

1st year PhD annual evaluation

Motion Planning and Control for Hybrid Locomotion of Wheeled-Legged Systems

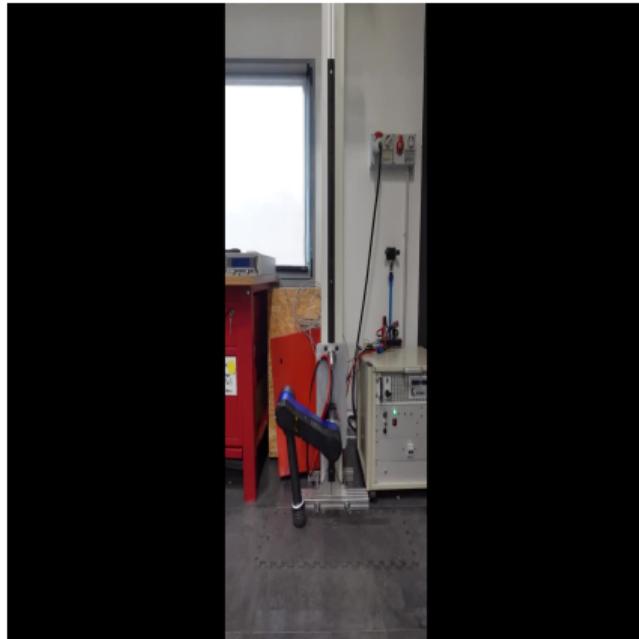
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Tutors: Nikos Tsagarakis, Arturo Laurenzi

Istituto Italiano di Tecnologia, October 10, 2023

Beautiful slide with video

Here is an example of embedding a video in Beamer.



Normal slide

Thanks for your attention!

Any questions?

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