

# André Biedenkapp

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## Personal Information

**Date of birth:** 13.07.1992

**Nationality:** German

## Research Interests

- Dynamic Algorithm Configuration [see, e.g., 1, 6, 10, 13, 14, 17, 18]
- Learning to Learn [see, e.g., 11, 12]
- Deep Reinforcement Learning [see, e.g., 15, 26, 5]
- Automated Machine Learning and Reinforcement Learning [see, e.g., 9, 7, 15, 16, 22]

## Education

### PhD (Dr. rer. nat.)

Albert-Ludwigs-University Freiburg

Supervised by Prof. Frank Hutter and Prof. Marius Lindauer

2018 – 2022

Thesis: Dynamic Algorithm Configuration by Reinforcement Learning (Grade: **Summa Cum Laude**)

### Summer School

**Reinforcement Learning Summer SCHOOL (RLSS'19)**

In: Lille, France

July 2019

Topics: Reinforcement Learning and Bandits

### Computer Science

Albert-Ludwigs-University Freiburg

Master of Science (M.Sc.)

2014 – 2017

Thesis: Per Instance Algorithm Configuration (Grade: 1.0)

Supervisor: Prof. Dr. Frank Hutter

### Computer Science

Albert-Ludwigs-University Freiburg

Bachelor of Science (B.Sc.)

2011 – 2014

Thesis: Data Analysis for the Selection of Recording Channels on Multielectrode-Arrays (Grade: 1.7)

Supervisor: Prof. Dr. Wolfram Burgard

## Publications

 [Google Scholar](#)

 [DBLP](#)

 [0000-0002-8703-8559](#)

Journal and conference rankings are according to CORE'20 (<https://www.core.edu.au/conference-portal>)

### Thesis

- [1] **A. Biedenkapp**. “Dynamic Algorithm Configuration by Reinforcement Learning”. *Grade: Summa Cum Laude (best possible grade)*. PhD thesis. Freiburg, Germany: University of Freiburg, Department of Computer Science, Machine Learning Chair, Oct. 2022.
- [2] **A. Biedenkapp**. “Per Instance Algorithm Configuration”. *Grade: 1.0 (best possible grade)*. Master's Thesis. Freiburg, Germany: University of Freiburg, Department of Computer Science, Machine Learning Chair, 2017.
- [3] **A. Biedenkapp**. “Data Analysis for the Selection of Recording Channels on Multielectrode-Arrays”. Bachelor's Thesis. Freiburg, Germany: University of Freiburg, Department of Computer Science, Autonomous Intelligent Systems, Mar. 2014.

### Journal Publications

- [4] R. Rajan, J. L. B. Diaz, S. Guttikonda, F. Ferreira, **A. Biedenkapp**, J. O. von Hartz, and F. Hutter. “MDP Playground: An Analysis and Debug Testbed for Reinforcement Learning”. In: *Journal of Artificial Intelligence Research (JAIR)* 77 (2023). *Journal Rating: A*, pp. 821–890.
- [5] C. Benjamins, T. Eimer, F. Schubert, A. Mohan, S. Döhler, **A. Biedenkapp**, B. Rosenhan, F. Hutter, and M. Lindauer. “Contextualize Me – The Case for Context in Reinforcement Learning”. In: *Transactions on Machine Learning Research (TMLR)* (2023). ISSN: 2835-8856. URL: <https://openreview.net/forum?id=Y42xVBQusn>.

- [6] S. Adriaensen, **A. Biedenkapp**, G. Shala, N. Awad, T. Eimer, M. Lindauer, and F. Hutter. “Automated Dynamic Algorithm Configuration”. In: *Journal of Artificial Intelligence Research (JAIR)* 75 (2022). *Journal Rating: A*, pp. 1633–1699. DOI: <https://doi.org/10.1613/jair.1.13922>.
- [7] J. Parker-Holder, R. Rajan, X. Song, **A. Biedenkapp**, Y. Miao, T. Eimer, B. Zhang, V. Nguyen, R. Calandra, A. Faust, F. Hutter, and M. Lindauer. “Automated Reinforcement Learning (AutoRL): A Survey and Open Problems”. In: *Journal of Artificial Intelligence Research (JAIR)* 74 (2022). *Journal Rating: A*, pp. 517–568. DOI: <https://doi.org/10.1613/jair.1.13596>.
- [8] M. Lindauer, K. Eggenberger, M. Feurer, **A. Biedenkapp**, D. Deng, C. Benjamins, R. Sass, and F. Hutter. “SMAC3: A Versatile Bayesian Optimization Package for Hyperparameter Optimization”. In: *Journal of Machine Learning Research (JMLR) – MLOSS* 23.54 (2022). *Journal Rating: A\**, pp. 1–9. URL: <http://jmlr.org/papers/v23/21-0888.html>.

## Conference Publications.....

- [9] G. Shala, **A. Biedenkapp**, F. Hutter, and J. Grabocka. “Gray-Box Gaussian Processes for Automated Reinforcement Learning”. In: *Proceedings of the International Conference on Learning Representations (ICLR’23)*. Published online: [iclr.cc](https://iclr.cc), *Acceptance rate: 31.8%*, *Conference Rating: A\**. 2023.
- [10] **A. Biedenkapp\***, N. Dang\*, M. S. Krejca\*, F. Hutter, and C. Doerr. “Theory-inspired Parameter Control Benchmarks for Dynamic Algorithm Configuration”. In: *Proceedings of the Genetic and Evolutionary Computation Conference (GECCO’22)*. **Joint first authorship**, *Conference Rating: A*, *Won the Best Paper Award (GECH track)*. ACM, July 2022.
- [11] **A. Biedenkapp**, R. Rajan, F. Hutter, and M. Lindauer. “TempoRL: Learning When to Act”. In: *Proceedings of the Thirty-eighth International Conference on Machine Learning*. *Acceptance rate: 21.5%*, *Conference Rating: A\**. July 2021, pp. 914–924.
- [12] T. Eimer, **A. Biedenkapp**, F. Hutter, and M. Lindauer. “Self-Paced Context Evaluation for Contextual Reinforcement Learning”. In: *Proceedings of the Thirty-eighth International Conference on Machine Learning*. *Acceptance rate: 21.5%*, *Conference Rating: A\**. July 2021, pp. 2948–2958.
- [13] T. Eimer, **A. Biedenkapp**, M. Reimer, S. Adriaensen, F. Hutter, and M. Lindauer. “DACBench: A Benchmark Library for Dynamic Algorithm Configuration”. In: *Proceedings of the Thirtieth International Joint Conference on Artificial Intelligence (IJCAI’21)*. *Acceptance rate: 19.3%*, *Conference Rating: A\**. [ijcai.org](https://ijcai.org), Aug. 2021, pp. 1668–1674.
- [14] D. Speck\*, **A. Biedenkapp\***, F. Hutter, R. Mattmüller, and M. Lindauer. “Learning Heuristic Selection with Dynamic Algorithm Configuration”. In: *Proceedings of the Thirty-First International Conference on Automated Planning and Scheduling (ICAPS’21)*. **Joint first authorship**, *Acceptance rate: ~30%*, *Conference Rating: A\**. Aug. 2021, pp. 597–605.
- [15] B. Zhang, R. Rajan, L. Pineda, N. Lambert, **A. Biedenkapp**, K. Chua, F. Hutter, and R. Calandra. “On the Importance of Hyperparameter Optimization for Model-based Reinforcement Learning”. In: *Proceedings of the International Conference on Artificial Intelligence and Statistics (AISTATS’21)*. *Acceptance rate: 29.8%*, *Conference Rating: A*. Apr. 2021.
- [16] J. KH Franke, G. Köhler, **A. Biedenkapp**, and F. Hutter. “Sample-Efficient Automated Deep Reinforcement Learning”. In: *Proceedings of the International Conference on Learning Representations (ICLR’21)*. Published online: [iclr.cc](https://iclr.cc), *Acceptance rate: 28.7%*, *Conference Rating: A\**. May 2021.
- [17] G. Shala\*, **A. Biedenkapp\***, N. Awad, S. Adriaensen, F. Hutter, and M. Lindauer. “Learning Step-Size Adaptation in CMA-ES”. In: *Proceedings of the Sixteenth International Conference on Parallel Problem Solving from Nature (PPSN’20)*. **Joint first authorship**, *Conference Rating: A*. Sept. 2020, pp. 691–706.
- [18] **A. Biedenkapp**, H. F. Bozkurt, T. Eimer, F. Hutter, and M. Lindauer. “Dynamic Algorithm Configuration: Foundation of a New Meta-Algorithmic Framework”. In: *Proceedings of the European Conference on Artificial Intelligence (ECAI)*. *Acceptance rate: 26.8%*, *Conference Rating: A*. June 2020, pp. 427–434.

- [19] **A. Biedenkapp**, J. Marben, M. Lindauer, and F. Hutter. "CAVE: Configuration Assessment, Visualization and Evaluation". In: *Proceedings of the International Conference on Learning and Intelligent Optimization (LION'18)*. June 2018.
- [20] **A. Biedenkapp**, M. Lindauer, K. Eggenberger, C. Fawcett, H. Hoos, and F. Hutter. "Efficient Parameter Importance Analysis via Ablation with Surrogates". In: *Proceedings of the AAAI conference. Acceptance rate: 24.6%, Conference Rating: A\**. Feb. 2017, pp. 773–779.

#### Workshop Publications & Preprints.....

- [21] G. Shala, **A. Biedenkapp**, and J. Grabocka. "Hierarchical Transformers are Efficient Meta-Reinforcement Learners". In: *arXiv:2402.06402* (2024).
- [22] G. Shala, **A. Biedenkapp**, F. Hutter, and J. Grabocka. "Gray-Box Gaussian Processes for Automated Reinforcement Learning". In: *Workshop on Meta-Learning (MetaLearn@NeurIPS'22)*. 2022.
- [23] G. Shala, S. Pineda Arango, **A. Biedenkapp**, F. Hutter, and J. Grabocka. "AutoRL-Bench 1.0". In: *Workshop on Meta-Learning (MetaLearn@NeurIPS'22)*. 2022.
- [24] R. Sass, E. Bergman, **A. Biedenkapp**, F. Hutter, and M. Lindauer. "DeepCAVE: An Interactive Analysis Tool for Automated Machine Learning". In: *Workshop on Adaptive Experimental Design and Active Learning in the Real World (ReALML@ICML'22)*. 2022.
- [25] **A. Biedenkapp**, D. Speck, S. Sievers, F. Hutter, M. Lindauer, and J. Seipp. "Learning Domain-Independent Policies for Open List Selection". In: *Workshop on Bridging the Gap Between AI Planning and Reinforcement Learning (PRL@ICAPS'22)*. 2022.
- [26] C. Benjamins, T. Eimer, F. Schubert, **A. Biedenkapp**, B. Rosenhan, F. Hutter, and M. Lindauer. "CARL: A Benchmark for Contextual and Adaptive Reinforcement Learning". In: *Workshop on Ecological Theory of Reinforcement Learning (EcoRL@NeurIPS'21)*. Sept. 2021.
- [27] S. Izquierdo, J. Guerrero-Viu, S. Hauns, G. Miotto, S. Schrod, **A. Biedenkapp**, T. Elsken, D. Deng, M. Lindauer, and F. Hutter. "Bag of Baselines for Multi-objective Joint Neural Architecture Search and Hyperparameter Optimization". In: *Workshop on Automated Machine Learning (AutoML@ICML'21)*. May 2021.
- [28] S. Müller, **A. Biedenkapp**, and F. Hutter. "In-Loop Meta-Learning with Gradient-Alignment Reward". In: *AAAI workshop on Meta-Learning Challenges (MetaLearning@AAAI'21)*. Feb. 2021.
- [29] N. Awad, G. Shala, D. Deng, N. Mallik, M. Feurer, K. Eggenberger, **A. Biedenkapp**, D. Vermetten, H. Wang, C. Doerr, M. Lindauer, and F. Hutter. "Squirrel: A Switching Hyperparameter Optimizer Description of the entry by AutoML.org & IOHprofiler to the NeurIPS 2020 BBO challenge". In: *arXiv:2012.08180* (Dec. 2020). **Winning entry of the BBO Competition@NeurIPS'20 on a meta-learnable search space.**
- [30] **A. Biedenkapp**, R. Rajan, F. Hutter, and M. Lindauer. "Towards TempoRL: Learning When to Act". In: *Workshop on Inductive Biases, Invariances and Generalization in RL (BIG@ICML'20)*. July 2020.
- [31] T. Eimer, **A. Biedenkapp**, F. Hutter, and M. Lindauer. "Towards Self-Paced Context Evaluation for Contextual Reinforcement Learning". In: *Workshop on Inductive Biases, Invariances and Generalization in RL (BIG@ICML'20)*. July 2020.
- [32] **A. Biedenkapp**, H. F. Bozkurt, F. Hutter, and M. Lindauer. "Towards White-Box Benchmarks for Algorithm Control". In: *IJCAI 2019 DSO Workshop*. Aug. 2019.
- [33] M. Lindauer, M. Feurer, K. Eggenberger, **A. Biedenkapp**, and F. Hutter. "Towards Assessing the Impact of Bayesian Optimization's Own Hyperparameters". In: *IJCAI 2019 DSO Workshop*. Aug. 2019.
- [34] M. Lindauer, K. Eggenberger, M. Feurer, **A. Biedenkapp**, J. Marben, P. Müller, and F. Hutter. "BOAH: A Tool Suite for Multi-Fidelity Bayesian Optimization & Analysis of Hyperparameters". In: *arXiv:1908.06756* (Aug. 2019).

## Blog Posts.....

- [35] T. Eimer, R. Rajan, A. Mohan, and **A. Biedenkapp**. “2023 in AutoRL”. In: *autorl.org* (Jan. 2024). URL: <http://autorl.org/blog/retrospective/#2023-in-autorl>.
- [36] **A. Biedenkapp**, R. Rajan, F. Hutter, and M. Lindauer. “TempoRL - Learning When to Act”. In: *Personal Blog* (May 2022). URL: <https://andrebieidenkapp.github.io/blog/2022/temporl/>.
- [37] **A. Biedenkapp**, N. Dang, M. S. Krejca, F. Hutter, and C. Doerr. “Theory-Inspired Parameter Control Benchmarks for DAC”. In: *Personal Blog* (May 2022). URL: <https://andrebieidenkapp.github.io/blog/2022/gecco/>.
- [38] N. Lambert, B. Zhang, R. Rajan, and **A. Biedenkapp**. “The Importance of Hyperparameter Optimization for Model-based Reinforcement Learning”. In: <https://bair.berkeley.edu/blog> (Apr. 2021). URL: <https://bair.berkeley.edu/blog/2021/04/19/mbrl/>.
- [39] R. Rajan, **A. Biedenkapp**, T. F. Runge, and J. Franke. “AutoRL: AutoML in the Realm of Deep Reinforcement Learning”. In: <https://www.automl.org/automl-blog> (Apr. 2021). URL: <https://www.automl.org/blog-autorl>.
- [40] **A. Biedenkapp**. “Learning Step-Size Adaptation in CMA-ES”. In: <https://www.automl.org/automl-blog> (Aug. 2020). URL: <https://www.automl.org/learning-step-size-adaptation-in-cma-es>.
- [41] **A. Biedenkapp**. “Dynamic Algorithm Configuration”. In: <https://www.automl.org/automl-blog> (Feb. 2020). URL: <https://www.automl.org/dynamic-algorithm-configuration>.
- [42] **A. Biedenkapp** and F. Hutter. “BOHB”. In: <https://www.automl.org/automl-blog> (Aug. 2018). URL: [https://www.automl.org/blog\\_bohb](https://www.automl.org/blog_bohb).
- [43] **A. Biedenkapp**, K. Eggensperger, M. Feurer, and F. Hutter. “2nd AutoML Challenge”. In: <https://www.automl.org/automl-blog> (Aug. 2018). URL: <https://www.automl.org/blog-2nd-automl-challenge>.

## Patents

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- [44] **A. Biedenkapp**, G. Shala, S. Adriaensen, N. Awad, M. Lindauer, and F. Hutter. “Method and Device for Learning a Strategy and for Implementing the Strategy”. U.S. pat. req. 17/305,586. Robert Bosch GmbH. July 9, 2021. Filed.
- [45] S. Müller, **A. Biedenkapp**, and F. Hutter. “Verbesserte Vorrichtung zum Anlernen von maschinellen Lernsysteme für Bildverarbeitung”. German pat. DE202021100225. Robert Bosch GmbH. Feb. 12, 2021. URL: <https://depatisnet.dpma.de/DepatisNet/depatisnet?action=bibdat&docid=DE202021100225U1>.
- [46] D. Speck, **A. Biedenkapp**, R. Matmüller, F. Hutter, and M. Lindauer. “Device and Method for Planning and Operation of a Technical System”. U.S. pat. req. 17/242,790. Robert Bosch GmbH. Apr. 28, 2021. Filed.
- [47] D. Speck, **A. Biedenkapp**, R. Matmüller, F. Hutter, and M. Lindauer. “Device and Method for Planning and Operation of a Technical System”. European pat. req. EP20178576.3 – 1203. Robert Bosch GmbH. *Also filed requests for US patent and CN patent*. June 1, 2020. URL: <http://v3.espacenet.com/textdoc?IDX=EP3920103>. Filed.
- [48] **A. Biedenkapp**, H. F. Bozkurt, F. Hutter, and M. Lindauer. “Method, Device and Computer Program for Adjusting a Hyperparameter”. European pat. req. EP3748551. Robert Bosch GmbH. June 11, 2020. URL: <http://v3.espacenet.com/textdoc?IDX=EP3748551>. Filed.

## Work experience

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Position held.....	
<b>Machine Learning Lab</b> <i>Postdoctoral Researcher</i> Topic: Automated Reinforcement Learning	<b>Albert-Ludwigs-University Freiburg</b> <i>Since 10.2022</i>
Past positions.....	
<b>Machine Learning Lab</b> <i>Doctoral Researcher</i> Topic: Dynamic Algorithm Configuration	<b>Albert-Ludwigs-University Freiburg</b> <i>02.2018 - 10.2022</i>
<b>Machine Learning Lab</b> <i>Student Assistant</i> Assisting in the implementation of research projects	<b>Albert-Ludwigs-University Freiburg</b> <i>10.2015 - 09.2017</i>
<b>Chair of Computer Architecture</b> <i>Student Assistant</i> Maintenance of the mobile robots for the Hardware-Labcourse	<b>Albert-Ludwigs-University Freiburg</b> <i>04.2014 - 09.2014</i>

## Teaching Experience

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<b>Meta-Algorithmics &amp; AutoML</b> <i>Undergraduate lecture</i> Guest Lecture as part of the "Artificial Intelligence Practice" course at the St. Andrews University	<i>04.2023</i>
<b>Dynamic Algorithm Configuration and Optimization</b> <i>Seminar, Achieved the top grade (1.0) in the student teaching evaluation</i> Responsible for setting up the seminar. Jointly held with Prof. Frank Hutter and Dr. Noor Awad	<i>10.2022 - 02.2023</i>
<b>Automated Machine Learning</b> <i>Lab course</i> Responsible for setting up the lab course. Jointly held with Prof. Frank Hutter and Rhea Sukthanker	<i>10.2022 - 02.2023</i>
Teaching Assistant.....	
<b>Foundations of Deep Learning</b> <i>Graduate course</i> Grading of exercises & creating the exam.	<b>(Flipped Classroom)</b> <i>10.2023 - 03.2024</i>
<b>Automated Machine Learning</b> <i>Graduate course, Ranked first place in the student teaching evaluation</i> Creation and grading of exercises & final project.	<b>(Flipped Classroom)</b> <i>04.2023 - 09.2023</i>
<b>Automated Machine Learning</b> <i>Graduate course</i> Creation and grading of exercises & final project.	<b>(Flipped Classroom)</b> <i>04.2022 - 09.2022</i>
<b>Automated Machine Learning</b> <i>Graduate course</i> Creation of coding exercises. Involved in setting up the MOOC	<b>Massive Open Online Course (MOOC)</b> <i>Published 04.2021</i>
<b>Automated Machine Learning</b> <i>Graduate course, Virtual, Ranked first place in the student teaching evaluation</i> Creation and grading of exercises & final project. Setting up online teaching through Zoom and GitHub classroom.	<b>(Flipped Classroom)</b> <i>04.2021 - 09.2021</i>
<b>Automated Machine Learning</b> <i>Graduate course, Virtual</i> Creation and grading of exercises & final project. Setting up online teaching through Zoom and GitHub classroom.	<b>(Flipped Classroom)</b> <i>04.2020 - 09.2020</i>
<b>Automated Machine Learning</b> <i>Graduate course</i> Creation and grading of exercises & final project	<i>04.2019 - 09.2019</i>

<b>Machine Learning for Automated Algorithm Design</b> <i>Graduate course</i> Creation and grading of exercises & final project	10.2018 – 03.2019
<b>Machine Learning for Automated Algorithm Design</b> <i>Graduate course</i> Creation and grading of exercises & final project	10.2017 – 03.2018
<b>Hardware-Labcourse</b> <i>Undergraduate course</i> Assisting students with practical exercises	04.2014 – 09.2014

## Student Supervision.....

<b>MSc Thesis</b> <i>L. Gieringer</i> <i>Working Title:</i> Towards General Offline RL-Based Dynamic Algorithm Configuration	<i>started 01.2024</i>
<b>MSc Thesis</b> <i>J. Fix</i> <i>Working Title:</i> Towards Dynamical Learning Rate Adaptation in Neural Network Optimization Using Multi-Teacher Offline RL	<i>started 01.2024</i>
<b>MSc Project</b> <i>P. Bordne</i> <i>Working Title:</i> Multi-Timescale Multi-Agent RL for Dynamic Algorithm Configuration	<i>started 06.2023</i>
<b>MSc Thesis</b> <i>J. Hog, Joint supervision with R. Rajan and V. Nguyen</i> Meta Learning Through Time With Population-Based Bandits	05.2023 – 12.2023
<b>MSc Project</b> <i>J. Fix &amp; L. Gieringer, Joint supervision with N. Awad</i> Crowd Control: A case study in scaling individual DE population members using Offline RL for DAC	05.2023 – 10.2023
<b>MSc Thesis at the University of St. Andrews</b> <i>M. Hossain, Joint supervision with N. Dang</i> Dynamic Algorithm Configuration with Proximal Policy Optimisation	04.2023 – 08.2023
<b>MSc Thesis</b> <i>F. Diederichs, Joint supervision with N. Awad</i> On the Applicability of Offline Reinforcement Learning for Dynamic Algorithm Configuration of Differential Evolution	09.2022 – 02.2023
<b>MSc Thesis</b> <i>B. Zhang, Joint supervision with R. Rajan, Published at AISTATS'21</i> On the Importance of Hyperparameter Optimization in Model-based Reinforcement Learning	04.2020 – 10.2020
<b>MSc Project &amp; Thesis</b> <i>G. Shala, Published at PPSN'20</i> Learning to Optimize CMA-ES	04.2019 – 05.2020
<b>MSc Thesis</b> <i>H. F. Bozkurt</i> RL-DCBO: Reinforcement Learning Guided Dynamic Control for Bayesian Optimization	03.2019 – 11.2019
<b>MSc Thesis</b> <i>T. Eimer, Follow up work published at ICML'21</i> Improved Meta-Learning for Algorithm Control through Self-Paced Learning	12.2018 – 09.2019
<b>MSc Thesis</b> <i>K. Hättig</i> Model-Based Population Based Training	12.2018 – 09.2019
<b>MSc Thesis</b> <i>O. Brunner, Joint supervision with D. Speck at GKI-Freiburg</i>	11.2018 – 04.2019

## MSc Project

T. Eimer & K. Hättig

04.2018 – 12.2018

Algorithm State Description for Algorithm Control

## Presentations

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### Invited Talks & Competitively-Selected Tutorials.....

#### Meta-Algorithmics & AutoML

*Invited Lecture (part of CS5011), University of St. Andrews, Scotland (online)* 04.2023

#### Learning to Dynamically Optimise Algorithms

*Seminar on Advances in Probabilistic Machine Learning, Aalto University Helsinki, Finland (online)* 11.2022

#### Dynamic Algorithm Configuration

*ELLIS Meetup Freiburg, Freiburg, Germany* 03.2022

#### Advances of Dynamic Algorithm Configuration

*Bosch Center for Artificial Intelligence, Renningen, Germany* 06.2021

#### Algorithm Configuration: Challenges, Methods and Perspectives

*IJCAI 2020 Tutorial* 01.2021

Jointly with Prof. Marius Lindauer

#### Algorithm Configuration: Challenges, Methods and Perspectives

*PPSN 2020 Tutorial* 09.2020

Jointly with Prof. Marius Lindauer

#### Challenges of Dynamic Algorithm Configuration

*Bosch Center for Artificial Intelligence, Renningen, Germany* 03.2020

#### Dynamic Algorithm Configuration

*Institut für Informationsverarbeitung (TNT), University of Hannover* 01.2020

### Conference Presentations.....

#### The Genetic and Evolutionary Computation Conference

Online

*GECCO (Oral, Joint video presentation with all authors)*

07.2022

Theory-inspired Parameter Control Benchmarks for Dynamic Algorithm Configuration

#### International Conference on Machine Learning

Online

*ICML (Poster)*

07.2021

TempoRL: Learning When to Act

#### International Conference on Parallel Problem Solving from Nature

Leiden

*PPSN (Poster), Netherlands*

08.2020

Learning Step-SizeAdaptation in CMA-ES

#### European Conference on Artificial Intelligence

Santiago de Compostela

*ECAI (Oral), Spain*

08.2020

Dynamic Algorithm Configuration: Foundation of a New Meta-Algorithmic Framework

#### Learning and Intelligent OptimizationN Conference

Kalamata

*LION (Oral), Greece*

06.2018

CAVE: Configuration Assessment, Visualization and Evaluation

#### AAAI Conference on Artificial Intelligence

San Francisco

*AAAI (Poster), California, USA*

02.2017

Efficient Parameter Importance Analysis via Ablation with Surrogates

### Workshop Presentations.....

#### Bridging the Gap Between AI Planning and Reinforcement Learning

Online

*PRL@ICAPS'22*

06.2022

Learning Domain-Independent Policies for Open List Selection

<b>Inductive Biases, Invariances and Generalization in Reinforcement Learning</b> <i>BIG@ICML'20</i> Towards TempoRL: Learning When to Act	<b>Online</b> 07.2020
<b>Data Science Meets Optimisation</b> <i>DSO@IJCAI'19, Macau (SAR), China</i> Towards White-box Benchmarks for Algorithm Control	<b>Macau</b> 08.2019

## Funding Acquisition

Research grants, as proposal contributor.....	
<b>Alliance Sorbonne Université project under the Emergence 2023/24 funding call</b>	<b>€ 60 000</b>
<i>Team member &amp; involved in drafting the proposal, PI: Carola Doerr</i>	09.2023 - 08.2025
<b>DFG<sup>1</sup> Collaborative Research Center "Small Data"</b>	
<i>Involved in drafting project C04, WP PI: Noor Awad, WP co-PI: Joschka Bödecker</i>	10.2023 - 09.2027
<b>CZS<sup>2</sup> Breakthroughs project "ReScaLe"</b>	
<i>Contributed to the draft of WP5, WP PI: Noor Awad, WP co-PI: Joschka Bödecker</i>	06.2021 - 05.2028

## Scholarships, Honors and Awards

<b>Best Paper Award</b>	
<i>GECCO'22, Theory-inspired Parameter Control Benchmarks for Dynamic Algorithm Configuration</i>	2022
GECH Track	
<b>Best Reviewers (Top 10%)</b>	
<i>ICML'21</i>	2021
<b>Black-Box Optimization Competiton@NeurIPS'20</b>	<b>1st place</b>
<i>Part of the AutoML &amp; IOHprofiler Team, 1st place on a meta-learning friendly search space</i>	2020
Leaderboard: <a href="https://bbobchallenge.com/altleaderboard">https://bbobchallenge.com/altleaderboard</a>	
<b>Black-Box Optimization Competiton@NeurIPS'20</b>	<b>3rd place*</b>
<i>Part of the AutoML &amp; IOHprofiler Team, Leaderboard: <a href="https://bbobchallenge.com/leaderboard">https://bbobchallenge.com/leaderboard</a></i>	2020
*Due to a bug the initial evaluation failed. After re-evaluation our team would have gotten the third place.	

## Professional Service

Organizer.....	
<b>AutoML Conference - Online Experience Chair</b>	
<i>2023 &amp; 2024</i>	
Jointly with Gabi Kadlecová in 2024 and 2023 jointly with Hayeon Lee, Mohammed Abdelfattah & Richard Song	
<b>COSEAL Chair</b>	
<i>since August 2022, Jointly with Alexander Tornede and Lennart Schäpermeier</i>	
<b>2nd AutoML Fall School</b>	
<i>2022, Local Organiser</i>	
<b>ELLIS Unit Meetups Freiburg</b>	
<i>07.2022-12.2022, Co-Organiser with Simon Ging</i>	
Involved in setting up the first "ELLIS Social" followup event in 2023	
Journal Reviewing.....	
<b>Autonomous Agents and Multi-Agent Systems</b>	<b>JAAMAS</b>
<i>2023</i>	
<b>Journal of Artificial Intelligence Research</b>	<b>JAIR</b>
<i>2024, 2023, 2022</i>	

<sup>1</sup>Deutsche Forschungsgemeinschaft – German Research Council

<sup>2</sup>Carl Zeiss Stiftung



<b>IEEE Transactions on Evolutionary Computation</b> 2022	<b>TEVC</b>
<b>Computational Intelligence</b> 2022	<b>CI</b>
<b>Journal of the Association for Computing Machinery</b> 2022, 2021	<b>Journal of the ACM</b>
Program Committee Membership at Conferences.....	
<b>AAAI Conference on Artificial Intelligence</b> 2018	<b>AAAI</b>
<b>AutoML Conference</b> 2024, 2023, 2022	<b>AutoML</b>
<b>European Conference on Artificial Intelligence</b> 2024, 2020	<b>ECAI</b>
<b>International Conference on Machine Learning</b> 2024, 2023, 2021, 2019	<b>ICML</b>
<b>International Conference on Learning Representations</b> 2024	<b>ICLR</b>
<b>Neural Information Processing Systems</b> 2023, 2022, 2021	<b>NeurIPS</b>
<b>NeurIPS Datasets and Benchmarks</b> 2021 (Track 1 & Track 2)	<b>NeurIPS DBT</b>
Program Committee Membership at Workshops.....	
<b>ICLR Workshop on Agent Learning in Open-Endedness</b> 2022	<b>ALOE</b>
<b>ICML Workshop on Automated Machine Learning</b> 2021, 2020, 2019, 2018	<b>AutoML@ICML</b>
<b>European Workshop on Reinforcement Learning</b> 2023, 2022	<b>EWRL</b>
<b>NeurIPS Workshop on Meta-Learning</b> 2019	<b>MetaLearn@NeurIPS</b>

## Programming Skills

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**Excellent:** Python, Bash,  $\text{\LaTeX}$       **Good:** C, C#, C++, Julia      **Basic:** Matlab, Java

## Selected Open-Source Projects

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**GitHub Page:** <https://github.com/AndreBiedenkapp>

<https://github.com/automl/DAC>

*DAC*

Role: Developer

DAC is the first dynamic algorithm configurator which enables configuration not only to specific problem instances but also at each time-step. To gain insights into the strengths and weaknesses of this reinforcement learning based configurator DAC comes with example white-box benchmarks.

<https://github.com/automl/DACBench>

*DACBench*

Role: Contributor

DACBench is a benchmark library for Dynamic Algorithm Configuration. Its focus is on reproducibility and comparability of different DAC methods as well as easy analysis of the optimization process.

<https://github.com/automl/ParameterImportance>

*PyImp*

Role: Developer

PyImp is an easy to use tool that helps developers to identify the most important parameters of their algorithms. Given the data of a configuration run with SMAC3, PyImp allows for usage of various parameter importance methods to determine which parameters have the most influence on the algorithms behaviour.

<https://github.com/automl/SMAC3>

*SMAC3*

Former Role: Contributor

Python implementation of SMAC (sequential model-based algorithm configuration). SMAC is a tool for automated algorithm configuration.

## Languages

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**Native:** German

**Fluent:** English

**Basic:** French