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Thesis
submitted to the
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(1) Wenn eine der in den §§ 154 bis 156 bezeichneten Handlungen aus Fahrlässigkeit begangen worden ist, so
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Abstract

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Überblick

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Acknowledgements

Thank you!

Conventions

Throughout this thesis we use the following conventions.

Text conventions

Definitions of technical terms or short excursus are set off in coloured boxes.

EXCURSUS:

Excursus are detailed discussions of a particular point in a book, usually in an appendix, or digressions in a written text.

Definition:
Excursus

Source code and implementation symbols are written in typewriter-style text.

`myClass`

The whole thesis is written in Canadian English.

Download links are set off in coloured boxes.

File: `myFile`^a

^ahttp://hci.rwth-aachen.de/public/folder/file_number.file

Chapter 1

Introduction

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Chapter 2

Related work

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Chapter 3

Hardware Prototype and Software Development

In this chapter we first describe the basic differences between the two most popular touch input technologies and which is best suited for wearable scenarios. Then we proceed with showing several iterations of the hardware prototypes using pinstripe and the corresponding software. Furthermore we describe the disadvantages and improvements of each iteration. The results of two user studies are discussed afterwards.

3.1 Resistive vs. Capacitive Touch

The two most popular touch input technologies are resistive and capacitive. Both serve the same purpose but the underlying principle differs making them more or less suited for wearable computing.

Advantages and Disadvantages of Resistive and Capacitive Touch Technology

3.1.1 Capacitive Touch

Characteristics of Capacitive Touch
ToDo: find simple explanation of capacitive touch.

The advantages of capacitive touch is the easy support for multi-touch input and the almost no need to press down the area of the sensor. The main disadvantage is the human body itself, since it generates its own capacitive field which makes it hard to detect the intentional touch. This flaw is intensified by the movement of the textile due to body movement. **TODO: source! Especially for earlier findings why it is worse than resistive**

3.1.2 Resistive Touch

Characteristics of
Resistive Touch

Resistive touch technology uses two separated layers of striped electrodes such that it is arranged to a matrix. The spacing material in ordinary resistive touch screens is either an air filled chamber or a non-conductive material which separates both layers while no external force is applied. Therefore one can operate it with a stylus or with gloves since no conductivity is required. On the one hand this solves the main disadvantage of the capacitive method regarding wearable computing, on the other hand it is still prone to deformation and thus to unintentional contacts.

Going for Resistive
Touch

After taking all characteristics into account we decided to go for the resistive touch technology, because we can drop all considerations of capacitive noise caused by the human body.

3.2 System Design

MSP430 for first
prototype
**ToDo: exact
specification of
pinstripe and
micro-controller und
den gripper probe
Klemmkabeln!!**

All prototypes presented here are using pinstripe, a fabric with separated conductive lines. For the first prototype we were using the Texas Instruments MSP430G2452 micro-controller. Each row and column of the pinstripe has to be connected to a *digitalRead* pin of the micro-controller. The MSP430 controller has 16 of these pins but only 14 can be used since two pins are used for serial communication. This results in a matrix resolution of 7 by 7 at maximum.

RESOLUTION IN PINSTRIPE CONTEXT:

When speaking of a certain resolution of our prototype, we talk about the number of connected rows and columns. Since the pinstripe fabric is of a static size, the higher the resolution the larger the prototype gets.

We are using the TI EK-TM4C1294XL for the advanced prototypes. This board has the ability to connect more than 40 pins for *digitalRead* to operate a 20 by 20 pinstripe matrix. The board is connected to a Computer via USB for serial communication.

For programming the micro-controller we are using the Energia IDE¹. It is an easy to use IDE to upload programs to the TI micro-controller. The micro-controller itself is solely responsible for sending the data of the sensor to the computer via serial communication. Meaning that it tests a pin against ground for each other line and column. A *1* is written to the serial-port when it is connected to another line or column and *0* otherwise. This is done for each pin where *numberOfPinstripes* is the number of all lines and columns. For each prototype an integer array is declared and can easily be commented and uncommented depending on the prototype. The where the pin numbers are sorted such that the first pins correspond to the x-axis and the last pins to the negative y-axis. After all pins were tested we send a line-break to determine the end of the current input.

Definition:

*Resolution in
pinstripe context*

Programming
Environment:
Energia IDE and
Processing to gather,
send and process
input data

```
void loop() {  
  for (int i = 0; i < numberOfPinstripes; i++)  
  {  
    pinMode(array[i], INPUT_PULLUP);  
    delay(2);  
    state = digitalRead(array[i]) ? '0' : '1';  
    pinMode(array[i], OUTPUT);  
    digitalWrite(array[i], LOW);  
    Serial.print(state);  
  }  
}
```

¹<http://energia.nu>

```
Serial.println();
delay(3);
}
```

We are using Processing², a Java based IDE, to structure the input stream from the micro-controller for further analyses. This includes several programs which either displays the raw touch points for debugging purpose or filters and interprets the sensor data. The changes of software are described along with each hardware iteration.

3.3 Early Testing

better note
something here

After deciding to go for the resistive approach, the essential challenge is to find a spacing material with certain characteristics. The material should

- be flexible by means of being wearable.
- reliably separate the pinstripe fabric while no touch is intended.
- concede rather easily when intended force is applied.

ToDo: Find names of
the fabrics and
materials

ToDo: insert picture
here
Combine materials to
improve results

We start by trying some leftovers from recent research projects. Then we place the materials between the pinstripe fabric to examine different behaviors. We glued both layers of the pinstripe fabric to sheets of paper to eliminate stretching and curling of the fabric. Some of the materials are cut with a laser-cutter. We cut equidistant circular holes to provide space for the pinstripe layers to connect. We attached 4 by 4 pinstripes to the MSP430 micro-controller. For displaying where a touch is present, we created a simple program with Processing. Almost all available materials are not well suited for our purpose, since they are either too thick, thin or stiff. When combining up to two materials, which are leading to permanent contacts on their own, the results are improving.

²<http://processing.org>

3.4 First Iteration of the Prototype

Chapter 4

Evaluation

In this chapter we will take a closer look at the performance of the prototypes in different physical conditions. Since the prototype is designed as a wearable, we have to take some continuously changing conditions into account.

4.1 Physical Limitation Study

The human body is in motion almost all the time, and the clothes are not fixed to it. This looseness, and the changing subsurface are variables that may influence the performance of our prototype.

Another variable is the friction of the overlaying material. Depending on the fabric and method of fashioning, it can, more or less likely, happen that the user slips of the touch-sensing area, or experiences an unpleasant feeling in the operating finger.

4.2 Study Design

4.3 Study Procedure

4.4 Participants

4.5 Results and Analysis

Chapter 5

Evaluation

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Chapter 6

Summary and future work

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6.1 Summary and contributions

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6.2 Future work

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Appendix A

TITLE OF THE FIRST APPENDIX

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Appendix B

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abbrv, *see* abbreviation

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