

Tolerances

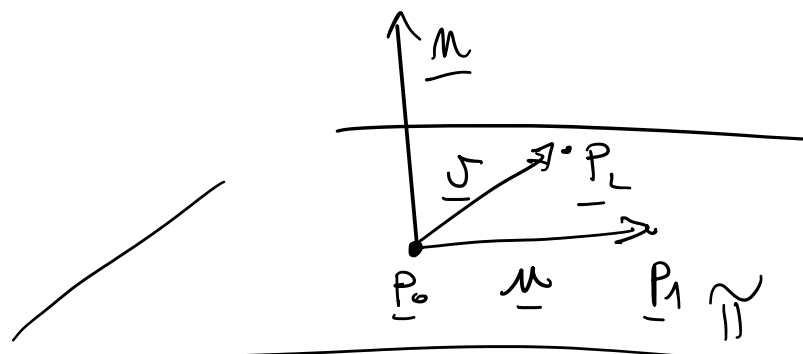
Problem 4: Given two planes π_1, π_2 , find the intersection line $r \perp$

Solution: we recall the definition of the plane in $d=3$

$$\pi = \{x \in \mathbb{E}^3 \mid x = \alpha_0 \underline{p}_0 + \alpha_1 \underline{p}_1 + (1 - \alpha_0 - \alpha_1) \underline{p}_2, \alpha = (\alpha_0, \alpha_1) \in \mathbb{R}^2\}$$

now, we rewrite as

$$x = \underline{p}_0 + \alpha_0 (\underline{p}_2 - \underline{p}_0) + \alpha_1 (\underline{p}_1 - \underline{p}_0)$$



If we define $\underline{n} = \frac{\underline{p}_2 - \underline{p}_0}{\|\underline{p}_2 - \underline{p}_0\|} \times \frac{\underline{p}_1 - \underline{p}_0}{\|\underline{p}_1 - \underline{p}_0\|}$, we can rewrite the equation as

$$\underline{n}^T x = \underline{n}^T \underline{p}_0 + \alpha_0 \underbrace{\underline{n}^T (\underline{p}_2 - \underline{p}_0)}_{\underline{n} \perp \underline{p}_2 - \underline{p}_0} + \alpha_1 \underbrace{\underline{n}^T (\underline{p}_1 - \underline{p}_0)}_{\underline{n} \perp \underline{p}_1 - \underline{p}_0}$$

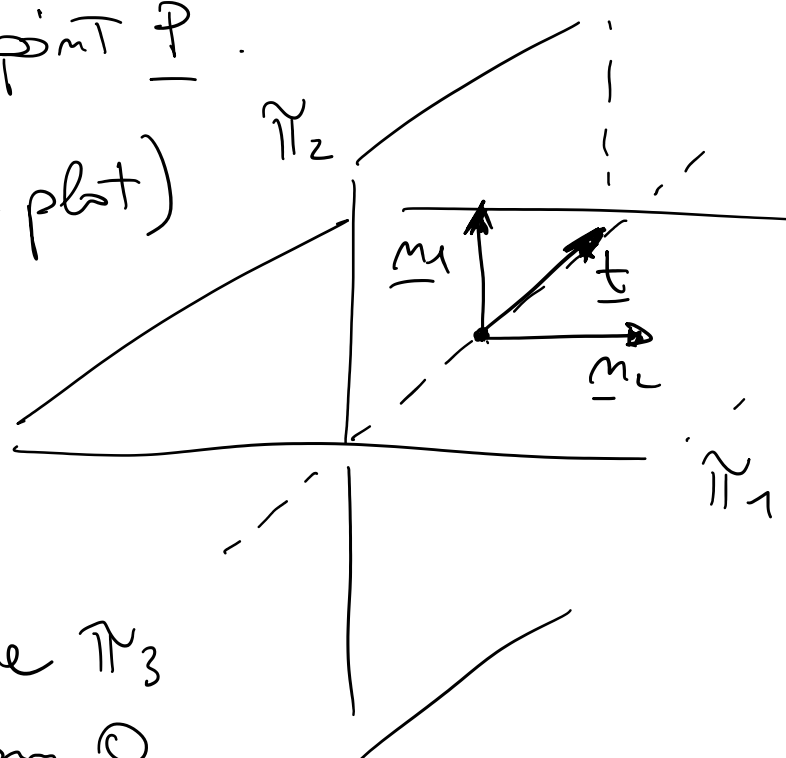
obtaining the plane equation

$$\underline{n}^T x = \underline{n}^T \underline{p}_0 \Rightarrow n_1 x_1 + n_2 x_2 + n_3 x_3 = d = n_1 p_1^0 + n_2 p_2^0 + n_3 p_3^0$$

To find the line r intersection of π_1, π_2 we have to compute the tangent \underline{t} and a point \underline{p} .

1) To compute \underline{t} is sufficient (from the plot)

$$\underline{t} = \underline{n}_1 \times \underline{n}_2$$



2) To compute \underline{p} we find the intersection of π_1, π_2 and a plane π_3 orthogonal to \underline{t} and passing from $\underline{0}$

$$\underline{p}: \begin{cases} \underline{n}_1^T \underline{p} = d_1 \\ \underline{n}_2^T \underline{p} = d_2 \\ \underline{t}^T \underline{p} = 0 \end{cases} \Rightarrow \underbrace{\begin{bmatrix} -\underline{n}_1 \\ -\underline{n}_2 \\ -\underline{t} \end{bmatrix}}_{\underline{A}} \underbrace{\begin{pmatrix} p_1 \\ p_2 \\ p_3 \end{pmatrix}}_{\underline{p}} = \underbrace{\begin{pmatrix} d_1 \\ d_2 \\ 0 \end{pmatrix}}_{\underline{b}}$$

Again there exists a solution if $\det(\underline{A}) \neq 0$

$$\Rightarrow \text{NO CANCELLATION} \quad \underline{t} \cdot (\underline{n}_1 \times \underline{n}_2) \neq 0$$

□

To implement all the algorithms we have to remember that we have a FINITE ALGEBRA, thus the numbers are in MACHINE NUMBERS

$$a \in \mathbb{R} \Rightarrow \bar{a} \in \mathcal{F}, \quad \frac{|a - \bar{a}|}{|a|} < \epsilon, \quad |\epsilon| \leq \epsilon_m$$

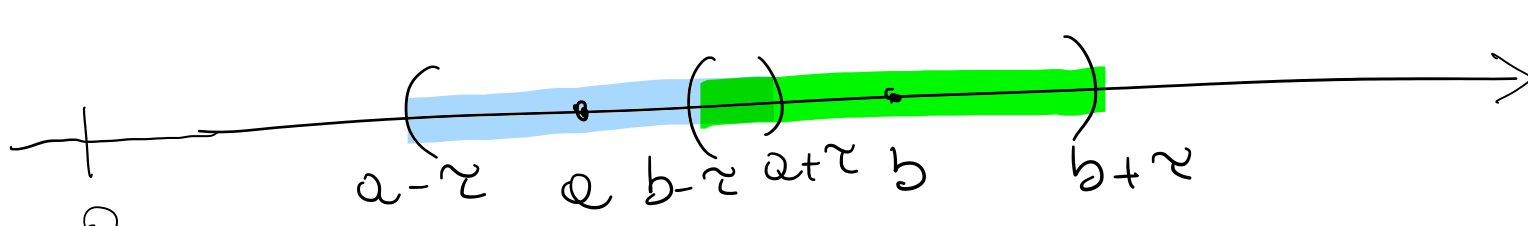
where \mathcal{F} is the MACHINE NUMBERS SET and ϵ_m is the MACHINE PRECISION

$$\mathcal{F} = \{a \in \mathbb{R} : a = (-1)^s 0.a_1 a_2 \dots a_t \cdot N^q, 0 \leq a_i < N, a_t \neq 0, L \leq q \leq U, s \in \{0, 1\} \} \cup \{0\}$$

$$\epsilon_m = \frac{1}{2} N^{1-t}, \quad \text{with } t \text{ the length of the mantissa.}$$

For this reason, when we have to perform the comparisons on the algorithms we need to take in account a TOLERANCE τ

$$\text{EXAMPLE: } a \approx b, a, b \in \mathbb{R} \Rightarrow \frac{|a - b|}{\max(|a|, |b|, 1)} < \tau$$



$$a > b, a, b \in \mathbb{R} \Rightarrow \frac{a - b}{\max(|a|, |b|, 1)} > \tau$$

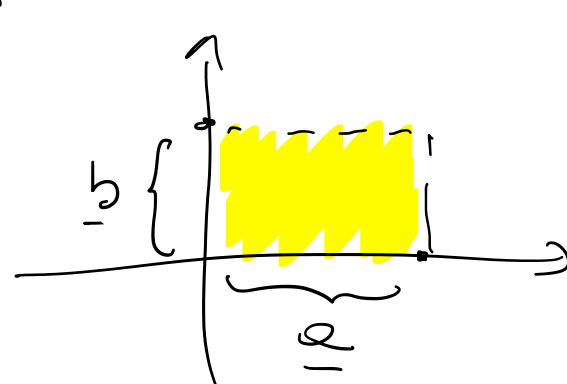
NOTE: It is a good practice in a code to fix a single tolerance for all the operations, in order to have consistency in all the operations.

EXAMPLE τ is the tolerance for the 1D operations.

For the 2D operations, such as the AREA computation we take $\approx \tau^2$ as tolerance.

Indeed, we admit only polygons with edges with length $> \tau$.

Thus, choosing τ^2 we say that the smallest polygon admissible is the rectangle with edges $|a| = \tau$ and $|b| = \tau$.



Another important thing to consider is the CATASTROPHIC CANCELLATION (cancellesone numerica), i.e. the approximation of $x_1 - x_2$ leads to a loss of the original numbers

Example $L_1 = 253.5 \text{ cm}, L_2 = 252.4 \text{ cm}$
 $\bar{L}_1 = 254 \text{ cm}, \bar{L}_2 = 252 \text{ cm}$
 with $\epsilon_m = \frac{1}{2} 10^{1-3} = \frac{1}{2} 10^{-2} = 0.005$
 $\frac{0.2535}{0.2524} = 0.252$
 $\frac{0.2535}{0.2524} = 0.252$
 $\frac{|L_1 - \bar{L}_1|}{|L_1|} = 0.002 < \epsilon_m$
 $\frac{|L_2 - \bar{L}_2|}{|L_2|} = 0.005 < \epsilon_m$

However $L_1 - L_2 \approx 1 \text{ cm}$ but $\bar{L}_1 - \bar{L}_2 \approx 2 \text{ cm}$, thus

$$\left| \frac{(L_1 - L_2) - (\bar{L}_1 - \bar{L}_2)}{(L_1 - L_2)} \right| = 1 \gg \epsilon_m$$

□

For example, in \mathbb{E}^2 , for the cross product $(\underline{w})_3 = (\underline{u} \times \underline{v})_3 = x_1 y_2 - x_2 y_1$

if $x_1 y_2 \approx x_2 y_1$ then catastrophic cancellation may happen.

In the area of a polygon an error can be made if we do not take in account this phenomenon.