

# Interactive Foreground Segmentation Using K-Means Clustering

## Methodology:

1. **K-Means Clustering:** The algorithm starts by performing K-Means clustering on color pixels. The number of clusters (N) is specified as an input parameter.
2. **Seed Pixels Extraction:** Seed pixels for foreground and background classes are extracted from auxiliary images where foreground pixels are marked in red and background pixels in blue.
3. **Lazy Snapping Algorithm:**
  - Compute the likelihood of a pixel belonging to each of the N clusters using an exponential function of the negative Euclidean distance.
  - Calculate the overall likelihood of a pixel to belong to a class as a weighted sum of all cluster likelihoods.
  - Assign a pixel to the class with the higher likelihood (foreground or background).

## Implementation Details:

- The algorithm is implemented using Python, OpenCV, NumPy, and scikit-learn's KMeans clustering.
- A class hierarchy is used, with `KMeansClustering` handling K-Means clustering and `LazySnapping` extending it to implement the Lazy Snapping algorithm.
- The `likelihood` function calculates the likelihood of a pixel based on Euclidean distances and weighting factors.
- Seed pixels are extracted based on color tolerance from the stroke images.
- The `lzsnap` function performs the Lazy Snapping algorithm on the input image using the extracted seed pixels and clustering results.

## Results and Analysis:

The segmentation results are displayed for different values of N (number of clusters) for each test image. The results are visually evaluated based on the quality of segmentation. Here are the observations and analysis:

1. **Van Gogh Image:**
  - For N=32 clusters, the segmentation appears reasonable but lacks fine details.
  - N=64 clusters show improved segmentation with clearer boundaries.
  - N=128 clusters further refine the segmentation but may introduce over-segmentation artifacts.
2. **Lady Image:**
  - Both stroke images lead to similar segmentation results, indicating robustness.
  - N=64 clusters provide a good balance between detail preservation and smooth segmentation.
  - Smaller N values lead to under-segmentation, while larger N values may introduce noise.
3. **Mona Lisa Image:**

- Segmentation results are visually pleasing for  $N=64$  clusters in both cases.
- Higher  $N$  values tend to create more detailed segmentation but may also introduce artifacts.

## **Conclusion and Recommendations:**

- The Lazy Snapping algorithm with K-Means clustering effectively segments foreground objects based on provided seed pixels.
- Optimal  $N$  value depends on the image complexity and desired level of detail in segmentation.
- For most cases,  $N=64$  clusters strike a good balance between segmentation accuracy and computational efficiency.
- Experimentation with different  $N$  values helps identify the optimal choice based on segmentation quality and runtime considerations.
- Further refinement and optimization can be explored, such as adaptive  $N$  selection based on image content or incorporating additional features for clustering.