

Full guide to the computation of stability derivatives in MSC Nastran

The process of computing aeroelastic stability (and control) derivatives in Nastran is straightforward.

A proper aircraft model must be defined. This model shall contain at least:

- the main wing
- a control surface (depending on the desired derivative)

A half span model can be used to model the aircraft thanks to symmetry options.

The main wing is modelled in a specific way: first, the geometry is defined and the elastic axis is chosen; then the main spar is modelled.

The movement of the nodes of the main spar can be determined through a bar/beam model or inputted through a GENEL entry from previous tests.

The fuselage of the aircraft can be considered rigid in a first test phase.

The tail can be modelled in a similar fashion to the wing or defined as fully rigid.

In fact, the deflection of the tail can be modelled through the control surface option.

Where needed, lumped masses can be inserted in the model.

When the structural model is complete, the aerodynamics are to be modelled.

The best way is to model the wing as an aerodynamic surface composed of aerodynamic panels.

The tail can be treated in the same way.

After the definition of aerodynamic panels, the splining process shall be carried out.

Finally, after defining a suitable reference system for the rotation of the tail, the latter can be assigned as control surface.

More reference systems can be introduced to compute the aerodynamics of the problem.

IMPORTANT: if a half span model is used with symmetry, when asked to input span and surface the ENTIRE SPAN and SURFACE are to be inserted (double the half span).

The same applies for the tail.

Beware that the tail can be assigned a reduced effectiveness.

In order to perform a static aeroelastic analysis two constraints can be defined:

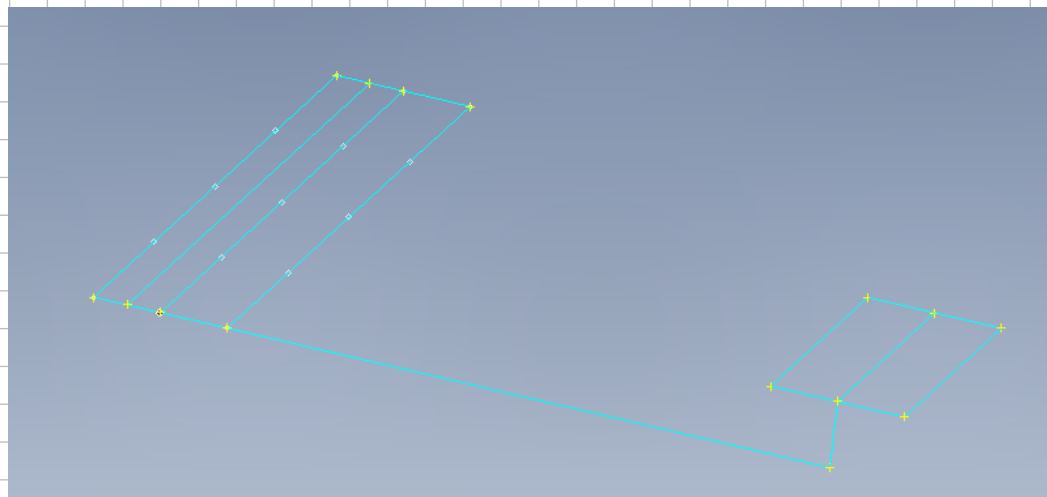
the first, positioned at the root of the wing, represents the blocked dofs, which are not studied in the problem at hand

the second set is called SUPORT and it's used by NASTRAN to determine the degrees of freedom of the problem, so it must be COMPLEMENTARY to the first one

Finally, trim conditions need to be applied. The trim conditions must be sufficient to fully determine the dofs. The use of a control surface is necessary.

OBS: the flow is directed in the positive direction of the x-axis, as all aero refs. must be

LONGITUDINAL STABILITY DERIVATIVES COMPUTATION



Half span 5 m

Chord 1 m

Tail span 2 m

Tail chord 1 m

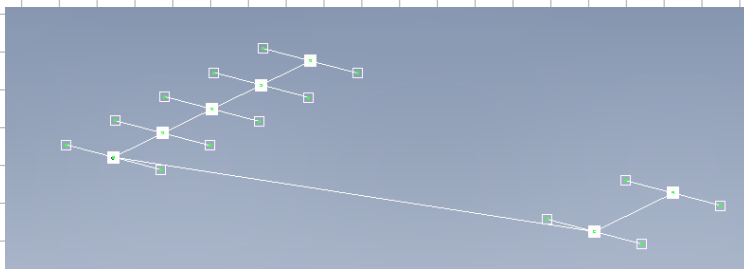
Distance of the tail EA
from the wing EA 5 m

Material
 $E=7e10$ Pa
 $\nu=0.33$

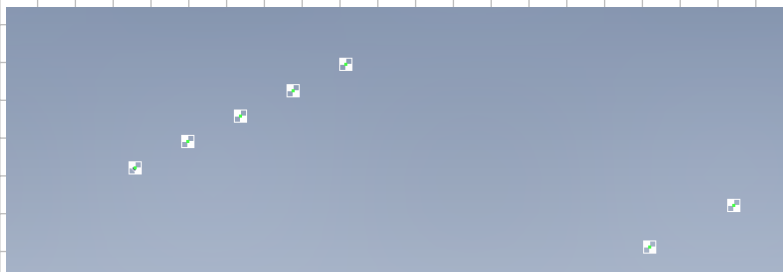
The elastic axis is at 50 % of the chord

Wing spar modelled as 4 bars, with circular section with $r=0.3m$

The tail is rigidly connected to the wing spar, ribs are modelled as rigid elements

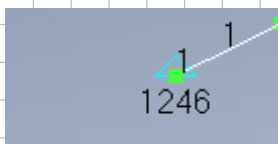


The tail is modelled as a single bar with
the same properties as before

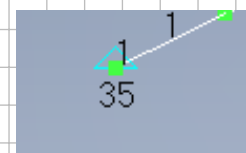


800 kg masses, representing the mass of
the material, are positioned in the nodes

The constraints are defined: for the wing root all dofs are blocked except for vertical translation and pitch around the elastic axis.



constrained

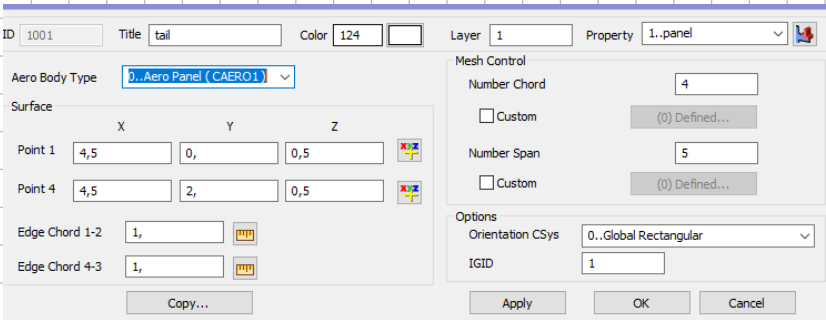
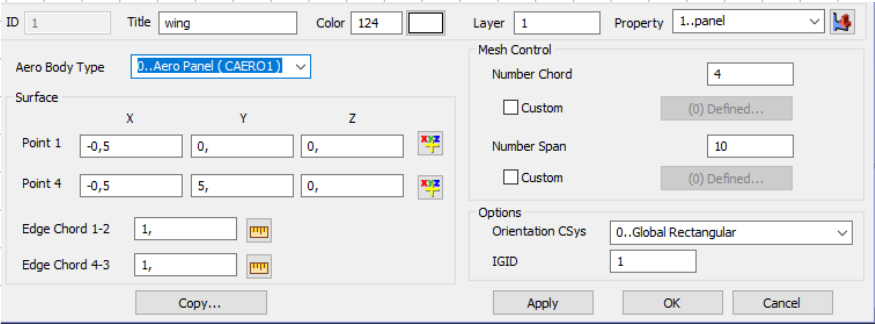
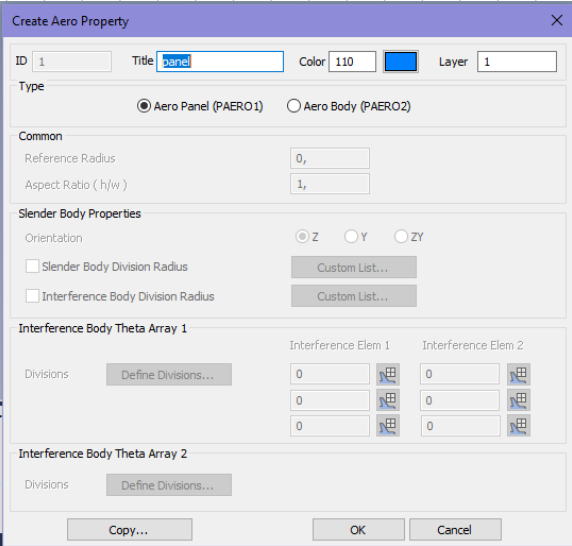


SUPORTed

OBS: the wing spar model can be used to produce a GENEL entry, to be used as usual

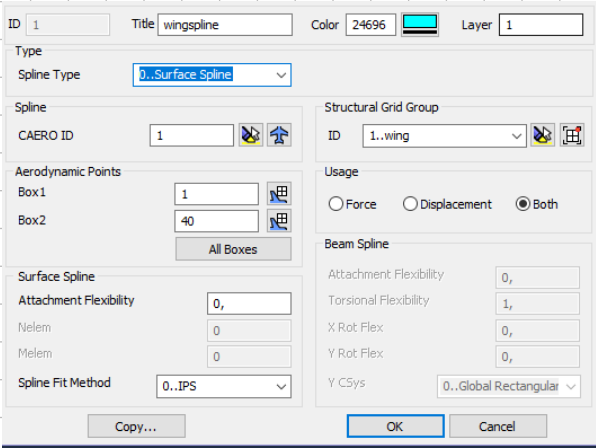
The inclusion of the UD entry does not cause any variation of the derivatives related to the SUPORTed dofs.

Aerodynamics

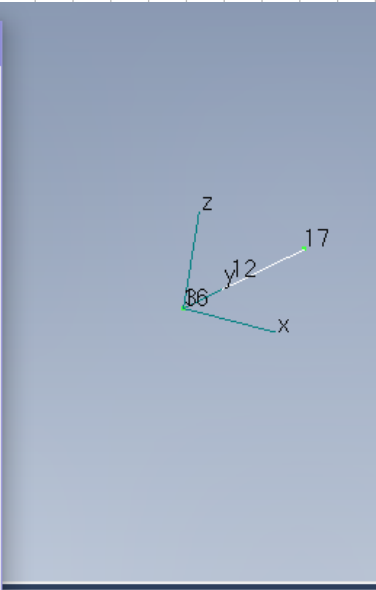
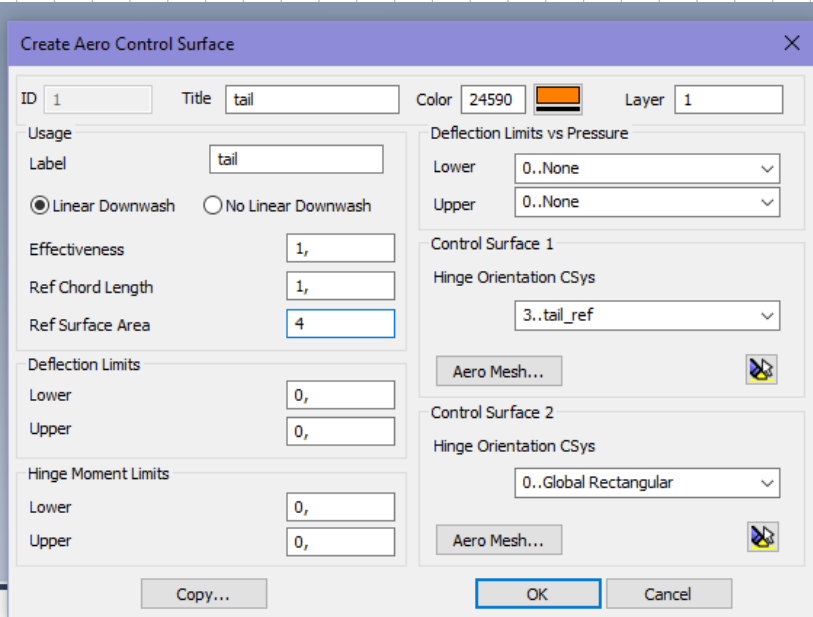


Creation of aerodynamic panel

Creation of aerodynamic surfaces

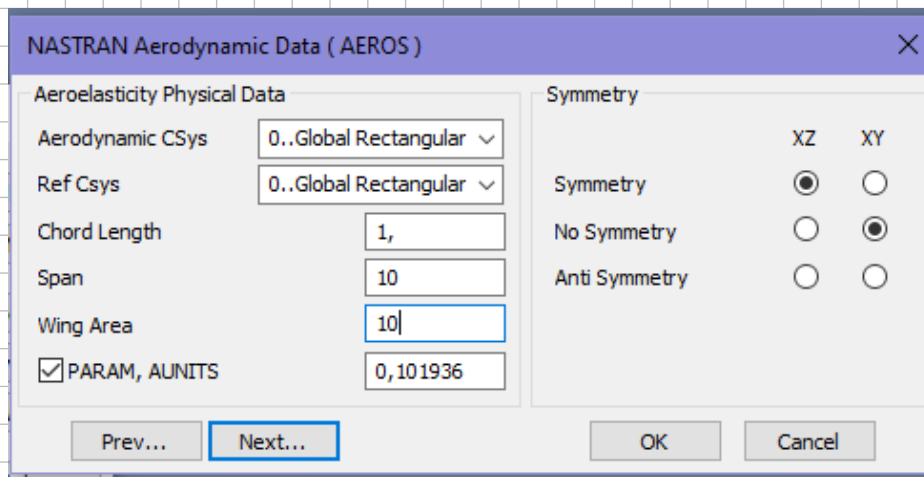


Splining procedure



Creation of control surface, note that the ref area is 4, based on the full tail span

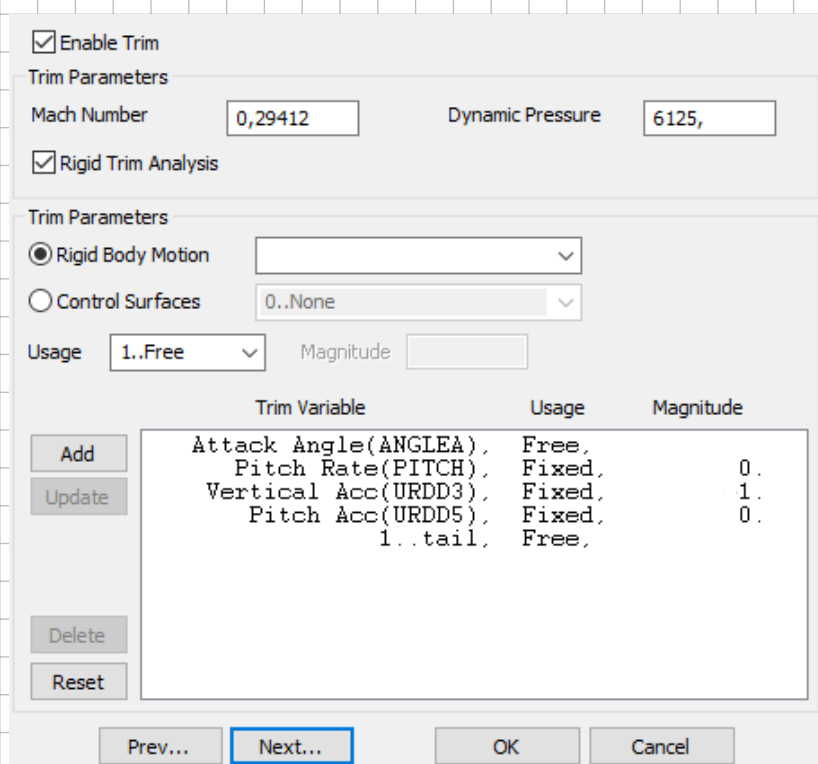
Definition of static aeroelastic analysis



The NASTRAN Aerodynamic Data (AEROS) dialog box is shown. It contains two main sections: 'Aeroelasticity Physical Data' and 'Symmetry'. In the 'Aeroelasticity Physical Data' section, 'Aerodynamic CSys' and 'Ref CSys' are both set to '0..Global Rectangular'. 'Chord Length' is '1', 'Span' is '10', and 'Wing Area' is '10'. The 'PARAM, AUNITS' checkbox is checked, and the value is '0,101936'. In the 'Symmetry' section, 'Symmetry' is selected with a radio button, and 'XZ' and 'XY' are also indicated. The 'Next...' button is highlighted.

Note the PARAM, AUNITS entry:
if set to 1/9.81 allows for
simpler input of the vertical
acceleration as a load factor

Note the full span/surface and the symmetry indication



The Trim Parameters dialog box is shown. It has a 'Trim Parameters' section with 'Mach Number' set to '0,29412' and 'Dynamic Pressure' set to '6125'. The 'Rigid Trim Analysis' checkbox is checked. Below this, there are two 'Trim Parameters' sections. The first has 'Rigid Body Motion' selected with a radio button, and 'Control Surfaces' set to '0..None'. The second has 'Usage' set to '1..Free' and 'Magnitude' set to '1'. A table lists the trim variables and their usage and magnitude:

Trim Variable	Usage	Magnitude
Attack Angle(ANGLEA)	Free	
Pitch Rate(PITCH)	Fixed	0
Vertical Acc(URDD3)	Fixed	1
Pitch Acc(URDD5)	Fixed	0
1..tail	Free	

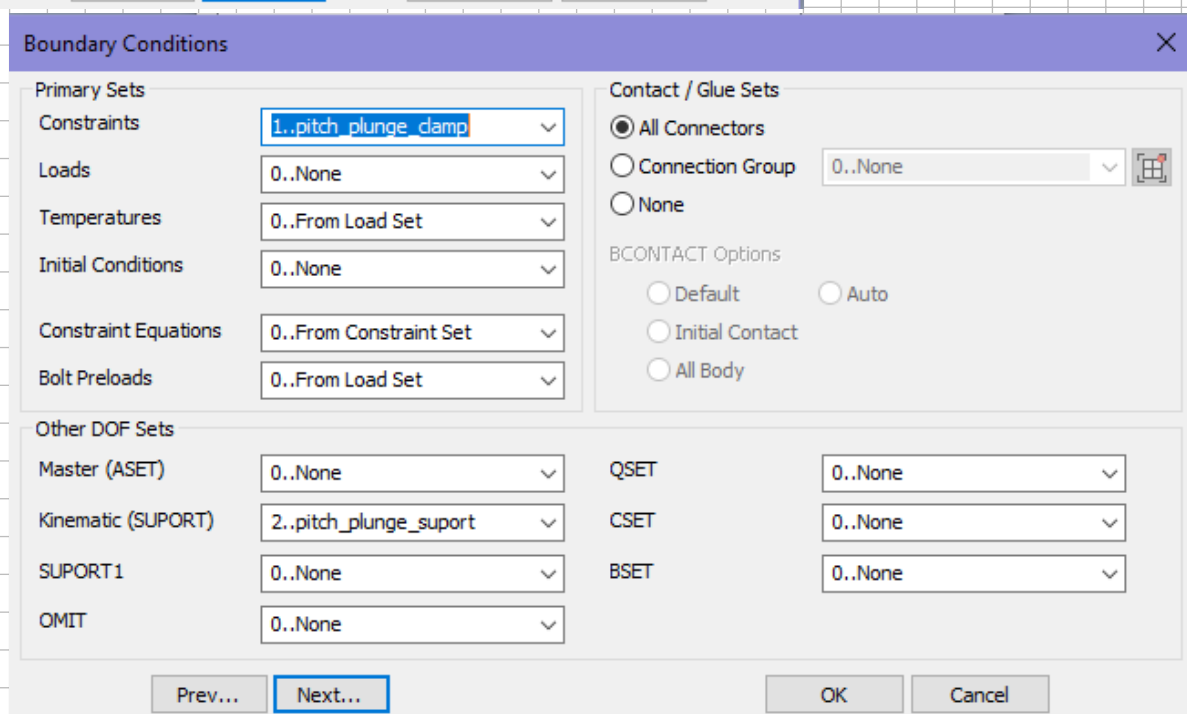
The 'Next...' button is highlighted.

The test is performed at 100 m/s

This is a static trim test, where
 $q=0$, $\theta_{acc}=0$, $vert\ acc=1$

The angle of attack and the tail
deflection are left free

The vertical acc is set to 1, as z
is upwards and AUNITS has been employed



The Boundary Conditions dialog box is shown. It has two main sections: 'Primary Sets' and 'Contact / Glue Sets'. In the 'Primary Sets' section, 'Constraints' is set to '1..pitch_plunge_damp', 'Loads' is '0..None', 'Temperatures' is '0..From Load Set', 'Initial Conditions' is '0..None', 'Constraint Equations' is '0..From Constraint Set', and 'Bolt Preloads' is '0..From Load Set'. In the 'Contact / Glue Sets' section, 'All Connectors' is selected with a radio button, and 'Connection Group' is '0..None'. Below this, 'BCONTACT Options' are set to 'Default'. In the 'Other DOF Sets' section, 'Master (ASET)' is '0..None', 'Kinematic (SUPPORT)' is '2..pitch_plunge_suport', 'SUPPORT1' is '0..None', and 'OMIT' is '0..None'. The 'Next...' button is highlighted.

This last tab
requires the
indication of the
constraints and
SUPPORT

Discussion of the results

TRIM VARIABLE		COEFFICIENT	RIGID		ELASTIC		INERTIAL	
			UNSPUNED	SPLINED	RESTRAINED	UNRESTRAINED	RESTRAINED	UNRESTRAINED
REF. COEFF.	CX	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
	CY	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
	CZ	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
	CMX	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
	CMY	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
	CMZ	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
TAIL	CX	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	-3.527181E-02	0.000000E+00
	CY	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
	CZ	8.176011E-01	8.176011E-01	8.176011E-01	8.176011E-01	0.000000E+00	8.176011E-01	0.000000E+00
	CMX	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
	CMY	-3.722689E+00	-3.722689E+00	-3.722689E+00	-3.722689E+00	0.000000E+00	-3.722689E+00	0.000000E+00
	CMZ	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
ANGLEA	CX	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	3.341201E-02	0.000000E+00
	CY	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
	CZ	3.189289E+00	3.189289E+00	3.189289E+00	3.189289E+00	0.000000E+00	3.189289E+00	0.000000E+00
	CMX	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
	CMY	-2.136143E+00	-2.136143E+00	-2.136143E+00	-2.136143E+00	0.000000E+00	-2.136143E+00	0.000000E+00
	CMZ	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
PITCH	CX	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	-3.438663E-01	0.000000E+00
	CY	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
	CZ	9.823486E+00	9.823486E+00	9.823486E+00	9.823486E+00	0.000000E+00	9.823486E+00	0.000000E+00
	CMX	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
	CMY	-3.893929E+01	-3.893929E+01	-3.893929E+01	-3.893929E+01	0.000000E+00	-3.893929E+01	0.000000E+00
	CMZ	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
URDD3	CX	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
	CY	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
	CZ	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	8.969213E-01	0.000000E+00	0.000000E+00
	CMX	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
	CMY	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	-1.281316E+00	0.000000E+00	0.000000E+00
	CMZ	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
URDD5	CX	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	6.406581E-02	0.000000E+00	0.000000E+00
	CY	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
	CZ	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	-1.281316E+00	0.000000E+00	0.000000E+00
	CMX	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00
	CMY	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	6.470647E+00	0.000000E+00	0.000000E+00
	CMZ	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00

The derivatives are expressed exactly in the global reference system

TRANSFORMATION FROM BASIC TO REFERENCE COORDINATES:									
{ X }		[1.0000	0.0000	0.0000]	{ X }		{ 0.0000E+00 }
{ Y }	=	[0.0000	1.0000	0.0000]	{ Y }	+	{ 0.0000E+00 }
{ Z }REF		[0.0000	0.0000	1.0000]	{ Z }BAS		{ 0.0000E+00 }

No transf. is applied

NON - DIMENSIONAL HINGE MOMENT DERIVATIVE COEFFICIENTS									
CONFIGURATION = AEROSG2D		XY-SYMMETRY = ASYMMETRIC		XZ-SYMMETRY = SYMMETRIC					
MACH = 2.9412E-01				Q = 6.1250E+03					
CONTROL SURFACE = TAIL		REFERENCE CHORD LENGTH = 1.000000E+00		REFERENCE AREA = 2.000000E+00					
TRIM VARIABLE		RIGID		ELASTIC		INERTIAL			
				RESTRAINED	UNRESTRAINED	RESTRAINED	UNRESTRAINED		
AT REFERENCE		0.000000E+00		0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00		
TAIL		1.047701E+00		1.047701E+00	1.047701E+00	0.000000E+00	0.000000E+00		
ANGLEA		7.826452E-01		7.826452E-01	7.826452E-01	0.000000E+00	0.000000E+00		
PITCH		1.015387E+01		1.015387E+01	1.015387E+01	0.000000E+00	0.000000E+00		
URDD3		0.000000E+00		0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00		
URDD5		0.000000E+00		0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00		

Another relevant output is the collection of hinge moment derivatives

AEROELASTIC TRIM VARIABLES									
ID		LABEL		TYPE		TRIM STATUS		VALUE OF UX	
		INTERCEPT		RIGID BODY		FIXED		1.000000E+00	
1		TAIL		CONTROL SURFACE		FREE		2.143481E-01	RADIANS
1		ANGLEA		RIGID BODY		FREE		2.262793E-01	RADIANS
2		PITCH		RIGID BODY		FIXED		0.000000E+00	NONDIMEN. RATE
3		URDD3		RIGID BODY		FIXED		1.000000E+00	LOAD FACTOR
4		URDD5		RIGID BODY		FIXED		0.000000E+00	RAD/S/S PER G
CONTROL SURFACE POSITION AND HINGE MOMENT RESULTS									
ACTIVE LIMITS ARE FLAGGED WITH AN (A), VIOLATED LIMITS ARE FLAGGED WITH A (V).									
CONTROL SURFACE		LOWER LIMIT		POSITION VALUE		UPPER LIMIT		HINGE MOMENT VALUE	
TAIL		-1.570796E+00		2.143481E-01		1.570796E+00		4.920446E+03	
						N/A			

The full collection of trim data is provided

A E R O S T A T I C D A T A R E C O V E R Y O U T P U T T A B L E S										
CONFIGURATION = AEROSG2D			XY-SYMMETRY = ASYMMETRIC			XZ-SYMMETRY = SYMMETRIC				
MACH = 2.941200E-01			Q = 6.125000E+03							
CHORD = 1.0000E+00			SPAN = 1.0000E+01			AREA = 1.0000E+01				
TRANSFORMATION FROM REFERENCE TO WIND AXES:										
ANGLE OF ATTACK =			2.262793E-01 RADIANS (12.964851 DEGREES)					
ANGLE OF SIDESLIP =			0.000000E+00 RADIANS (0.000000 DEGREES)					
{ X }		[0.974508		0.000000		0.224353]		{ X }
{ Y }		[0.000000		1.000000		0.000000]		{ Y }
{ Z } WIND =		[-0.224353		0.000000		0.974508]		{ Z } REF

This section determines the rotation matrix from body axes to wind axes, aligned with the asymptotic wind

STRUCTURAL		MONITOR POINT		TOTAL	VEHICLE COEFFICIENTS:								
	AXIS		RIGID AIR	+	RESTRAINED INCR.	-	INERTIAL	+	RIGID-APPLIED	+	RESTRAINED INCR.	=	BALANCE
	----		-----		-----		-----		-----		-----		-----
BODY	CX		0.000000E+00		0.000000E+00		0.000000E+00		0.000000E+00		0.000000E+00		0.000000E+00
WIND	CD		2.012272E-01		0.000000E+00		2.012272E-01		0.000000E+00		0.000000E+00		2.775558E-17
BODY	CY		0.000000E+00		0.000000E+00		0.000000E+00		0.000000E+00		0.000000E+00		0.000000E+00
WIND	CY-WIND		0.000000E+00		0.000000E+00		0.000000E+00		0.000000E+00		0.000000E+00		0.000000E+00
BODY	CZ		8.969213E-01		0.000000E+00		8.969213E-01		0.000000E+00		0.000000E+00		1.110223E-16
WIND	CL		8.740569E-01		0.000000E+00		8.740569E-01		0.000000E+00		0.000000E+00		1.110223E-16
BODY	CMX		1.649093E-01		0.000000E+00		1.857908E-01		0.000000E+00		0.000000E+00		-2.088157E-02
WIND	CM-ROLL		1.607054E-01		0.000000E+00		1.810546E-01		0.000000E+00		0.000000E+00		-2.034925E-02
BODY	CMY		-1.281316E+00		0.000000E+00		-1.281316E+00		0.000000E+00		0.000000E+00		0.000000E+00
WIND	CM-PITCH		-1.281316E+00		0.000000E+00		-1.281316E+00		0.000000E+00		0.000000E+00		0.000000E+00
BODY	CMZ		0.000000E+00		0.000000E+00		0.000000E+00		0.000000E+00		0.000000E+00		0.000000E+00
WIND	CM-YAW		-3.699793E-02		0.000000E+00		-4.168278E-02		0.000000E+00		0.000000E+00		4.684847E-03
AERODYNAMIC		MONITOR POINT		TOTAL	VEHICLE COEFFICIENTS:								
	AXIS		RIGID AIR	+	RESTRAINED INCR.	-	INERTIAL	+	RIGID-APPLIED	+	RESTRAINED INCR.	=	BALANCE
	----		-----		-----		-----		-----		-----		-----
BODY	CX		0.000000E+00		0.000000E+00		N/A		N/A		0.000000E+00		0.000000E+00
WIND	CD		2.012272E-01		0.000000E+00		N/A		N/A		0.000000E+00		2.012272E-01
BODY	CY		0.000000E+00		0.000000E+00		N/A		N/A		0.000000E+00		0.000000E+00
WIND	CY-WIND		0.000000E+00		0.000000E+00		N/A		N/A		0.000000E+00		0.000000E+00
BODY	CZ		8.969213E-01		0.000000E+00		N/A		N/A		0.000000E+00		8.969213E-01
WIND	CL		8.740569E-01		0.000000E+00		N/A		N/A		0.000000E+00		8.740569E-01
BODY	CMX		1.649093E-01		0.000000E+00		N/A		N/A		0.000000E+00		1.649093E-01
WIND	CM-ROLL		1.607054E-01		0.000000E+00		N/A		N/A		0.000000E+00		1.607054E-01
BODY	CMY		-1.281316E+00		0.000000E+00		N/A		N/A		0.000000E+00		-1.281316E+00
WIND	CM-PITCH		-1.281316E+00		0.000000E+00		N/A		N/A		0.000000E+00		-1.281316E+00
BODY	CMZ		0.000000E+00		0.000000E+00		N/A		N/A		0.000000E+00		0.000000E+00
WIND	CM-YAW		-3.699793E-02		0.000000E+00		N/A		N/A		0.000000E+00		-3.699793E-02

???

AEROSTATIC DATA RECOVERY OUTPUT TABLES												
CONFIGURATION = AEROSG2D				XY-SYMMETRY = ASYMMETRIC				XZ-SYMMETRY = SYMMETRIC				
MACH = 2.941200E-01				Q = 6.125000E+03								
CHORD = 1.0000E+00				SPAN = 1.0000E+01				AREA = 1.0000E+01				
AERODYNAMIC PRESSURES ON THE AERODYNAMIC ELEMENTS												
		AERODYNAMIC PRES.				AERODYNAMIC						
GRID	LABEL	COEFFICIENTS				PRESSURES						
1	LS	2.923780E+00				1.790815E+04						
2	LS	1.248628E+00				7.647844E+03						
3	LS	7.470595E-01				4.575739E+03						
4	LS	4.142232E-01				2.537117E+03						
5	LS	2.915091E+00				1.785493E+04						
6	LS	1.244403E+00				7.621971E+03						
7	LS	7.442420E-01				4.558482E+03						
8	LS	4.125138E-01				2.526647E+03						
9	LS	2.896927E+00				1.774368E+04						
10	LS	1.235543E+00				7.567698E+03						
11	LS	7.383217E-01				4.522221E+03						
12	LS	4.089218E-01				2.504646E+03						
13	LS	2.867513E+00				1.756352E+04						
14	LS	1.221107E+00				7.479278E+03						

The pressure is computed in all aerodynamic elements

AEROSTATIC DATA RECOVERY OUTPUT TABLES									
CONFIGURATION = AEROSG2D				XY-SYMMETRY = ASYMMETRIC			XZ-SYMMETRY = SYMMETRIC		
MACH = 2.941200E-01				Q = 6.125000E+03					
CHORD = 1.0000E+00				SPAN = 1.0000E+01			AREA = 1.0000E+01		
AERODYNAMIC FORCES ON THE AERODYNAMIC ELEMENTS									
GROUP	GRID	ID	LABEL	T1	T2	T3	R1	R2	R3
1	1	1	LS	0.000000E+00	0.000000E+00	2.238519E+03	0.000000E+00	1.399074E+02	0.000000E+00
1	2	2	LS	0.000000E+00	0.000000E+00	9.559805E+02	0.000000E+00	5.974878E+01	0.000000E+00
1	3	3	LS	0.000000E+00	0.000000E+00	5.719674E+02	0.000000E+00	3.574796E+01	0.000000E+00
1	4	4	LS	0.000000E+00	0.000000E+00	3.171397E+02	0.000000E+00	1.982123E+01	0.000000E+00
1	5	5	LS	0.000000E+00	0.000000E+00	2.231867E+03	0.000000E+00	1.394917E+02	0.000000E+00

The forces are computed for all aero elements

STRUCTURAL MONITOR POINT INTEGRATED LOADS									
CONFIGURATION = AEROSG2D				XY-SYMMETRY = ASYMMETRIC			XZ-SYMMETRY = SYMMETRIC		
MACH = 2.941200E-01				Q = 6.125000E+03					
CONTROLLER STATE:									
TAIL = 2.1435E-01		ANGLEA = 2.2628E-01		URDD3 = 1.0000E+00					
MONITOR POINT NAME = AEROSG2D				COMPONENT =			CLASS = COEFFICIENT		
LABEL = Full Vehicle Integrated Loads									
CP = 0		X = 0.00000E+00		Y = 0.00000E+00		Z = 0.00000E+00		CD = 0	
AXIS	RIGID AIR	ELASTIC REST.	INERTIAL	RIGID APPLIED	REST. APPLIED				
----	-----	-----	-----	-----	-----				
CX	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00				
CY	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00				
CZ	5.493643E+04	5.493643E+04	5.493643E+04	0.000000E+00	0.000000E+00				
CMX	1.010069E+05	1.010069E+05	1.137969E+05	0.000000E+00	0.000000E+00				
CMY	-7.848062E+04	-7.848062E+04	-7.848062E+04	0.000000E+00	0.000000E+00				
CMZ	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00	0.000000E+00				
1 STATIC_AERO_CLASSIC				**STUDENT EDITION* FEBRUARY 14, 2024 MSC Nastran 3/30/23 PAGE 21					
0									

AERODYNAMIC MONITOR POINT INTEGRATED LOADS									
CONFIGURATION = AEROSG2D				XY-SYMMETRY = ASYMMETRIC			XZ-SYMMETRY = SYMMETRIC		
MACH = 2.941200E-01				Q = 6.125000E+03					
CONTROLLER STATE:									
TAIL = 2.1435E-01		ANGLEA = 2.2628E-01		URDD3 = 1.0000E+00					
MONITOR POINT NAME = AEROSG2D				COMPONENT =			CLASS = COEFFICIENT		
LABEL = Full Vehicle Integrated Loads									
CP = 0		X = 0.00000E+00		Y = 0.00000E+00		Z = 0.00000E+00		CD = 0	
AXIS	RIGID AIR	ELASTIC REST.							
----	-----	-----							
CX	0.000000E+00	0.000000E+00							
CY	0.000000E+00	0.000000E+00							
CZ	5.493643E+04	5.493643E+04							
CMX	1.010069E+05	1.010069E+05							
CMY	-7.848062E+04	-7.848062E+04							
CMZ	0.000000E+00	0.000000E+00							

Computation of integrated loads

DISPLACEMENT VECTOR									
POINT	ID.	TYPE	T1	T2	T3	R1	R2	R3	
	1	G	0.0	0.0	0.0	0.0	0.0	0.0	
	2	G	0.0	0.0	-2.495972E-05	-4.071082E-05	3.029830E-05	0.0	
	3	G	0.0	0.0	-1.008727E-04	-7.849120E-05	5.063143E-05	0.0	
	4	G	0.0	0.0	-2.175911E-04	-1.046171E-04	6.193333E-05	0.0	
	5	G	0.0	0.0	-3.572742E-04	-1.140837E-04	6.476733E-05	0.0	
	6	G	0.0	0.0	-9.810573E-06	-4.071082E-05	3.029830E-05	0.0	
	7	G	0.0	0.0	-7.555699E-05	-7.849120E-05	5.063143E-05	0.0	
	8	G	0.0	0.0	-1.866244E-04	-1.046171E-04	6.193333E-05	0.0	
	9	G	0.0	0.0	-3.248906E-04	-1.140837E-04	6.476733E-05	0.0	
	10	G	0.0	0.0	0.0	0.0	0.0	0.0	
	11	G	0.0	0.0	-4.010887E-05	-4.071082E-05	3.029830E-05	0.0	
	12	G	0.0	0.0	0.0	0.0	0.0	0.0	

Computation of displacements