



**Politecnico
di Torino**

DiSAT

DISAT
Department of Applied Science and Technology

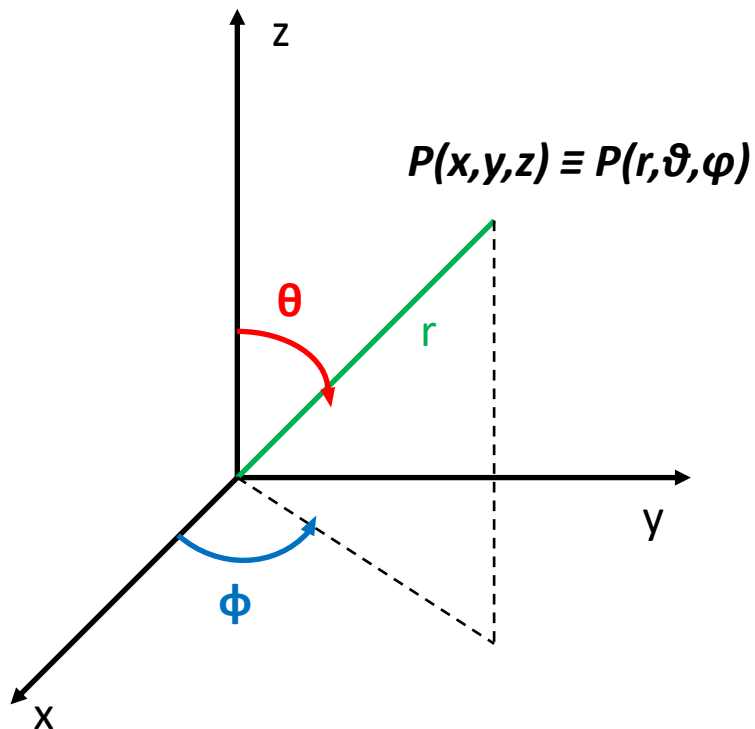
Fisica II

Esercitazione 3

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$r: [0, \infty)$ $\theta: [0, \pi]$ $\phi: [0, 2\pi)$

$$x = r \sin \theta \cos \phi$$

$$y = r \sin \theta \sin \phi$$

$$z = r \cos \theta$$

$$r = \sqrt{x^2 + y^2 + z^2}$$

$$\theta = \arccos \frac{z}{\sqrt{x^2 + y^2 + z^2}}$$

$$\phi = \arctan \frac{y}{x}$$



$$x = r \sin\theta \cos\phi$$

$$y = r \sin\theta \sin\phi$$

$$z = r \cos\theta$$

$$dx \, dy \, dz = |\det J| \, dr \, d\theta \, d\phi$$

Matrice jacobiana

$$J = \begin{bmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \phi} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \phi} & \frac{\partial y}{\partial \theta} \\ \frac{\partial z}{\partial r} & \frac{\partial z}{\partial \phi} & \frac{\partial z}{\partial \theta} \end{bmatrix}$$

$$\det J = \begin{vmatrix} \sin\theta \cos\phi & -r \sin\theta \sin\phi & r \cos\theta \cos\phi \\ \sin\theta \sin\phi & r \sin\theta \cos\phi & r \cos\theta \sin\phi \\ \cos\theta & 0 & -r \sin\theta \end{vmatrix}$$



$$\det J = \begin{vmatrix} \sin\theta \cos\phi & -r \sin\theta \sin\phi & r \cos\theta \cos\phi \\ \sin\theta \sin\phi & r \sin\theta \cos\phi & r \cos\theta \sin\phi \\ \cos\theta & 0 & -r \sin\theta \end{vmatrix} =$$

$$\det J = \begin{vmatrix} \sin\theta \cos\phi & -r \sin\theta \sin\phi & r \cos\theta \cos\phi \\ \sin\theta \sin\phi & r \sin\theta \cos\phi & r \cos\theta \sin\phi \\ \cos\theta & 0 & -r \sin\theta \end{vmatrix} =$$

$$= \sin\theta \cos\phi (r \sin\theta \cos\phi \cdot (-r \sin\theta) - (0 \cdot r \cos\theta \sin\phi))$$



$$\det J = \begin{vmatrix} \sin\theta \cos\phi & -r \sin\theta \sin\phi & r \cos\theta \cos\phi \\ \sin\theta \sin\phi & r \sin\theta \cos\phi & r \cos\theta \sin\phi \\ \cos\theta & 0 & -r \sin\theta \end{vmatrix} =$$

$$= \sin\theta \cos\phi (r \sin\theta \cos\phi \cdot (-r \sin\theta) - (0 \cdot r \cos\theta \sin\phi)) + \\ + r \sin\theta \sin\phi (\sin\theta \sin\phi \cdot (-r \sin\theta) - (\cos\theta \cdot r \cos\theta \sin\phi)) +$$

$$\det J = \begin{vmatrix} \sin\theta \cos\phi & -r \sin\theta \sin\phi & r \cos\theta \cos\phi \\ \sin\theta \sin\phi & r \sin\theta \cos\phi & r \cos\theta \sin\phi \\ \cos\theta & 0 & -r \sin\theta \end{vmatrix} =$$

$$\begin{aligned} &= \sin\theta \cos\phi (r \sin\theta \cos\phi \cdot (-r \sin\theta) - (0 \cdot r \cos\theta \sin\phi)) + \\ &+ r \sin\theta \sin\phi (\sin\theta \sin\phi \cdot (-r \sin\theta) - (\cos\theta \cdot r \cos\theta \sin\phi)) + \\ &+ r \cos\theta \cos\phi (\sin\theta \sin\phi \cdot 0 - (\cos\theta \cdot r \sin\theta \cos\phi)) = \end{aligned}$$

$$\det J = \begin{vmatrix} \sin\theta \cos\phi & -r \sin\theta \sin\phi & r \cos\theta \cos\phi \\ \sin\theta \sin\phi & r \sin\theta \cos\phi & r \cos\theta \sin\phi \\ \cos\theta & 0 & -r \sin\theta \end{vmatrix} =$$

$$= \sin\theta \cos\phi (r \sin\theta \cos\phi \cdot (-r \sin\theta) - (0 \cdot r \cos\theta \sin\phi)) +$$

$$+ r \sin\theta \sin\phi (\sin\theta \sin\phi \cdot (-r \sin\theta) - (\cos\theta \cdot r \cos\theta \sin\phi)) +$$

$$+ r \cos\theta \cos\phi (\sin\theta \sin\phi \cdot 0 - (\cos\theta \cdot r \sin\theta \cos\phi)) =$$

$$= -r^2 \sin^3\theta \cos^2\phi +$$

$$-r^2 \sin^3\theta \sin^2\phi - r^2 \sin\theta \cos^2\theta \sin^2\phi +$$

$$-r^2 \cos^2\theta \sin\theta \cos^2\phi =$$

$$\det J = \begin{vmatrix} \sin\theta \cos\phi & -r \sin\theta \sin\phi & r \cos\theta \cos\phi \\ \sin\theta \sin\phi & r \sin\theta \cos\phi & r \cos\theta \sin\phi \\ \cos\theta & 0 & -r \sin\theta \end{vmatrix} =$$

$$\begin{aligned} &= -r^2 \sin^3\theta \cos^2\phi + \\ &-r^2 \sin^3\theta \sin^2\phi - r^2 \sin\theta \cos^2\theta \sin^2\phi + \\ &-r^2 \cos^2\theta \sin\theta \cos^2\phi = \end{aligned}$$

$$= -r^2 \sin\theta (\sin^2\theta \cos^2\phi + \sin^2\theta \sin^2\phi + \cos^2\theta \sin^2\phi + \cos^2\theta \cos^2\phi) =$$

$$= -r^2 \sin\theta [\sin^2\theta (\cos^2\phi + \sin^2\phi) + \cos^2\theta (\sin^2\phi + \cos^2\phi)] =$$

$$\det J = \begin{vmatrix} \sin\theta \cos\phi & -r \sin\theta \sin\phi & r \cos\theta \cos\phi \\ \sin\theta \sin\phi & r \sin\theta \cos\phi & r \cos\theta \sin\phi \\ \cos\theta & 0 & -r \sin\theta \end{vmatrix} =$$

$$= -r^2 \sin^3\theta \cos^2\phi +$$

$$-r^2 \sin^3\theta \sin^2\phi - r^2 \sin\theta \cos^2\theta \sin^2\phi +$$

$$-r^2 \cos^2\theta \sin\theta \cos^2\phi =$$

$$= -r^2 \sin\theta (\sin^2\theta \cos^2\phi + \sin^2\theta \sin^2\phi + \cos^2\theta \sin^2\phi + \cos^2\theta \cos^2\phi) =$$

$$= -r^2 \sin\theta \left[\underbrace{\sin^2\theta (\cos^2\phi + \sin^2\phi)}_1 + \underbrace{\cos^2\theta (\sin^2\phi + \cos^2\phi)}_1 \right] =$$

$$\det J = \begin{vmatrix} \sin\theta \cos\phi & -r \sin\theta \sin\phi & r \cos\theta \cos\phi \\ \sin\theta \sin\phi & r \sin\theta \cos\phi & r \cos\theta \sin\phi \\ \cos\theta & 0 & -r \sin\theta \end{vmatrix} =$$

$$= -r^2 \sin^3\theta \cos^2\phi +$$

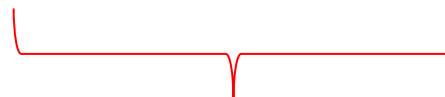
$$-r^2 \sin^3\theta \sin^2\phi - r^2 \sin\theta \cos^2\theta \sin^2\phi +$$

$$-r^2 \cos^2\theta \sin\theta \cos^2\phi =$$

$$= -r^2 \sin\theta (\sin^2\theta \cos^2\phi + \sin^2\theta \sin^2\phi + \cos^2\theta \sin^2\phi + \cos^2\theta \cos^2\phi) =$$

$$= -r^2 \sin\theta [\sin^2\theta (\cos^2\phi + \sin^2\phi) + \cos^2\theta (\sin^2\phi + \cos^2\phi)] =$$

$$= -r^2 \sin\theta [\sin^2\theta + \cos^2\theta] =$$



$$\det J = \begin{vmatrix} \sin\theta \cos\phi & -r \sin\theta \sin\phi & r \cos\theta \cos\phi \\ \sin\theta \sin\phi & r \sin\theta \cos\phi & r \cos\theta \sin\phi \\ \cos\theta & 0 & -r \sin\theta \end{vmatrix} =$$

$$\begin{aligned} &= -r^2 \sin^3\theta \cos^2\phi + \\ &-r^2 \sin^3\theta \sin^2\phi - r^2 \sin\theta \cos^2\theta \sin^2\phi + \\ &-r^2 \cos^2\theta \sin\theta \cos^2\phi = \end{aligned}$$

$$= -r^2 \sin\theta (\sin^2\theta \cos^2\phi + \sin^2\theta \sin^2\phi + \cos^2\theta \sin^2\phi + \cos^2\theta \cos^2\phi) =$$

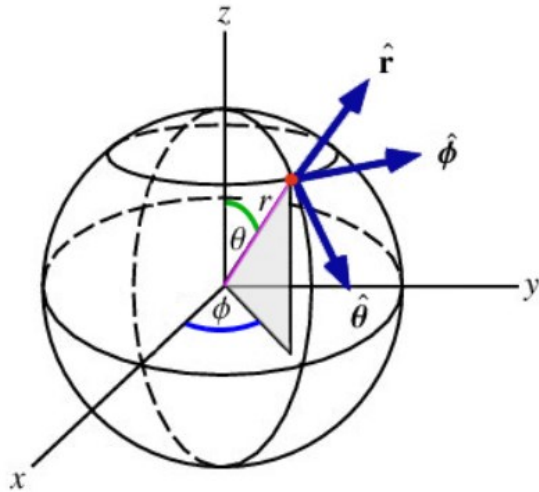
$$= -r^2 \sin\theta [\sin^2\theta (\cos^2\phi + \sin^2\phi) + \cos^2\theta (\sin^2\phi + \cos^2\phi)] =$$

$$= -r^2 \sin\theta [\sin^2\theta + \cos^2\theta] =$$

$$\boxed{= -r^2 \sin\theta}$$

Approfondimento coordinate sferiche

Gradiente in coordinate sferiche



$$r = \sqrt{x^2 + y^2 + z^2}$$

$$\theta = \arccos \frac{z}{\sqrt{x^2 + y^2 + z^2}}$$

$$\phi = \arctan \frac{y}{x}$$

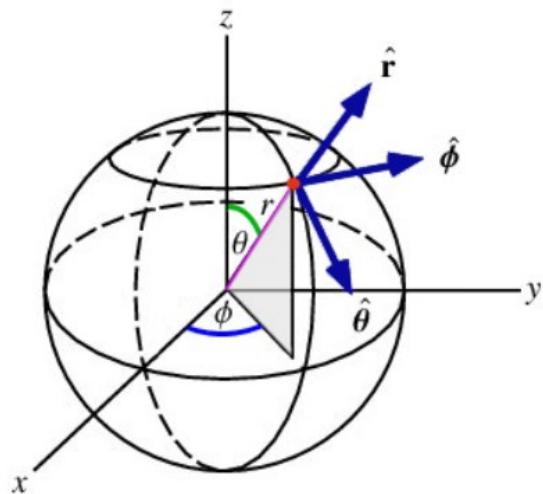
$$\nabla (f(r, \theta, \varphi)) = \frac{\partial f}{\partial x} \hat{u}_x + \frac{\partial f}{\partial y} \hat{u}_y + \frac{\partial f}{\partial z} \hat{u}_z$$

$$\frac{\partial f(r, \theta, \varphi)}{\partial x}$$

$$\begin{aligned} r(x, y, z) \\ \theta(x, y, z) \\ \varphi(x, y, z) \end{aligned}$$

$$\frac{\partial f(r(x, y, z), \theta(x, y, z), \varphi(x, y, z))}{\partial x}$$

Approfondimento coordinate sferiche



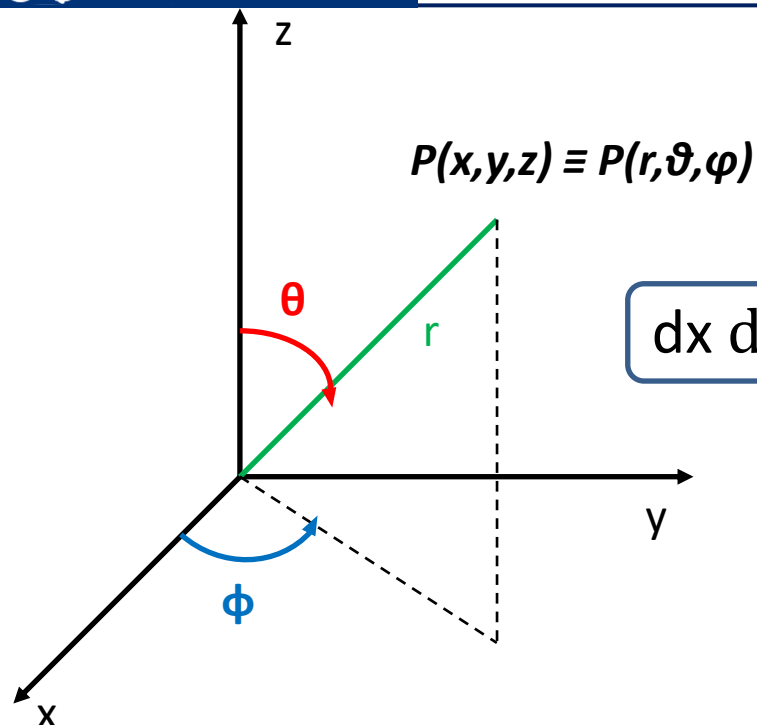
$$\begin{aligned}\hat{u}_x &= \sin\theta \cos\varphi \hat{u}_r + \cos\theta \cos\varphi \hat{u}_\theta - \sin\varphi \hat{u}_\varphi \\ \hat{u}_y &= \sin\theta \sin\varphi \hat{u}_r + \cos\theta \sin\varphi \hat{u}_\theta + \cos\varphi \hat{u}_\varphi \\ \hat{u}_z &= \cos\theta \hat{u}_r - \sin\theta \hat{u}_\theta\end{aligned}$$

Gradiente in coordinate sferiche

$$\nabla (f(r, \theta, \varphi)) = \frac{\partial f}{\partial x} \hat{u}_x + \frac{\partial f}{\partial y} \hat{u}_y + \frac{\partial f}{\partial z} \hat{u}_z$$

$$\begin{aligned}\nabla (f(r, \theta, \varphi)) &= \left(\frac{\partial r}{\partial x} \frac{\partial f}{\partial r} + \frac{\partial \theta}{\partial x} \frac{\partial f}{\partial \theta} + \frac{\partial \varphi}{\partial x} \frac{\partial f}{\partial \varphi} \right) \hat{u}_x + \\ &+ \left(\frac{\partial r}{\partial y} \frac{\partial f}{\partial r} + \frac{\partial \theta}{\partial y} \frac{\partial f}{\partial \theta} + \frac{\partial \varphi}{\partial y} \frac{\partial f}{\partial \varphi} \right) \hat{u}_y + \\ &+ \left(\frac{\partial r}{\partial z} \frac{\partial f}{\partial r} + \frac{\partial \theta}{\partial z} \frac{\partial f}{\partial \theta} + \frac{\partial \varphi}{\partial z} \frac{\partial f}{\partial \varphi} \right) \hat{u}_z\end{aligned}$$

$$\nabla (f(r, \theta, \varphi)) = \frac{\partial f}{\partial r} \hat{u}_r + \frac{1}{r} \frac{\partial f}{\partial \theta} \hat{u}_\theta + \frac{1}{r \sin \theta} \frac{\partial f}{\partial \varphi} \hat{u}_\varphi$$



$$dx \, dy \, dz$$

Integrazione su tutto lo spazio

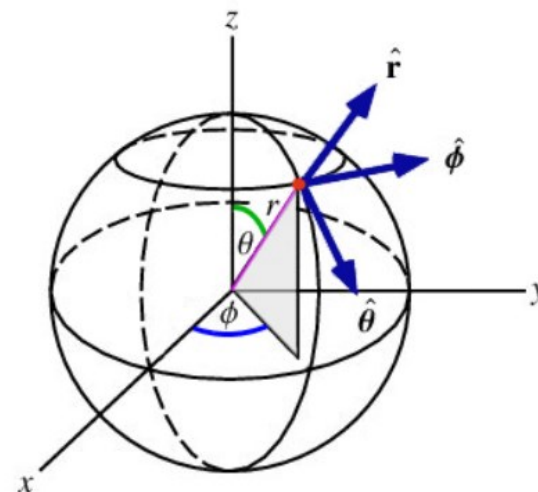
$$dV = r^2 \sin \theta \, dr \, d\theta \, d\phi$$

$$\int_0^{2\pi} d\phi \int_0^{\pi} \sin \theta \, d\theta \int_0^{\infty} r^2 \, dr$$

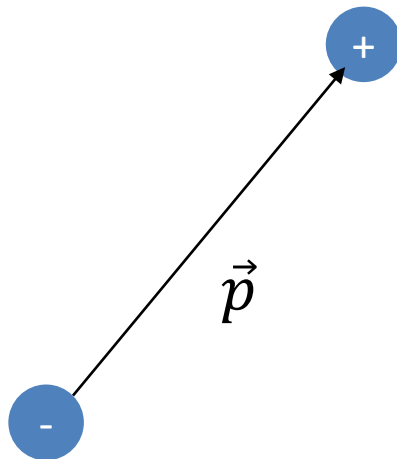
$$\phi: [0, 2\pi) \quad \theta: [0, \pi] \quad r: [0, \infty)$$

Gradiente in coordinate sferiche

$$\nabla (f(r, \theta, \varphi)) = \frac{\partial f}{\partial r} \hat{u}_r + \frac{1}{r} \frac{\partial f}{\partial \theta} \hat{u}_\theta + \frac{1}{r \sin \theta} \frac{\partial f}{\partial \varphi} \hat{u}_\varphi$$



Consideriamo un sistema costituito da due cariche elettriche puntiformi $+q$ e $-q$, poste ad una certa distanza a l'una dall'altra. Tale sistema si chiama **dipolo elettrico**.



Possiamo definire il vettore **momento di dipolo elettrico**:

$$\vec{p} = q a \hat{u}_{-,+}$$

orientato dalla carica negativa a quella positiva.

Lo scopo della lezione è studiare il campo elettrico generato dal dipolo. Per effettuare il conto, è conveniente utilizzare le *coordinate sferiche*.

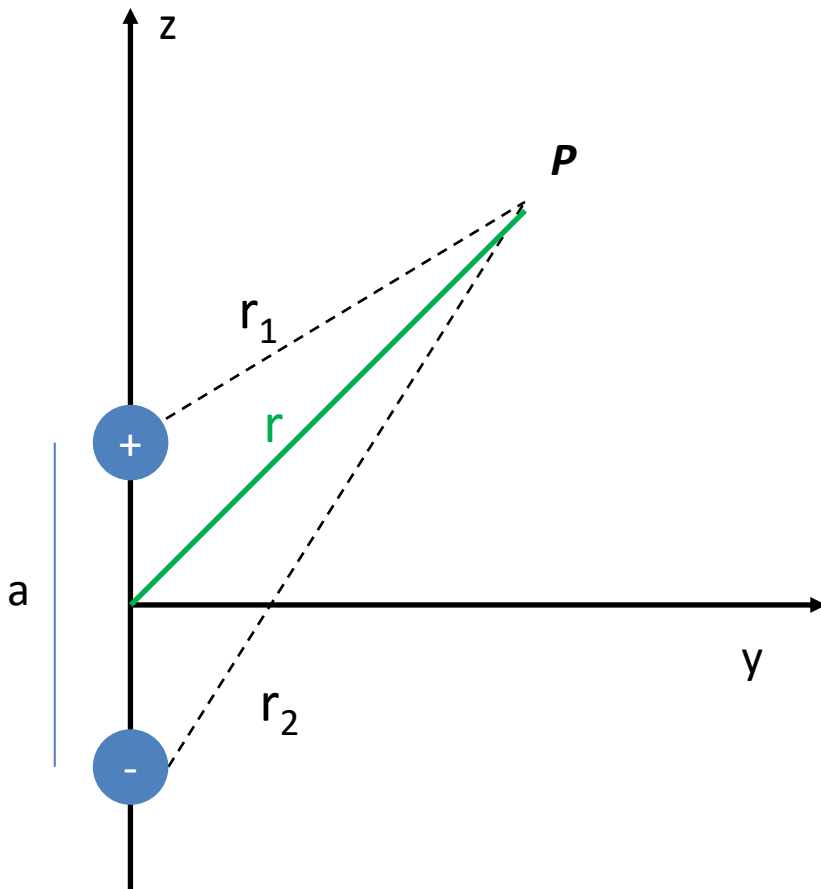
Potenziale elettrostatico

$$V(P) = \frac{q}{4 \pi \epsilon_0} \left(\frac{1}{r_1} - \frac{1}{r_2} \right)$$
$$= \frac{q}{4 \pi \epsilon_0} \left(\frac{r_2 - r_1}{r_1 r_2} \right)$$

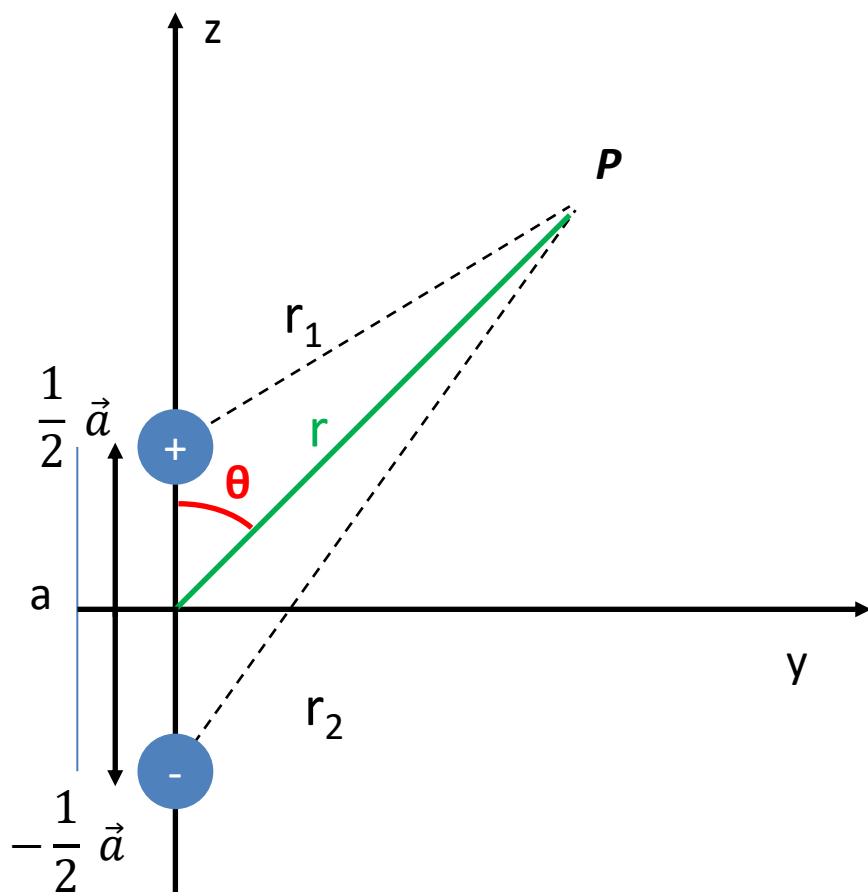
Vogliamo utilizzare

$$\vec{E} = - \vec{\nabla} V$$

per calcolare il campo elettrostatico.



Dipolo elettrico



$$r_1^2 = \left| \vec{r} - \frac{1}{2} \vec{a} \right|^2 \quad r_2^2 = \left| \vec{r} + \frac{1}{2} \vec{a} \right|^2$$

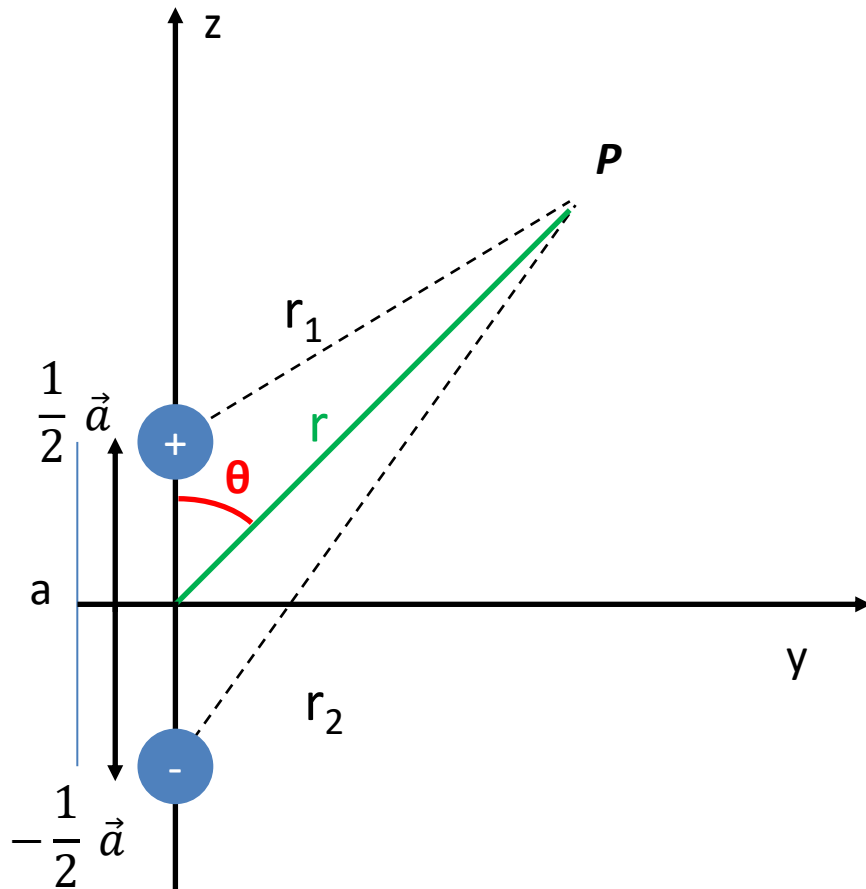
$$\left| \vec{r} + \frac{1}{2} \vec{a} \right| = \sqrt{r^2 + \frac{1}{4}a^2 + 2r \frac{1}{2}a \cos \theta}$$

Teorema del coseno

$$\begin{aligned} r_1^2 &= r^2 - r a \cos \theta + \frac{a^2}{4} \\ &= r^2 \left[1 - \frac{a}{r} \cos \theta + \frac{a^2}{4r^2} \right] \end{aligned}$$

$$\begin{aligned} r_2^2 &= r^2 + r a \cos \theta + \frac{a^2}{4} \\ &= r^2 \left[1 + \frac{a}{r} \cos \theta + \frac{a^2}{4r^2} \right] \end{aligned}$$

Consideriamo adesso il caso $r \gg a$



$$r_1^2 = r^2 \left[1 - \frac{a}{r} \cos \theta + \frac{a^2}{4r^2} \right]$$

$$r_2^2 = r^2 \left[1 + \frac{a}{r} \cos \theta + \frac{a^2}{4r^2} \right]$$

$$r_1 \approx r \sqrt{1 - \frac{a}{r} \cos \theta}$$

$$r_2 \approx r \sqrt{1 + \frac{a}{r} \cos \theta}$$

$$V(P) = \frac{q}{4 \pi \epsilon_0} \left(\frac{r_2 - r_1}{r_2 r_1} \right)$$

Calcoliamo l'espressione per il potenziale in **approssimazione di grandi distanze**



$$r_1 \approx r \sqrt{1 - \frac{a}{r} \cos \theta}$$

$$r_2 \approx r \sqrt{1 + \frac{a}{r} \cos \theta}$$

$$r \gg a$$

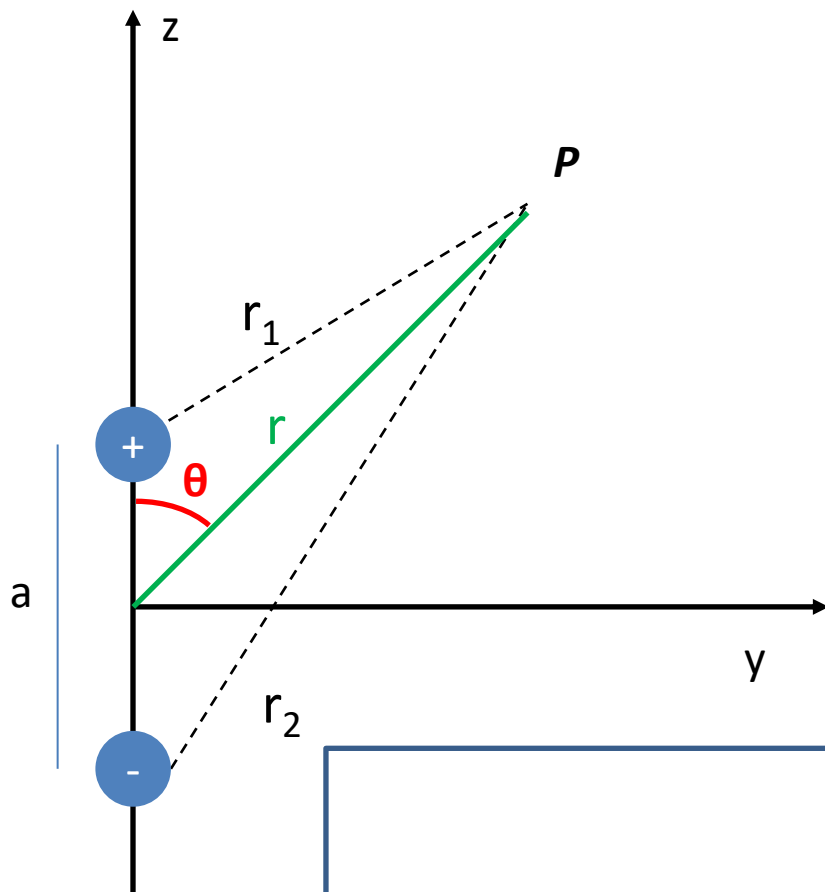
$$V(P) = \frac{q}{4 \pi \epsilon_0} \left(\frac{\mathbf{r}_2 - \mathbf{r}_1}{\mathbf{r}_2 \mathbf{r}_1} \right)$$

$$\begin{aligned} \mathbf{r}_2 - \mathbf{r}_1 &= r \left[\sqrt{1 + \frac{a}{r} \cos \theta} - \sqrt{1 - \frac{a}{r} \cos \theta} \right] \approx r \left[1 + \frac{1}{2} \frac{a}{r} \cos \theta - 1 + \frac{1}{2} \frac{a}{r} \cos \theta \right] \\ &= a \cos \theta \end{aligned}$$

$$\begin{aligned} \mathbf{r}_1 \mathbf{r}_2 &= r^2 \sqrt{\left(1 - \frac{a}{r} \cos \theta\right) \left(1 + \frac{a}{r} \cos \theta\right)} = r^2 \sqrt{1 - \cancel{\frac{a^2}{r^2}} \cos^2 \theta} \\ &\approx r^2 \end{aligned}$$

Dipolo elettrico

Punto P molto lontano dal dipolo: $r \gg a$.



Approssimazioni

$$r_2 - r_1 = a \cos \theta$$

$$r_2 r_1 = r^2$$

$$V(P) = \frac{q}{4 \pi \epsilon_0} \left(\frac{r_2 - r_1}{r_1 r_2} \right)$$



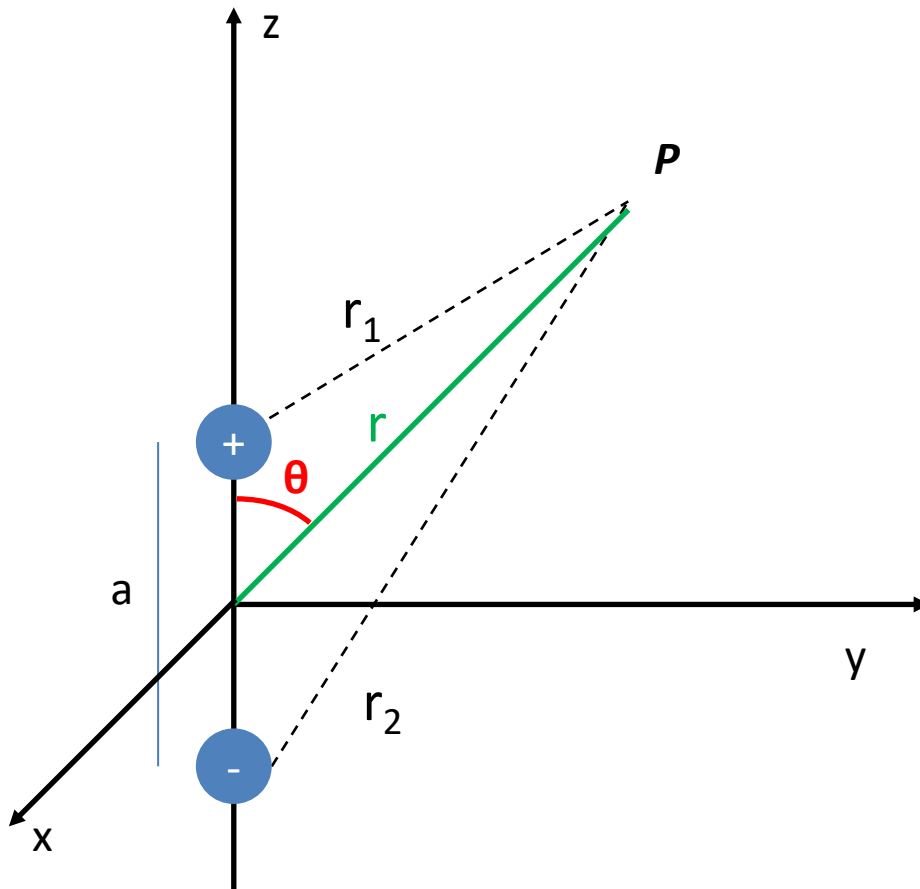
$$V(P) = \frac{q a \cos \theta}{4 \pi \epsilon_0 r^2} = \frac{\vec{p} \cdot \hat{u}_r}{4 \pi \epsilon_0 r^2}$$

Potenziale elettrostatico in approssimazione di grandi distanze

Calcoliamo il campo elettrostatico a partire dal potenziale:

$$\vec{E} = - \vec{\nabla} V$$

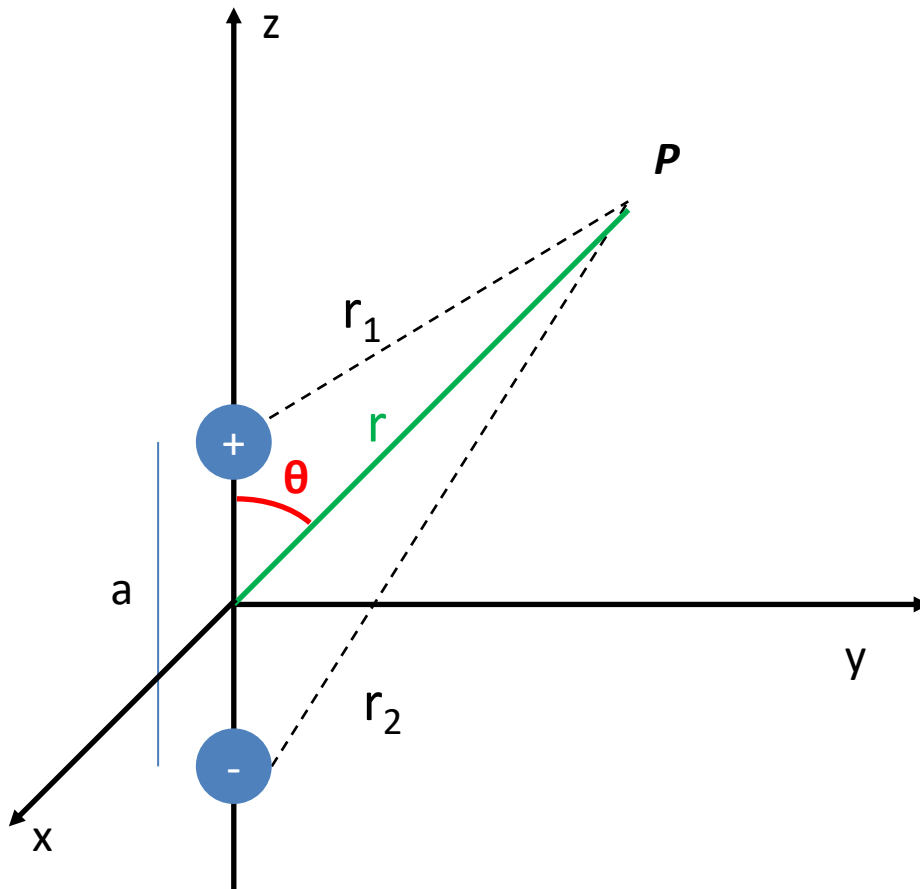
$$\nabla (V(r, \theta)) = \frac{\partial V}{\partial r} \hat{u}_r + \frac{1}{r} \frac{\partial V}{\partial \theta} \hat{u}_\theta + \frac{1}{r \sin \theta} \frac{\partial V}{\partial \varphi} \hat{u}_\varphi$$



Calcoliamo il campo elettrostatico a partire dal potenziale:

$$\vec{E} = - \vec{\nabla} V$$

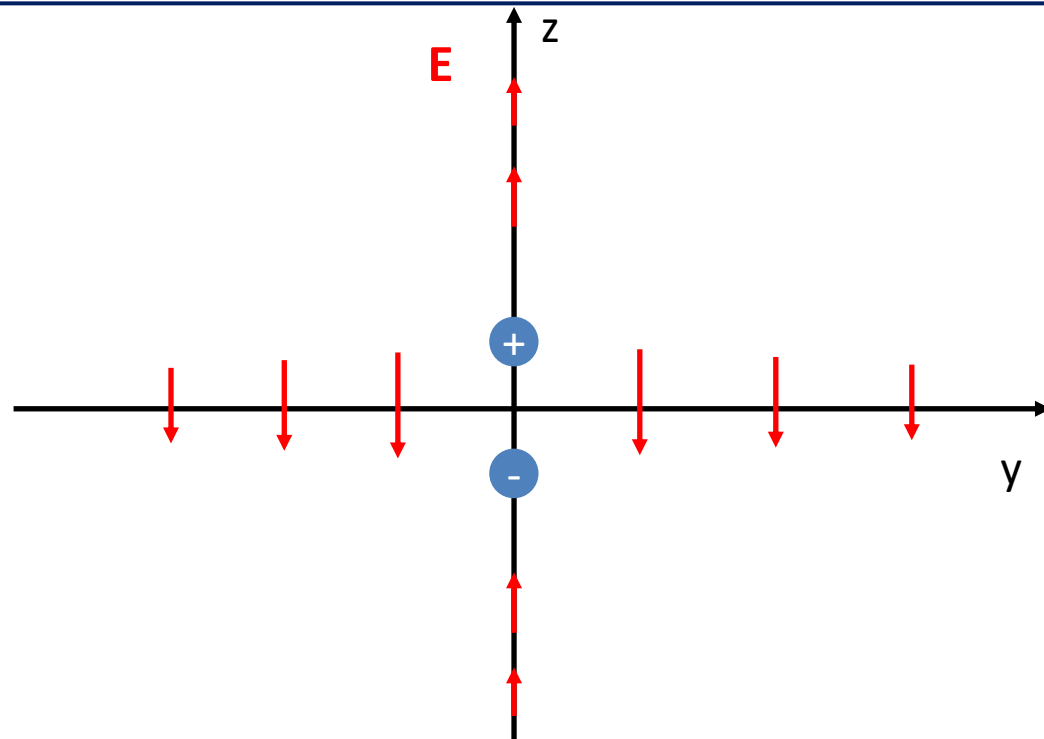
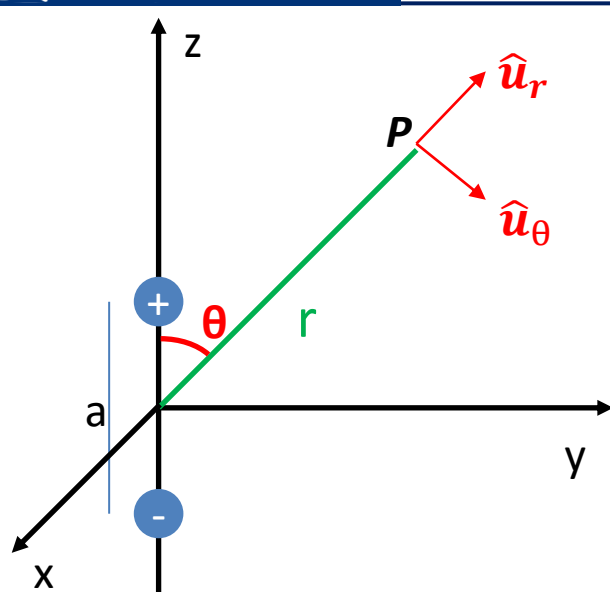
$$\nabla (V(r, \theta)) = \frac{\partial V}{\partial r} \hat{u}_r + \frac{1}{r} \frac{\partial V}{\partial \theta} \hat{u}_\theta + \frac{1}{r \sin \theta} \frac{\partial V}{\partial \varphi} \hat{u}_\varphi$$



$$E_r = - \frac{\partial V}{\partial r} = \frac{2 p \cos \theta}{4 \pi \epsilon_0 r^3}$$

$$E_\theta = - \frac{1}{r} \frac{\partial V}{\partial \theta} = \frac{p \sin \theta}{4 \pi \epsilon_0 r^3}$$

$$E_\varphi = 0$$

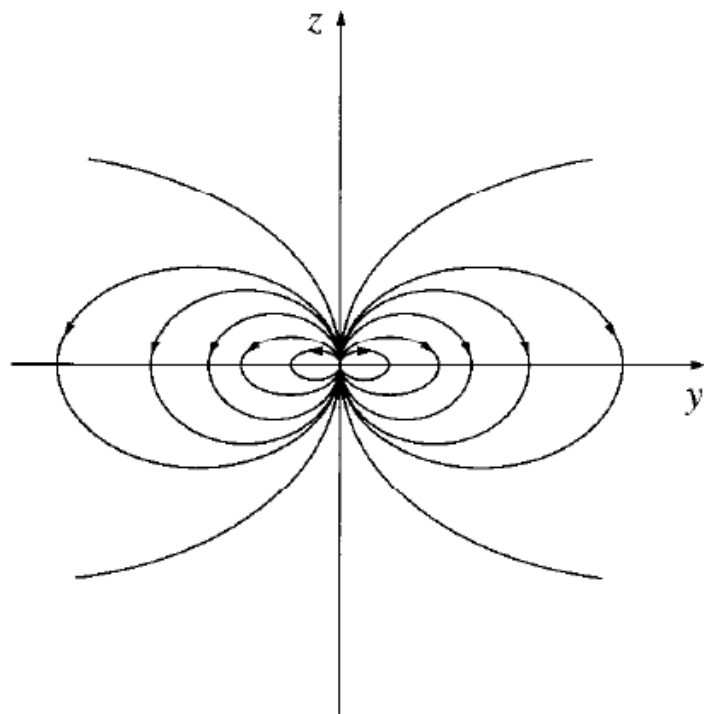


$$E_r = -\frac{\partial V}{\partial r} = \frac{2 p \cos \theta}{4 \pi \epsilon_0 r^3}$$

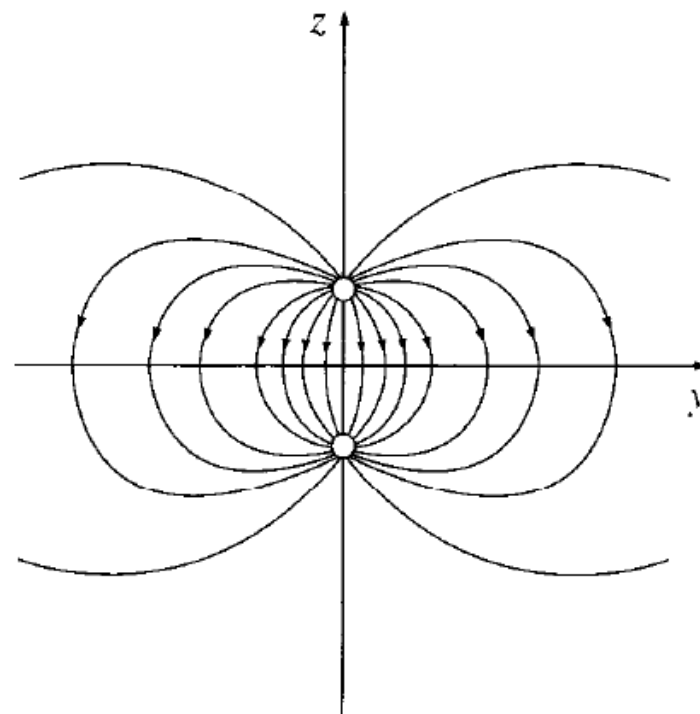
$$E_\theta = -\frac{1}{r} \frac{\partial V}{\partial \theta} = \frac{p \sin \theta}{4 \pi \epsilon_0 r^3}$$

$$E_\phi = 0$$

Nota bene: il risultato trovato è valido a grandi distanze dal dipolo, ovvero quando $r \gg a$.

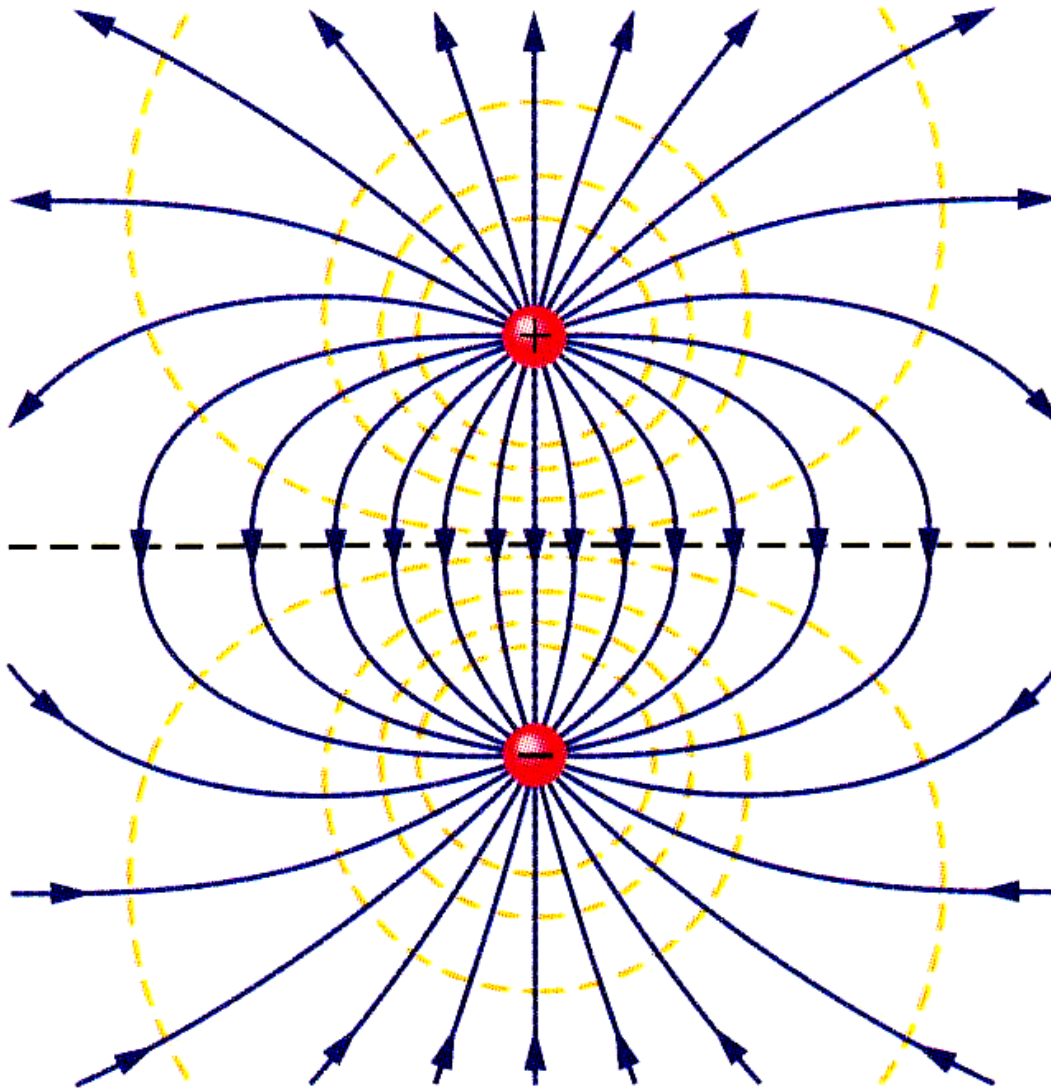


(a) Field of a "pure" dipole



(a) Field of a "physical" dipole

Dipolo elettrico



Linee di campo E

$V = \text{cost.}$

$$V(P) = \frac{q a \cos \theta}{4 \pi \epsilon_0 r^2} = \frac{\vec{p} \cdot \hat{u}_r}{4 \pi \epsilon_0 r^2}$$

$$E_r = -\frac{\partial V}{\partial r} = \frac{2 p \cos \theta}{4 \pi \epsilon_0 r^3}$$

$$E_\theta = -\frac{1}{r} \frac{\partial V}{\partial \theta} = \frac{p \sin \theta}{4 \pi \epsilon_0 r^3}$$

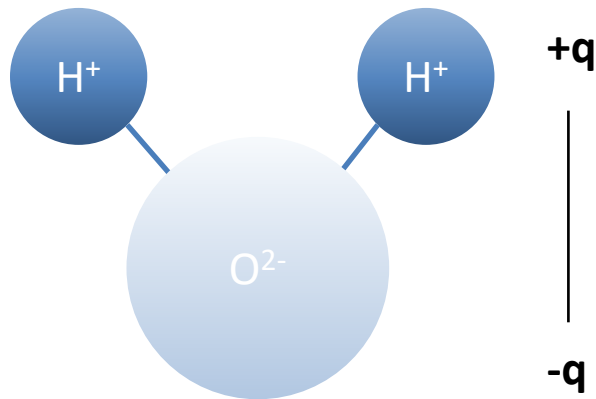
$$E_\varphi = 0$$

Approssimazione di dipolo

Le espressioni per il campo elettrostatico e per il potenziale sono valide per sistemi più complessi rispetto a quello presentato



La definizione di momento di dipolo può essere generalizzata a sistemi di cariche neutri costituiti da più di due cariche, su scale dimensionali molto diverse



Molecola H_2O

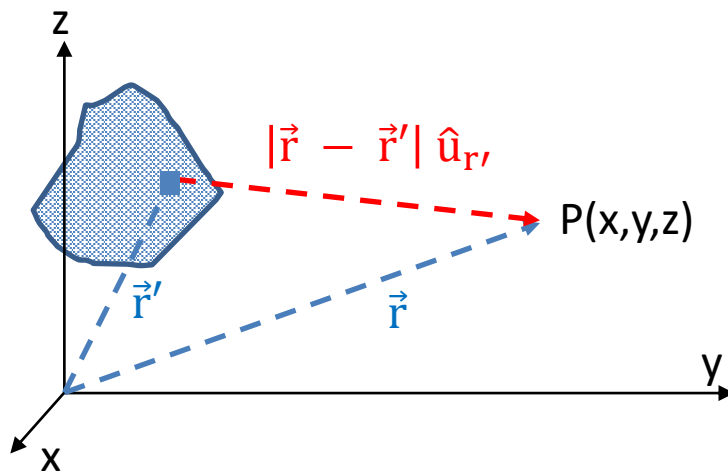


Antenna

Approssimazione di dipolo

Consideriamo una generica distribuzione di carica localizzata:

$$V(\vec{r}) = \frac{1}{4 \pi \epsilon_0} \int_{\tau} \frac{\rho(\vec{r}')}{|\vec{r} - \vec{r}'|} dV' = \frac{1}{4 \pi \epsilon_0} \int_{\tau} \frac{\rho(\vec{r}')}{\sqrt{r^2 - 2\vec{r} \cdot \vec{r}' + r'^2}} dV'$$



$$= \frac{1}{4 \pi \epsilon_0} \int_{\tau} \frac{\rho(\vec{r}')}{r \left[1 - 2 \frac{\vec{r} \cdot \vec{r}'}{r^2} + \frac{r'^2}{r^2} \right]^{1/2}} dV'$$

$$= \frac{1}{4 \pi \epsilon_0} \int_{\tau} \frac{\rho(\vec{r}')}{r} \left[1 - 2 \frac{\vec{r} \cdot \vec{r}'}{r^2} + \frac{r'^2}{r^2} \right]^{-1/2} dV'$$

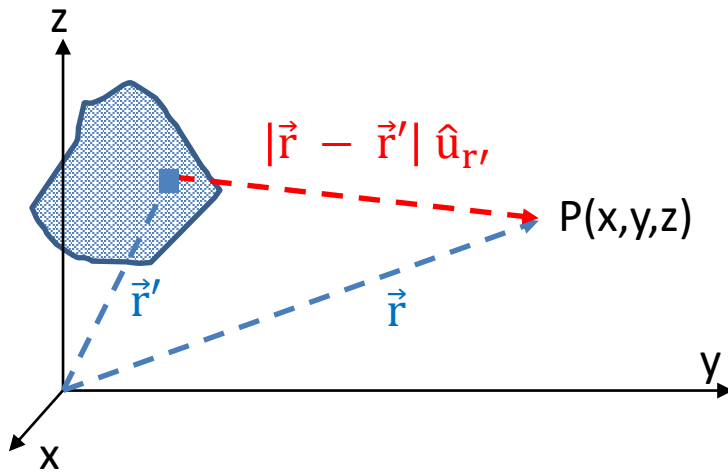
Consideriamo l'approssimazione di grandi distanze rispetto alle dimensioni della distribuzione di carica:

$$r \gg r' \quad \forall r' \text{ in } \tau$$

Approssimazione di dipolo

$$(1 + x)^{-1/2} \approx 1 - \frac{1}{2}x$$

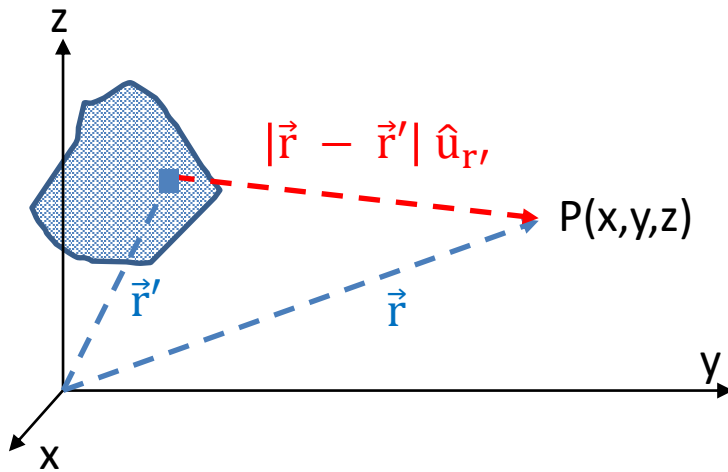
$$x = \frac{r'^2}{r^2} - 2 \frac{\vec{r} \cdot \vec{r}'}{r^2}$$



Approssimazione di dipolo

$$(1 + x)^{-1/2} \approx 1 - \frac{1}{2}x \quad \Rightarrow \quad \approx \frac{1}{4\pi\epsilon_0} \int_{\tau} \frac{\rho(\vec{r}')}{r} \left[1 + \frac{\vec{r} \cdot \vec{r}'}{r^2} - \frac{1}{2} \frac{r'^2}{r^2} \right] dV'$$

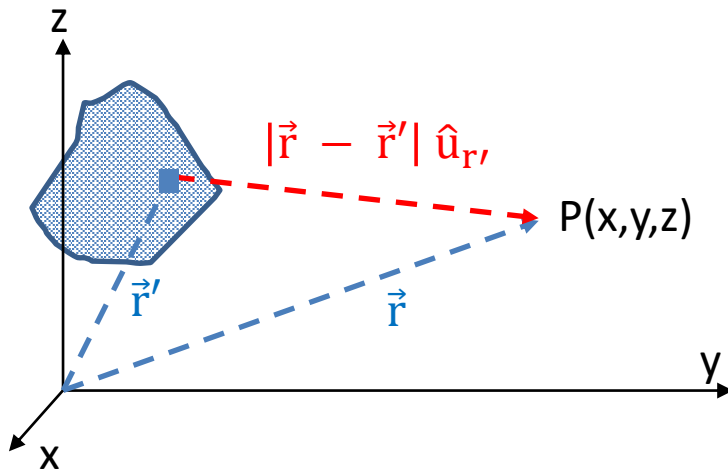
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Approssimazione di dipolo

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$$x = \frac{r'^2}{r^2} - 2 \frac{\vec{r} \cdot \vec{r}'}{r^2}$$



Approssimazione di dipolo

$$(1 + x)^{-1/2} \approx 1 - \frac{1}{2}x$$

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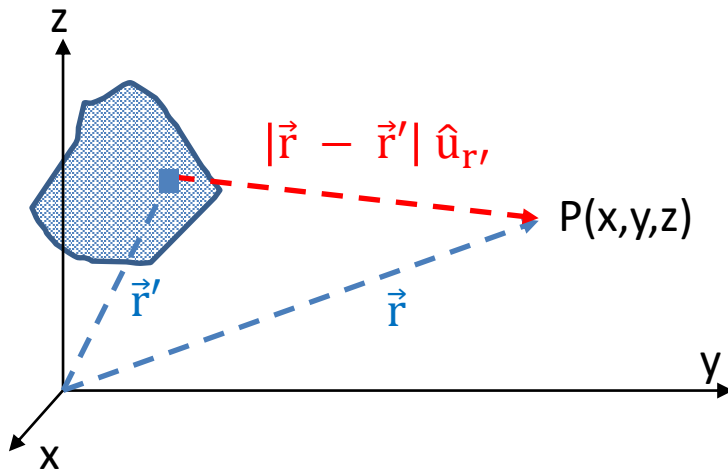
$$\approx \frac{1}{4 \pi \epsilon_0} \int_{\tau} \frac{\rho(\vec{r}')}{r} \left[1 + \frac{\vec{r} \cdot \vec{r}'}{r^2} - \frac{1}{2} \frac{r'^2}{r^2} \right] dV'$$

$$\sim \frac{1}{r}$$

$$\sim \frac{1}{r^2}$$



$$\approx \frac{1}{4 \pi \epsilon_0} \int_{\tau} \frac{\rho(\vec{r}')}{r} dV' + \frac{1}{4 \pi \epsilon_0} \int_{\tau} \frac{\rho(\vec{r}') \vec{r} \cdot \vec{r}'}{r^3} dV'$$



Approssimazione di dipolo

$$(1 + x)^{-1/2} \approx 1 - \frac{1}{2}x$$

$$x = \frac{r'^2}{r^2} - 2 \frac{\vec{r} \cdot \vec{r}'}{r^2}$$



$$\approx \frac{1}{4 \pi \epsilon_0} \int_{\tau} \frac{\rho(\vec{r}')}{r} \left[1 + \frac{\vec{r} \cdot \vec{r}'}{r^2} - \frac{1}{2} \frac{r'^2}{r^2} \right] dV'$$

$\downarrow \sim \frac{1}{r}$
 $\downarrow \sim \frac{1}{r^2}$

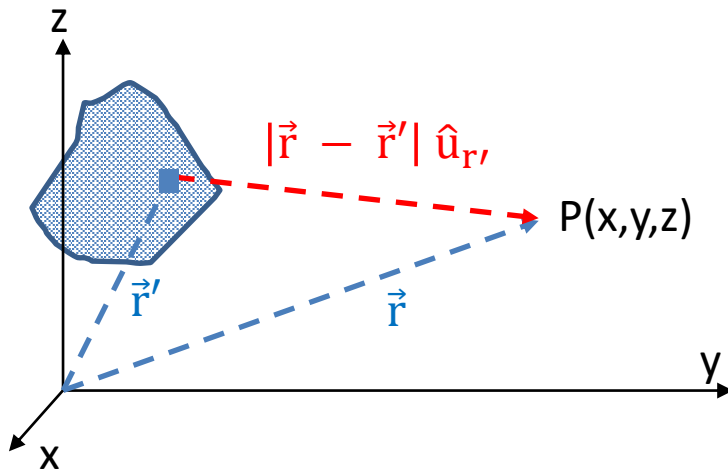


$$\approx \frac{1}{4 \pi \epsilon_0} \int_{\tau} \frac{\rho(\vec{r}')}{r} dV' + \frac{1}{4 \pi \epsilon_0} \int_{\tau} \frac{\rho(\vec{r}') \vec{r} \cdot \vec{r}'}{r^3} dV'$$



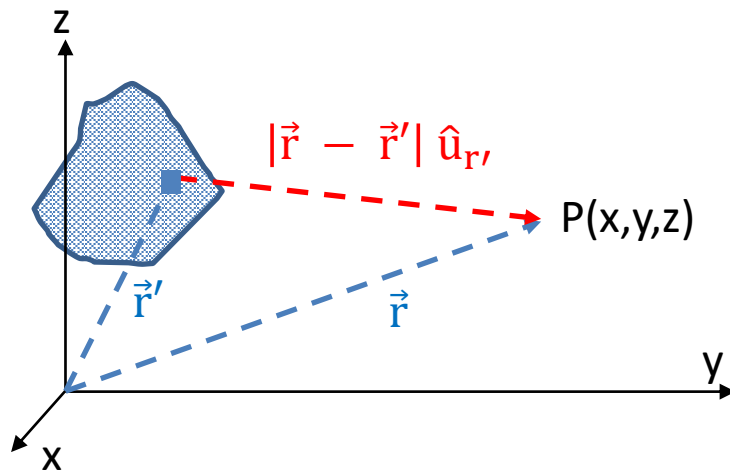
$$\vec{r} \cdot \vec{r}' = r r' \cos \theta$$

$$= \frac{1}{4 \pi \epsilon_0} \frac{Q}{r} + \frac{1}{4 \pi \epsilon_0} \frac{\vec{p} \cdot \hat{u}_r}{r^2}$$



Approssimazione di dipolo

$$V(\vec{r}) = \frac{1}{4 \pi \epsilon_0} \frac{Q}{r} + \frac{1}{4 \pi \epsilon_0} \frac{\vec{p} \cdot \hat{u}_r}{r^2}$$



per **sistemi neutri** la carica
totale $Q = 0$

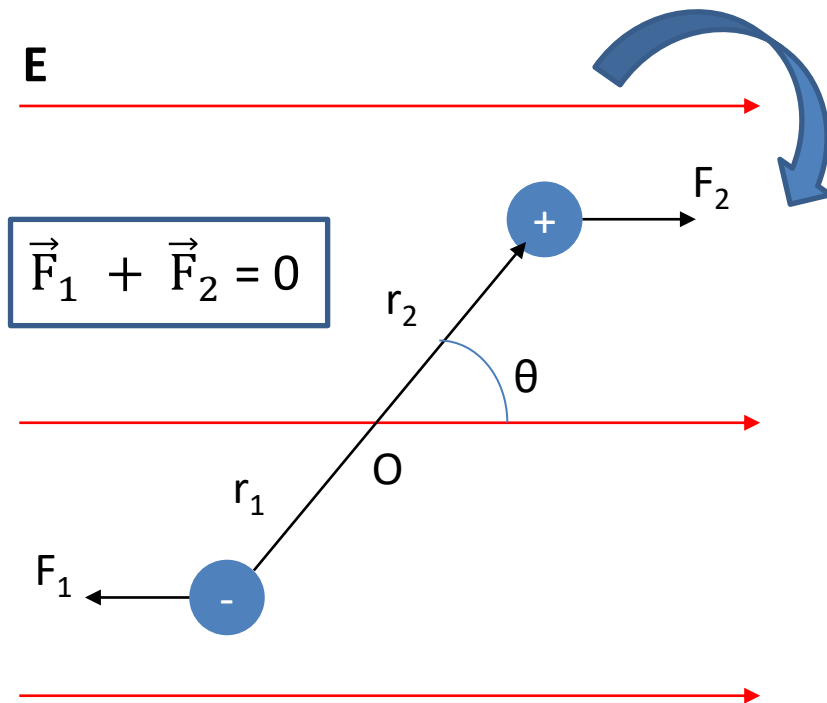
$$V(\vec{r}) = \frac{1}{4 \pi \epsilon_0} \frac{\vec{p} \cdot \hat{u}_r}{r^2}$$

A grandi distanze possiamo approssimare la distribuzione di carica con un dipolo di momento:

$$\vec{p} = \int_{\tau} \rho(\vec{r}') \vec{r}' d\tau'$$

Forza elettrica su dipolo

Passiamo allo studio dell'interazione tra un dipolo e un ***campo elettrico esterno uniforme***.



Momento meccanico

$$\vec{M} = (\vec{r}_2 - \vec{r}_1) \times \vec{F}_2 = \vec{p} \times \vec{E}$$

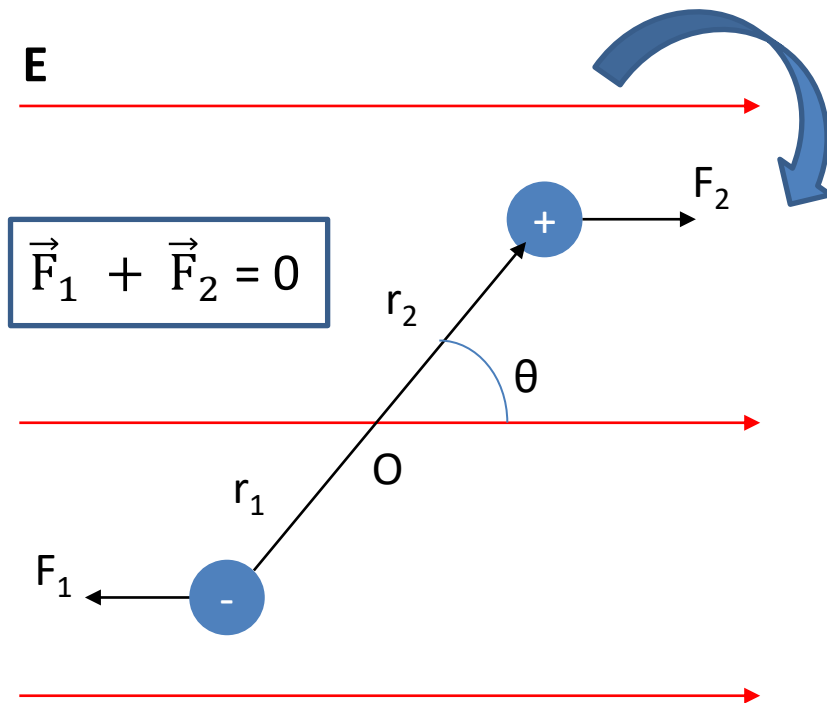
Il momento di dipolo ruota fino ad essere parallelo e concorde al campo elettrostatico.

$$W = \int_{\theta_0}^{\theta} M d\theta$$

\downarrow
 $p E \sin\theta$

Forza elettrica su dipolo

Passiamo allo studio dell'interazione tra un dipolo e un ***campo elettrico esterno uniforme***.



Momento meccanico

$$\vec{M} = (\vec{r}_2 - \vec{r}_1) \times \vec{F}_2 = \vec{p} \times \vec{E}$$

Il momento di dipolo ruota fino ad essere parallelo e concorde al campo elettrostatico.

$$W = \int_{\theta_0}^{\theta} M d\theta$$



$$-p E \cos\theta$$

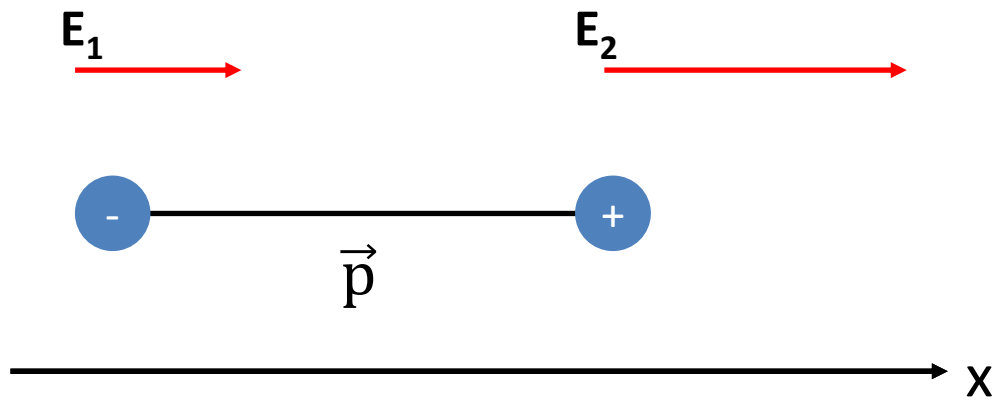
Energia potenziale elettrostatica di dipolo

$$U_e(\theta) = -\vec{p} \cdot \vec{E}$$

Forza elettrica su dipolo

Cosa succede quando il *campo elettrico esterno non è uniforme*?

Supponiamo che E cresca al crescere di x e che il dipolo sia orientato come il campo elettrico.



- Se il dipolo è **concorde** al campo E tende a spostarsi dove esso è **più intenso**
- Se il dipolo è **discorde**, si sposta dove il campo è **meno intenso**

Approssimazione distanza tra le cariche a piccola

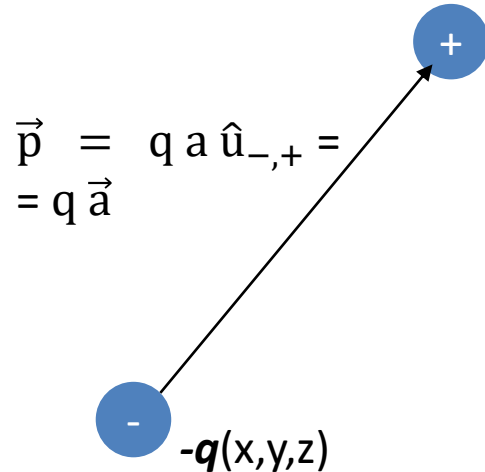
$$E_2 = E_1 + \frac{\partial E}{\partial x} a$$

$$F = q (E_2 - E_1) = p \frac{\partial E}{\partial x}$$

Forza elettrica su dipolo

Caso più generale: **campo elettrico qualsiasi** e dipolo **non allineato**.

$$+q(x + a_x, y + a_y, z + a_z)$$



Energia potenziale sistema

$$U_e = qV(x + a_x, y + a_y, z + a_z) - qV(x, y, z)$$

Approssimazione a piccolo

$$U_e = q a_x \frac{\partial V}{\partial x} + q a_y \frac{\partial V}{\partial y} + q a_z \frac{\partial V}{\partial z} = -\vec{p} \cdot \vec{E}$$



$$\vec{F} = -\vec{\nabla} U_e$$

- Il dipolo subisce sia l'azione del momento meccanico che tende ad allinearlo al campo elettrico, sia una forza risultante calcolabile tramite gradiente dell'energia potenziale (dato che il campo elettrico è conservativo.)