

Data Science - Module 5

Machine Learning Computer Vision in Python

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Lecture / Lab Outline

- Working with images
- Transformations on images
- Basic filters / edge detection with Python
- Torchvision package
- Convolutional Neural Networks



What is an image

- An image is a grid (matrix) of pixels
- Consider gray-scale images
- Each pixel has an intensity value (0-255, 0-1)
 - Large values → “brightness” (white)
 - Small values → darkness (black)
- Size of matrix is Width x Height
- Each pixel can be considered as a feature
- Very large dimensional space for most of the images



Multi channels images

- A channel is a single matrix of pixel intensities
- You can combine multiple channels to get a colored image
- Standard RGB images are obtained by combining three matrices
 - Red ($W \times H$) (0-1, 0-255)
 - Green ($W \times H$) (0-1, 0-255)
 - Blue ($W \times H$) (0-1, 0-255)
- Even more features! Size: $W \times H \times C$ or $C \times W \times H$
- An additional channel (alpha channel) is often added to manage transparency of each pixel.





Color spaces

- Gray, RGB, BGR, HSV... (many, many others)
- Each color space determines the final color based on the combination of its components
 - RGB → specify brightness for each base color
 - HSV → specify hue, saturation and brightness (value)
 - <http://colorizer.org/>
- Different color spaces suits different needs. You can use standard RGB if you are unsure.



Color histogram

- Describe content of image based on color(s) distribution
- For each channel, plot histogram of intensities
- Useful to roughly compare images

1D Convolutions

- Time series I , filter/kernel F
- I longer than F
- 1D convolution (flip kernel)

$$(I * F)(t) = \int_{-\infty}^{\infty} I(\tau)F(t - \tau)d\tau$$

- Cross-correlation is very similar, but filter is not flipped

2D convolutions

- Image I, filter/kernel F. Both are 2D matrices.
- I larger than F
- Filter = $\begin{bmatrix} 0 & 1 & 2 \\ 2 & 2 & 0 \\ 0 & 1 & 2 \end{bmatrix}$
- To flip or not to flip?
 - Assume already flipped
 - Otherwise, call it cross-correlation

Input Image

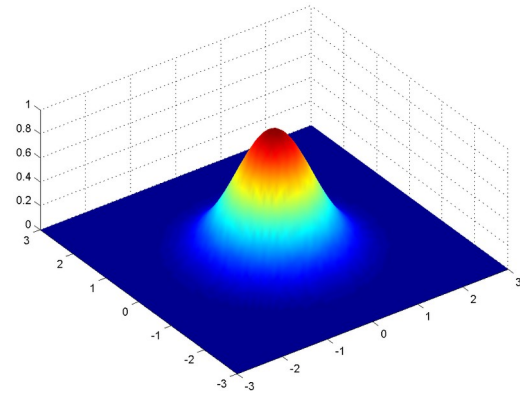
3_0	3_1	2_2	1	0
0_2	0_2	1_0	3	1
3_0	1_1	2_2	2	3
2	0	0	2	2
2	0	0	0	1

Output

12.0	12.0	17.0
10.0	17.0	19.0
9.0	6.0	14.0

Smoothing

- Let's use convolutions!
- Smoothing / Blurring an image
- Need convolution with a special filter
 - Gaussian filter of fixed size $\exp\left(-\frac{H^2 + W^2}{2\sigma^2}\right)$
 - There are many other choices depending on what you want to filter out
- Standard deviation defines the “aperture” of the filter



https://commons.wikimedia.org/wiki/File:Gaussian_2d.png

Edge detection

- What is an edge?
 - A region (actually, more a line) in which color intensity drastically changes
- How can we identify that? Gradients!
- Prewitt operator → two matrices, representing finite difference method on horizontal and vertical direction
- Sobel extend Prewitt by adding “focus” on the central difference

$$G_x = \begin{bmatrix} +1 & 0 & -1 \\ +2 & 0 & -2 \\ +1 & 0 & -1 \end{bmatrix}$$

$$G_y = \begin{bmatrix} +1 & +2 & +1 \\ 0 & 0 & 0 \\ -1 & -2 & -1 \end{bmatrix}$$

$$G_x = I(x+1, y) - I(x-1, y)$$



Image segmentation

- Group together pixels, hopefully discovering semantically relevant regions
- Mmmm... sounds a lot like clustering
- Try out K-Means on an image
- Get clusters as result
- Plot the image by coloring pixels belonging to the same cluster with the same color
- It helps to provide additional features (like positional information about pixel) and to choose an appropriate color space
 - Random link: https://en.wikipedia.org/wiki/CIELAB_color_space

Superpixels

- Merge together similar pixels
- Can greatly simplify feature space
- Remove redundant information
- Do not need any task-specific information



<https://i.stack.imgur.com/XjYuD.jpg>



Applications of Computer Vision

- Image classification → classify the entire image
- Object recognition → classification of (possibly multiple) objects
- Object detection → bounding boxes + classification
- Image segmentation → assign each pixel to a “cluster”



TorchVision: PyTorch for Images

- Tightly associated to Pytorch → ML/DL oriented
- You won't find a lot of functions which are in OpenCV
- You will find a lot of functions to manage images with neural networks
- You will find datasets → download, data loading, batching, shuffling... automatically managed.



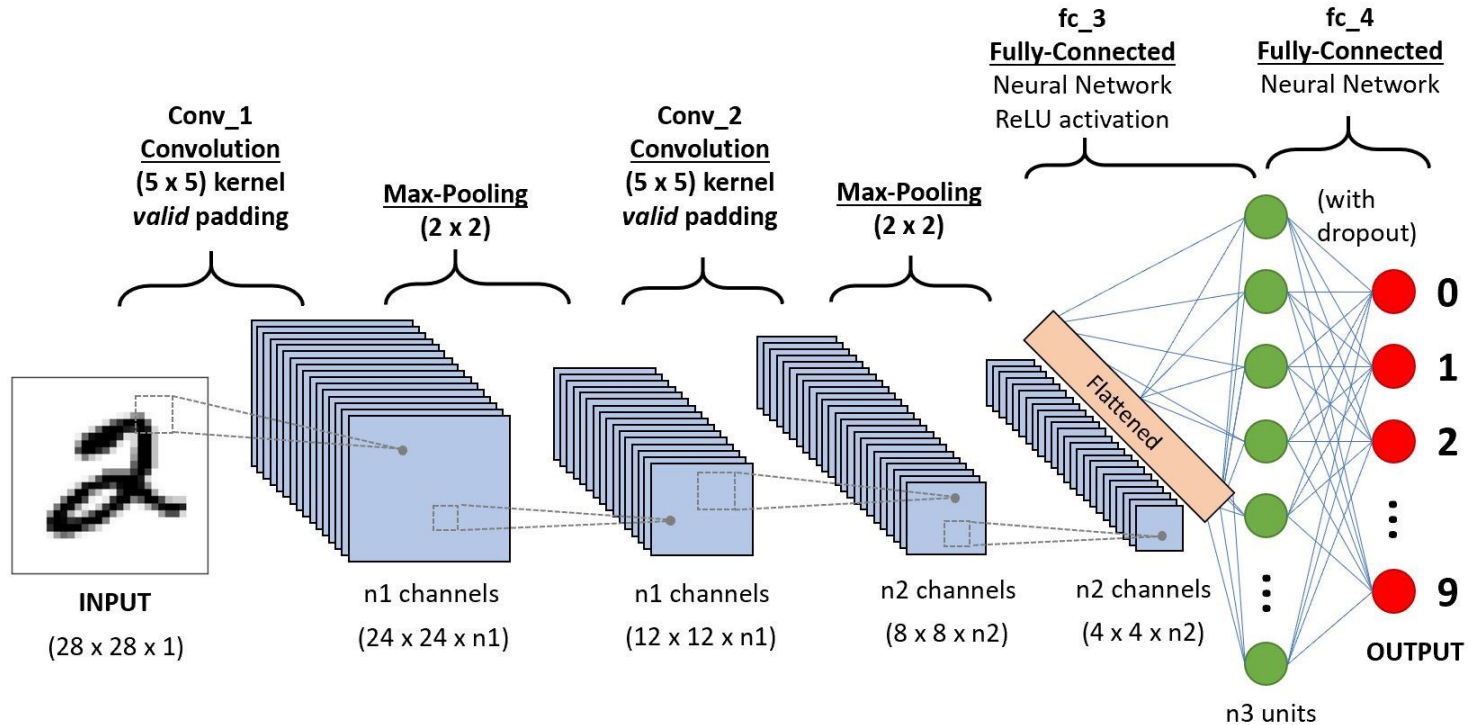
How to manage images with neural networks?

- Feedforward networks: MLP
 - Flatten image, each pixel is a feature
 - Large input layer
 - Very expensive in the #parameters
- Convolutional Neural Networks: CNN
 - Inductive bias: spatial locality → exploit the fact that we are dealing with images
 - Shared parameters → same adapted filter, applied over image
 - End-to-End: backprop + gradient descent

Convolutional Neural Networks (CNNs)

- Convolutions → we have already seen them
 - In CNN, the parameters are the kernel values (initialized randomly)
 - Padding: add zero to the border of the image s.t. image size stays the same (same padding). Valid padding is sometimes used to indicate no padding
 - Stride: how many pixels to skip when sliding the kernel over the image
- Pooling → ensure invariance to small rotation / translations
 - Use a kernel which takes the maximum of the values in the current region of the image
→ downsizing image
- CNN = consecutive block of conv + relu + pooling
- At the end, flatten result + MLP to classify

CNN structure





Implement a CNN vs. use a CNN

- CNN architecture is complex, there exist many different ones and it is not obvious how to build them
- Images are not simple datasets → needs lots of patterns to train a CNN on reasonably complex tasks
- Implement a CNN from scratch → only if you cannot do otherwise
- Use a *pretrained* CNN and *finetune it*:
 - CNN trained on a large corpus of images (e.g. ImageNet)
 - Remove the MLP component
 - Add your MLP and train it end-to-end (slower learning rate for the convolution kernels) on your custom, smaller dataset. Most of the capabilities you need are already in the CNN!