

A Software Ecosystem for Research in Reinforcement Learning-based Receding Horizon Control[§]

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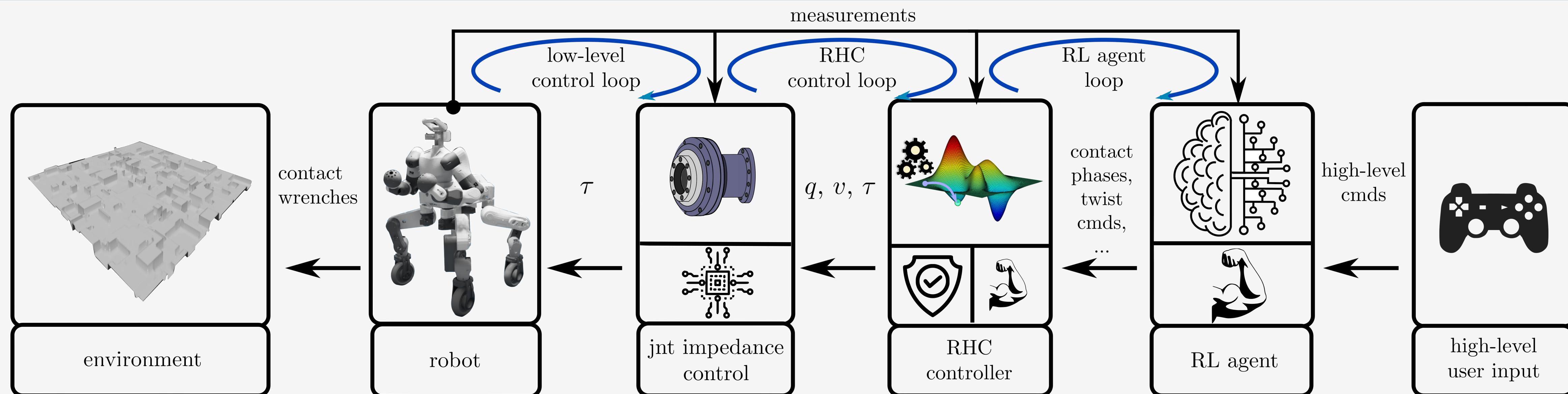
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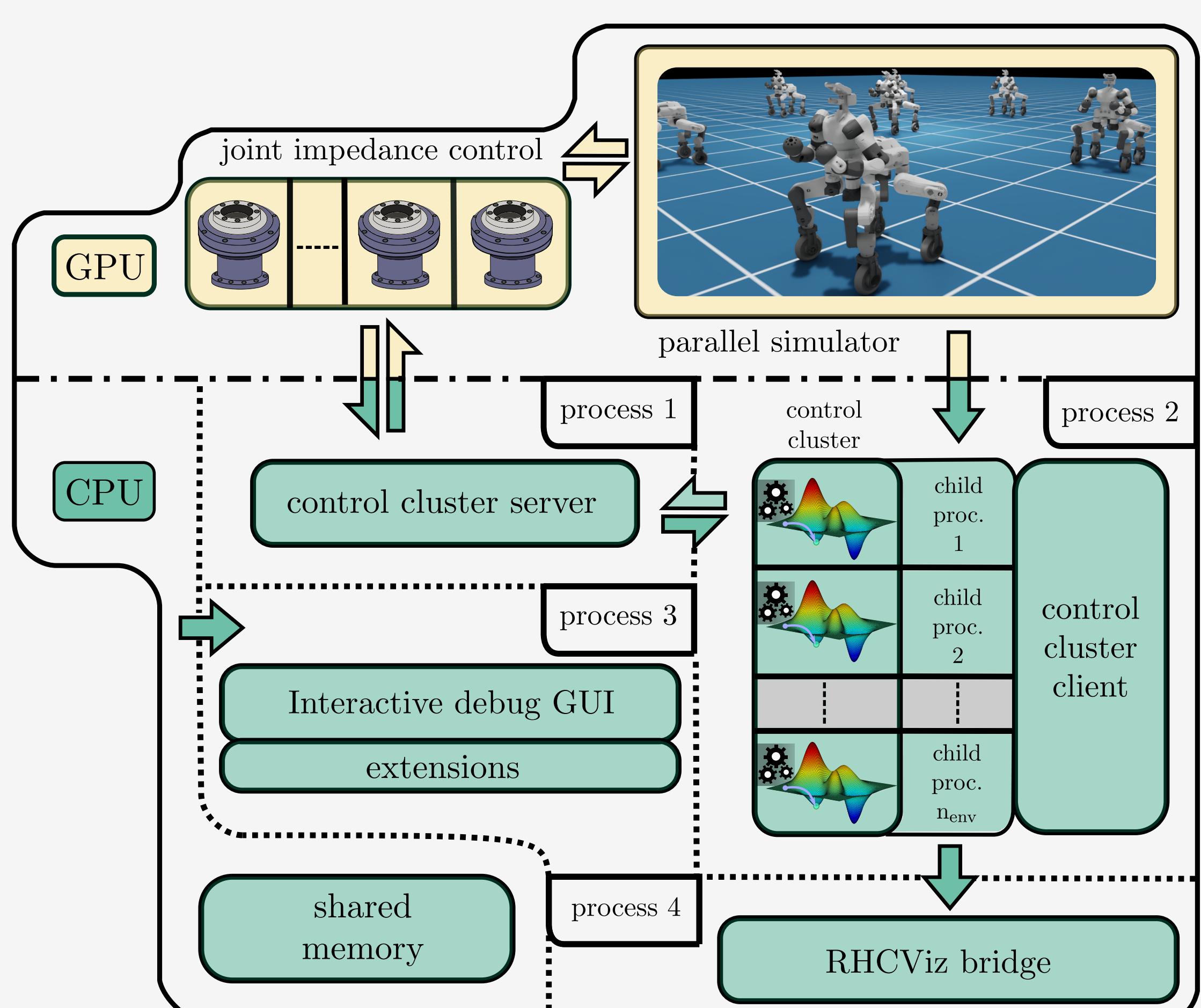
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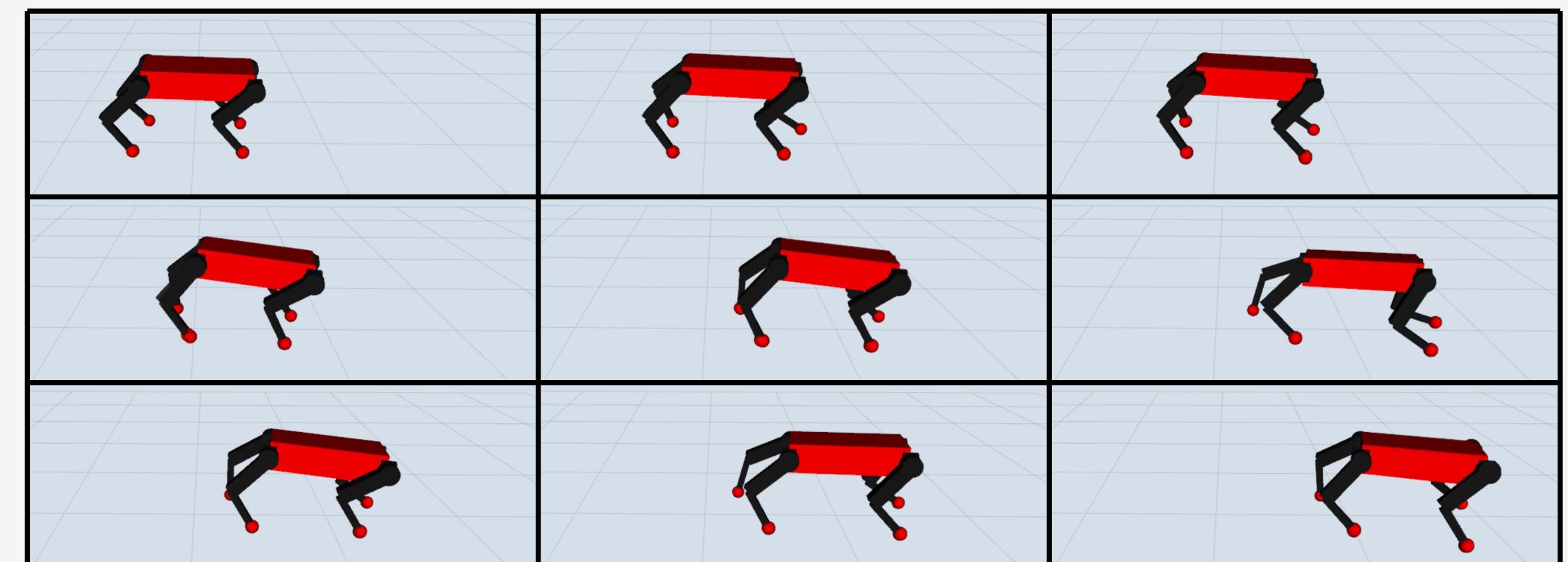
A Hybrid Approach: combining Receding Horizon Control and Reinforcement Learning



Software architecture



A proof-of-concept example: preliminary results



A proof-of-concept example: quadruped walking on flat ground

Next steps

Contact Information



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Resources



<https://github.com/AndrePatri/LRHControl>

