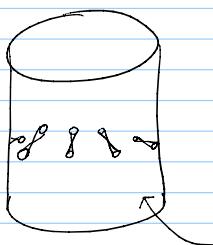


Causal Structure & "Singularities"Definition:

We say that (M, g) is time-orientable if at each point $p \in M$ we can separate the non-spacelike vectors

$$\xi \in T_p(M), g(\xi, \xi) \leq 0$$



into two classes, which will be called future-directed and past-directed so that this separation is continuous in M .

Consider e.g. such a spacetime, which is the outside of a cylinder.

If the metric has the drawn light cones, M is not (continuously) time-orientable.

Lemma:

If (M, g) is time-orientable, then there

exist smooth nonvanishing timelike vector fields, v , on M .

Note:

If such a v is given, we can define at each $p \in M$ the future-directed vectors ξ as those non-spacelike vectors for which $g(v, \xi) > 0$, i.e. the past-directed non-spacelike ξ obey $g(v, \xi) < 0$. (Alternatively the "future" and "past" designations can be globally swapped.)

Why? Consider basis in $T_p(M)$ so that $g_{vv} = g_{uu}$ and $v = \begin{pmatrix} v_0 \\ 0 \end{pmatrix}$. Then $g(v, \xi) = -v_0 \xi_0$, i.e. "sign" of ξ is well-defined relative to v .

Assumption: We will henceforth only consider time-orientable space-times, and we will always assume a time orientation has been chosen.

Time-like curves

Definition: A curve (or "path") $\gamma: \mathbb{R} \rightarrow M$ is called a

"future-directed timelike curve"

Note: there is no restriction to geodesics. These are all paths that material objects can travel, given suitable engine or outside forces.

if each $\dot{\gamma}(t) \in T_{\gamma(t)}(M)$ is a future-directed timelike vector.

Note: Here $\dot{\gamma}(t)=0$ is not allowed because timelikeness requires $g(\dot{\gamma}, \dot{\gamma}) < 0$.

Definition: A curve (or "path") $\gamma: \mathbb{R} \rightarrow M$ is called a

"future-directed causal curve"

Note: These are all paths that matter or massless particles (light, gluons etc.) can travel.

if each $\dot{\gamma}(t) \in T_{\gamma(t)}(M)$ is a future-directed non-spacelike vector.

Note: Here, $\dot{\gamma}(t)=0$ is allowed because non-spacelikeness merely requires $g(\dot{\gamma}, \dot{\gamma}) \leq 0$.

Definition:

Past-directed timelike or causal curves are defined analogously.

The past & future of an event

Definition:

The "chronological future" of a $p \in M$ is the set

$$I^+(p)$$

Mnemonic help:
 $I^+(p)$ is the set
of events an actual
chronometer could
reach from p .

of events that can be reached from p on
a future-directed timelike curve.

Note: $I^+(p)$ is always an open subset of M (because
if γ is a timelike future-directed curve from p then
any sufficiently small perturbation of γ is
also a timelike future-directed curve starting from p .)

We will assume
that there are no
closed timelike curves.
For travellers on such
curves, life would repeat
itself but we know that
everybody ages, so it can't.
I.e. on such spacetimes
there'd be no thermodynamic
arrow of time in whose
direction entropy increases.

Note: Since $j = 0$ is excluded we have

$$p \notin I^+(p)$$

→ except if there is a closed timelike
curve through p .

Definition:

The "causal future" of a $p \in M$
is the set

$$J^+(p)$$

In $J^+(p)$ is any event that
could be causally affected
by what happened at p .

of events that can be reached from p on
a future-directed causal curve.

Note: Clearly, we always have $p \in J^+(p)$ because $j_i = 0$ is allowed.

Definitions:

□ Analogously, one defines the chronological past $I^-(p)$ and the causal past $J^-(p)$.

□ One defines the pasts and futures of a set S of events through:

$$I^\pm(S) := \bigcup_{p \in S} I^\pm(p), \quad J^\pm(S) := \bigcup_{p \in S} J^\pm(p)$$

□ Their boundaries are denoted: $\underline{I}^\pm(S), \underline{J}^\pm(S)$

Example: Assume $S := \{\text{events travelled by immortal observer}\}$
Then $\underline{J}^-(S) = \underline{\text{event horizon}}$ of this observer.

Relation to geodesics:

□ The above definitions do not refer to geodesics.

□ For Minkowski space, clear:

$I^+(p)$ = set of events reachable by future-directed timelike geodesics from p .

$\dot{I}^+(p)$ = set of events reachable by future-directed null geodesics from p .

But this is not true in general spacetimes!

Intuition: E.g. singularities can be in the way of a geodesic.

□ But locally, the situation is as for Minkowski space:

Theorem:

Assume $p \in M$ and $U \subset M$ is

a convex normal neighborhood of p .

(Any 2 pts in U are connected by a unique geodesic.)

Then: a) $I^+(p)|_U =$ set of events reachable by future-

(means "restricted to") directed timelike geodesics from p .

b) $\dot{I}^+(p)|_U =$ set of events reachable by future-directed null geodesics from p .

c) If $q \in J^+(p) - I^+(p)$ then any causal curve between p and q is a null geodesic.

Recall:

□ The "chronological future" of a set S is the set $I^+(S)$

of events that can be reached from S on a future-directed timelike curve.

□ The "causal future" of a set S

is the set $J^+(S)$

recall: includes null curves.

of events that can be reached from S on a future-directed causal curve.

□ In Minkowski space: $J^+(S) = I^+(S) \cup \dot{I}^+(S)$

Recall: $\dot{I}^+(S)$ is the boundary of $I^+(S)$

Properties of $I^+(S)$, in general?

□ Definition:

A subset $Q \subset M$ is called

"achronal"

if no two points in Q can be connected by a future-directed time-like curve, i.e., by a curve that, e.g., a clock (with mass) could travel. Thus, $Q \subset M$

is achronal iff:

$$I^+(Q) \cap Q = \emptyset$$

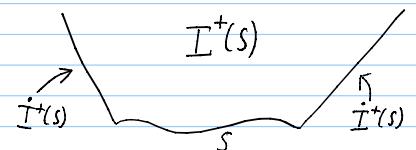
empty set

□ Theorem:

For all $S \subset M$, the set

$$\dot{I}^+(S)$$

(if not empty) is an achronal 3-dimensional submanifold of M .



□ Example: In Minkowski space, if S is a point p , then $I^+(p)$ is the boundary of the light cone.

Indeed, no two points of the boundary of the light cone are connected by time-like paths.

□ In general spacetimes, however:

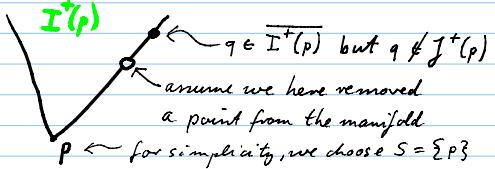
It is clear that

$$\overline{J^+(S)} = \overline{I^+(S)} \quad \text{← bar denotes closure of the set}$$

but we notice that, generally:

$$J^+(S) \neq \overline{I^+(S)}$$

□ Example:



⇒ here, $q \in \overline{I^+(p)}$, but $q \notin J^+(p)$ because there is no nonspacelike curve between p and q .

↔ Idea:

Let us use the extendibility or nonextendibility of curves (or especially of geodesics) as indicator for the absence or existence of a singularity.

Definition:

□ We say that a point $p \in M$ is future (past) end point of a curve γ if

\forall neighborhoods U of p there exists a $t_0 \in \mathbb{R}$ so that

$$\gamma(t) \in U \quad \forall t > t_0 \quad \left(t < t_0 \text{ for past end point} \right)$$

□ Note: p need not be reached by γ !

and every point $p \in M$ is
an element of open sets \mathcal{U}_M .

Since $p \in M$, it is always possible to extend
a curve γ continuously beyond p . Note: $p \in M$!

\Rightarrow The existence of an endpoint here indicates not
a singularity, or 'hole' in the manifold, but merely that we chose to
end the curve before it is necessary!

Definition:

□ We say that a curve γ is future (past)
inextendible if it does not possess a future (past) endpoint.

□ Intuition: If γ future inextendible, then:

a.) γ runs to ∞ , or

b.) γ runs around forever, or

c.) γ hits a hole, i.e., singularity, thus can't
be continuously extended:



Theorem:

Assume $\mathcal{G} \subset M$ is closed and assume:

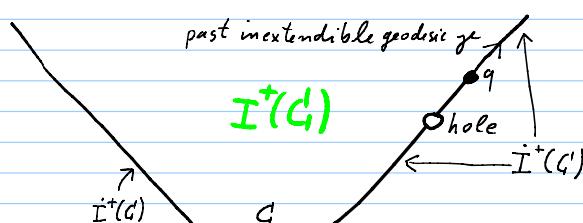
$$q \in I^+(G), q \notin G$$

Then, q lies on a null geodesic γ inside $I^+(G)$
and the curve γ either:

a.) has past endpoint on G

or b.) is past inextendible (because meets hole)

Example for b.:

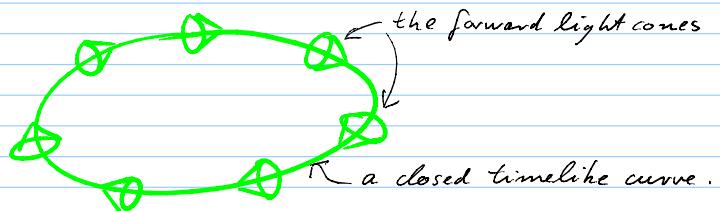


Strategy:

- Study inextensible curves!
- This includes these cases:
 - a.) γ hits singularity - will be main interest!
 - b.) γ running off to ∞ .
 - c.) γ going round and round forever.

→ Must address potential causality problems of case c)

Example:



Note: This is not a problem with time-orientability here!