

Recall: Physical motivation for the "Metric Tensor"

□ In Minkowski space, in inertial and cartesian coordinates:

$$\begin{aligned} \text{[distance } (x, \hat{x}) \text{]}^2 &= -(x^0 - \hat{x}^0)^2 + (x^1 - \hat{x}^1)^2 + (x^2 - \hat{x}^2)^2 + (x^3 - \hat{x}^3)^2 \\ &\quad \text{↑ 4-dim space-time distance!} \\ &\quad \text{↑ indep. of choice of inertial cts.} \\ &= g_{\mu\nu} (x^\mu - \hat{x}^\mu) (x^\nu - \hat{x}^\nu) \\ &\quad \text{with } g_{\mu\nu} = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \end{aligned}$$

□ In Minkowski space, in an arbitrary coordinate system:

$$\begin{aligned} \text{[distance } (x, \hat{x}) \text{]}^2 &= g_{\mu\nu}(x) (x^\mu - \hat{x}^\mu) (x^\nu - \hat{x}^\nu) + O^3 \\ &\quad \text{↑ e.g. polar cts, or accelerated cts} \quad \text{with } g_{\mu\nu}(x) \neq g_{\mu\nu} \quad \text{↑ complicated higher order terms} \end{aligned}$$

□ Generalization to curved space-time, historically:

Allow even such $g_{\mu\nu}(x)$ which in no coordinate system obey:

$$g_{\mu\nu}(x) = \eta_{\mu\nu} \text{ for all } x \in M$$

$\Rightarrow g_{\mu\nu}(x)$ is not simply $\eta_{\mu\nu}$ in noninertial coordinates

\Rightarrow Such $g_{\mu\nu}(x)$ take us beyond special relativity!

□ Enforce Einstein's equivalence principle:

Require $g_{\mu\nu}$ to be such that

Recall equiv. principles (EP):

If freely falling small masses

fall equally \Rightarrow "weak EP"

+ same internal non-grav. physics \Rightarrow "Einst. EP"

+ same internal grav. physics \Rightarrow "strong EP"

for each $x \in M$ there exists a coordinate

system so that at least at x :

$$g_{\mu\nu}(x) = \eta_{\mu\nu} \quad \begin{pmatrix} \text{i.e., locally, special relativity holds} \\ \text{dist}(x, z) = g_{\mu\nu}(x-z)(x-z) + O^3 \\ \text{to lowest noninertial order.} \end{pmatrix}$$

Recall: Math. definition of the metric tensor:

① g is covariant tensor of rank (0,2)

(because η is in special relativity)

$$\text{e.g. } \theta^{\mu}(x) = dx^{\mu}$$

② Thus, if n cotangent vector fields $\theta^{\mu}(x)$ form bases at each point x , then

g is of the form:

$$g(x) = g_{\mu\nu}(x) \theta^{\mu}(x) \otimes \theta^{\nu}(x)$$

[recall: $g_{\mu\nu}(x) = g_{\nu\mu}(x)$ and $g_{\mu\nu}$ is invertible (since nondegenerate)]

③ $g_{\mu\nu}(x)$ invertible \Rightarrow there exists a tensor \tilde{g}' of rank (2,0):

$$\tilde{g}'(x) = g^{\mu\nu}(x) \overset{\text{dual basis}}{\circ} e_{\mu}(x) \otimes e_{\nu}(x) \text{ with } g'^{\mu\nu}(x) g_{\mu\nu}(x) = \delta_g'$$

→ Modern view of the Einsteinian equivalence principle:

Recall: We asked that for each point $p \in M$ there is a coordinate

system so that, when choosing the bases $\{dx^i\}, \{\frac{\partial}{\partial x^i}\}$

then $g(x) = g_{\mu\nu}(x) dx^{\mu} \otimes dx^{\nu}$, $g_{\mu\nu}(x) = g(x) \left(\frac{\partial}{\partial x^{\mu}} \otimes \frac{\partial}{\partial x^{\nu}} \right)$

obeys: $g_{\mu\nu}(p) = \eta_{\mu\nu}$ (in general only at p)

Modern formulation of the Einsteinian equivalence principle:

Independently of any choice of coordinate system:

There are choices of dual bases $\{\theta^{\mu}(x)\}, \{e_{\mu}(x)\}$ of $T_x(M), T_x(M)^*$,

so that: $g_{\mu\nu}(x) = g(e_{\mu}(x), e_{\nu}(x)) = \eta_{\mu\nu} \quad \forall x \in M$

Now, knowing distances through $g_{\mu\nu}$, what else follows?

□ Distances yield volumes, namely $g_{\mu\nu}(x)$ induces an $\Omega(x)$.

□ g, g^* yield duality of covariance and contravariance.

□ g yields "Hodge star" $*: \Lambda_p \rightarrow \Lambda_{n-p}$ duality.

for Riemannian manifolds

□ $*$ yields $(,)$ making the Λ_p Hilbert spaces.

□ g yields co-derivative $\delta: \Lambda_p \rightarrow \Lambda_{p-1}$

□ d, δ yield the Laplacian/d'Alambertian $\Delta: \Lambda_p \rightarrow \Lambda_p$

⇒ We can formulate wave equations on M !

Proposition:

Given a notion of distance, i.e., a metric, g , this also

induces a volume form Ω .

(i.e., a positive $\Omega \in \Lambda_n(M)$, i.e.)
that when integrated over any
portion of M yields a positive number

Namely:

□ Assume, as always, that M is oriented.

□ Consider a positive chart.

(i.e. has positive $\det(\text{Jacobian})$ with given atlas)

Then:

$$\Omega := |\det(g_{ij}(x))|$$

$$\Omega := \sqrt{|g|} dx^1 \wedge dx^2 \wedge \dots \wedge dx^n$$

is a well-defined volume form.

Proof: □ Nonzero for all $p \in M$?

Yes, because g is assumed non-degenerate.

□ Well-defined, i.e., is definition chart-independent?

Yes: To see this, change chart: $x \rightarrow \tilde{x}$

Then:

$$\tilde{g}_{ij}(\tilde{x}(x)) = g_{rs}(x) \frac{\partial x^r}{\partial \tilde{x}^i} \frac{\partial x^s}{\partial \tilde{x}^j} \text{ because covariant}$$

i.e., as matrices:

$$\tilde{g} = \left(\frac{\partial x}{\partial \tilde{x}} \right)^T g \left(\frac{\partial x}{\partial \tilde{x}} \right) \text{ now take determinant:}$$

$$\Rightarrow |\tilde{g}| = \left| \frac{\partial x}{\partial \tilde{x}} \right|^2 |g| \quad \text{i.e. } |\tilde{g}|^{1/2} = \left| \frac{\partial x}{\partial \tilde{x}} \right| |g|^{1/2}$$

$$\text{Also: } d\tilde{x}^1 \wedge \dots \wedge d\tilde{x}^n = \det \left(\frac{\partial \tilde{x}}{\partial x} \right) dx^1 \wedge \dots \wedge dx^n$$

$$\Rightarrow |\tilde{g}|^{1/2} d\tilde{x}^1 \wedge \dots \wedge d\tilde{x}^n = \underbrace{\left| \frac{\partial \tilde{x}}{\partial x} \right|}_{1^n} |g|^{1/2} dx^1 \wedge \dots \wedge dx^n \checkmark$$

Notation: (Ω is an n -form. What are its coefficients, as a covariant $(0,n)$ tensor?)

□ Define:

$$\epsilon_{i_1, \dots, i_n} := \begin{cases} +1 & \text{if } (i_1, \dots, i_n) \text{ is even permutation of } (1, 2, \dots, n) \\ -1 & \text{if } (i_1, \dots, i_n) \text{ is odd permutation of } (1, 2, \dots, n) \\ 0 & \text{else} \end{cases}$$

unlike in SRT, $\epsilon_{...}$ is
not canonical, because
 Ω is: \rightarrow

□ Then, Ω also reads:

$$\Omega = \sqrt{|g|} dx^1 \wedge \dots \wedge dx^n \quad (\text{n-form})$$

$$= \underbrace{\sqrt{|g|} \epsilon_{i_1, \dots, i_n}}_{=: \Omega_{i_1, \dots, i_n}} dx^{i_1} \otimes dx^{i_2} \otimes \dots \otimes dx^{i_n}$$

$$\Omega = \Omega_{i_1, \dots, i_n} dx^{i_1} \otimes \dots \otimes dx^{i_n} \quad (\text{covariant tensor})$$

□ Ω is called the "canonical", or "(pseudo)Riemannian",
or "metric", volume form.

Q: Other use of g ?

A: One needs g to formulate d'Alembertian Δ , or \square , for wave equations.

Why? a) \square should be non-directional 2nd derivative, but $d^2 = 0$.

b) need e.g. $\square: \Lambda^0 \rightarrow \Lambda^0$ for Klein-Gordon, i.e., null degree of forms conserved by \square .

Strategy:

- A) Use g for a covariant \leftrightarrow contravariant tensors relation
- B) Define a map "Hodge *": $\Lambda_r \rightarrow \Lambda_{n-r}$
- C) Define the "Codervative": $\delta: \Lambda_r \rightarrow \Lambda_{r+1}$
- D) Define "Laplacian/d'Alembertian": $\square := d\delta + \delta d$

Then, e.g., the Klein Gordon equation reads:

$$(\square + m^2) \phi = 0$$

A) Covariant \leftrightarrow contravariant tensors equivalence through g :

B $g(x)$ can be used as a map: by evaluation of one tensor factor:

$$\begin{aligned} g(x): T_x(M)' &\rightarrow T_x(M), \\ g(x): \xi^i(x) e_i(x) &\rightarrow g_{\mu\nu}(x) \theta^{\mu}(x) \otimes \theta^{\nu}(x) (\xi^i(x) e_i(x)) \\ &= g_{\mu\nu}(x) \xi^{\mu}(x) \theta^{\nu}(x) \in T_x(M), \end{aligned}$$

\Rightarrow For the coefficient

functions we have: $g: \xi^{\mu}(x) \rightarrow w_{\mu}(x) = g_{\mu\nu} \xi^{\nu}(x)$ (relative to bases θ^i, e_j)

C Conversely, \bar{g}' acts as:

$$\bar{g}'(x): T_x(M) \rightarrow T_x(M)'$$

$$\bar{g}'(x): w_{\mu}(x) \rightarrow \xi^{\mu} = \bar{g}^{\mu\nu}(x) w_{\nu}(x)$$

D In this way, g, \bar{g}' can lower or raise any tensor index, e.g.: $g: t^{ij}_K \rightarrow t_i{}^j{}_K = g_{ik} t^{ij}{}_K$
and: $\bar{g}': t^{ij}{}_K \rightarrow t^{ij}{}_K = g^{jk} t^{ij}{}_K$

B) The Hodge $*$ map: $\Lambda_p \rightarrow \Lambda_{n-p}$

Recall:
 $\dim(\Lambda_p) = \binom{n}{p} = \binom{m}{n-p} = \dim(\Lambda_{n-p})$

Idea: \square each $v \in \Lambda_p$ is a covariant tensor

\square through g it is equivalent to a contravariant tensor \tilde{v}

\square can feed Ω with \tilde{v} to obtain $*v \in \Lambda_{n-p}$.

Concretely:

anything totally antisymmetric

$$\square \text{ Consider any } v := \frac{1}{p!} v_{i_1 \dots i_p} dx^{i_1} \wedge \dots \wedge dx^{i_p} \in \Lambda_p$$

↓
convenient because drops out here
= coefficients as a covariant tensor

$$= v_{i_1 \dots i_p} dx^{i_1} \otimes \dots \otimes dx^{i_p}$$

one could choose other bases.

\square Use g^i to define a contravariant image of v :

$$\tilde{v} = \tilde{v}^{i_1 \dots i_p} \frac{\partial}{\partial x^{i_1}} \otimes \dots \otimes \frac{\partial}{\partial x^{i_p}}$$

$$\text{where } \tilde{v}^{i_1 \dots i_p} := g^{i_1 j_1} g^{i_2 j_2} \dots g^{i_p j_p} v_{j_1 \dots j_p}$$

\square Apply Ω on \tilde{v} :

$$\Omega(\tilde{v}) = \underbrace{\Omega_{i_1 \dots i_p} \tilde{v}^{i_1 \dots i_p}}_{!!} dx^{i_{p+1}} \otimes \dots \otimes dx^{i_n} \in \Lambda_{n-p}$$

$n-p$ factors

\square Define $*v := \Omega(\tilde{v})$, i.e.:

$$*v = (*v)_{i_1 \dots i_{n-p}} dx^{i_1} \otimes \dots \otimes dx^{i_{n-p}}$$

$$*v = \frac{1}{(n-p)!} (*v)_{i_1 \dots i_{n-p}} dx^{i_1} \wedge \dots \wedge dx^{i_{n-p}}$$

Proposition:

Assume $v \in \Lambda_p$. Then

$$**v = (-1)^{p(n-p)+s} v$$

E.g. $s=1$ for space-time

What is s ? The "signature" of g is $\text{sgn}(g) = (r, s)$, where in diagonal form: $g = \begin{pmatrix} 1 & & & \\ & \ddots & & \\ & & r & \\ & & & -1 & \ddots \end{pmatrix}$

Use $*$ to turn $\Lambda(M)$ into an "Inner Product Space":

Definition:

The Hodge $*$ provides a "scalar" (or also called "inner") product for $\Lambda(M)$:

Exercises:

- 1.) Write (α, β) in coordinates
- 2.) Show that (\cdot, \cdot) is always positive definite on Λ_0 , i.e., $(\omega, \omega) > 0 \quad \forall \omega \in \Lambda_0, \omega \neq 0$.

$$(\alpha, \beta) := \int_M \underbrace{\alpha \wedge * \beta}_{\text{p-form}} \quad \begin{matrix} \text{(n-p) form} \\ M \end{matrix}$$

This definition is extended linearly to forms that are lin. comb. of forms of arb. degree, p .

Notes: □ If g is indefinite, then also (\cdot, \cdot) is indefinite.

□ If g is positive definite, i.e., if M is Riemannian, then (\cdot, \cdot) is positive definite and Λ becomes a Hilbert space.

c) (\cdot, \cdot) yields an adjoint for d , the Co-derivative δ :

Recall: For any operator $A: D_A \subset \mathcal{X} \rightarrow \mathcal{X}$ (with D_A dense, i.e., $\overline{D_A} = \mathcal{X}$), its adjoint A^* is defined to have the domain

$$D_{A^*} := \left\{ v \in \mathcal{X} \mid \exists w \in \mathcal{X} \quad \forall z \in D_A: \langle v, Az \rangle = \langle w, z \rangle \right\}$$

and this action: $A^*v := w$. We then have:

$$\langle A^*v, z \rangle = \langle v, Az \rangle \quad \forall z \in D_A, v \in D_{A^*}$$

Definition:

The co-derivative, δ , is the (anti-)adjoint of d with respect to the inner product (\cdot, \cdot) on $\Lambda(M)$:

$$(\delta \alpha, \beta) := -(\alpha, d\beta) \quad \forall \alpha \in D_\delta, \beta \in D_d$$

C) The Codifferential δ explicitly

Clearly: $\delta : \Lambda^r(M) \rightarrow \Lambda^{r+s}(M)$

Proposition: $\delta : \omega \rightarrow (-1)^{np+n+s} * d * \omega$ (Some authors define
 δ as the negative of this)

Properties: $\square \quad \delta^2 = 0$

\square In coordinates:

$$(\delta \omega)^{i_1 \dots i_{p+1}} = \frac{1}{\sqrt{|g|}} \left(T_g \omega^{k \dots i_{p+1}} \right)_{,k}$$

\square If M is contractible (and in every contractible part):

$$\delta \omega = 0 \Rightarrow \exists \omega : \omega = \delta \omega$$

Exercises: \square Show the above.

\square Determine whether or not δ is a derivation.

Use d and δ to obtain the Maxwell equations on M

\square Define:

"Field strength": $F_{\mu\nu}(x) := \begin{pmatrix} 0, -E_1, -E_2, -E_3 \\ E_1, 0, B_3, -B_2 \\ E_2, -B_3, 0, B_1 \\ E_3, B_2, -B_1, 0 \end{pmatrix}$, $\overset{\text{electric field}}{\nwarrow}$

$\overset{\text{"Field strength" 2-form}}{\longleftarrow}$

$\overset{\text{magn. field}}{\swarrow}$

"Current" 3-form $\rightarrow j(x) := \frac{1}{3!} \epsilon_{\mu\nu\lambda\sigma} j^\mu dx^\nu \wedge dx^\lambda \wedge dx^\sigma$

$\overset{\text{"current 4-vector" }}{\swarrow}$

\square Then: The Maxwell Eqns read:

"Homogeneous
Maxwell equations"
(indep. of metric)

$dF = 0, \delta F = * j$

"Inhomogeneous
Maxwell equations"
(dependent on the metric)

\sim Current 1-form, i.e., cotangent vector field

Remarks:

□ F is assumed to be an exact 2-form, i.e.,:

$$F = dA$$

(the 1-form A is called the 4-potential)

□ This already implies the homogeneous Maxwell equations:

$$dF = d^2A = 0 !$$

→ One calls them "structure equations".

□ General relativity also possesses structure equations.

Remark:

The gauge principle of electrodynamics is the observation that, for any $w \in \Lambda_0$:

$$A \text{ and } \tilde{A} := A + dw$$

describe the same physics.

The Aharonov - Bohm effect and topological phases in general, can make A itself visible when Poincaré lemma doesn't apply.

They do because the (classically) observable fields are only the E and B fields in F and since $d^2 = 0$:

observable
 E and B fields

$$F = dA = d\tilde{A}$$

D The Laplacian/d'Alembertian, Δ , \square :

□ Definition of the Laplacian:

$$\Delta := \delta d + d\delta$$

Some authors define
 Δ as the negative of this
and let δ be the adjoint of d .

□ Clear: $\Delta : \Lambda^p(M) \rightarrow \Lambda^p(M)$

□ If signature $s=1$: Then also called d'Alembertian
and denoted $\square := d\delta + \delta d$.

□ Action on, e.g., $f \in \Lambda_0(M)$ in a chart: Exercise: verify

$$\square f = \frac{1}{\sqrt{|g|}} \left(\sqrt{|g|} g^{rr} f_{rr} \right)_r \quad \left(= \left(-\frac{\partial^2}{\partial x^1 \partial x^1} + \frac{\partial^2}{\partial x^2 \partial x^2} + \frac{\partial^2}{\partial x^3 \partial x^3} + \frac{\partial^2}{\partial x^4 \partial x^4} \right) f \right)$$

if $g = \gamma$

Properties of the d'Alembertian, \square , in the Hilbert space $\Lambda(M)$: if Λ is a Hilbert space

* Defined: $\square : \Lambda_r(M) \rightarrow \Lambda_r(M)$

$$\square : \mathcal{D} \rightarrow (\delta d + d\delta) \mathcal{D}$$

* In the Hilbert space $\Lambda(M)$:

$$\square = \delta d + d\delta \text{ always } (\alpha, \square \beta) = (\square \alpha, \beta)$$

* \square is self-adjoint, $\square = \square^*$, for suitable boundary conditions, or if $\partial M = \emptyset$,
and assuming $(,)$ is positive definite.

* Exercises: □ Verify $\square = \square^*$ formally, using only $\delta = -d^*$.

□ Verify that $\square \ast = \ast \square$, $\square d = d \square$, $\square \delta = \delta \square$.

Consequences of the self-adjointness of Δ : - if \mathcal{H} is a Hilbert space

A) The operators Δ and \square can be diagonalized, with real spectrum.

B) For Riemannian manifolds, $\text{spec}(\Delta) \subset [0, \infty)$.

C) For compact Riem. manifolds (of finite volume): $\text{spec}(\Delta)$ is discrete.

D) Then, $\text{spec}(\Delta)$ is carrying a lot of information about (M, g) !
 Still the finite volume Riemannian case.

Remark: There exists a related mathematical discipline, called "Spectral Geometry", combining differential geometry with functional analysis, i.e., the languages of general relativity and quantum theory!

Application: Klein-Gordon "action":

$$g^{\mu\nu} e_\mu \otimes e_\nu (\overset{\epsilon T^2}{\phi_{,\mu} \theta^\mu} \otimes \overset{\epsilon T_1}{\phi_{,\nu} \theta^\nu})$$

$$S[\phi] := \frac{1}{2} \int_M g^{\mu\nu} \overset{\uparrow \text{Klein-Gordon field } \phi \in \mathcal{F}(M)}{\phi_{,\mu} \phi_{,\nu}} \Omega \quad \left(\begin{array}{l} \text{Recall special relativity:} \\ S[\phi] = \int_{\mathbb{R}^4} \eta^{\mu\nu} \phi_{,\mu} \phi_{,\nu} d^4x \end{array} \right)$$

$$= \frac{1}{2} \int_M g^{\mu\nu}(x) \left(\frac{\partial}{\partial x^\mu} \phi \right) \left(\frac{\partial}{\partial x^\nu} \phi \right) \sqrt{|g(x)|} d^m x$$

next: integrate by parts!

$$= \frac{1}{2} \int_M -\phi \underbrace{\frac{\partial}{\partial x^\nu} \left(\sqrt{|g|} g^{\mu\nu} \frac{\partial}{\partial x^\mu} \phi \right)}_{= \square \phi} \frac{1}{\sqrt{|g|}} \underbrace{\sqrt{|g|} d^m x}_{= \Omega}$$

$$= -\frac{1}{2} \int_M \phi (\square \phi) \Omega$$

Obtain the Klein Gordon wave equation:

□ Recall: Euler Lagrange equation $\frac{\partial \mathcal{L}}{\partial \phi} = \frac{\partial}{\partial x^\mu} \frac{\partial \mathcal{L}}{\partial \dot{\phi}_\mu}$

□ Here: $\mathcal{L} = -\frac{1}{2} \phi \square \phi$ (the 0-form that we are integrating: $S' = \int_m \mathcal{L} \Omega$)

□ Obtain Klein Gordon equation:

$$\square \phi = 0 \quad \left(\begin{array}{l} \text{with "mass": } \mathcal{L} = -\frac{1}{2} \phi (\square + m^2) \phi \\ \text{yielding } (\square + m^2) \phi = 0 \end{array} \right)$$

Q: Which physical fields are described by K-G fields?

A: □ Meson fields

↓ there are many sorts of mesons. Most important mesons: "Pions". They transmit the nuclear force among protons & neutrons

□ Higgs field (gives all particles their mass. Found at LHC. Nobel to Higgs, Englert (Brout), mid 2013)

□ Inflaton field (crucial ingredient in modern cosmology → see later)