MADOCALIB ver.1.4 Manual

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I Overview

This manual describes how to use the MADOCA-PPP (Multi-GNSS Advanced Orbit and Clock Augmentation - Precise Point Positioning) test library called MADOCALIB. The purpose of distributing MADOCALIB is to facilitate the user algorithm implementation of MADOCA-PPP. MADOCALIB is constructed based on RTKLIB and functions of PPP-AR and message conversion copyrighted by the third party and provides RNX2RTKP and CSSR2SSR.

RNX2RTKP is a utility for post-process positioning. It implements a processing mode called PPP (Precise Point Positioning) to make use of MADOCALIB. In this processing mode, the following functions are added to RTKLIB ver.2.4.3b34:

- To use the Galileo E1-E5a signal for PPP calculation
- To read the Compact SSR message of MADOCA-PPP
- To select GNSSs to be used for PPP calculation, and
- To select frequencies to be used for PPP calculation for each GNSS
- To process the ionospheric correction data of MADOCA-PPP

Users can refer to its output as a reference to achieve the performance criteria of MADOCA-PPP.

MADOCALIB also has a processing mode called PPP-AR (Precise Point Positioning-Ambiguity Resolution). Please note that the performance of MADOCA-PPP with the PPP-AR method is currently not defined in the specification documents but the PPP-AR mode will be continuously improved with the expectation of better performance than the PPP mode.

CSSR2SSR is a utility for post-processing conversion of L6E message file containing MADOCA-PPP compact SSR data to RTCM3 SSR message file.

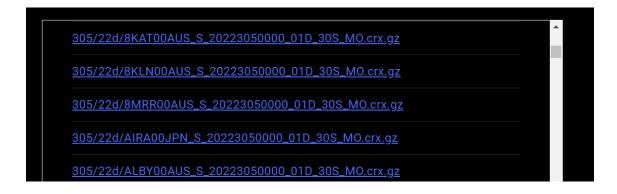
II Usage of Utilities

II-1 RNX2RTKP

To run the RNX2RTKP the following files are required.

- a) RINEX OBS and NAV
- b) ATX file (.atx)
- c) QZSS L6 correction data (.16)
- d) Configuration file (.conf)
- 1. The RINEX OBS and NAV data can be downloaded from the following MIRAI's URL. https://go.gnss.go.jp/mirai/miraiarchive/





RINEX OBS files are saved in Compact RINEX format, so converting them to RINEX v3 is required. The RNXCMP (a tool that converts the Hatanaka compact RINEX format (extension crx) is used to convert to the commonly used RINEX format (extension rnx)) and can be obtained from the following

URL:

https://terras.gsi.go.jp/ja/crx2rnx.html

For Windows 64-bit environment, download RNXCMP_4.1.0_Windows_mingw_64bit.

2. The antenna phase information file (e.g. igs20.atx, igs14.atx) can be obtained from the below URL.

https://cddis.nasa.gov/Data_and_Derived_Products/GNSS/GNSS_product_holdings.html

*For monitoring stations that do not use the same combination of antenna and radome used for IGS stations, a dedicated antenna phase information file needs to be used instead of the above file.

3. The QZSS L6 correction data can be downloaded from the following QZSS Web URL. Since the files are separated for each hour, they need to be integrated according to the time to be evaluated. (For example, a file for one day on Jun.10, 2024 is generated by executing the command type "copy /b 2024162*.204.16 2024162all.204.16" at the Command Prompt.) https://sys.gzss.go.jp/dod/en/archives.html

- 4. As for the configuration file, the following sample file included in the MADOCALIB package can be used.
 - sample.conf

This sample configuration file is tuned specifically for PPP processing for observation data at 30-second intervals at MIRAI or IGS stations, using the MADOCA-PPP archive data as augmentation data. Therefore, it is recommended that the parameters be tuned accordingly for each case if augmentation data other than the MADOCA-PPP archive data is used, or where observation data conditions such as data intervals are different.

- 5. Place the following files in the Windows local environment.
 - · RINEX OBS, NAV files
 - igs20.atx (or igs14.atx)
 - · L6 archive data (extension 16)
 - · conf file (sample.conf)
 - · rnx2rtkp.exe

- 2024162all.200.l6
- 2024162all.201.l6
- 2024162all.204.l6
- igs20.atx
- 📆 rnx2rtkp.exe
- sample.conf
- TSK200JPN_S_20241620000_01D_30S_MO.rnx
- 🚮 TSK200JPN_S_20241620000_01D_MN.rnx
- 6. The following settings are required in the conf file to process for PPP/PPP-AR.
 - 6-1. Describe the path of the ANTEX file (igs20.atx) in the conf file.

Example: See lines 99 and 100 below.

file-satantfile= (specify the path where igs20.atx is saved)

file-revantfile= (Specify the path where igs20.atx is saved)

Alternatively, from version 1.4, the ANTEX file path can be specified not only by the conf file but also by command line arguments with "-ant" option. If specified in both, the command line argument is applied.

6-2. Setting the PPP-AR mode to ON

(Noted: 6-2 is skipped for PPP mode)

By setting the following,

Line 18: pos1-ionoopt=est-stec

Line 30: pos2-armode=continuous

If you want to select GNSS to use for the AR process, you can set the following,

pos2-arsys=1 # GPS only

pos2-arsys=8 # Galileo only

pos2-arsys=9 # GPS, Galileo

pos2-arsys=16 # QZSS only

pos2-arsys=17 # GPS, QZSS

pos2-arsys=24 # Galileo, QZSS

pos2-arsys=25 # GPS, Galileo, QZSS

Note that you also need to configure the following section 6.3.

6-3. Setting the used navigation satellite systems

Example: See line 28 below.

Line 28: pos1-navsys=29 (GPS+GLO+GAL+QZS)

If you want to use PPP with GPS+GAL+QZS, you should set the sum of these numbers to "25" because GPS is "1", GAL is "8", and QZS is "16".

6-4. Setting the used signals

The setting in line 8 below should be fixed for PPP using L1+L2 or L1+L5 signals.

Line 8: pos1-frequency=11+2

Additionally, you should set the types of signals and frequencies of used GPS and QZSS with the options on lines 43-46 below.

In the example below, L1C/A and L2P of GPS IIR-M, L1C/A and L2P of GPS IIF, L1C/A and L2P of GPS IIIA, and L1C and L5 of QZSS are used.

Line 43: pos2-siggpsIIR-M=0

Line 44: pos2-siggpsIIF=0

Line 45: pos2-siggpsIIIA=0

Line 46: pos2-sigqzs1_2=0

6-5. Setting the ionospheric correction to ON

By setting the following,

Line 18: pos1-ionoopt=est-stec

Line 29: pos2-ionocorr=on

In addition to the above settings, to apply ionospheric correction using L6D, you can specify the L6D archive file using the following command line argument -mdciono [.16]. Here, two -mdciono arguments can be specified because ionospheric corrections are delivered via two L6D signals of PRN200 and PRN201.

Example:

rnx2rtkp.exe -k "conf file" "OBS file" "NAV file" "L6E file[.l6]" -mdciono "L6D file[.l6]" -mdciono "L6D file[.l6]" -o pos file

6

*The first L6 file[.16] is L6E archive data, the second and third L6 file[.16] are L6D archive data

```
1 #42
2 # sample.conf : configuration for ppped
3 #4
4 # Rev.2024/06/13e
5 #4
          6 ed
7 post-posmode
8 post-frequency
9 post-soltype
10 post-elmask
11 post-snrmask_r
12 post-snrmask_b
13 post-snrmask_l
                                                                                                                                                                                                                                                      # (0:single,1:dgps,2:kinematic,3:static,4:movingbase,5:fixed,6:ppp-kine,7:ppp-static,8:ppp-fixed)  # (1:11,2:11+2,3:11+2+3,4:11+2+3+4,5:11+2+3+4+5)  # (0:forward,1:backward,2:combined)  # (de)  # (de)  # (0:off,1:on)  # # (0:off,1:on)  #
                                                                                                                                                                      =ppp-kine
=11+2
                                                                                                                                                                     =forward
                                                                                                                                                                   =10
=off
                                                                                                                                                                   =off  # (U:off,1:on) = 
-off  # (0:off,1:on) = 
-0,0,0,0,0,0,0,0,0 = 
-0,0,0,0,0,0,0,0,0 = 
-0,0,0,0,0,0,0,0 = 
-0,0,0,0,0,0,0,0 = 
-off  # (0:off,1:on) = 
-on  # (0:off,1:on,2:otl) = 
-dual-freq  # (0:off,1:saas,2:sbas,3:dual-freq,4:est-stec,5:ionex-tec,6:qzs-brdc) = 
-est-ztd  # (0:off,1:saas,2:sbas,3:est-ztd,4:est-ztgrad) = 
-cot-determent  # (0:otf,1:saas,2:sbas,3:est-ztd,4:est-ztgrad) = 
# (prn ...)e
# (prn ...)e
# (1:gps+2:sbas+4:glo+8:gal+16:qzs+32:bds+64:navic)e
# (0:off,1:on)e
# (0:off,1:continuous,2:instantaneous,3:fix-and-hold)e
                                                                                                                                                                     =
=29
=off
                                                                                                                                                                     =off
=25
                                                                                                                                                                                                                                                          # (0:off,1:on)+
# (0:off,1:on)+
# (0:off,1:on)+
                                                                                                                                                                      =on
                                                                                                                                                                     =on
=2.5←
=15
=10←
                                                                                                                                                                                                                                                          # (deg) <del><</del>
                                                                                                                                                                     =99 \( \)
=5 \( \)
=0.15
=100
=30 \( \)
                                                                                                                                                                                                                                                          # (0:L1C/A-L2P,1:L1C/A-L2C) \( \varphi\) # (0:L1C/A-L2P,1:L1C/A-L2C,2:L1C/A-L5) \( \varphi\) # (0:L1C/A-L2P,1:L1C/A-L2C,2:L1C/A-L5) \( \varphi\) # (0:L1C-L5,1:L1C/A-L2C) \( \varphi\) # (0:L1C-L5,1:L1C/A-L2C) \( \varphi\)
                                                                                                                                                                      =0
                                                                                                                                                                      =0
                                                                                                                                                                      =()
                                                                                                                                                                                                                                                          # (0:10-L5,1:10/A-L20)@
# (0:10,1:xyz,2:enu,3:nmea)@
# (0:off,1:on)@
# (0:off,1:on)@
# (0:off,1:on)@
# (0:gpst,1:utc,2:jst)@
                                                                                                                                                                     =IIh
=on
                                                                                                                                                                     =on
=off
                                                                                                                                                                     =gpst
=hms
=3←
                                                                                                                                                                                                                                                          # (0:tow,1:hms)
                                                                                                                                                                                                                                                        # (0:deg,1:dms) <
                                                                                                                                                                     =deg
                                                                                                                                                                     =off
=0
                                                                                                                                                                                                                                                          # (0:off,1:on) <
                                                                                                                                                                   -01 # (0.01,1.01) # (m) # (0:internal,1:ggm96,2:egm08_2.5,3:egm08_1,4:gsi2000) # = all # (0:all,1:single) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # (5) # 
                                                                                                                                                                   =a||
=0
=0
                                                                                                                                                                                                                                                        # (s) \(\varphi\)
# (0:off,1:state,2:residual) \(\varphi\)
   63 out-outstat
```

```
64 stats-eratio1
65 stats-eratio2
66 stats-uraratio
67 stats-errphase
68 stats-errphase
                                                                                                                                                                                                      =300 <del>←</del>
=0.1 <del>←</del>
                                                                                                                                                                                                  =0.1e =0.003 # (m) e =0.003 # (m) e =0.0001 # (m) e =0.001 # (m) e =0.0001 # (m) e =0.0001 # (m) e =0.0001 # (m) e =0.0001 # (m) e =0 # (deg m) e =0.0001 # (deg m) e =-6335367.6285 # (m|m) e =*e
                               stats-errphase
stats-errphaseel
         69 stats-prnbias
70 stats-prniono
 Sixts-prinors
70 stats-prinors
71 stats-prinors
72 stats-prinors
73 antl-postype
74 antl-posl
75 antl-pos2
76 antl-pos3
77 antl-antdele
78 antl-antdele
80 antl-antdelu
81 ant2-postype
82 ant2-posl
83 ant2-pos2
84 ant2-pos2
84 ant2-pos3
85 ant2-antdele
87 ant2-antdele
88 ant2-antdele
89 ant2-maxaveep
90 ant2-initrst
91 misc-timeinterp
92 misc-sbasatsel
                                                                                                                                                                                                                                                                                                                             (m) e

(m) e

(0:11h,1:xyz,2:single,3:posfile,4:rinexhead,5:rtcm,6:raw) e

(deg|m) e
                                                                                                                                                                                                      =*~
                                                                                                                                                                                                                                                                                                          # (m) e
# (m) e
# (m) e
# (0:1h,1:xyz,2:single,3:posfile,4:rinexhead,5:rtcm,6:raw) e
# (deg|m) e
# (deg|m) e
# (deg|m) e
                                                                                                                                                                                                        =0
=0
                                                                                                                                                                                                    =0
=11h
                                                                                                                                                                                                    =90
=0
                                                                                                                                                                                                    -0 # (deg|m)←
=-6335367.6285 # (m|m)←
=←
                                                                                                                                                                                                                                                                                                          # (m) \( \dagger \)
# (m) \( \dagger \)
                                                                                                                                                                                                    =0
=0
                                                                                                                                                                                                    =0
=0←
                                                                                                                                                                                                    =off
=off
=0
=e
                                                                                                                                                                                                                                                                                                          # (0:off,1:on) \( \begin{aligned} \pm & (0:off,1:on) \( \epsilon \epsilon \) \( \pm & (0:all) \( \epsilon \eppilon \epsilon \epsilon \epsilon \epsilon \epsilon \eppi
   91 misc-timeinterp
92 misc-sbasatsel
93 misc-rnxopt1
94 misc-rnxopt2
95 misc-pppopt
96 misc-rtcmopt
97 #file-satantfil
98 #file-rcvantfil
                                                                                                                                                                                                      = 🚄
                           misc-pppopt
misc-rtcmppt
#file-satantfile
#file-rcvantfile
file-satantfile
file-satantfile
file-staposfile
file-goidfile
file-dobfile
file-pofile
                                                                                                                                                                                                    =..\forage :..\forage = sample_data\forage igs20.atx</ri>
=..\forage = sample_data\forage igs20.atx</ri>
                                                                                                                                                                                                    =igs20.atx
                                                                                                                                                                                                  =igs20.atx+
=+
=+
                                   file-eopfile
file-blqfile
107 file-tempdir
108 file-geexefile
109 file-solstatfile
110 file-tracefile
```

- 7. Finally, start the Command Prompt and move to the folder containing rnx2rtkp.exe specified in step 5.
- 8. Execute the following command.

Command format:

rnx2rtkp.exe -k conf file OBS file NAV file L6 file -o output file

Example:

```
rnx2rtkp.exe -k sample.conf TSK200JPN_S_20241620000_01D_30S_MO.rnx
TSK200JPN_S_20241620000_01D_MN.rnx 2024162all.204.l6 -o test.pos
```

A file (test.pos) containing time series positioning results of PPP is obtained.

Contents of test.pos (below, excerpt)

```
| Manager | Mana
```

II-2 CSSR2SSR

To run the CSSR2SSR the following files are required.

a) QZSS L6E correction data (.16)

Specify the L6E message file as a file in command line argument. The results are output as a file specified with -o options.

Supported Compact SSR messages (cssr) are as bellow.

[Vendor ID]

"010b" : MADOCA-PPP

[Message Type, Sub Type]

MT4073, 1 : mask MT4073, 2 : orbit MT4073, 3 : clock

MT4073, 4 : code bias MT4073, 5 : phase bias

MT4073,7 : ura

Supported SSR messages (ssr) are as bellow.

[Message Type]

SSR Message	:	GPS	GLONASS	Galieo	QZSS
SSR Orbit Correction	 :	1057	1063	1240 (*1)	1246 (*1)
Clock Correction	:	1058	1064	1241 (*1)	1247 (*1)
URA	:	1061	1067	1244 (*1)	1250 (*1)
Code Bias	:	1059 (*2)	1065 (*2)	1242 (*1*2)	1248 (*1)
Phase Bias	:	1265 (*2)	1266 (*2)	1267 (*1*2)	1268 (*1*2)

[format]

nothing * :RTCM 10403.3

(*1) : Proposal of new RTCM SSR Messages

SSR Stage 1:Galileo, QZSS, SBAS, BDS 2014-04-17 v05

(*2) : Proposal of new RTCM SSR Messages SSR Stage 2:Satellite Phase Biases 2014-04-17 v05

Of the signals stored in MADOCA-PPP, those not defined in RTCM SSR use the following signal and tracking mode identifier.

GNSS :Signal and Tracking Mode Identifier

GPS :16- L5 I+Q

:17- L1 L1C(D+P)

Galileo: 3- E1 B+C

: 7- E5a I+Q

synopsis:

cssr2ssr.exe [options] file

options:

-td y/m/d date for message time (y=year, m=month, d=day)

-o file output ssr file

-d dump debug log on decoding cssr [default : no dump]

file input 16E message file

example:

cssr2ssr.exe -td 2024/06/10 -o 2024162all.204.rtcm3 2024162all.204.l6

III Sample BAT file

III-1 RNX2RTKP

Batch files and configuration files showing an example of executes PPP, PPP-AR and PPP-AR with ionospheric correction are included in the package.

Move to the folder of "sample_data" and execute exec_ppp. bat for PPP, exec_pppar. bat for PPP-AR or exec_pppar_ion. bat for PPP-AR with ionospheric correction. These BAT files execute PPP/PPP-AR from 00min00sec to 59min30sec every hour.

III-2 CSSR2SSR

Move to the folder of "sample_data" and execute exec_cssr2ssr. bat for conversion of L6E message file containing MADOCA-PPP compact SSR data to RTCM3 SSR message file.