


B.C. So Let's look at the first term

$$u'w \Big|_{x_1}^{x_2} = u'(x_2)w(x_2) - u'(x_1)w(x_1)$$

$$F(L) = P = \nabla(L)A = E u'(L)A$$

$$u(0) = 0$$


Restriction

Constraint on weighting function
 w has to be zero wherever
 u is known

For one element, we'll apply shape functions

so far

$$\int_{x_1}^{x_2} (\bar{E} u'' + f) w dx = E u' w \Big|_{x_1}^{x_2} - \int_{x_1}^{x_2} \bar{E} u' w' dx + \int_{x_1}^{x_2} f w dx = 0$$

$$u = N_1 u_1 + N_2 u_2$$

$$u' = \frac{\partial u}{\partial x} = N_1' u_1 + N_2' u_2$$

$$w = N_1 w_1 + N_2 w_2$$

$$w' = N_1' w_1 + N_2' w_2$$

notation

$$w(x_1) = w_1$$

$$w(x_2) = w_2$$

$$u(x_1) = u_1$$

$$u(x_2) = u_2$$

First term

$$E u' w \Big|_{x_1}^{x_2} = E \left[u'(x_2) w(x_2) - u'(x_1) w(x_1) \right]$$

$$= E \begin{bmatrix} w_1 & w_2 \end{bmatrix} \begin{bmatrix} -u'_1 \\ u'_2 \end{bmatrix}$$

Second term

$$\int_{x_1}^{x_2} E u' w' dx = \int_{x_1}^{x_2} E (N_1' u'_1 + N_2' u'_2) dx$$

$$= \begin{bmatrix} w_1 & w_2 \end{bmatrix} \left[\int_{x_1}^{x_2} \begin{bmatrix} N_1' \\ N_2' \end{bmatrix} E \begin{bmatrix} N_1' & N_2' \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} dx \right]$$

Third term

$$\int_{x_1}^{x_2} f w dx = \int_{x_1}^{x_2} f (N_1 w_1 + N_2 w_2) dx$$

$$= \begin{bmatrix} w_1 & w_2 \end{bmatrix} \left[\int_{x_1}^{x_2} \begin{bmatrix} N_1 \\ N_2 \end{bmatrix} f dx \right]$$

Summing the three terms

$$\underline{[w_1 \ w_2]} \left[E \begin{bmatrix} -u_1' \\ u_2' \end{bmatrix} - \int_{x_1}^{x_2} \begin{bmatrix} N_1' \\ N_2' \end{bmatrix} E \begin{bmatrix} N_1' & N_2' \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} dx + \int_{x_1}^{x_2} f \begin{bmatrix} N_1 \\ N_2 \end{bmatrix} dx \right] = 0$$

$$[w_1 \ w_2] \begin{bmatrix} * \\ * \end{bmatrix} = 0$$

you can cancel w_1, w_2 because it's an arbitrary set of numbers.

We can simplify

$$\int_{x_1}^{x_2} \begin{bmatrix} N_1' \\ N_2' \end{bmatrix} E \begin{bmatrix} N_1' & N_2' \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} dx = \int_{x_1}^{x_2} f \begin{bmatrix} N_1 \\ N_2 \end{bmatrix} dx$$

local stiffness

$$+ E \begin{bmatrix} -u_1' \\ u_2' \end{bmatrix}$$

local force vector

e.g.
H.W problem



$u=0$

$$\int_{x_1}^{x_2} E \begin{bmatrix} N_1' & N_2' \\ N_1' & N_2' \end{bmatrix} dx = K \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\int_{x_1}^{x_2} f \begin{bmatrix} N_1 \\ N_2 \end{bmatrix} dx + E \begin{bmatrix} -u_1' \\ u_2' \end{bmatrix} = f$$

Assemble

1

2

3

4

1

2

3

4

$\int_{x_1}^{x_2} N_1' dx$
 $\int_{x_1}^{x_2} N_1' N_2' dx$
 $\int_{x_1}^{x_2} N_2' dx$
 $\int_{x_2}^{x_3} N_1' dx$
 $\int_{x_2}^{x_3} N_1' N_2' dx$

3

4

$\int_{x_2}^{x_3} N_1' N_2' dx$
 $\int_{x_2}^{x_3} N_2' dx$
 $\int_{x_3}^{x_4} N_1' dx$
 $\int_{x_3}^{x_4} N_1' N_2' dx$

4

$\int_{x_3}^{x_4} N_1' N_2' dx$
 $\int_{x_3}^{x_4} N_2' dx$

u_1

u_2

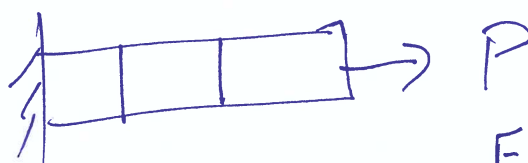
u_3

u_4

$$= \left[\begin{array}{l} \int_{x_1}^{x_2} f N_1^{(1)} dx \\ \int_{x_1}^{x_2} f N_2^{(1)} dx + \int_{x_2}^{x_3} f N_1^{(2)} dx \\ \int_{x_2}^{x_3} f N_2^{(2)} dx + \int_{x_3}^{x_4} f N_1^{(3)} dx \\ \int_{x_3}^4 f N_2^{(3)} dx \end{array} \right]$$

$$+ E \left[\begin{array}{c} -u_1' \\ u_2' - u_2' \\ u_3' - u_3' \\ u_4' \end{array} \right]$$

with $EU_4' = \frac{F(L)}{A} = \frac{P}{A}$



$$-EU_1' = \frac{P}{A}$$

HW 3

-solve using
Galerkin FE with 2 nodes 1 element

$$u'' + \omega c = 0$$

$$0 < x < 1 \quad u(0) = 0$$

$$u(1) = 0$$

This is the same as
the previous problem where I
solved $E \frac{\partial^2 u}{\partial x^2} + f = 0$

with $F=1, f=x$

*nocode

2D finite element method

- Deriving stiffness matrix and force vector for deformation (elastic) problems

Indicial notation (3D)

$$u_i v_i = u_1 v_1 + u_2 v_2 + u_3 v_3$$

$$= \underline{u} \cdot \underline{v} \text{ (dot product)}$$

(repeated index i)

$$a_{ij} v_j = a_{i1} v_1 + a_{i2} v_2 + a_{i3} v_3$$

$$= \begin{bmatrix} a_{11} v_1 + a_{12} v_2 + a_{13} v_3 \\ a_{21} v_1 + a_{22} v_2 + a_{23} v_3 \\ a_{31} v_1 + a_{32} v_2 + a_{33} v_3 \end{bmatrix} = \underline{A} \underline{v}$$

$$= \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}$$

$\underline{A} : a_{ij} \leftarrow$ vector of a vector which is a matrix

$\underline{v} : v_i \leftarrow$ single free subscript means vector

Last time we did divergence theorem

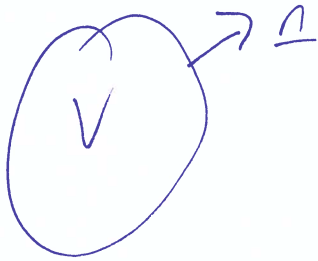
$$\int_V (a_{ij})_{,j} dV = \int_V (a_{i1,1} + a_{i2,2} + a_{i3,3}) dV$$

\ / repeated

$$= \int_V \sum_{i=1}^3 \begin{bmatrix} a_{11,1} + a_{12,2} + a_{13,3} \\ a_{21,1} + a_{22,2} + a_{23,3} \\ a_{31,1} + a_{32,2} + a_{33,3} \end{bmatrix} dV$$

Divergence theorem

$$\int_V (a_{ij})_{,j} dV = \int_S a_{ij} n_j dS$$



$\underline{n} = n_j =$ unit normal vector to the surface

Galerkin method in 2D

Equilibrium equation
using indicial notation

$$\nabla_{ij,j} + f_i = 0$$

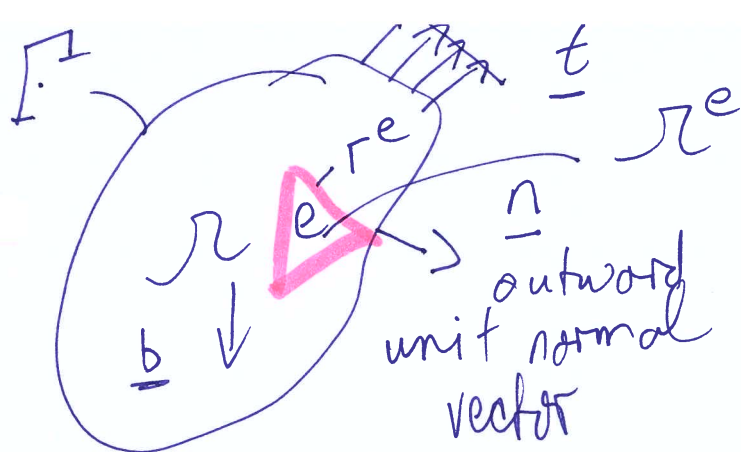
In 2D $i, j = \{1, 2\}$

$$\nabla_{i1,1} + \nabla_{i2,2} + f_i = 0$$

derive
local
stiffness
matrix

<p>in 1D $i=1, j=1$</p> <p>$\nabla_{11,1} + f_1 = 0$</p> <p>$\frac{\partial \sigma_{xx}}{\partial x} + f_x = 0$</p>
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$$\begin{matrix} i=1 \\ (x) \\ i=2 \\ (y) \end{matrix} \begin{bmatrix} \frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \sigma_{xy}}{\partial y} + f_x \\ \frac{\partial \sigma_{yx}}{\partial x} + \frac{\partial \sigma_{yy}}{\partial y} + f_y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$



e : finite element

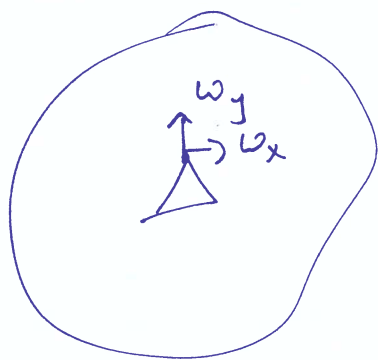
Γ^e - surface area of element

Ω^e - volume of the element

Strong form of that one element

$$\int_{\Omega^e} (\nabla_{i,j} + f_i) w_i \, d\Omega = 0$$

w_i = weighting function which is a vector field



$$\underline{w} = \begin{bmatrix} w_x \\ w_y \end{bmatrix} = w_i \quad \underline{2D}$$

Step 1: ... - u-v rule of differentiation

$$\nabla_{i,j} w_i = (\nabla_{i,j} w_i)_{,j} - (\nabla_{i,j} w_{i,j})$$