Department of Computer Engineering

T.E. (Computer Sem VI) <u>Assignment -1</u> Artificial Intelligence (CSC604)

Student Name: ANDRE JOHN Roll No: 9544

CO Addressed:—CSC604.1 -To conceptualize the basic ideas and techniques underlying the design of intelligent systems.

Assignment 1:

- 1. Explain the concept of rationality in the context of intelligent agents. How does rationality relate to the behavior of agents in their environments? Provide examples to illustrate your explanation.
- 2. Discuss the nature of environments in which intelligent agents operate. What are the key characteristics that define an environment, and how do they influence the design and behavior of agents? Provide examples of different types of environments and the challenges they present to agents.
- 3. Describe the structure of intelligent agents and the types of agents commonly used in artificial intelligence. What are the components of an agent, and how do they interact to achieve intelligent behavior? Provide examples of different types of agents and their applications in real-world scenarios.
- 4. Outline the process of problem-solving by searching, including the role of problem-solving agents and the formulation of problems. How do problem-solving agents analyze and approach problems, and what methods do they use to search for solutions? Illustrate your explanation with examples of problem-solving tasks and the strategies employed by agents to solve them.

Rubrics for the First Assignments:

Indicator	Average	Good	Excellent	Marks
Organization (2)	Readable with some missing points and structured (1)	Readable with improved points coverage and structured (1)	Very well written and fully structured	
Level of content(4)	All major topics are covered, the information is accurate (2)	Most major and some minor criteria are included. Information is accurate (3)	All major and minor criteria are covered and are accurate (4)	
Depth and breadth of discussion and representation(4)	Minor points/information maybe missing and representation isminimal (1)	Discussion focused on some points and covers themadequately (2)	Information is presented indepth and is accurate (4)	
Total				

Signature of the Teacher

Rationality in the context of intelligent agents refers to the ability of an agent to make decisions that maximize its expected utility as achieve the goals based on the given information and available resources. Arational agent is one that consistently chooses the best action on sequence of actions from among the available options to achieve its objectives.

Rationality is closely related to the behaviour of agents in their environments in the sense that rational agents will adopt their behaviour based on feedback from their environment to improvement to improve their decision-making process and achieve better ontromes. This adaption may involves touch adjusting strategies to better align with goals.

Examples 3

(i) Sef-driving cars: These can be considered rational if they havigate

Safely and efficiently to its destination while obeying traffic rules and

pedespian activity to make real-time decisions about speed, lane changes

and navigation routes.

- (ii) Al Chess: In the game of chess, an Al agent san be considered rational if it selects mones that maximize its chances of winning the game. The agent evaluates the potential outcomes of different mones based on its knowledge of the game rules and board position, and then selects the more that leads to the most favourable outcome.
- The noture of environments in which intelligent agents operate are fully observable vs partially observable, deterministic vs stochastic, competition vs collaborative, single-agent vs multi-agent, static vs dynamic, discrete vs continous, episodic, vs sequential, etc.

 The key characteristics that define an environment and how do they influence the design and behaviour of agents are as follows:

Go

(i) Percept: An environment provides resceptual input to the agent, which includes any

information the agent can oftain through its sensors.

(ii) Action: Agents interact with their environments by executing actions. The set of possible actions an agent can take depends on the environment's dynamics and the agent's capabilities.

(iii) State Space : The state space represents all possible configurations of the environment. It encompasses the current state as well as potential future states resulting from agent actions of environmental changes

agent actions or environmental changes.

(N) Accessibility of Information : Some environments provide agents with complete information about their state and the consequences of actions, while others only offer partial or incomplete information.

(v) Spatio-temporal characteristictis: Spatial characteristics include dimensions, topology and accessibility, while temporal aspects involve factors such as timing,

sequencing, and delation of events.

Examples: (i) Chess: Chess is deterministic, fully observable environment with a discrete State space of a limited set of actions. The challenge for agents lies in explaing the vast space state to anticipate opponents' moves and devise winning strategies.

i) Stock Market: The stock market is a dynamic, stochastic environment with pertially Observable information. Agents must analyze market hands, news and economic indicators to make informed deistons about suying, selling or holding stocks anidst uncertarity and volatility.

3) Structure of Intelligent Agents:

(i) Perceptual Component: Enables agent la perciene its environment through sensors, captuing relevant information. Ex: Autonomous rehides, cameras, lidas, etc.

(ii) Knowledge Base: It is the memory where information is stored about the envisonment, pest experiences and learned behaviours. Ex: Viotual personal assistant

(iii) Decision-Making Component: It processes perceptual input and knowledge to make decisions and select action. Ex: Healthcare diagnostic system

(iv) Action Component: Based on the decisions made, the agent executes actions in the environment through actuations or effectors. Intelligent Igents are:

(1) Reachine Agents: These agents respond directly to environmental stimuli without maintain an internal state or memory. Ex: Obstacle-avoidance Robit (ii) Deliberate Agents: They employ internal models of the environment, Jeasoning, and planning to make decisions. Ex: AI Chess player. (iii) hearning Agents: They improve their performance ones time through learning from experience. Ex: Reinforcement learning algorithms. (iv) flybrid Agents: They combine characteristics of multiple bypes, leveraging reactive, deliberative and learning approaches as needed. Ex: Autonomous rehicles 4) (i) Role of Broblem - Solving Agents !-- Identify and solve problems to achieve their goals. - Analyse the current state, goal state, and possible actions to reach goal > Employ various search algorithms to explore the space of possible Solutions efficiently. (ii) Formulation of Problems:--> By defining initial state, goal state, action, and constraints. -> Provides structural representation of the problem, enabling to analyze and solve it systematically (iii) Analyzing and Approaching Boblems:--> To understand structure, constraints and possible solutions. - Employ heuristics, domain knowledge, and problem-specific strategie to guide the search process effectively. -> Agents may de compose complex problems into smaller subproblems to easier resolution FOR EDUCATIONAL USE Sundaram

(iv) Methods used for Searching Solutions:

-> Uninformed search: Agents explore the problem space systematically w/o

considering domain-specific knowledge. Ex: BFS, DFS.

-> I formed Search: Domain-specific knowledge or heuristics to guide the Search towards promising solutions. Ex: A* search, greedy Best first search.

-> Local Search: Agents Eteratively Emprone candidate solutions by making

small modifications. Ex: Hill Climbing, simulated Annealing.

(V) Examples:

-> Routing Planning: In navigation systems, problem-solving agents search for the shostest path of two locations on a map. They analyze the road network, consider traffic conditions and employ algorithms like A* search to find optimal routes.

-> Ruggle Solving: In sudoku/Rubik's cube, agends aim to find solutions satisfying certain constraints. They analyze the puzzle's initial state, explore possible moves, and use strategies like constraint propagation or backtracking to solve the Muzzle.

to Solve the Mizzle.

Automated Planning: In robotics or automated systems, problem-solving agents plan sequences of actions to achieve desired outcomes. They analyze the environment, consider constraints, and employ planning algorithms like STRIPS OF POSL to generate action sequences.