

Catastrophic Forgetting in Deep Graph Networks: an Introductory Benchmark for Graph Classification



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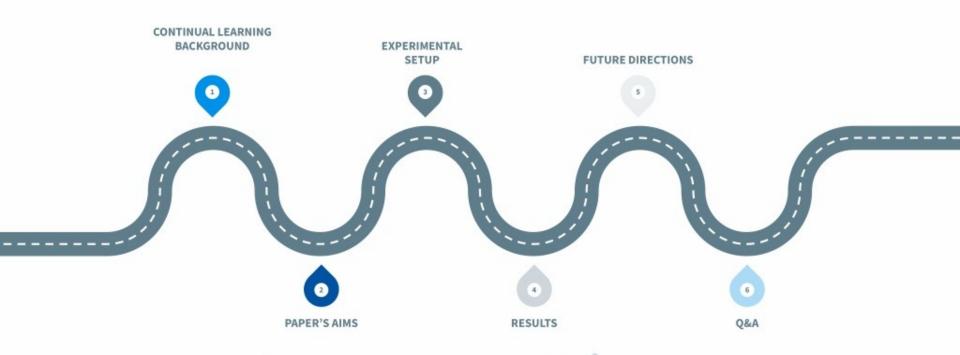
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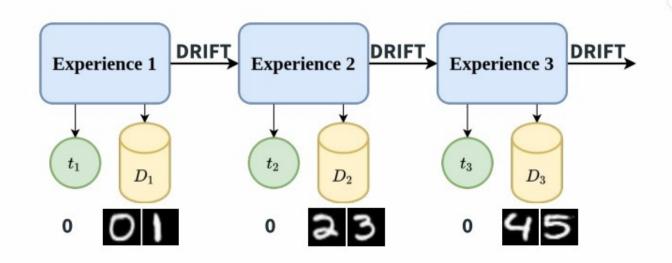
Outline











WE STUDIED CATASTROPHIC FORGETTING

Why bothering?

Training on the entire data may even lead to superior results! However...

- 0 Datasets may be huge → no training on the edge •
- 0 New data after deployment → retraining
 - Expensive 😔
 - Inefficient → most of the information is already in the model •





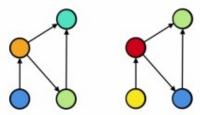




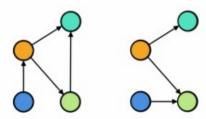
Paper's Aim (1)

Does CL work on graphs?

- Graph distribution drift
- GRL regularization strategies?
- Graph classification



node distribution drift



neighborhood distribution drift



Paper's Aim (2)

Reproducible Research + Framework

- Foster future research
- Avoid common mistakes
- Handle boilerplate code



https://github.com/diningphil/continual learning for graphs



CL + GRL techniques

Elastic Weight Consolidation (EWC)
$$\longrightarrow \mathcal{R}(\Theta, \Omega) = \lambda \sum_{i=1}^{n-1} \Omega_i \|\Theta_i - \Theta_n\|_2^2$$

$$\rightarrow \mathcal{R}(\Theta_{n}, \Theta_{n-1}; \mathbf{x}, \mathbf{y}) = \alpha \text{ KL}[p_{\Theta_{n}}(\mathbf{y}|\mathbf{x}) \mid\mid p_{\Theta_{n-1}}(\mathbf{y}|\mathbf{x})]$$

$$p\left(\mathbf{A} \mid \mathbf{Z}\right) = \prod_{i=1}^{N} \prod_{j=1}^{N} p\left(A_{ij} \mid \mathbf{z}_{i}, \mathbf{z}_{j}\right)$$
 with $p\left(A_{ij} = 1 \mid \mathbf{z}_{i}, \mathbf{z}_{j}\right) = \sigma(\mathbf{z}_{i}^{\top} \mathbf{z}_{j})$ [Ref. 3

Replay Memory

Naive Strategy

Which Models?

A DICAL AND STATES

Structure-agnostic Baseline

- Impact of structure in CL
- MLP + Mean Global Pooling

Generic and simple DGN

- Based on GraphSAGE
- Mean aggregator & Global Pooling

$$\mathbf{h}_{v} = \psi(\mathbf{x}_{v}), \quad x_{v} \in \mathcal{X}_{g},$$

$$\psi(x_{v}) = \mathbf{W}_{L}^{T}(\sigma(\dots(\sigma(\mathbf{W}_{1}^{T}x_{v} + \mathbf{b}_{1})\dots) + \mathbf{b}_{L}))$$

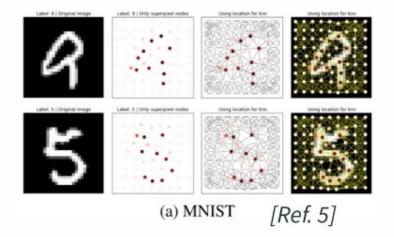
$$\mathbf{h}_{g} = \Psi_{g}(\{\mathbf{h}_{v} \mid v \in \mathcal{V}_{g}\})$$

$$\left[\mathbf{h}_v^{\ell+1} = \phi^{\ell+1} \left(\mathbf{h}_v^{\ell}, \ \Psi_n(\{\psi^{\ell+1}(\mathbf{h}_u^{\ell}) \mid u \in \mathcal{N}_v\})\right)\right]$$

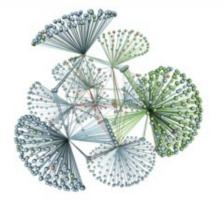
$$\mathbf{h}_g = \Psi_g \Big(\{ \mathbf{h}_v \mid v \in \mathcal{V}_g \} \Big)$$

MLP GRAPH CONVOLUTION(S) GLOBAL POOLING

Datasets



CIFAR10 (same preprocessing of MNIST)



OGBG-PPA



- Class-incremental Scenario
- Monitor ACC = $\frac{1}{T} \sum_{t=1}^{T} R_{T,t}$
- Hold-out + Hyper-param optimization for all models

	MNIST	CIFAR10	OGBG-PPA
Size	70000	60000	158100
Node Attrs.	3	5	0
Edge Attrs.	0	0	7
Classes	10	10	37
Avg $ V_q $	70,57	117,63	243,4
Avg $ \mathcal{E}_q $	564,63	941,07	2266,1
Data Split	55K/5K/15K	45K/5K/15K	49%/29%/22%
Class Split	2+2+2+2+2	2+2+2+2+2	17+5+5+5+5



Results

Baseline: Competitive!



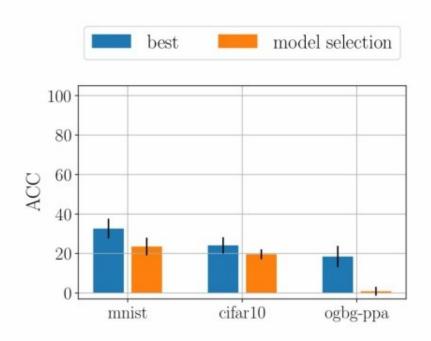
Are DGNs ignoring the structure?

	Model	Strategy			
	Model	Naïve	EWC	Replay	LWF
MNIST	Baseline	$19.56_{\pm0.1}$	19.39 _{±0.1}	86.13 _{±4.5}	33.16 _{±13.1}
	DGN	$19.19_{\pm 0.1}$	$18.95_{\pm0.3}$	$79.52_{\pm 1.9}$	$32.64_{\pm 5.0}$
	DGN+reg	$19.31_{\pm 0.1}$	-	81.42 _{±2.4}	-
CIFAR10	Baseline	17.49 _{±0.1}	17.49 _{±0.1}	42.87 _{±3.7}	26.77 _{±5.1}
	DGN	$17.11_{\pm 0.2}$	$17.10_{\pm0.2}$	$39.55_{\pm 2.3}$	$24.13_{\pm 4.1}$
	DGN+reg	$17.13_{\pm0.1}$	-	46.61 _{±3.5}	-
OGBG-PPA	Baseline	14.53 _{±0.5}	13.90 _{±0.8}	55.96 _{±3.0}	20.83 _{±6.1}
	DGN	$14.47_{\pm0.3}$	$14.15_{\pm 0.5}$	$56.34_{\pm 2.5}$	18.46 _{±5.4}
	DGN+reg	$15.18_{\pm0.8}$	-	57.27 _{±3.2}	_

Table 2: Mean accuracy and mean standard deviation (in parenthesis) among all steps. Replay results are related to memory size of 1000. Results are averaged over 5 final runs. We treat the regularization loss as a separate strategy.







The road ahead

- Better understand the role of graph distribution drift on forgetting
 - Design ad-hoc regularization
- Need more benchmarks!
- Study node classification and other tasks



References



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Questions? Thank you!

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