Sistemi Operativi I

Corso di Laurea in Informatica 2022-2023



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- We introduce many concepts associated with multi-threaded computer systems
- We look at a number of issues related to multi-threaded programming and its effect on the design of operating systems

Threads: Overview

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- Traditional (heavyweight) processes have a single thread of control
 - There is only one program counter, and one sequence of instructions that can be carried out at any given time
- Multi-threaded applications have multiple threads within a single process, each having their own program counter, stack, and set of registers
 - But sharing common code, data, and certain structures, such as open files

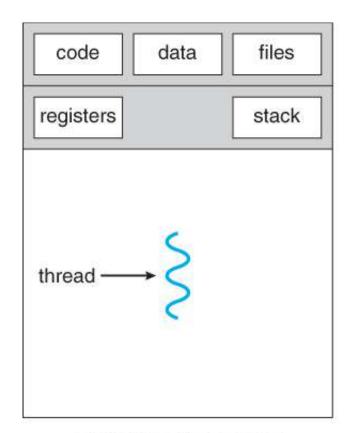
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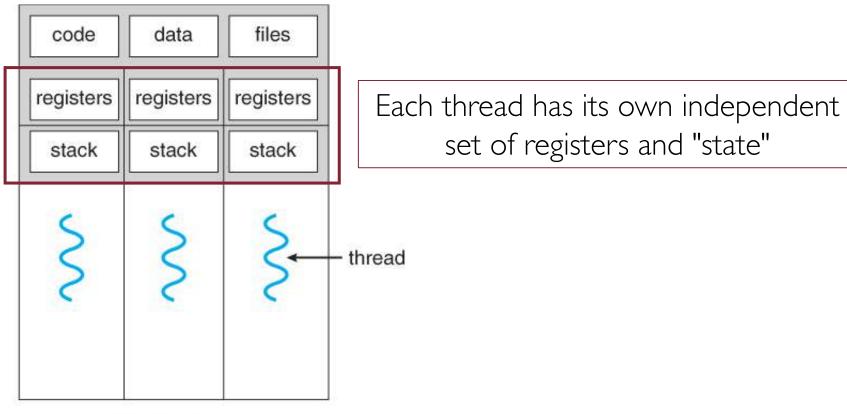
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- A thread defines a single sequential execution stream within a process (i.e., program counter, stack, registers)
- A thread is bound to a specific process
- Each process may have several threads of control within it
 - The process' address space is shared among all its threads
 - No system calls are required for threads to cooperate with each other
 - Simpler than message passing and shared memory

Single- vs. Multi-Threaded Process



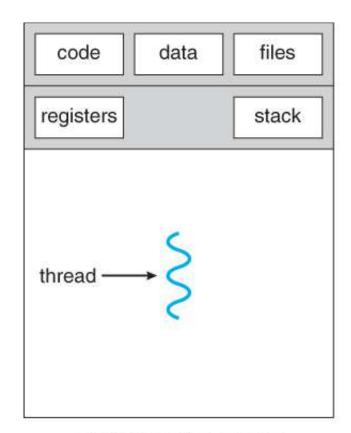




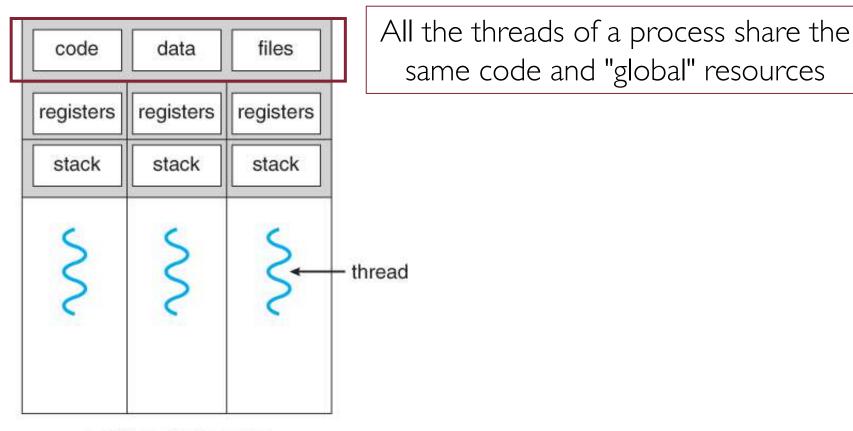
set of registers and "state"

multithreaded process

Single- vs. Multi-Threaded Process

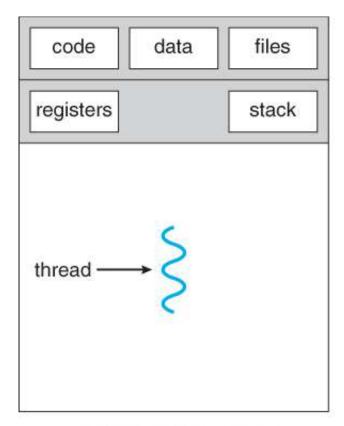


single-threaded process

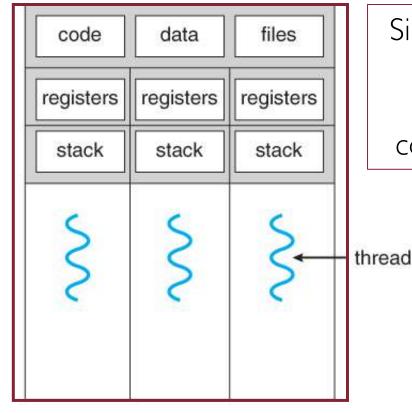


multithreaded process

Single- vs. Multi-Threaded Process







Since all the threads live in the same address space, communication between them is easier than communication between processes

multithreaded process

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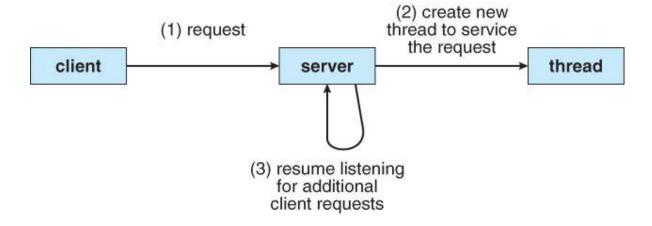
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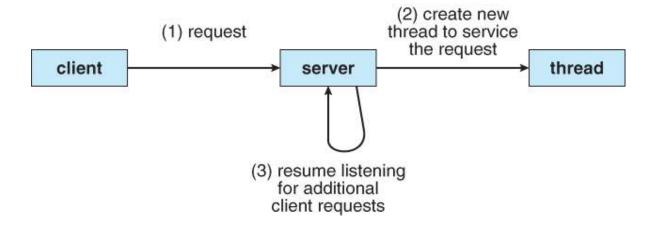
Example: word processor

• a thread may check spelling and grammar while another thread handles user input (keystrokes), and a third does periodic backups of the file being edited

Multi-threaded Web Server

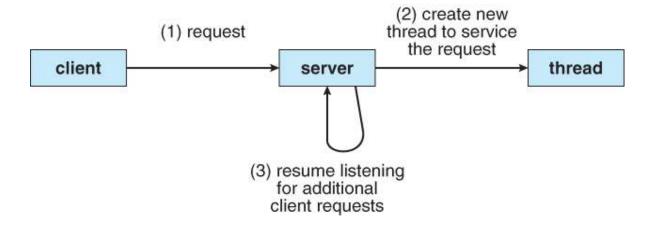


Multi-threaded Web Server



Multiple threads allow for multiple requests to be satisfied simultaneously, without having to serve requests sequentially or to fork off separate processes for every incoming request

Multi-threaded Web Server



What if the server process spawns off a new process for each incoming request rather than a thread?

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- There are at least 2 reasons why this is not the best choice:
 - Inter-thread communication is significantly quicker than inter-process one
 - Context-switches between threads is a lot faster than between processes

- 4 main benefits:
 - Responsiveness → one thread may provide rapid response while other threads are blocked or slowed down doing intensive computations

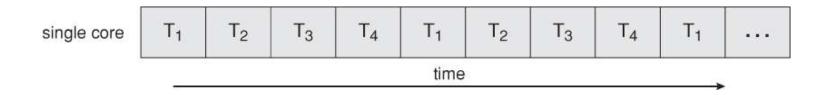
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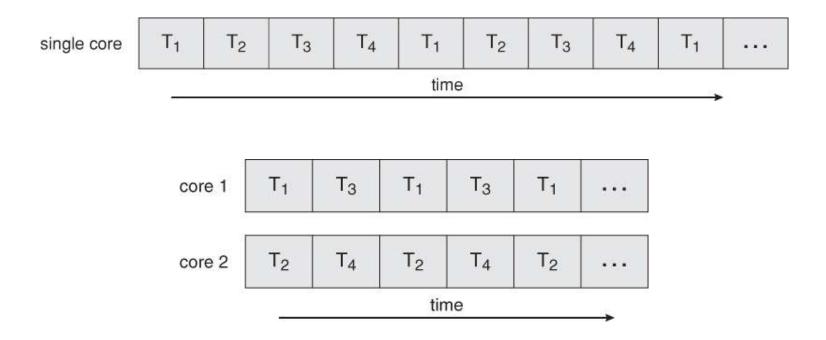
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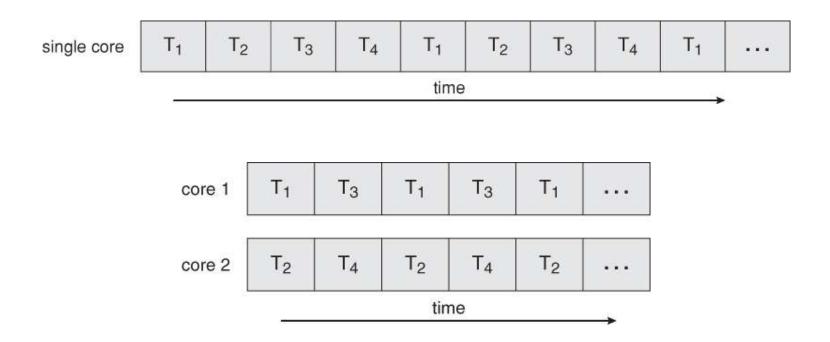
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 - Economy → creating and managing threads (and context switches between them) is much faster than performing the same tasks for processes
 - Scalability (multi-processor architectures) → A single threaded process can only run on one CPU, whereas a multi-threaded process may be split amongst all available processors/cores

Multi-core Programming

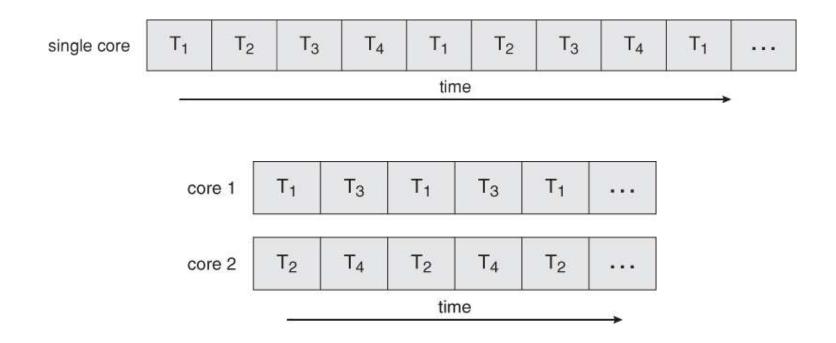
- A recent trend in computer architecture is to produce chips with multiple cores, or CPUs on a single chip
- A multi-threaded application running on a traditional single-core chip would have to interleave the threads
- On a multi-core chip, however, threads could be spread across the available cores, allowing true parallel processing!



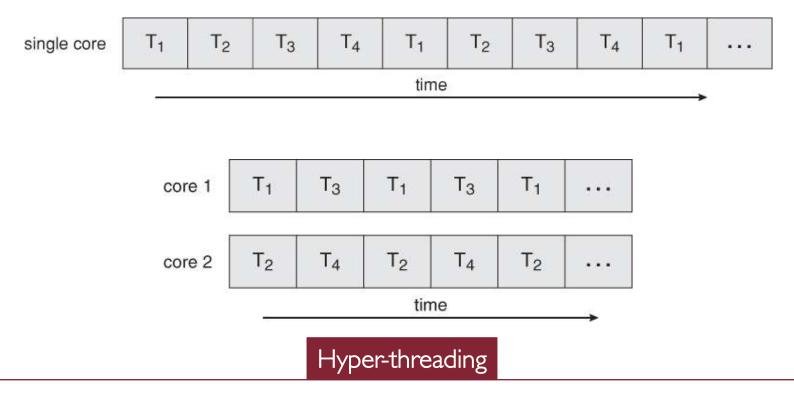




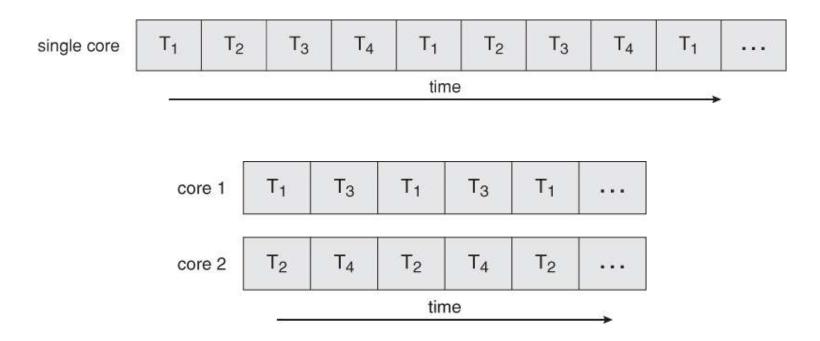
Multi-core chips require new OS scheduling algorithms to make better use of the multiple cores available



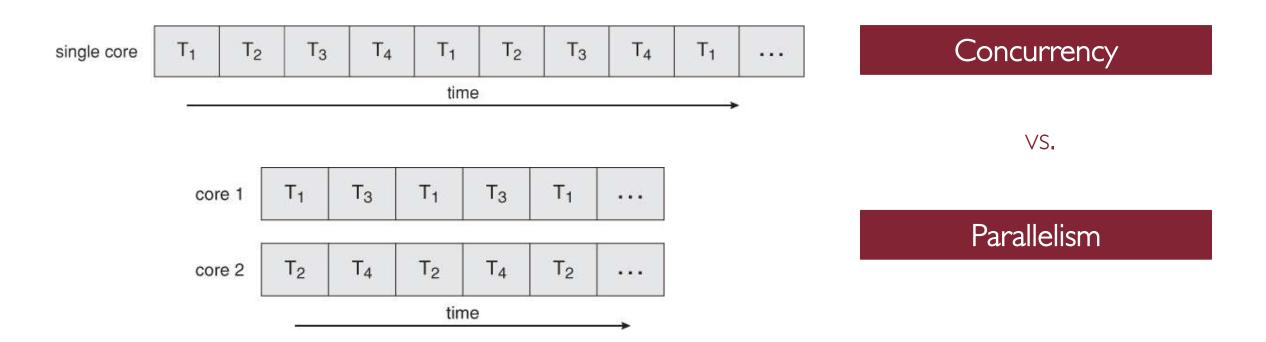
CPUs have been developed to support more simultaneous threads per core in hardware (e.g., Intel's hyper-threading)



Each physical core appears as two processors to the OS, allowing concurrent scheduling of two processes per core



Single- vs. Multi-core Programming



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 - Data parallelism: divides the data up amongst multiple cores (threads), and performs the same task on each chunk of the data
 - Task parallelism: divides the different tasks to be performed among the different cores and performs them simultaneously
- In practice, no program is ever divided up solely by one or the other of these, but instead by some sort of hybrid combination



address space



thread



address space



thread

multiple threads

single thread



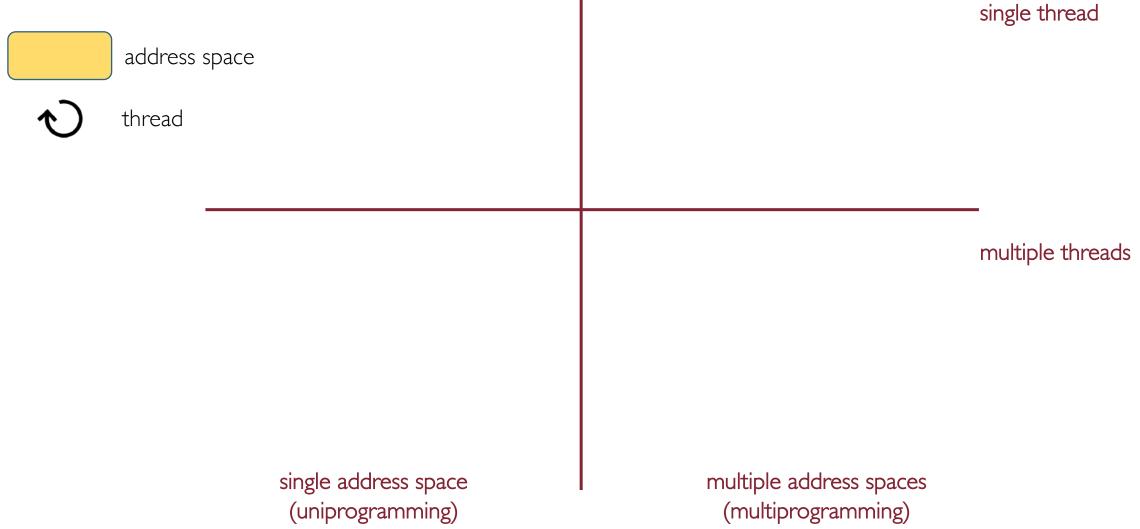
address space

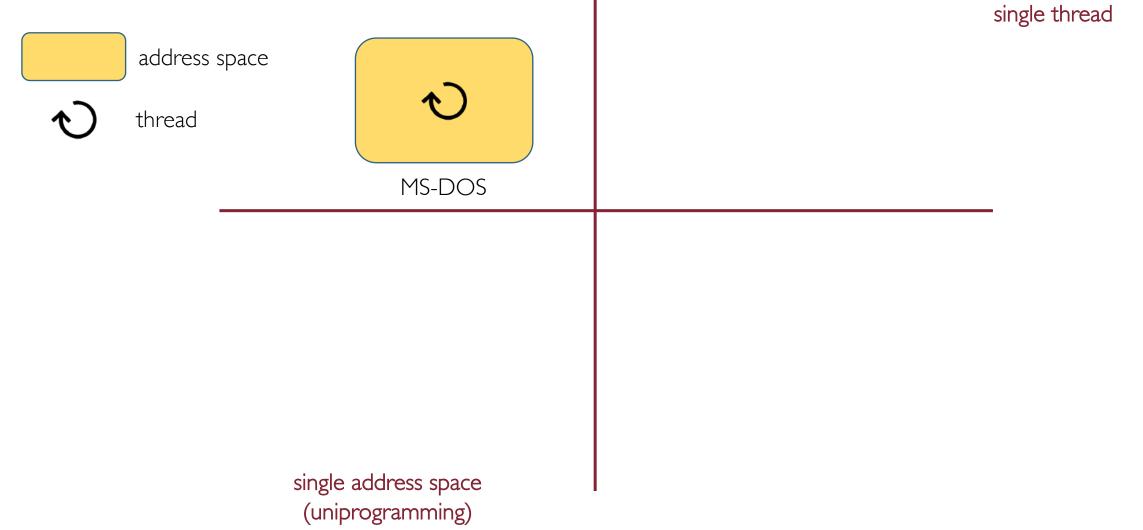


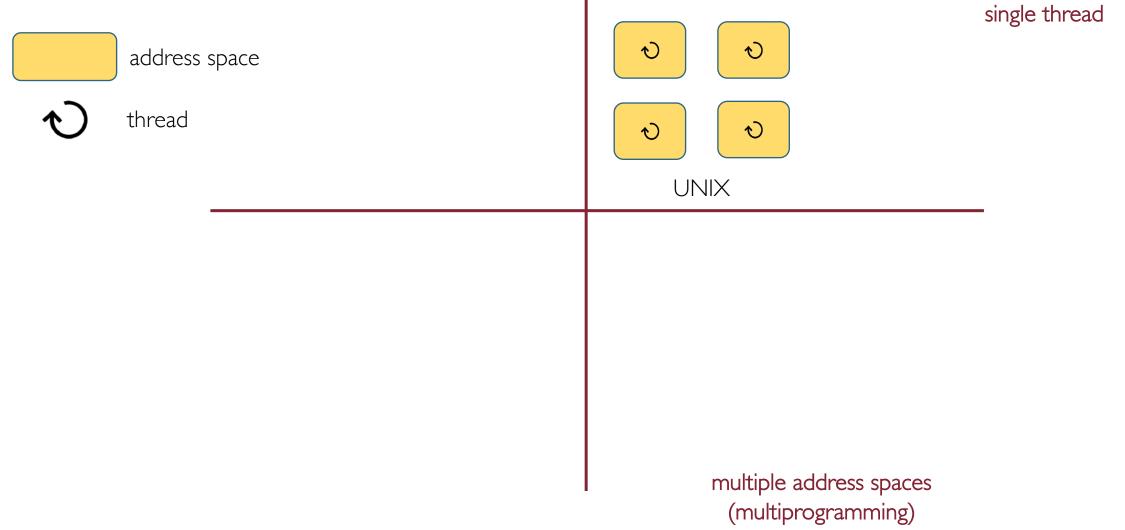
thread

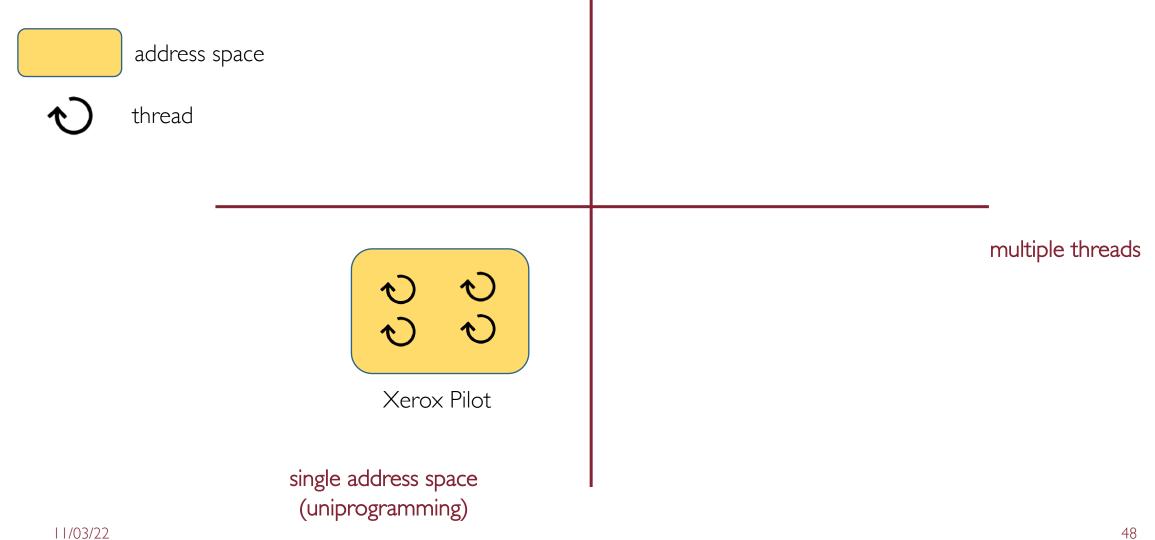
single address space (uniprogramming)

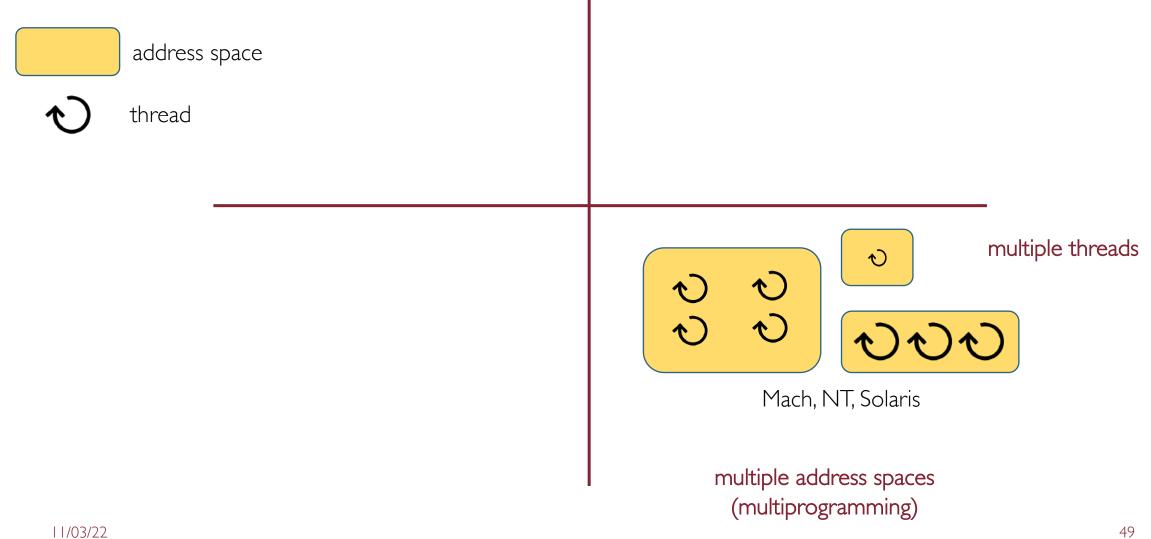
multiple address spaces (multiprogramming)

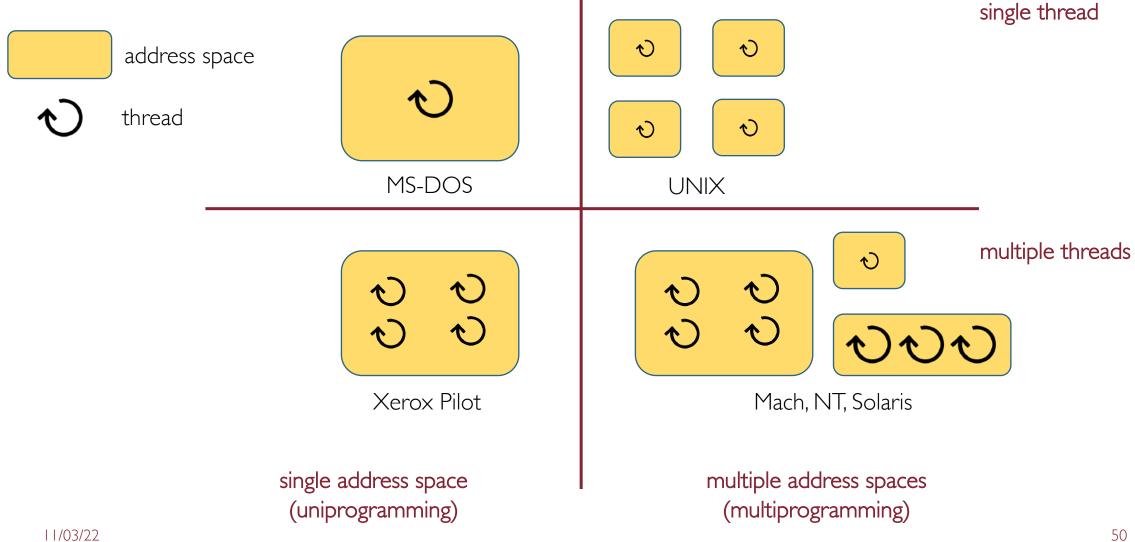












Multi-threading: Support and Management

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User threads

• managed in user space by a user-level thread library, without OS intervention

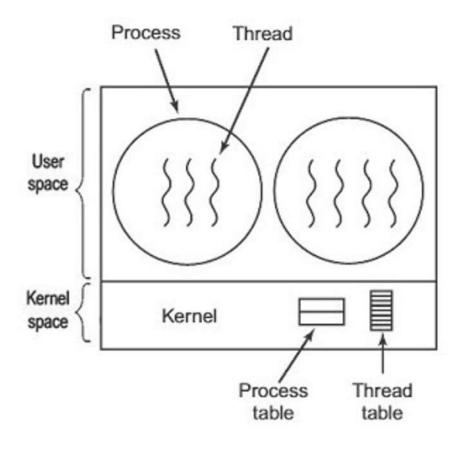
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- The OS is responsible for supporting and managing all threads
- One Process Control Block (PCB) for each process, one Thread Control Block (TCB) for each thread
- The OS usually provides system calls to create and manage threads from user space

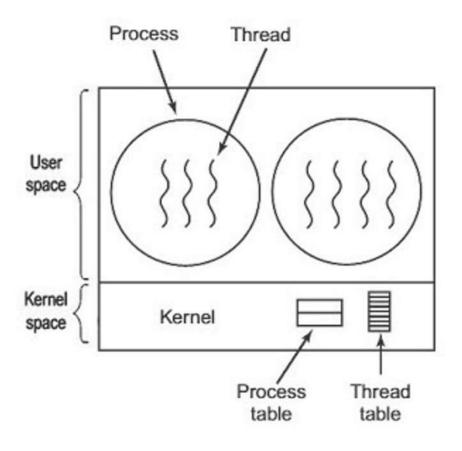
Kernel Threads: PROs



PROs

- The kernel has full knowledge of all threads
- Scheduler may decide to give more CPU time to a process having a large numer of threads
- Good for applications that frequently block
- Switching between threads is faster than switching between processes

Kernel Threads: CONs



CONs

- Significant overhead and increase in kernel complexity
- Slow and inefficient (need kernel invocations)
- Context switching, although lighter, is managed by the kernel

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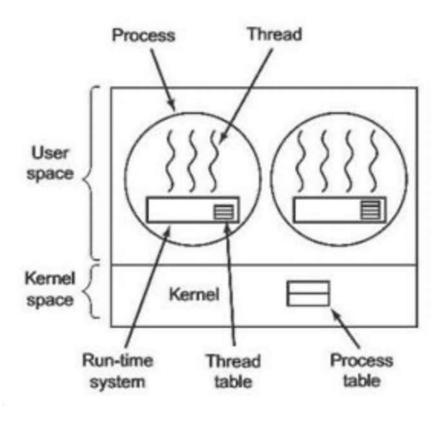
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- Ideally, thread operations should be as fast as a function call

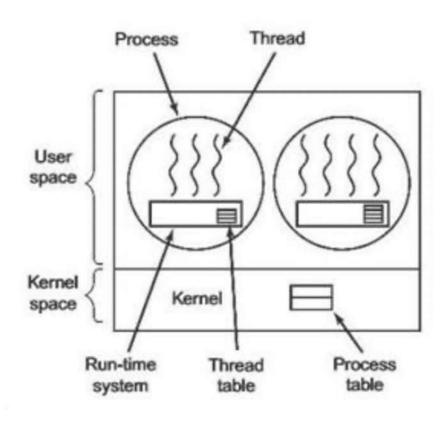
User Threads: PROs



PROs

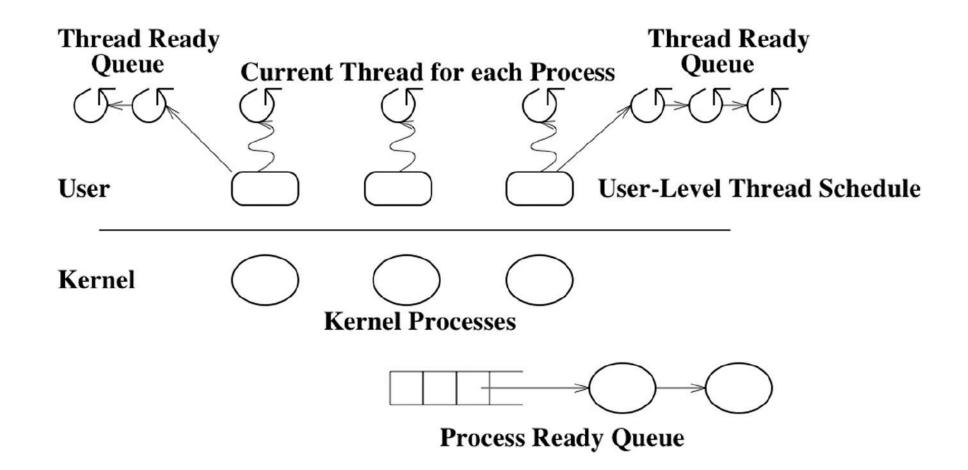
- Really fast and lightweight
- Scheduling policies are more flexible
- Can be implemented in OSs that do not support threading
- No system calls involved, just user-space function calls
- No actual context switch

User Threads: CONs

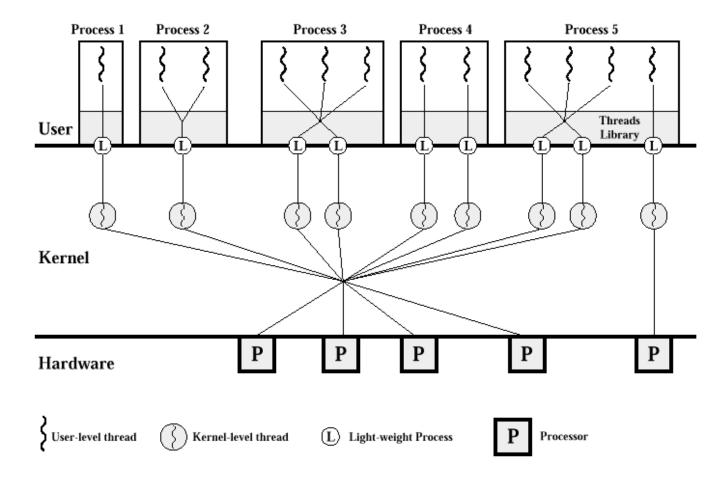


• CONs

- No true concurrency of multi-threaded processes
- Poor scheduling decisions
- Lack of coordination between kernel and threads
 - A process with I 00 threads competes for a time slice with a process with just I thread
- Requires non-blocking system calls, otherwise all threads within a process have to wait



Hybrid Management: Lightweight Processes



Multi-threading Models

- In a specific implementation, user threads must be mapped to kernel threads in one of the following ways:
 - Many-to-One
 - One-to-One
 - Many-to-Many
 - Two-level

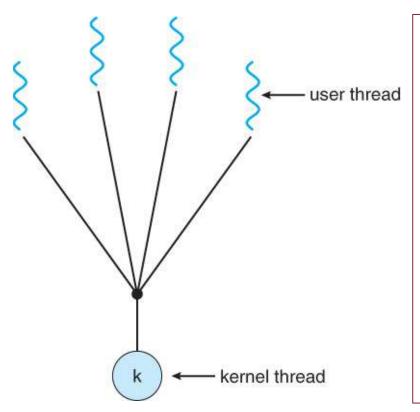
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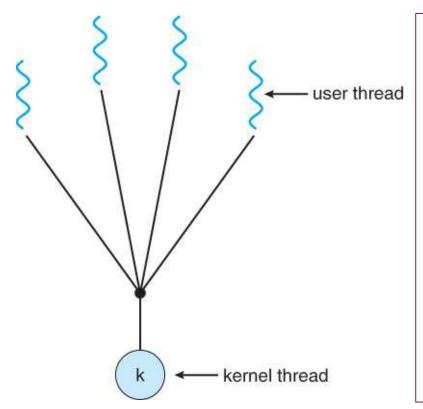
A kernel thread is the unit of execution that is scheduled by the OS to run on the CPU (similar to single-threaded process)

Many-to-One Model



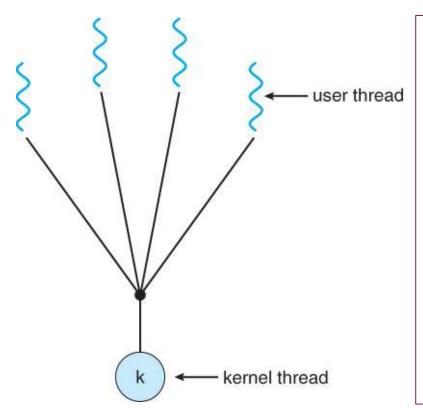
- Many user threads are all mapped onto a single kernel thread
- The process can only run one user thread at a time because there is only one kernel thread associated with it
- As single kernel thread can operate on a single CPU, multiuser-thread processes cannot be split across multiple CPUs
- If a blocking system call is made, the entire process blocks, even if other user threads would be able to continue

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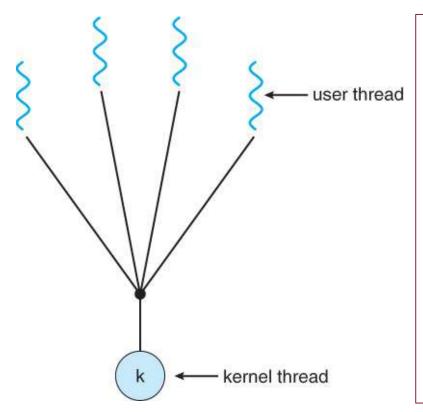
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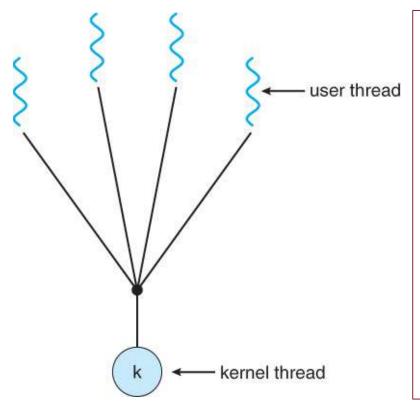
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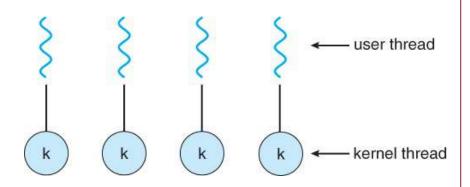
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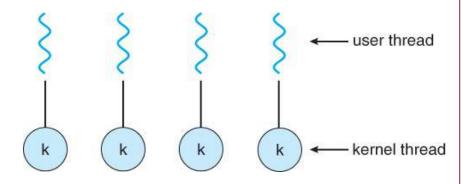
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pure user-level

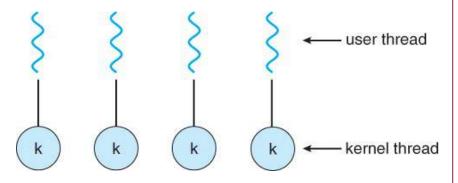


- A separate kernel thread to handle each user thread
- Overcomes the limitations of blocking system calls and splitting of processes across multiple CPUs
- The overhead of managing the one-to-one model is more significant and may slow down the system
- Most implementations of this model place a limit on how many threads can be created

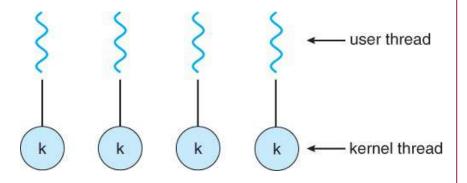
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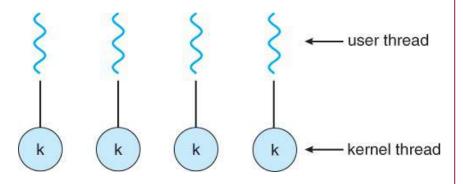
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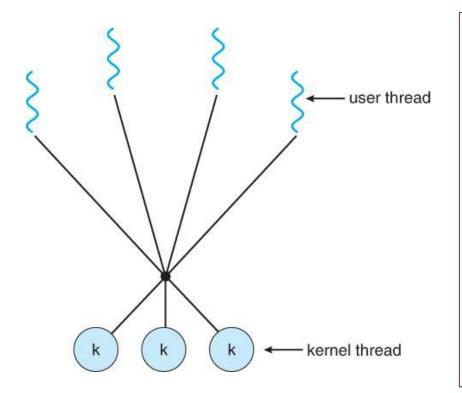


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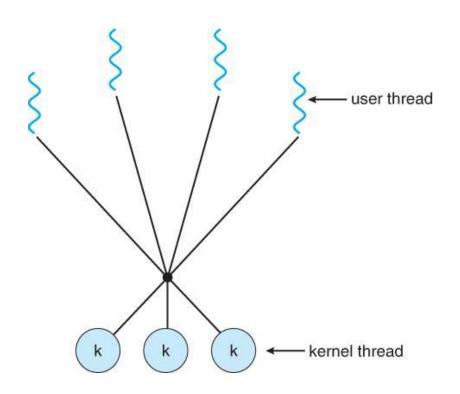


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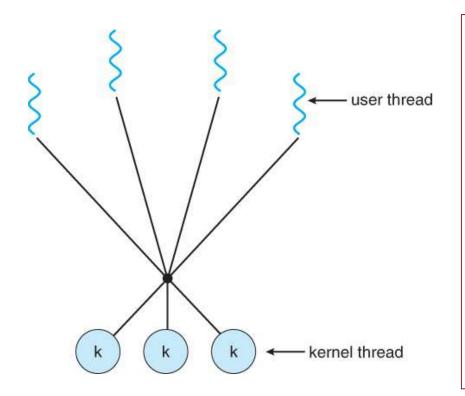
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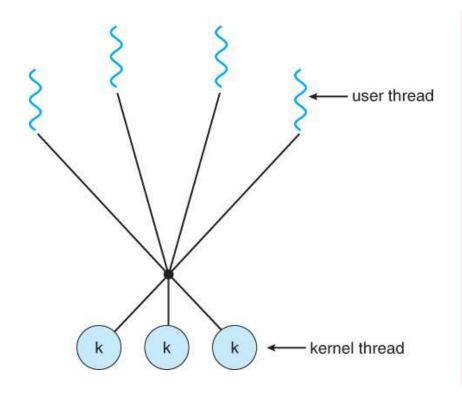
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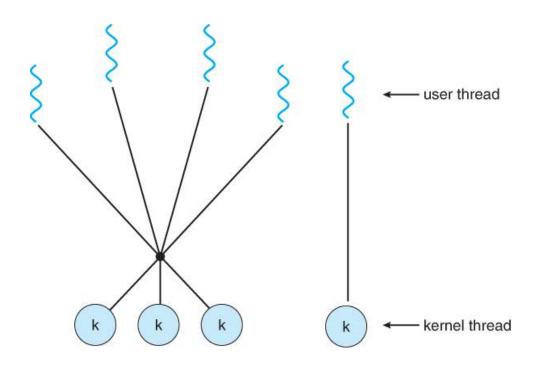


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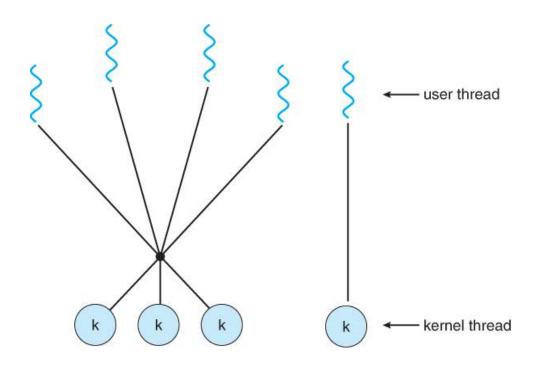
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Two-Level Model



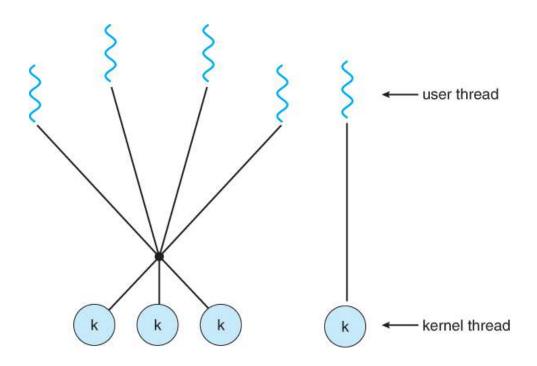
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- Mixes many-to-many with one-to-one
- Increases the flexibility of scheduling policies

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- 2 primary ways of implementing it:
 - user space -> API functions implemented entirely in user space (function calls)
 - kernel space → implemented in kernel space within a kernel that supports threads (system calls)

Thread Libraries: Examples

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Thread Libraries: Examples

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 - POSIX Pthreads → may be provided as either a user or kernel library, as an extension to the POSIX standard
 - Win32 threads -> provided as a kernel-level library on Windows systems
 - Java threads → the implementation of threads is based upon whatever OS and hardware the JVM is running on, e.g., either Pthreads or Win32 threads

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- Global variables are shared amongst all threads
- One thread can wait for the others to rejoin before continuing

Compute the sum of the first *N* integers on a separate thread

Compute the sum of the first N integers on a separate thread

```
#include <pthread.h>
#include <stdio.h>
int sum; /* this data is shared by the thread(s) */
void *runner(void *param); /* the thread */
int main(int argc, char *argv[])
  pthread_t tid; /* the thread identifier */
  pthread_attr_t attr; /* set of thread attributes */
  if (argc != 2) {
     fprintf(stderr, "usage: a.out <integer value>\n");
  if (atoi(argv[1]) < 0) [
     fprintf(stderr, "%d must be >= 0\n", atoi(argv[1]));
     return -1:
  /* get the default attributes */
  pthread_attr_init(&attr):
   /* create the thread */
  pthread_create(&tid,&attr,runner,argv[1]);
  /* wait for the thread to exit */
  pthread_join(tid,NULL);
  printf("sum = %d\n",sum);
/* The thread will begin control in this function *,
void *runner(void *param)
  int i, upper = atoi(param);
```

Figure 4.6 Multithreaded C program using the Pthreads API.

Compute the sum of the first N integers on a separate thread

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#include <pthread.h>
#include <stdio.h>
int sum; /* this data is shared by the thread(s) */
void *runner(void *param); /* the thread */
int main(int argc, char *argv[])
  pthread_t tid; /* the thread identifier */
  pthread_attr_t attr; /* set of thread attributes */
  if (argc != 2) {
     fprintf(stderr, "usage: a.out <integer value>\n");
  if (atoi(argv[1]) < 0) {
     fprintf(stderr, "%d must be >= 0\n", atoi(argv[1]));
     return -1:
  /* get the default attributes */
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  pthread_create(&tid, &attr, runner, argv[1]);
  /* wait for the thread to exit */
  pthread_join(tid,NULL);
  printf("sum = %d\n",sum);
/* The thread will begin control in this function */
void *runner(void *param)
  int i, upper = atoi(param);
  sum = 0:
  for (i = 1; i <= upper; i++)
    sum += i:
  pthread_exit(0);
```

Figure 4.6 Multithreaded C program using the Pthreads API.

Java Threads

- Java Threads can be created in 2 ways:
 - Extending the **Thread** class
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- Java Threads can be created in 2 ways:
 - Extending the **Thread** class
 - Implementing the **Runnable** Interface
- Both solutions require to override the **run** () method
- Note that Java doesn't support multiple inheritance!
 - If your class extends the **Thread** class, it cannot extend any other class
 - In such a situation, implementing **Runnable** is preferable

```
public class SingleThreadedServer implements Runnable {
   protected int
                           serverPort = 8080;
   protected ServerSocket serverSocket = null;
                           isStopped
   protected boolean
   public SingleThreadedServer(int port){
        this.serverPort = port;
   public void run() {
            this.serverSocket = new ServerSocket(this.serverPort);
        catch (IOException e) {
            throw new RuntimeException("Cannot open port " + this.serverPort, e);
        while(!this.isStopped) {
           Socket clientSocket = null;
                clientSocket = this.serverSocket.accept();
            } catch (IOException e) {
                if(this.isStopped) {
                   System.out.println("Server Stopped.");
                throw new RuntimeException(
                   "Error accepting client connection", e);
                processClientRequest(clientSocket);
           } catch (Exception e) {
        System.out.println("Server Stopped.");
   private void processClientRequest(Socket clientSocket) throws Exception {
```

This is the simplest (although not optimal) single-threaded implementation of a Java web server

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The Server Loop

- I. Wait for a client request
- 2. Process a single client request
- 3. Repeat from I

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A single-threaded server processes incoming requests in the very same thread that accepts connections

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The Server Loop

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A single-threaded server processes incoming requests in the very same thread that accepts connections

This is not a good idea as clients can connect to the server only when this is inside the serverSocket.accept() method call

```
public class MultiThreadedServer implements Runnable {
    protected int
                           serverPort
    protected ServerSocket serverSocket = null;
    protected boolean
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    public MultiThreadedServer(int port){
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    public void run() {
        try {
            this.serverSocket = new ServerSocket(this.serverPort);
        catch (IOException e) {
            throw new RuntimeException("Cannot open port " + this.serverPort, e);
        while(!this.isStopped) {
            Socket clientSocket = null;
            try {
                clientSocket = this.serverSocket.accept();
            } catch (IOException e) {
                if(this.isStopped) {
                    System.out.println("Server Stopped.");
                    return;
                throw new RuntimeException(
                    "Error accepting client connection", e);
            new Thread(new WorkerRunnable(clientSocket, "Multithreaded Server")).start();
        System.out.println("Server Stopped.");
```

The server loop is very similar to that of a single-threaded server

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public class MultiThreadedServer implements Runnable {
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This way the thread listening for incoming requests spends as much time as possible in the serverSocket.accept() call

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The server loop is very similar to that of a single-threaded server

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This way the thread listening for incoming requests spends as much time as possible in the serverSocket.accept() call

The risk of clients being denied access to the server because the listening thread is outside the accept () call is minimized

```
public class WorkerRunnable implements Runnable{
    protected Socket clientSocket = null;
    protected String serverText = null;

    public WorkerRunnable(Socket clientSocket, String serverText) {
        this.clientSocket = clientSocket;
        this.serverText = serverText;
    }

    public void run() {
        // process client request here ...
}
```

The server loop is very similar to that of a single-threaded server

A multi-threaded server passes the connection on to a worker thread that processes the request

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- Upon each request the web server receives it spawns off a new thread
- Creating new threads rather than new process is surely less expensive
- Still, some major problems might occur:
 - overhead to create a thread for each request
 - number of concurrent threads active on the system is possibly unbound
- Solution → use a thread pool

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- Those threads are placed in the "pool" waiting for some work to do
- When the web server gets a request it awakens a thread from the pool
- The worker thread processes the request and goes back to the pool once terminated
- If no threads are available in the pool the server simply waits for one

Thread Pools: Benefits

- Servicing a request with an existing thread is faster than waiting to create a thread
- A thread pool limits the number of threads that exist at any one point
- Separating the task to be performed from the mechanics of creating the task allows us to use different strategies for running the task
 - For example, the task could be scheduled to execute after a time delay or to execute periodically

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- Q: If one thread forks, is the entire process copied, or is the new process single-threaded?
- Al: System dependent
- A2: If the new process execs right away, there is no need to copy all the other threads, otherwise the entire process should be copied
- A3: Many versions of UNIX provide multiple versions of the fork call for this purpose

Threading Issues: Signal Handling

• Q: When a multi-threaded process receives a signal, to what thread should that signal be delivered?

Threading Issues: Signal Handling

- Q: When a multi-threaded process receives a signal, to what thread should that signal be delivered?
- A: There are 4 major options:
 - Deliver the signal to the thread to which the signal applies
 - Deliver the signal to every thread in the process
 - Deliver the signal to certain threads in the process
 - Assign a specific thread to receive all signals in a process

Threading Issues: Signal Handling (UNIX)

- UNIX allows individual threads to indicate which signals they are accepting and which they are ignoring
- Provides 2 separate system calls for delivering signals to process/threads, respectively:
 - kill(pid, signal)
 - pthread_kill(tid, signal)

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- Process Contention Scope (PCS)
 - competition occurs between threads that are part of the same process (multiple user threads mapped to a single kernel thread, managed by the thread library)
 - on systems implementing many-to-one and many-to-many threads

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- on systems implementing many-to-one and many-to-many threads

System Contention Scope (SCS)

- involves the system scheduler scheduling kernel threads to run on one or more
 CPUs
- on systems implementing one-to-one threads

Thread Scheduling: Activation

- Many implementations of threads provide a virtual processor as an interface between user thread and the kernel thread (many-to-many or two-tier)
- This virtual processor is known as a Lightweight Process (LWP)
- There is a one-to-one correspondence between LWPs and kernel threads
- The number of kernel threads available may change dynamically
- The application (user-level thread library) maps user threads onto available LWPs
- Kernel threads are scheduled onto the real processor(s) by the OS

Thread Scheduling: Activation

- The kernel communicates to the user-level thread library when certain events occur (e.g., a thread is blocking) via an upcall
- The upcall is handled in the thread library by an upcall handler
- The upcall also provides a new LWP for the upcall handler to run on, which it can then use to reschedule the user thread that is about to become blocked
- The OS will also issue upcalls when a thread unblocks, so the thread library can make appropriate adjustments
- If the kernel thread blocks then the LWP blocks, which blocks the user thread

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- A thread is a single execution stream within a process
- Thread vs. Process:
 - common vs. separate address spaces → quicker communication
 - lightweight vs. heavyweight → faster context switching
- User- vs. Kernel-level threads
- Scheduling algorithms operates (almost) transparently with threads