

Programming With Two-Level Type Theory

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What is this about

Concrete, unnamed, WIP language for high-level high-performance programming.

- High-level: FP abstractions, generic programming, strong types.
- High-performance: control over code generation, memory layout, allocation.

Non-goal: “systems” programming.

- We have substantial RTS with GC & full memory safety.

Past implementations: smaller demo [Kov22], Agda & Typed TH embedding [Kov24]

Currently in early stage of development: <https://github.com/AndrasKovacs/2ltt-impl>

Overview

- ① Motivation
- ② 2LTT intro
- ③ Monads
- ④ Fusion
- ⑤ Memory layout control
- ⑥ Region allocation

Motivation

I'm interested in high-performance type theory implementations.

GHC Haskell has been the clear best choice:

- High-throughput GC, decent code generation, unboxed types, compact regions, type classes, efficient laziness.

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- OCaml: GC leans more towards latency than throughput, less memory layout control.

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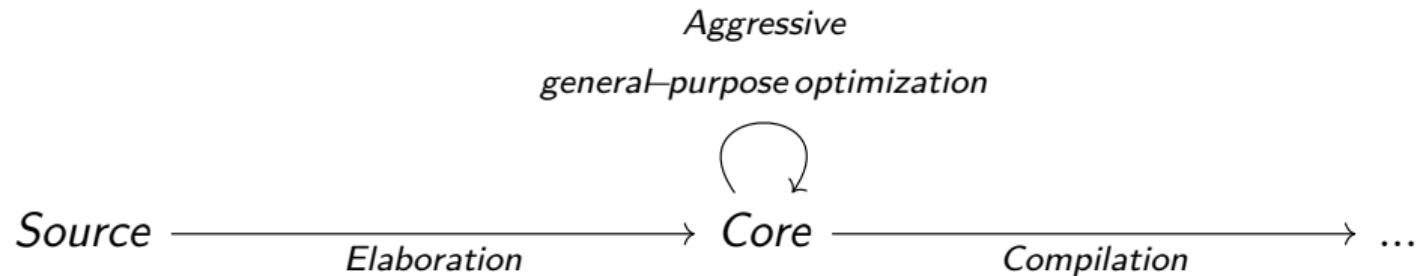
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However, major performance problems with GHC.

OxCaml: good progress but immature ecosystem ATM, legacy design constraints with many of the same problems as in GHC.

The GHC pipeline



The core simplifier is

- Complex.
- Unstable across GHC versions.
- Poorly controllable by users.

A lot of idiomatic Haskell relies on it for acceptable performance.

GHC example 1

Source:

```
f :: Reader Bool Int
f = do
  b <- ask
  if b then return 10
        else return 20
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-00 Core output:

```
dict1 :: Monad (Reader Int)
dict1 = MkMonad ...
dict2 :: MonadReader (Reader Int)
dict2 = MkMonadReader ...

f :: Reader Bool Int
f = (>>=) dict1 (ask dict2) (\b ->
  case b of True  -> return dict1 10
            False -> return dict1 20)
```

GHC example 2

`mapM` is third-order & rank-2 polymorphic, but almost all use cases should compile to first-order monomorphic code.

```
mapM :: Monad m => (a -> m b) -> m [a] -> m [b]
```

High-performance Haskell programming requires a read-eval-print-look-at-Core loop.

Revised pipeline



The *metalanguage* and the *object language* should be different.

- Simple object language supports better compilation & performance.
- Dependent type theory as metalanguage.

Main design question: explicit control in object language vs. optimizations in the compiler.

- Impractical manually: tail calls, dead code elimination, etc.

The 2LTT

Universes for stages:

- **Set** : **Set** contains **dependent** meta-level types.
- **Ty** : **Set** contains **simple** object-level types.
- **ValTy** : **Set** and **CompTy** : **Set** are subtypes of **Ty**.

Interaction between stages:

- **Lifting**: for $A : \text{Ty}$, we have $\uparrow A : \text{Set}$, as the type of metaprograms that produce A -typed object programs.
- **Quoting**: for $t : A$ and $A : \text{Ty}$, we have $\langle t \rangle : \uparrow A$ as the metaprogram which immediately returns t .
- **Splicing**: for $t : \uparrow A$, we have $\sim t : A$ which runs the metaprogram t and inserts its output in some object-level code.
- Definitional equalities: $\sim \langle t \rangle \equiv t$ and $\sim \sim t \equiv t$.

The object level

An object-level program:

```
data List (A : ValTy) := nil | cons A (List A)
```

```
f : List Int → List Int
```

```
f xs := case xs of
```

```
  nil      → nil
```

```
  cons x xs → cons (x + 10) (f xs)
```

Polarization:

- Functions have value arguments and are computations.
- Data types have value fields and are values.

The object level

Explicit type former for closures:

```
Close : CompTy → ValTy
close : A → Close A
open  : Close A → A
```

Mapping with closures:

```
map : Close (Int → Int) → List Int → List Int
map f xs = case xs of
  nil      → nil
  cons x xs → cons (open f x) (map f xs)
```

Closures are surprisingly rarely needed in practical programming!

Staging

Fully explicitly:

```
map : {A B : ValTy} → ( $\uparrow$ A →  $\uparrow$ B) ->  $\uparrow$ (List A) →  $\uparrow$ (List B)
map {A}{B} f as = <
  let go : List ~A → List ~B
    go as := case as of
      nil       → nil {~B}
      cons a as → cons {~B} ~( $f$  <a>) (go as)
  go ~as>
```

```
monoMap : List Int -> List Int
monoMap xs := ~(map ( $\lambda$  x. < $\sim$ x + 10>) <xs>)
```

Staging

Unstaged output:

```
monoMap : List Int → List Int
monoMap xs :=
  let go : List Int → List Int
    go as := case as of
      nil      → nil {Int}
      cons a as → cons {Int} (a + 10) (go as)
  go xs
```

With inference & elaboration

```
map : {A B : ValTy} → (A → B) → List A → List B
map f as =
  let go as := case as of
    nil      → nil
    cons a as → cons (f a) (go as)
  go as
```

```
monoMap : List Int → List Int
monoMap := map (λ x. x + 10)
```

How to compile: monads

Not easy! We want

- guaranteed closure-freedom for everything except CPS monads
- guaranteed fusion for straight-line code (e.g. jumps instead of constructor allocation in **Maybe**)
- proper handling of join points and tail calls
- modest code noise relative to Haskell

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Overview of the solution:

- The bulk of the logic is in a plain *library*.
- We use extra desugaring logic in **do**-blocks.
- It's good to have implicit coercions as an extra feature.
- *Tail calls* are guaranteed in the general-purpose optimizer.

Monads: the bulk of the logic

Monads only exist at compile time.

```
class Monad (M : Set → Set) where
  pure  : {A : Set} → A → M A
  (≫=) : {A B : Set} → M A → (A → M B) → M B
```

Recipe:

- ① We want to port a transformer stack from Haskell.
- ② We have an object-level type, same as in Haskell (but with polarities).
- ③ We have a meta-level transformer stack, which has an extra monad at the bottom, having *code generation as an effect*.
- ④ We define back-and-forth conversion between the object-level type and the metamonad.

The Gen monad

```
record Gen (A : Set) : Set = gen {unGen : {R : Ty} → (A → ↑R) → ↑R}

instance Monad Gen where ...

runGen : Gen ↑A → ↑A
runGen (gen f) = f id

class Monad M => MonadGen M where
  liftGen : Gen A → M A

genLet : MonadGen M => ↑A → M ↑A
genLet a = liftGen λ k. <let x := ~a; ~(k <x>)>
```

The Gen monad

```
f : Int  
f := ~ (runGen do  
  x ← genLet <10 + 20>  
  y ← genLet <~x * 10>  
  pure <~x + ~y>)
```

unstage

==>

```
f : Int  
f :=  
  let x := 10 + 20  
  let y := x * 10  
  x + y
```

Case splitting in Gen

```
data BoolM : Set = trueM | falseM
data Bool : ValTy := true | false

down : BoolM → ↑Bool
down x = case x of trueM → <true>; falseM → <false>

up : ↑Bool → BoolM
up = IMPOSSIBLE
```

However:

```
up : MonadGen M => ↑Bool → M BoolM
up b = liftGen λ k. <case ~b of true → ~(k trueM); false → ~(k falseM)>
```

Case splitting in MonadGen

We add **extra desugaring** in **MonadGen** **do**-blocks for case splitting.

```
f : Bool → Bool  
f b := runGen do  
  case b of  
    true → pure false  
    false → pure true
```

elaborate
==>

```
f : Bool → Bool  
f b := ~(runGen do  
  b ← up <b>  
  case b of  
    trueM → pure <false>  
    falseM → pure <true>)
```

Monads in general

Implicit conversion between metamonads and runtime types, defined by recursion on the transformer stack (details in [Kov24]). Overloading in `mtl`-style. Example:

<code>M : Ty</code>		
<code>M = StateT Int (ReaderT Bool Identity)</code>		
<code>f : M ()</code>		<code>f : M ()</code>
<code>f := do</code>		<code>f = stateT λ s. readerT λ r.</code>
<code>b <- ask</code>	<code>unstage</code>	<code>case r of</code>
<code>n <- get</code>	<code>==></code>	<code>true → let s := s + 10; (), s</code>
<code>case b of</code>		<code>false → let s := s * 10; (), s</code>
<code>true → put \$ n + 10</code>		
<code>false → put \$ n * 10</code>		

Monads in general

Only a modest amount of extra noise compared to Haskell.
(But no native implementation yet!)

All of **mtl** works. Closures are only needed in **ContT**.

Reader and **State** are computation types! We need to wrap them in **Close** to store them in data structures.

Memory layout control

All constructors are unboxed by default.

```
data Pair A B := pair A B  
data Sum A B := left A | right B
```

Recursive constructors must be guarded by a *pointer to a region*. **Hp** is the general GC-d heap.

```
data List A := nil | cons@Hp A (List A)
```

Weird sum type with just one unboxed constructor:

```
data Sum A B := left A | right@Hp B
```

Tag-free GC & bit-stealing

GC is *almost tag-free*: only 1 bit metadata per heap object.

Arbitrary data can be opportunistically stored into unused bits in pointers.

On x64: we use 16 bits in pointers for storage, 1 reserved for GC.

Huge space savings compared to GHC!

Tag-free GC & bit-stealing

Example: pure lambda terms with 32-bit variables.

```
data Tm := var UInt32 | app@Hp Tm Tm | lam@Hp Tm
```

Layout of `app (var 0) (var 1)`

```
| app | ptr |           -- 1 word  
    ↓  
| var | 0 | var | 1 |   -- 2 words
```

Same in GHC:

```
| app | ptr |           -- 1 word  
    ↓  
| app     | ptr       | ptr |       -- 3 words  
    ↓           ↓  
| var | 0 |     | var | 1 |   -- 4 words
```

Tag-free GC & bit-stealing

Implementation: explored back in the 90s [?].

In a simple type theory, it's enough to know the types (memory layouts) of GC roots.

For each monotype, we generate code for GC scanning & copying.

Only *stack frames* need to store runtime type information about roots.

Regions

```
Location : Set
Hp       : Location
Region   : Set
```

There's implicit coercion from **Region** to **Location**. The object language supports dependent functions of the form **(R : Region) →**

Lists with cons cells in a specified location:

```
data List (L : Location) (A : ValTy) := nil | cons@L A (List L A)
```

Regions

Example: list in a local region.

```
sum : {R : Region} → List R Int → Int
sum xs := case xs of nil → 0; cons x xs → x + sum xs

countDown : {R : Region} → Int → List R Int
countDown x := case x of 0 → nil
                  n → cons x (countDown (x - 1))

f : Int → Int
f x :=
  let R : Region
  let xs : List R Int := countDown x
  sum xs
```

András Kovács.

Staged compilation with two-level type theory.

Proc. ACM Program. Lang., 6(ICFP):540–569, 2022.

András Kovács.

Closure-free functional programming in a two-level type theory.

Proc. ACM Program. Lang., 8(ICFP):659–692, 2024.