \in F[X] \mid i < n_{stmt}\}$
- $v_{wit} = \{f_i \in F[X] \mid i < n_{wit}\}$
- $w_{stmt} = \{f_i \in F[X] \mid i < n_{stmt}\}$
- $w_{wit} = \{f_i \in F[X] \mid i < n_{wit}\}$

We introduce those collections in Lean 4 as variables as well:

```
variable {u_stmt : Finₓ n_stmt → F[X]}
variable {u_wit : Finₓ n_wit → F[X]}
variable {v_stmt : Finₓ n_stmt → F[X]}
variable {v_wit : Finₓ n_wit → F[X]}
variable {w_stmt : Finₓ n_stmt → F[X]}
variable {w_wit : Finₓ n_wit → F[X]}
```

Let $(r_i)_{i<n_{wit}}$ be a collection of elements of F (that is, each $r_i \in F$) parametrised with $\{0, \ldots, n_{wit}\}$. Define the target polynomial $t \in F[X]$ of degree n_{wit} as:

$$t = \prod_{i=0}^{n_{wit}} (x - r_i).$$

Crearly, these r_i's are roots of t. The definition in Lean 4:

```
variable (r : Finₓ n_wit → F)
def t : F[X] := ∏ i in finRange n_wit, (x : F[X]) - Polynomial.c (r i)
```

We think of the collection `r` as roots of the polynomial `t` as it can be observed from the definition. We use divisibility of t to verify the square span program condition.

The polynomial t has the following self-evident properties:

Lemma 1.

1. $\deg(t) = n_{wit}$;
2. *t is monic, that is, its leading coefficient is equal to* 1*;*
3. *If $n_{wit} > 0$, then* $\deg(t) > 0$.

We formalise these statements as follows (but we skip proofs):

```
lemma nat_degree_t : (t r).natDegree = n_wit
lemma monic_t : Polynomial.Monic (t r)
lemma degree_t_pos (hm : 0 < n_wit) : 0 < (t r).degree
```

Let $\{a_{wit_i} \mid i < n_{wit}\}$ and $\{a_{stmt_i} \mid i < n_{stmt}\}$ be collections of elements of F. A stamenent witness polynomial pair is a pair of single variable polynomials $(F_{wit_{sv}}, F_{stmt_{sv}})$ such that $F_{wit_{sv}}, F_{stmt_{sv}} \in F[X]$ and

- $F_{wit_{sv}} = \sum_{i=0}^{n_{wit}} a_{wit_i} u_{wit_i}(x)$
- $F_{stmt_{sv}} = \sum_{i=0}^{n_{stmt}} a_{stmt_i} u_{stmt_i}(x)$

Their Lean 4 counterparts:

```
def V_wit_sv (a_wit : Finₓ n_wit → F) : F[X] :=
  Σ i in finRange n_wit, a_wit i · u_wit i

def V_stmt_sv (a_stmt : Finₓ n_stmt → F) : F[X] :=
  Σ i in finRange n_stmt, a_stmt i · u_stmt i
```

Define the polynomial *sat* as:

$$sat = \sum_{i=0}^{n_{stmt}} a_{stmt_i} v_{stmt_i}(x) + \sum_{i=0}^{n_{wit}} a_{wit_i} v_{wit_i}(x) - \sum_{i=0}^{n_{stmt}} a_{stmt_i} w_{stmt_i}(x) + \sum_{i=0}^{n_{wit}} a_{wit_i} w_{wit_i}(x) \tag{3}$$

A pair $(F_{wit_{sv}}, F_{stmt_{sv}})$ satisfies *the square span program*, if the remainder of division of *sat* by t is equal to 0. This requirement is common for ZK-SNARK protocols and the square span program in general as we discussed in the introduction.

The Lean 4 analogue of the property defined above:

```
def satisfying (a_stmt : Finₓ n_stmt → F) (a_wit : Finₓ n_wit → F) :=
  (((Σ i in finRange n_stmt, a_stmt i · u_stmt i)
    + Σ i in finRange n_wit, a_wit i · u_wit i) *
  ((Σ i in finRange n_stmt, a_stmt i · v_stmt i)
    + Σ i in finRange n_wit, a_wit i · v_wit i) -
  ((Σ i in finRange n_stmt, a_stmt i · w_stmt i)
    + Σ i in finRange n_wit, a_wit i · w_wit i) : F[X]) %ₘ (t r) = 0
```

3 Common reference string elements

Assume we interpreted α, β, γ, and δ somehow with elements of F, say crs_α, crs_β, crs_γ, and crs_δ, that is, in Lean 4:

```
def crs_α  (f : Vars → F) : F := f Vars.α
def crs_β (f : Vars → F) : F := f Vars.β
def crs_γ (f : Vars → F) : F := f Vars.γ
def crs_δ (f : Vars → F) : F := f Vars.δ
```

For simplicity, we write this interpretation as a function $f : \{\alpha, \beta, \gamma, \delta\} \to F$ defined by equations:

$$f(a) = crs_a \text{ for } a \in \{\alpha, \beta, \gamma, \delta\}.$$

In addition to those four elements of F we have a collection of degrees for $a \in F$:

$$\{a^i \mid i < n_{var}\}$$

formalised as:

```
def crs_powers_of_x (i : Finₓ n_var) (a : F) : F := (a)^(i : ℕ)
```

We also introduce collections crs_l, crs_m, and crs_n for $a \in F$:

$$crs_l = \frac{((f(\beta)/f(\gamma)) \cdot (u_{stmt_i})(a)) + ((f(\alpha)/f(\gamma)) \cdot (v_{stmt_i})(a)) + w_{stmt_i}(a)}{f(\gamma)} \qquad \text{for } i < n_{stmt} \tag{4}$$

$$crs_l = \frac{((f(\beta)/f(\delta)) \cdot (u_{wit_i})(a)) + ((f(\alpha)/f(\delta)) \cdot (v_{wit_i})(a)) + w_{wit_i}(a)}{f(\delta)} \qquad \text{for } i < n_{wit} \tag{5}$$

$$crs_l = \frac{a^i \cdot t(a)}{f(\delta)}, \text{for } i < n_{var} \quad (6)$$

Their Lean 4 versions:

```
def crs_l (i : Finₓ n_stmt) (f : Vars → F) (a : F) : F :=
  ((f Vars.β / f Vars.γ) * (u_stmt i).eval (a) +
  (f Vars.α / f Vars.γ) * (v_stmt i).eval (a) +
  (w_stmt i).eval (a)) / f Vars.γ

def crs_m (i : Finₓ n_wit) (f : Vars → F) (a : F) : F :=
  ((f Vars.β / f Vars.δ) * (u_wit i).eval (a) +
  (f Vars.α / f Vars.δ) * (v_wit i).eval (a) +
  (w_wit i).eval (a)) / f Vars.δ

def crs_n (i : Finₓ (n_var - 1)) (f : Vars → F) (a : F) : F :=
  ((a)^(i : ℕ)) * (t r).eval a / f Vars.δ
```

Assume we have fixed elements of a field A_α, A_β, A_γ, A_δ, B_α, B_β, B_γ, B_δ, C_α, C_β, C_γ, $C_\delta \in F$.

We also have indexed collections:

- $\{A_x \in F \mid x < n_{var}\}$
- $\{B_x \in F \mid x < n_{var}\}$
- $\{C_x \in F \mid x < n_{var}\}$
- $\{A_l \in F \mid l < n_{stmt}\}$
- $\{B_l \in F \mid l < n_{stmt}\}$
- $\{C_l \in F \mid l < n_{stmt}\}$
- $\{A_m \in F \mid m < n_{wit}\}$
- $\{B_m \in F \mid m < n_{wit}\}$
- $\{C_m \in F \mid m < n_{wit}\}$
- $\{A_h \in F \mid h < n_{var-1}\}$
- $\{B_h \in F \mid h < n_{var-1}\}$
- $\{C_h \in F \mid h < n_{var-1}\}$

```
variable { A_α A_β A_γ A_δ B_α B_β B_γ B_δ C_α C_β C_γ C_δ  : F }
variable { A_x B_x C_x : Finₓ n_var → F }
variable { A_l B_l C_l : Finₓ n_stmt → F }
variable { A_m B_m C_m : Finₓ n_wit → F }
variable { A_h B_h C_h : Finₓ (n_var - 1) → F }
```

The adversary's proof representation is defined as the following three sums, for $x \in F$:

$$A = A_\alpha \cdot crs_\alpha + A_\beta \cdot crs_\beta + A_\gamma \cdot crs_\gamma + A_\delta \cdot crs_\delta + \\ + \sum_{i=0}^{n_{var}} A_{x_i} * x^i + \sum_{i=0}^{n_{stmt}} A_{l_i} * crs_l(x) + \\ + \sum_{i=0}^{n_{wit}} A_{m_i} * crs_m(x) + \sum_{i=0}^{n_{var}-1} A_{h_i} * crs_n(x) \quad (7)$$

$$
\begin{aligned}
B = B_\alpha \cdot crs_\alpha + B_\beta \cdot crs_\beta + B_\gamma \cdot crs_\gamma + B_\delta \cdot crs_\delta + \\
+ \sum_{i=0}^{n_{var}} B_{x_i} * x^i + \sum_{i=0}^{n_{stmt}} B_{l_i} * crs_l(x) + \\
+ \sum_{i=0}^{n_{wit}} B_{m_i} * crs_m(x) + \sum_{i=0}^{n_{var}-1} B_{h_i} * crs_n(x)
\end{aligned}
\quad (8)
$$

$$
\begin{aligned}
C = C_\alpha \cdot crs_\alpha + C_\beta \cdot crs_\beta + C_\gamma \cdot crs_\gamma + C_\delta \cdot crs_\delta + \\
+ \sum_{i=0}^{n_{var}} C_{x_i} * x^i + \sum_{i=0}^{n_{stmt}} C_{l_i} * crs_l(x) + \\
+ \sum_{i=0}^{n_{wit}} C_{m_i} * crs_m(x) + \sum_{i=0}^{n_{var}-1} C_{h_i} * crs_n(x)
\end{aligned}
\quad (9)
$$

Here, we provide the Lean 4 version of A only.

```
def A (f : Vars → F) (x : F) : F :=
  A_α * crs_α F f + A_β * crs_β F f + A_γ * crs_γ F f + A_δ * crs_δ F f +
  Σ i in (finRange n_var), (A_x i) * (crs_powers_of_x F i x) +
  Σ i in (finRange n_stmt), (A_l i) * (@crs_l F field n_stmt u_stmt v_stmt w_stmt i f x) +
  Σ i in (finRange n_wit), (A_m i) * (@crs_m F field n_wit u_wit v_wit w_wit i f x) +
  Σ i in (finRange (n_var - 1)), (A_h i) * (crs_n F r i f x)
```

A proof is called *verified*, if the following equation holds:

$$
A \cdot B = crs_\alpha \cdot crs_\beta + \left(\sum_{i=0}^{n_{stmt}} a_{stmt_i} \cdot crs_{l_i}(x) \right) \cdot crs_\gamma + C \cdot crs_\delta \quad (10)
$$

```
def verified (f : Vars -> F) (x : F) (a_stmt : Fin n_stmt -> F ) : Prop :=
  A f x * B f x =
    (crs_alpha F f * crs_beta F f) +
    ((\sum i in finRange n_stmt, (a_stmt i) * @crs_l i f x) *
      (crs_gamma F f) + C f x * (crs_delta F f))
```

4 Modified common reference string elements

We modify common reference string elements from the previous section as multivariate polynomials.

4.1 Coefficient lemmas

5 Formalised soundness

6 Groth16, Type III

In this section, we describe the Lean 4 formalisation of a Groth16 version called Type III, see [5]. It has certain specific moments.

In Type III, polynomials A, B, C have a slightly more simple form:

```
def A (f : Vars → F) : F[X] :=
(Polynomial.c A_α) * crs_α F f + (Polynomial.c A_β) * crs_β F f +
(Polynomial.c A_δ) * crs_δ F f +
Σ i in (finRange n_var), (Polynomial.c (A_x i)) * (crs_powers_of_x F i) +
Σ i in (finRange n_stmt), (Polynomial.c (A_l i)) * (@crs_l F field n_stmt u_stmt v_stmt w_stmt i
  f) +
Σ i in (finRange n_wit), (Polynomial.c (A_m i)) * (@crs_m F field n_wit u_wit v_wit w_wit i f) +
Σ i in (finRange (n_var-1)), (Polynomial.c (A_h i)) * (crs_n F r i f)

def B (f : Vars → F) : F[X] :=
  (Polynomial.c B_β) * (crs_β F f) + (Polynomial.c B_γ) * (crs_γ F f) +
  (Polynomial.c B_δ) * (crs_δ F f) +
  Σ i in (finRange n_var), (Polynomial.c (B_x i)) * (crs_powers_of_x F i)

def C (f : Vars → F) : F[X]  :=
  (Polynomial.c C_α) * crs_α F f + (Polynomial.c C_β) * crs_β F f +
  (Polynomial.c C_δ) * crs_δ F f +
  Σ i in (finRange n_var), (Polynomial.c (C_x i)) * (crs_powers_of_x F i) +
  Σ i in (finRange n_stmt), (Polynomial.c (C_l i)) * (@crs_l F field n_stmt u_stmt v_stmt w_stmt i
    f) +
  Σ i in (finRange n_wit), (Polynomial.c (C_m i)) * (@crs_m F field n_wit u_wit v_wit w_wit i f) +
  Σ i in (finRange (n_var - 1)), (Polynomial.c (C_h i)) * (crs_n F r i f)
```

References

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