Sistemi Operativi I

Corso di Laurea in Informatica 2022-2023



Dipartimento di Informatica Sapienza Università di Roma tolomei@di.uniroma1.it

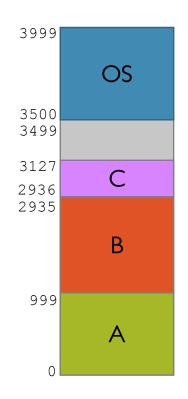


• So far, we have assumed each process is allocated into a contiguous space of physical memory

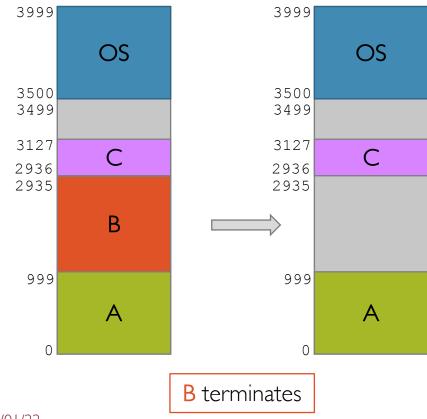
- So far, we have assumed each process is allocated into a contiguous space of physical memory
- One simple method is to divide upfront all available memory dedicated to user processes into equally-sized segments/partitions
 - Assign each process to a segment
 - Implicitly restricts the grade of multiprogramming (i.e., the number of simultaneous processes) and their size
 - No longer used!

An alternative approach is for the OS to keep track of **free** (unused) memory segments, as processes enter the system, grow, and terminate

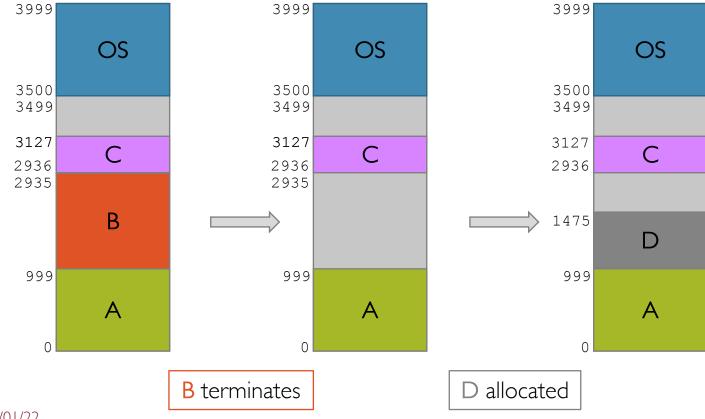
An alternative approach is for the OS to keep track of **free** (unused) memory segments, as processes enter the system, grow, and terminate



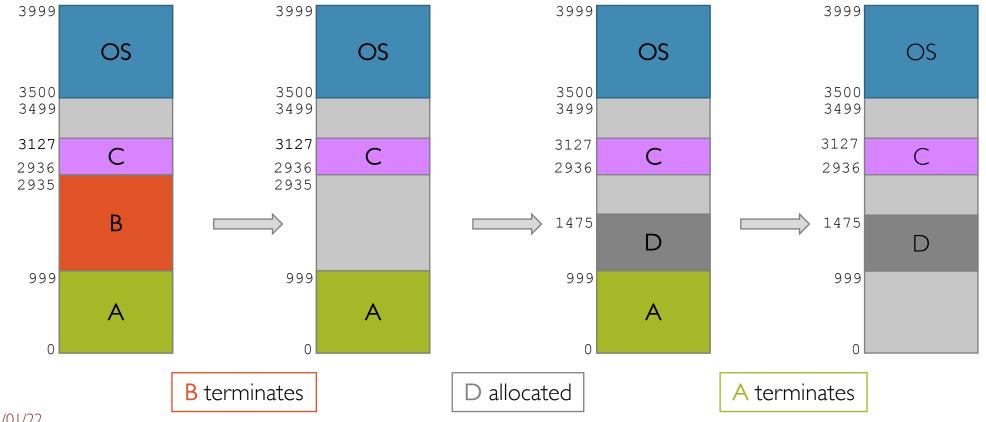
An alternative approach is for the OS to keep track of **free** (unused) memory segments, as processes enter the system, grow, and terminate

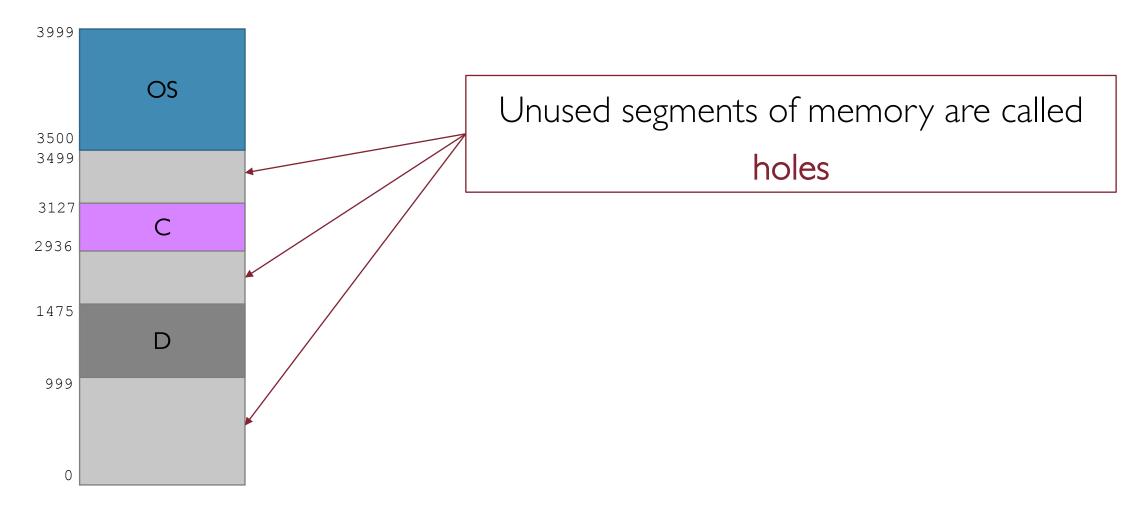


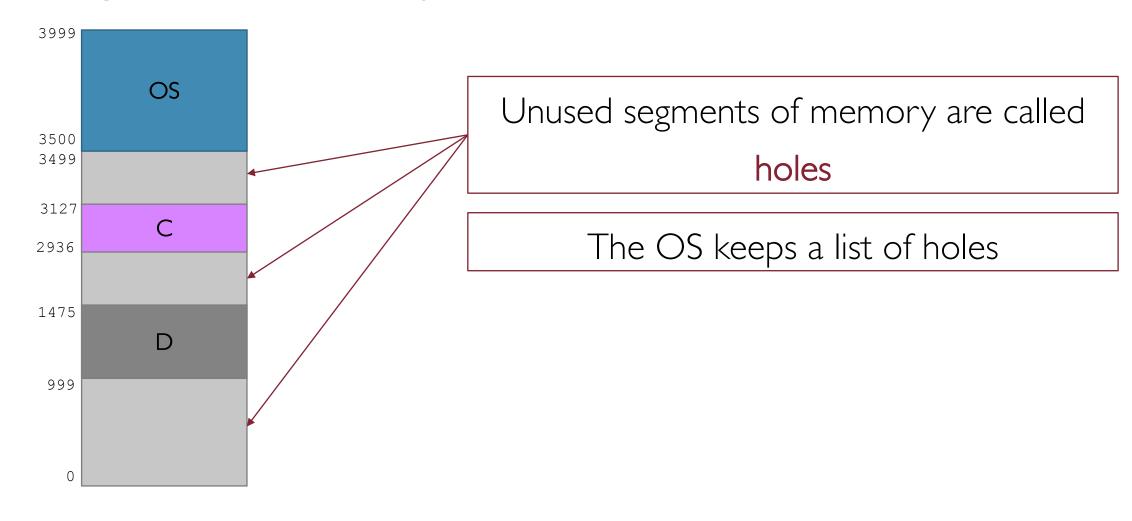
An alternative approach is for the OS to keep track of **free** (unused) memory segments, as processes enter the system, grow, and terminate

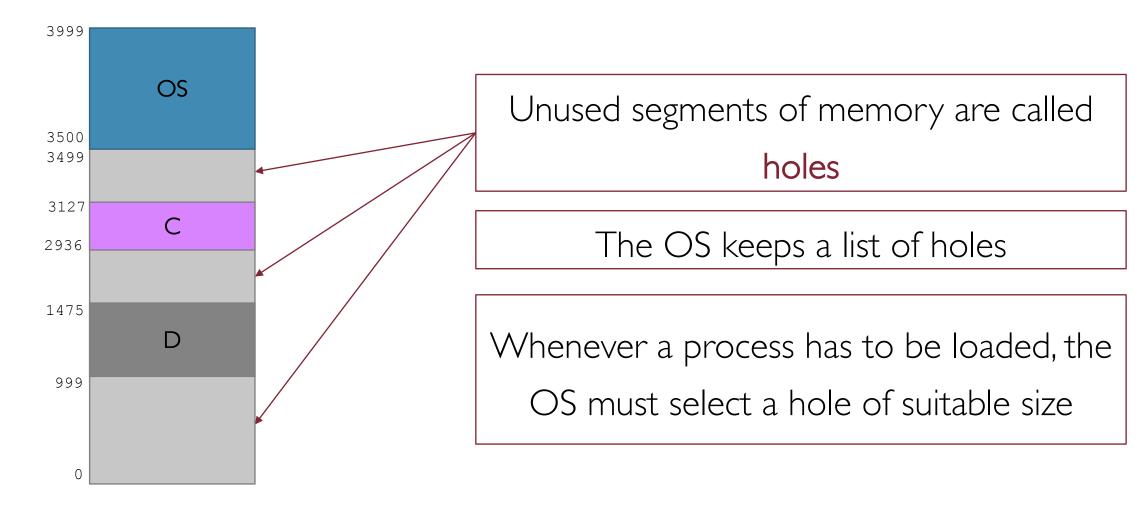


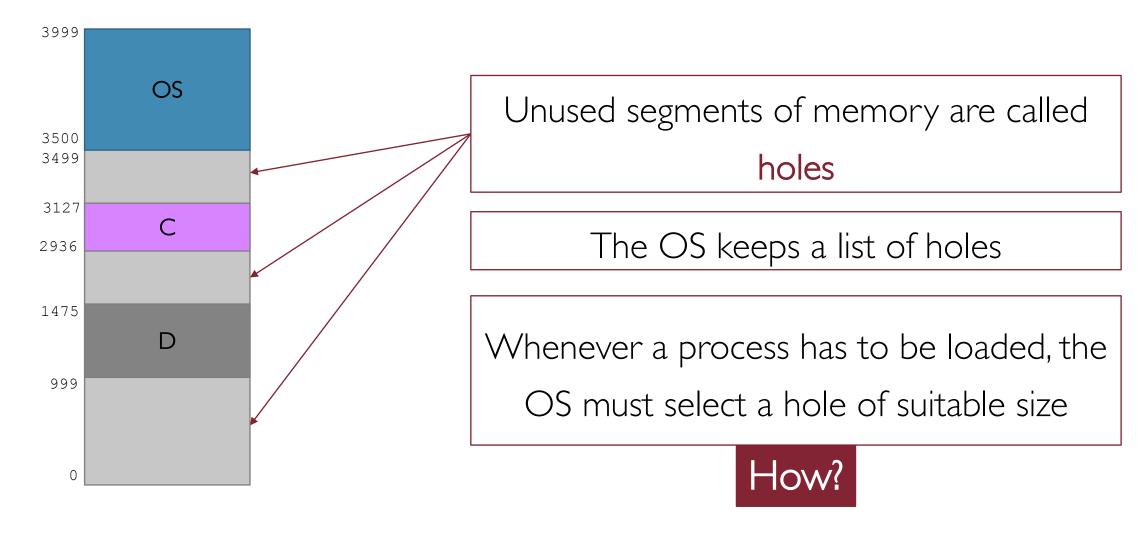
An alternative approach is for the OS to keep track of free (unused) memory segments, as processes enter the system, grow, and terminate











• Linearly scan the list of holes until one is found that is big enough to satisfy the request

- Linearly scan the list of holes until one is found that is big enough to satisfy the request
- Subsequent requests may either start from the beginning of the list or from the end of previous search

- Linearly scan the list of holes until one is found that is big enough to satisfy the request
- Subsequent requests may either start from the beginning of the list or from the end of previous search
- Complexity: O(n), where n is the number of holes

Suppose process X needs 100B of memory to be loaded, and the list of holes is as follows:



Suppose process X needs 100B of memory to be loaded, and the list of holes is as follows:



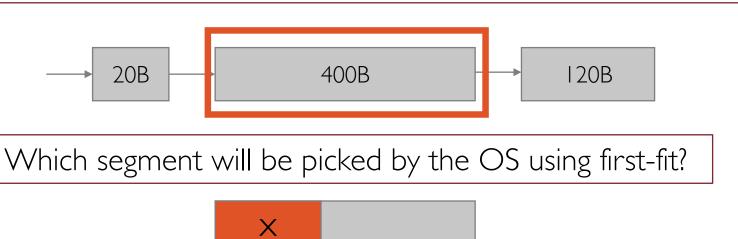
Which segment will be picked by the OS using first-fit?

Suppose process X needs 100B of memory to be loaded, and the list of holes is as follows:



Which segment will be picked by the OS using first-fit?

Suppose process X needs 100B of memory to be loaded, and the list of holes is as follows:



300B ("wasted")

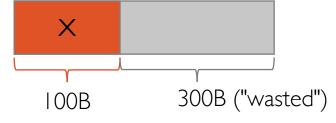
12/01/22

100B

Suppose process X needs 100B of memory to be loaded, and the list of holes is as follows:



Which segment will be picked by the OS using first-fit?

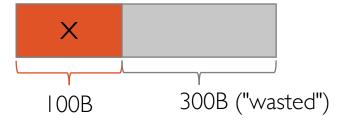


What if afterwards process Y requires 350B?

Suppose process X needs 100B of memory to be loaded, and the list of holes is as follows:



Which segment will be picked by the OS using first-fit?



What if afterwards process Y requires 350B?

We will not be able to satisfy this request even if theoretically we could

12/01/22

21

• Allocate the smallest hole that is big enough to satisfy the request

- Allocate the smallest hole that is big enough to satisfy the request
- This saves large holes for other process requests that may need them

- Allocate the smallest hole that is big enough to satisfy the request
- This saves large holes for other process requests that may need them
- However, the resulting unused portions of holes may be too small to be of any use, and will therefore be wasted

- Allocate the smallest hole that is big enough to satisfy the request
- This saves large holes for other process requests that may need them
- However, the resulting unused portions of holes may be too small to be of any use, and will therefore be wasted
- Complexity: still O(n) but can be O(log n) if the list of holes is kept sorted

- Allocate the smallest hole that is big enough to satisfy the request
- This saves large holes for other process requests that may need them
- However, the resulting unused portions of holes may be too small to be of any use, and will therefore be wasted
- Complexity: still O(n) but can be O(log n) if the list of holes is kept sorted

Do you know how which data structure can be used to achieve this?

- Allocate the smallest hole that is big enough to satisfy the request
- This saves large holes for other process requests that may need them
- However, the resulting unused portions of holes may be too small to be of any use, and will therefore be wasted
- Complexity: still O(n) but can be O(log n) if the list of holes is kept sorted

Do you know how which data structure can be used to achieve this?

Binary Search Tree (BST)

Suppose process X needs 100B of memory to be loaded, and the list of holes is as follows:

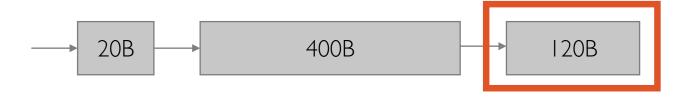


Suppose process X needs 100B of memory to be loaded, and the list of holes is as follows:



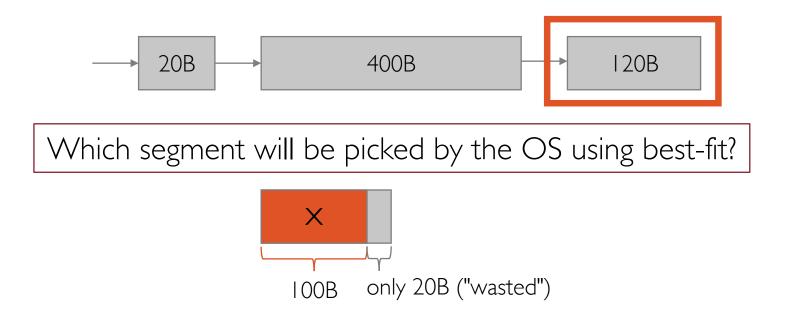
Which segment will be picked by the OS using best-fit?

Suppose process X needs 100B of memory to be loaded, and the list of holes is as follows:

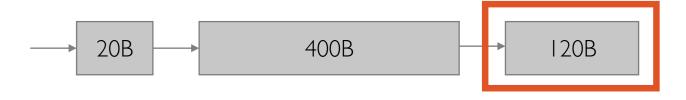


Which segment will be picked by the OS using best-fit?

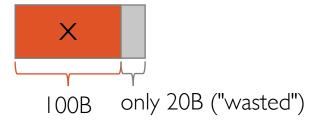
Suppose process X needs 100B of memory to be loaded, and the list of holes is as follows:



Suppose process X needs 100B of memory to be loaded, and the list of holes is as follows:

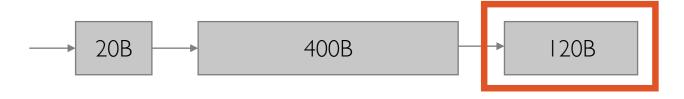


Which segment will be picked by the OS using best-fit?

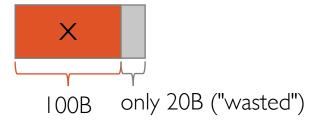


What if afterwards process Y requires 350B?

Suppose process X needs 100B of memory to be loaded, and the list of holes is as follows:



Which segment will be picked by the OS using best-fit?



What if afterwards process Y requires 350B?

We can now assign it the second available hole segment (400B)

• Allocate the largest hole available

- Allocate the largest hole available
- Might sound counterintuitive but this increases the likelihood that the remaining portion will be usable for satisfying future requests

- Allocate the largest hole available
- Might sound counterintuitive but this increases the likelihood that the remaining portion will be usable for satisfying future requests
- Simulations show that First-Fit and Best-Fit usually work best

Memory Allocation Policies: Worst-Fit

- Allocate the largest hole available
- Might sound counterintuitive but this increases the likelihood that the remaining portion will be usable for satisfying future requests
- Simulations show that First-Fit and Best-Fit usually work best
- First-Fit is also generally faster than Best-Fit

Fragmentation

Problem

Individual holes may be too small to serve a process request but they can be large enough if combined together

Fragmentation

Problem

Individual holes may be too small to serve a process request but they can be large enough if combined together

External Fragmentation

Fragmentation

Problem

Individual holes may be too small to serve a process request but they can be large enough if combined together

External Fragmentation

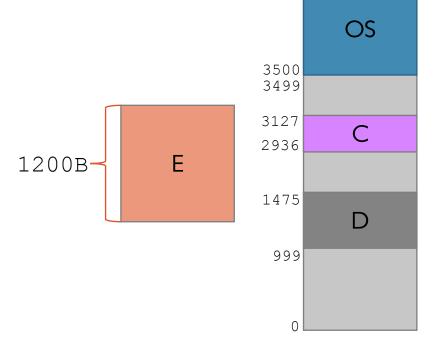
Internal Fragmentation

• Frequent loading and unloading processes causes holes to be broken into small (i.e., unusable) chunks

• Frequent loading and unloading processes causes holes to be broken into small (i.e., unusable) chunks

• It happens when there is enough memory to load a process in memory

but space is not contiguous



3999

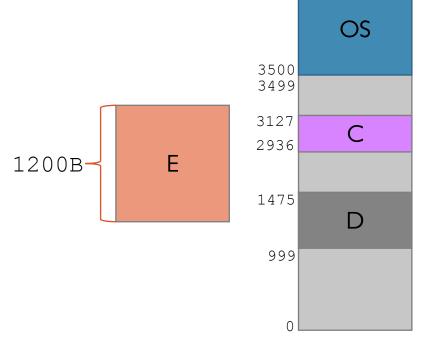
• Frequent loading and unloading processes causes holes to be broken into small (i.e., unusable) chunks

• It happens when there is enough memory to load a process in memory

but space is not contiguous

Simulations show that for every 2N allocated blocks, N are lost due to external fragmentation

1/3 of memory space is wasted on average



3999

• Frequent loading and unloading processes causes holes to be broken into small (i.e., unusable) chunks

• It happens when there is enough memory to load a process in memory

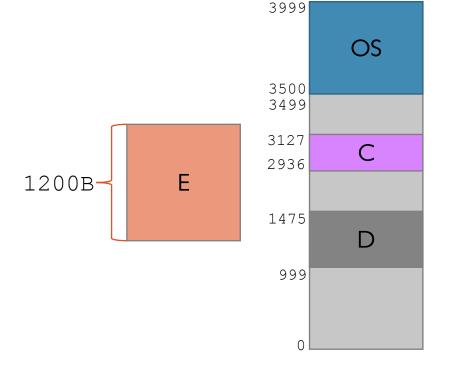
but space is not contiguous

Simulations show that for every 2N allocated blocks, N are lost due to external fragmentation

1/3 of memory space is wasted on average

Goal:

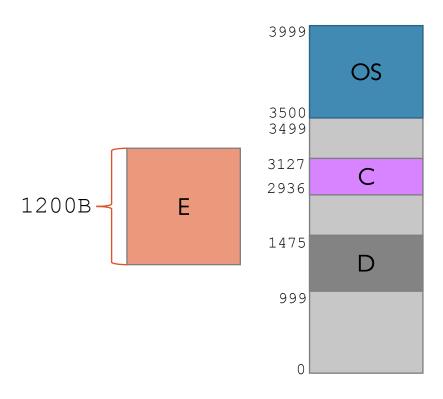
Allocation policy that minimizes wasted space!

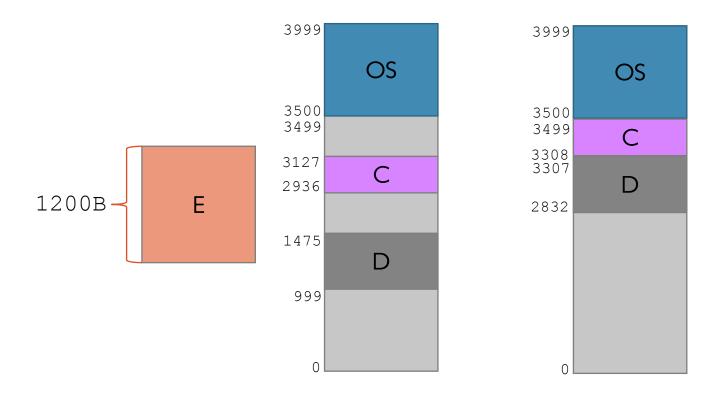


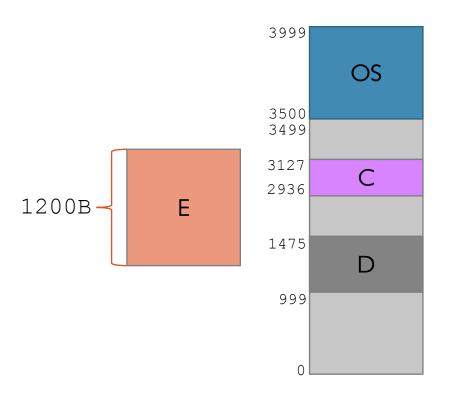
• It happens when memory internal to a segment is wasted

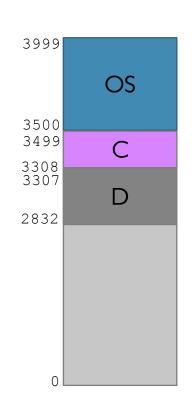
- It happens when memory internal to a segment is wasted
- For example, consider a process whose size is 8,846B and a hole of size 8,848B

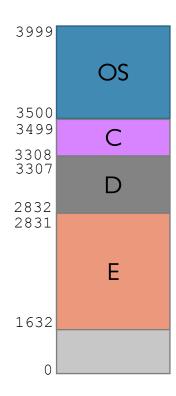
- It happens when memory internal to a segment is wasted
- For example, consider a process whose size is 8,846B and a hole of size 8,848B
- It may be much more efficient to allocate the process the whole block (and waste 2B) rather than keep track of a tiny 2B hole

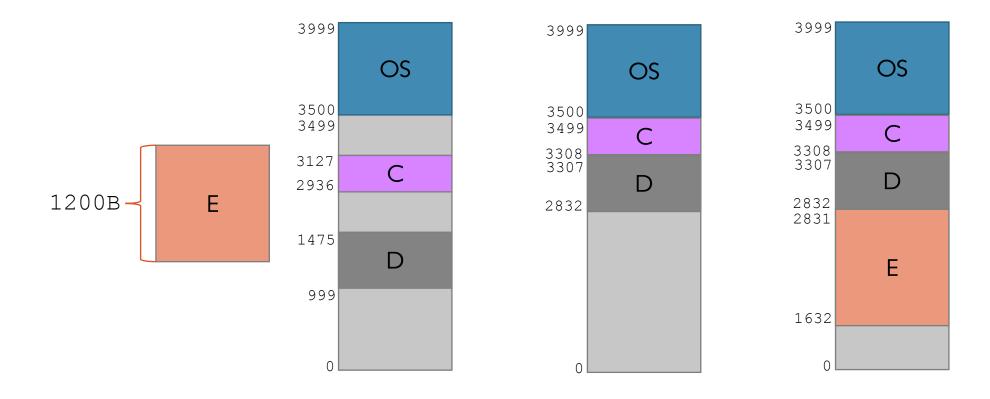




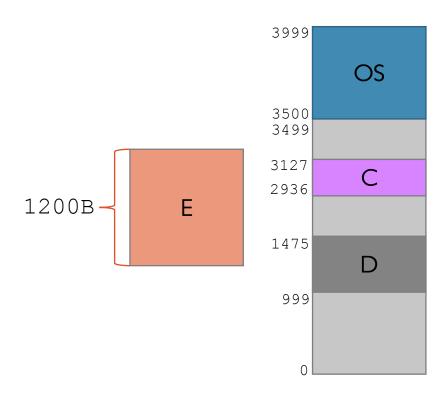


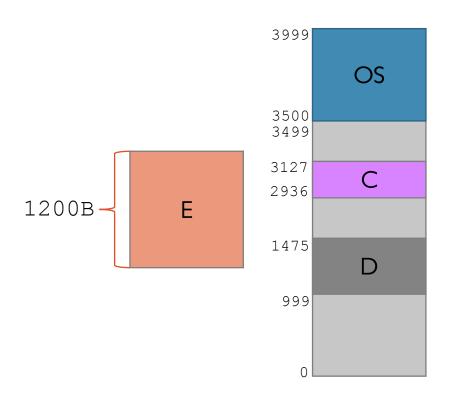


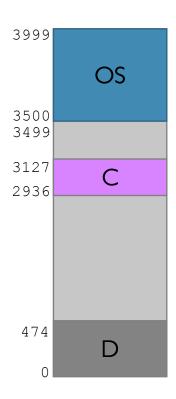


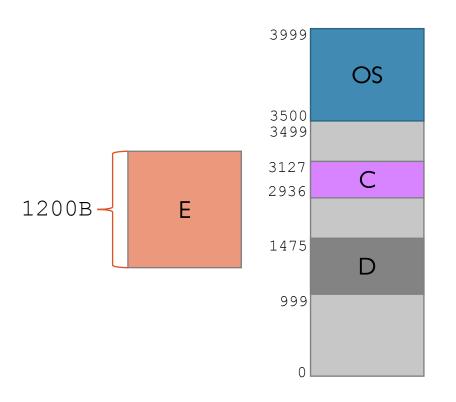


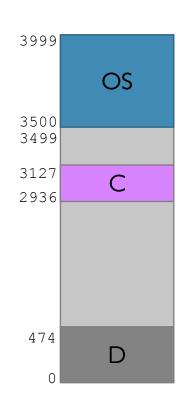
Only one hole is left but two processes need to be moved (C and D)

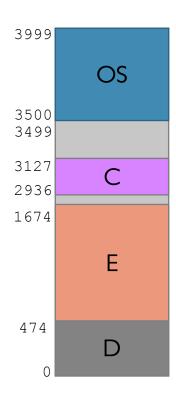


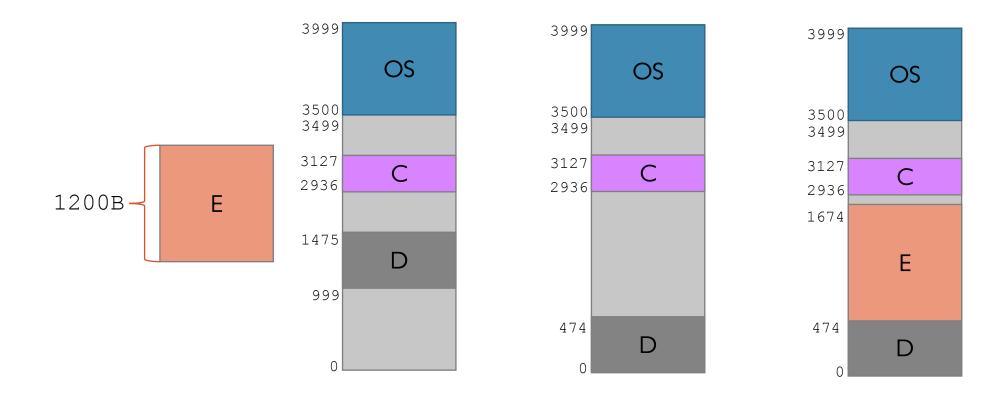












Still some holes left but only one process is moved (D) rather than two

• So far, we have assumed all processes are entirely loaded in memory (of course, when loaded!)

- So far, we have assumed all processes are entirely loaded in memory (of course, when loaded!)
- Remember: A process needs to sit physically in main memory only if the
 CPU executes its instructions and accesses its data

- So far, we have assumed all processes are entirely loaded in memory (of course, when loaded!)
- Remember: A process needs to sit physically in main memory only if the
 CPU executes its instructions and accesses its data
- If a process blocks (e.g., due to an I/O call) it doesn't need to be in memory while I/O is running

- So far, we have assumed all processes are entirely loaded in memory (of course, when loaded!)
- Remember: A process needs to sit physically in main memory only if the
 CPU executes its instructions and accesses its data
- If a process blocks (e.g., due to an I/O call) it doesn't need to be in memory while I/O is running
- That process can be "swapped out" from memory to disk to make room for other processes

• Once process becomes ready again, the OS must reload it in memory

- Once process becomes ready again, the OS must reload it in memory
- Swap in depends on the address binding used:
 - compile- or load-time: must be swapped back into the same memory location from which they were swapped out

- Once process becomes ready again, the OS must reload it in memory
- Swap in depends on the address binding used:
 - compile- or load-time: must be swapped back into the same memory location from which they were swapped out
 - execution-time: can be swapped back into any available location (updating base and limit registers)

- Once process becomes ready again, the OS must reload it in memory
- Swap in depends on the address binding used:
 - compile- or load-time: must be swapped back into the same memory location from which they were swapped out
 - execution-time: can be swapped back into any available location (updating base and limit registers)
- Using swapping, fragmentation can be tackled easily
 - Just run compaction before swapping-in a process

• Swapping is a very slow process compared to other operations due to the interaction with hard disk (more on this later)

• Swapping is a very slow process compared to other operations due to the interaction with hard disk (more on this later)

• Example:

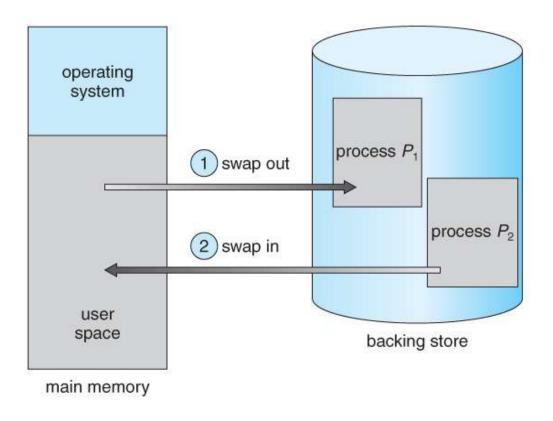
- 10 MB user process
- disk transfer rate = 40 MB/sec (250 msec just to do the data transfer)

• Swapping is a very slow process compared to other operations due to the interaction with hard disk (more on this later)

• Example:

- 10 MB user process
- disk transfer rate = 40 MB/sec (250 msec just to do the data transfer)
- Since swap-in may involve swapping-out another process, the overall time required will be ~ 500 msec

- Swapping is a very slow process compared to other operations due to the interaction with hard disk (more on this later)
- Example:
 - 10 MB user process
 - disk transfer rate = 40 MB/sec (250 msec just to do the data transfer)
- Since swap-in may involve swapping-out another process, the overall time required will be ~ 500 msec
- Time slice is usually way smaller than that!



Most modern OSs no longer use swapping, because it is too slow and there are faster alternatives available (e.g., paging)

Problems Seen So Far

- Contiguous allocation
 - Hard to grow or shrink process memory

Problems Seen So Far

- Contiguous allocation
 - Hard to grow or shrink process memory
- Fragmentation
 - Frequent compaction needed

Problems Seen So Far

- Contiguous allocation
 - Hard to grow or shrink process memory
- Fragmentation
 - Frequent compaction needed
- Process entirely loaded
 - Swapping helps but it may be too inefficient

Paging

• A memory management scheme that addresses the problems above

- A memory management scheme that addresses the problems above
- The logical address space of a process is still **contiguous** but it is divided into **fixed**-size blocks, called **pages**

- A memory management scheme that addresses the problems above
- The logical address space of a process is still contiguous but it is divided into fixed-size blocks, called pages
- Contiguous allocation is no longer required as logical pages can be mapped to noncontiguous physical frames

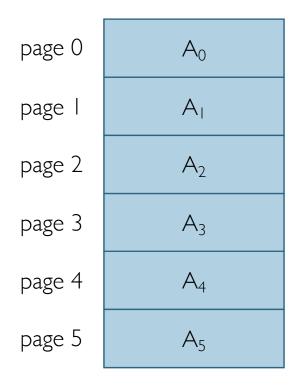
- A memory management scheme that addresses the problems above
- The logical address space of a process is still contiguous but it is divided into fixed-size blocks, called pages
- Contiguous allocation is no longer required as logical pages can be mapped to noncontiguous physical frames
- External fragmentation is eliminated because pages have fixed size
 - Internal fragmentation may still occur though

- A memory management scheme that addresses the problems above
- The logical address space of a process is still contiguous but it is divided into fixed-size blocks, called pages
- Contiguous allocation is no longer required as logical pages can be mapped to noncontiguous physical frames
- External fragmentation is eliminated because pages have fixed size
 - Internal fragmentation may still occur though

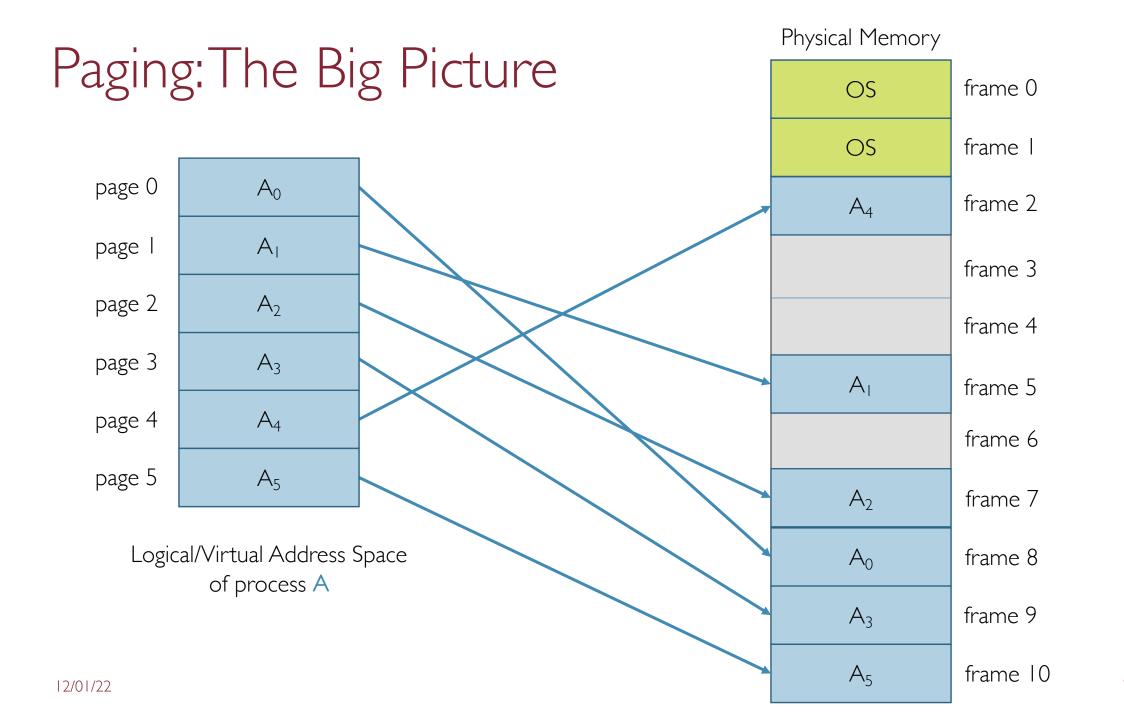
90/10 Rule

Processes spend 90% of their time accessing only 10% of their allocated memory space

Paging: The Big Picture



Logical/Virtual Address Space of process A



Basic OS Responsibilities for Paging

- The OS has 2 main responsibilities:
 - mapping between logical pages and physical frames
 - translating logical addresses to physical addresses

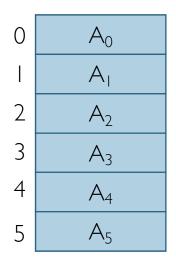
Basic OS Responsibilities for Paging

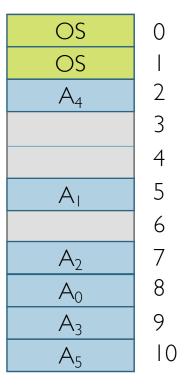
- The OS has 2 main responsibilities:
 - mapping between logical pages and physical frames
 - translating logical addresses to physical addresses
- All of this must be done efficiently!
 - Remember, memory addresses are referenced all the time

Basic OS Responsibilities for Paging

- The OS has 2 main responsibilities:
 - mapping between logical pages and physical frames
 - translating logical addresses to physical addresses
- All of this must be done efficiently!
 - Remember, memory addresses are referenced all the time
- OS needs dedicated support for doing it → Page Table

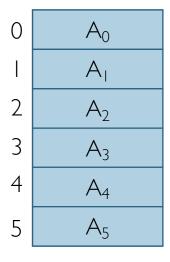
Page Table: Mapping Pages to Frames





Page Table: Mapping Pages to Frames

Lookup table to efficiently retrieve what frame a page is stored in

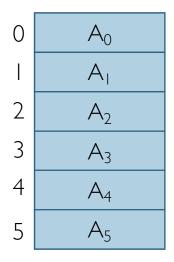


Page	Frame	
0	8	
	5	
2	7	
3	9	
4	2	
5	10	

OS 0 OS 1 A ₄ 2 3 4 A ₁ 5		
OS 1 2 3 4 A 5 6	OS	0
A ₄ 2 3 4 A ₁ 5	OS	I
3 4 A ₁ 5	A_4	2
A ₁ 5		3
A ₁ 5		4
	Aı	5
6		6
A_2 7	A_2	7
A_2 7 8 A_3 9	A_0	8
$ \begin{array}{c cccc} A_2 & 7 \\ A_0 & 8 \\ A_3 & 9 \\ A_5 & 1 \end{array} $	A_3	9
A_5	A_5	1(

Page Table: Mapping Pages to Frames

Lookup table to efficiently retrieve what frame a page is stored in



Page	Frame	
0	8	
	5	
2	7	
3	9	
4	2	
5	10	

OS	0
OS	
A_4	2 3
	3
	4
Aı	5 6
	6
A_2	7 8
A_{2} A_{0} A_{3} A_{5}	8
A_3	9
A_5	10

So far, we have simply assumed all pages of a process is mapped to physical frames, but we will see this is not always the case

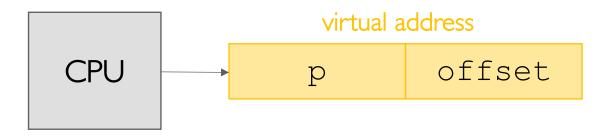
• Processes use virtual (logical) addresses to refer to memory (not page number!)

- Processes use virtual (logical) addresses to refer to memory (not page number!)
- Virtual (logical) address space is still contiguous starting from 0

- Processes use virtual (logical) addresses to refer to memory (not page number!)
- Virtual (logical) address space is still contiguous starting from 0
- Page table must ultimately translate virtual address to physical address

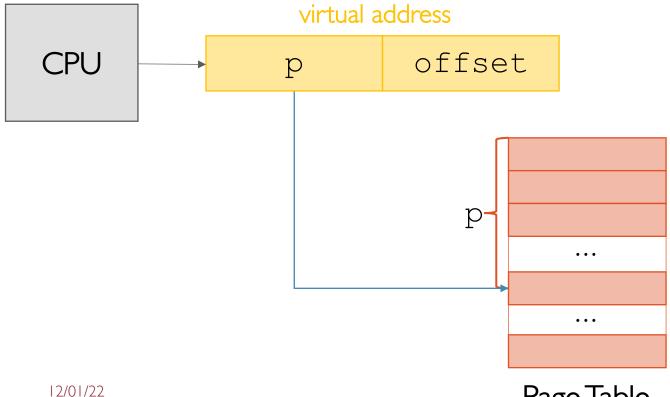
virtual address consists of 2 parts:

- p: page number where the address resides
- offset: relative from the beginning of the page



virtual address consists of 2 parts:

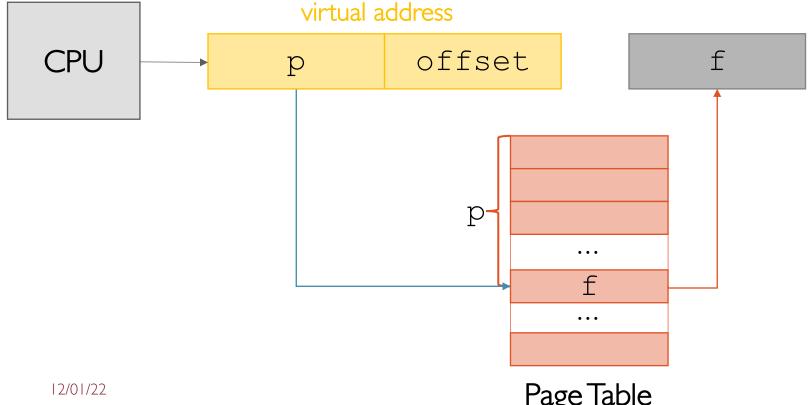
- p: page number where the address resides
- offset: relative from the beginning of the page



89

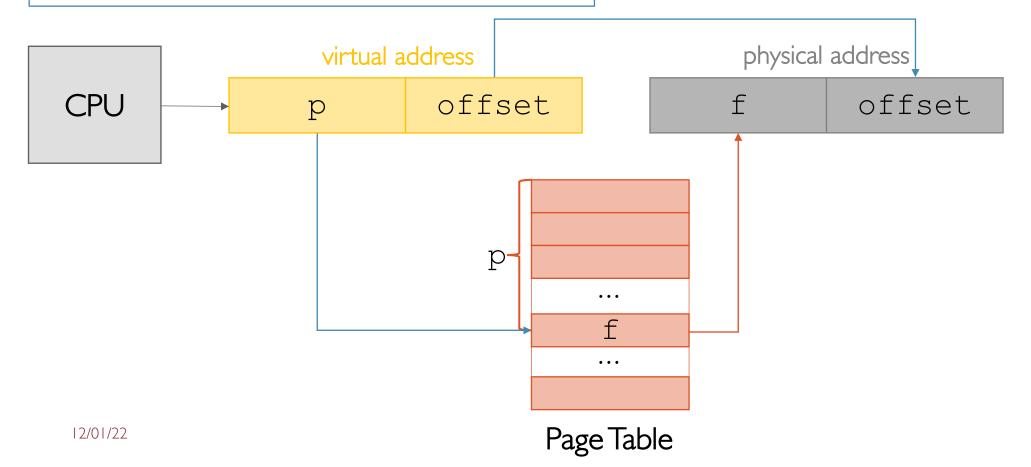
virtual address consists of 2 parts:

- p: page number where the address resides
- offset: relative from the beginning of the page

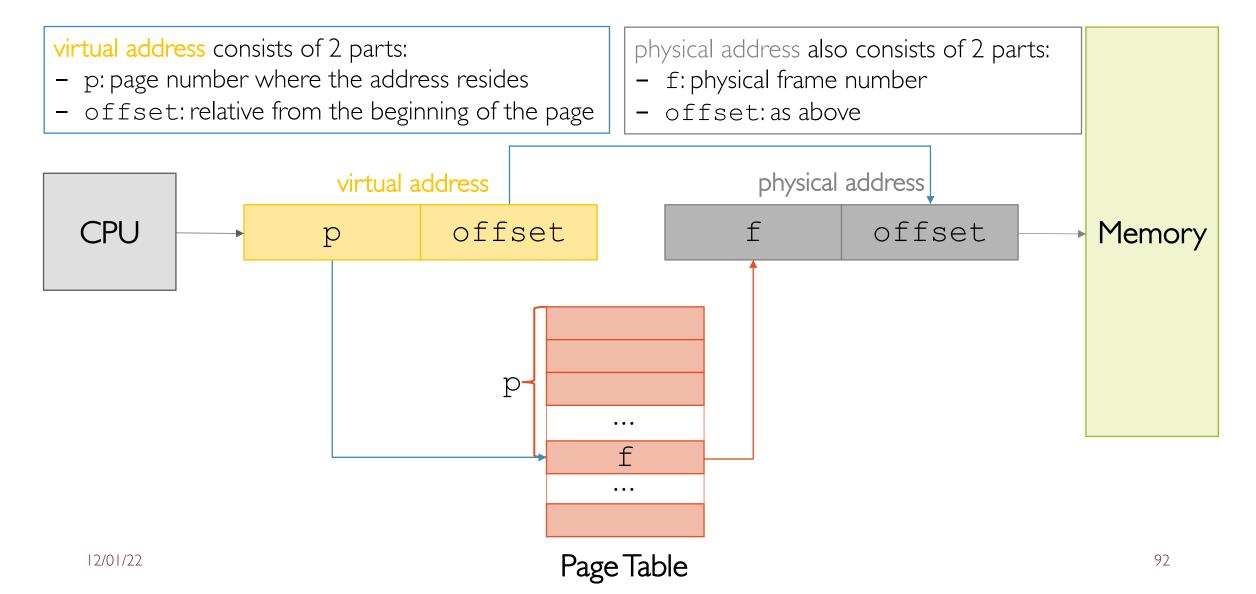


virtual address consists of 2 parts:

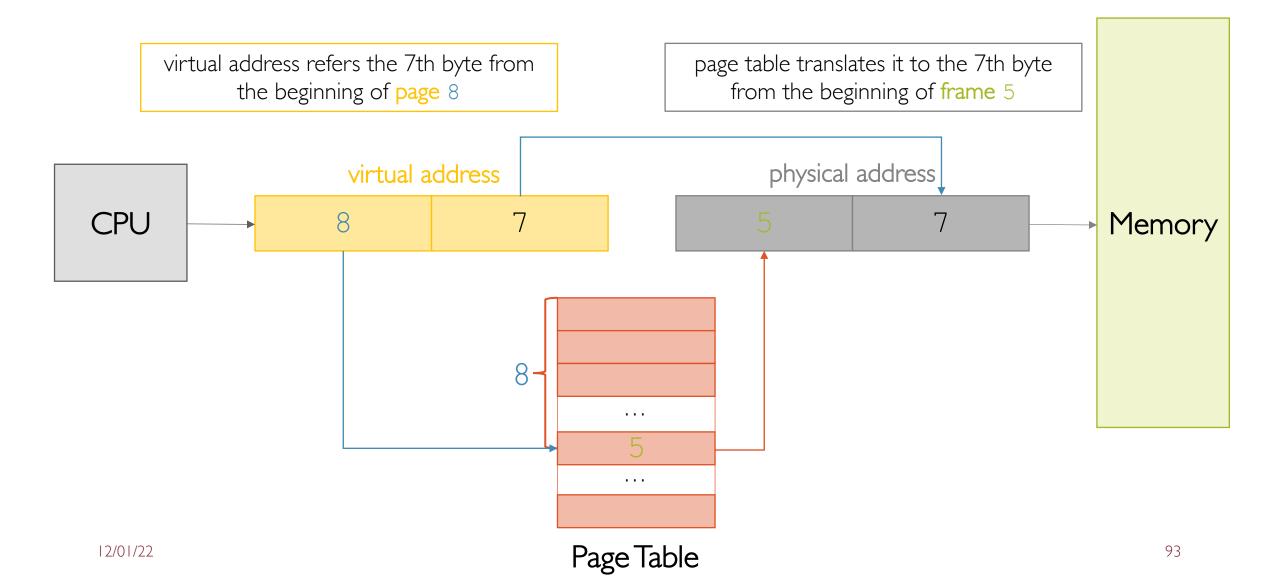
- p: page number where the address resides
- offset: relative from the beginning of the page



91



Page Table: Example of Address Translation



Paging as Dynamic Relocation

- Paging is a form of dynamic relocation
- Each virtual address is bound by the page table to a physical address
- Page table can be seen just as a set of base (relocation) registers, one for each frame
- Mapping is invisible to the user process: the OS maintains the page table and translation happens in hardware
- Protection is provided similarly to dynamic relocation (limit register)

How does page table translate a virtual address **x** into a physical address **y**?

How does page table translate a virtual address **x** into a physical address **y**?

I. Get the page number (\mathbf{p}) and the **offset** where the virtual address \mathbf{x} resides

9

How does page table translate a virtual address **x** into a physical address **y**?

I. Get the page number (\mathbf{p}) and the **offset** where the virtual address \mathbf{x} resides

2. Use **p** to index into the page table to retrieve the frame number **f**

How does page table translate a virtual address **x** into a physical address **y**?

I. Get the page number (\mathbf{p}) and the **offset** where the virtual address \mathbf{x} resides

2. Use \mathbf{p} to index into the page table to retrieve the frame number \mathbf{f}

3. Combine **f** with **offset** to obtain the physical address **y**

Suppose we have **50B** of physical memory available for user processes

Suppose we have **50B** of physical memory available for user processes

Assume we use paging with page (frame) size S = 10B

Suppose we have **50B** of physical memory available for user processes

Assume we use paging with page (frame) size S = 10B

Each process can generate virtual addresses in the range [0, 49]

Suppose we have **50B** of physical memory available for user processes

Assume we use paging with page (frame) size S = 10B

Each process can generate virtual addresses in the range [0, 49]

Suppose a process generates virtual address **x = 27**

Suppose we have **50B** of physical memory available for user processes

Assume we use paging with page (frame) size S = 10B

Each process can generate virtual addresses in the range [0, 49]

Suppose a process generates virtual address **x = 27**

$$p = x div S$$

page number

Suppose we have **50B** of physical memory available for user processes

Assume we use paging with page (frame) size S = 10B

Each process can generate virtual addresses in the range [0, 49]

Suppose a process generates virtual address **x = 27**

$$p = x div S$$

page number

$$p = 27 \frac{div}{10} = 2$$

Suppose we have **50B** of physical memory available for user processes

Assume we use paging with page (frame) size S = 10B

Each process can generate virtual addresses in the range [0, 49]

Suppose a process generates virtual address **x** = **27**

$$p = x div S$$

page number

$$p = 27 \frac{div}{10} = 2$$

offset =
$$x \mod S$$

offset

Suppose we have **50B** of physical memory available for user processes

Assume we use paging with page (frame) size S = 10B

Each process can generate virtual addresses in the range [0, 49]

Suppose a process generates virtual address **x** = **27**

$$p = x div S$$

page number

$$p = 27 div 10 = 2$$

offset =
$$x \mod S$$

offset

offset =
$$27 \mod 10 = 7$$

Suppose we have **50B** of physical memory available for user processes

Assume we use paging with page (frame) size S = 10B

Each process can generate virtual addresses in the range [0, 49]

Suppose a process generates virtual address **x** = **27**

$$p = x div S$$

page number

$$p = 27 div 10 = 2$$

offset =
$$x \mod S$$

offset

offset =
$$27 \mod 10 = 7$$

Paging: Implementation Details

 Page/frame numbers and page/frame sizes are determined by the architecture

Paging: Implementation Details

- Page/frame numbers and page/frame sizes are determined by the architecture
- Page/frame sizes are typically a power of 2, ranging between 5 I 2B and 8 I 9 2B (i.e., 8 KiB)

Paging: Implementation Details

- Page/frame numbers and page/frame sizes are determined by the architecture
- Page/frame sizes are typically a power of 2, ranging between 512B and 8192B (i.e., 8KiB)
- Powers of 2 make the translation from virtual to physical address easy (i.e., no need for **div** and **mod**)

Paging: Implementation Details

- Page/frame numbers and page/frame sizes are determined by the architecture
- Page/frame sizes are typically a power of 2, ranging between 512B and 8192B (i.e., 8KiB)
- Powers of 2 make the translation from virtual to physical address easy (i.e., no need for **div** and **mod**)



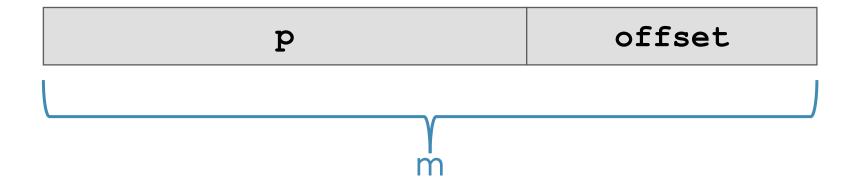
• Virtual address is made of m bits

- Virtual address is made of m bits
 - Then, virtual address space (i.e., the set of bytes addressable by each user process) is 2^m long, and ranges between [0, 2^m-1]

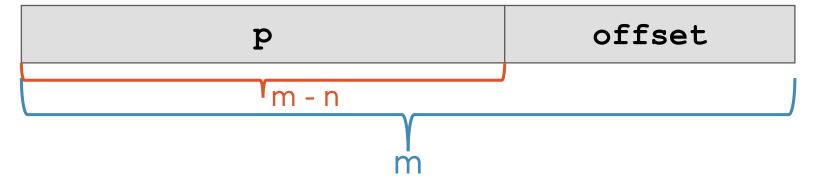
- Virtual address is made of m bits
 - Then, virtual address space (i.e., the set of bytes addressable by each user process) is 2^m long, and ranges between [0, 2^m-1]
- Assume page (frame) size is 2^n , n < m

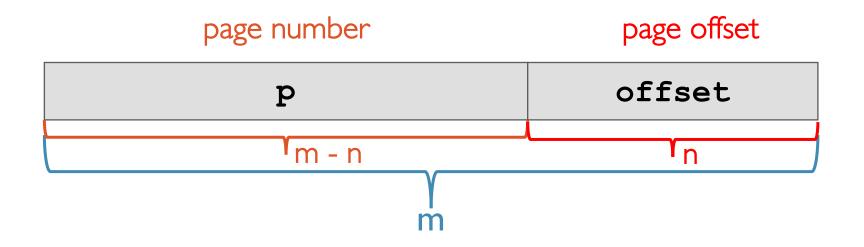
- Virtual address is made of m bits
 - Then, virtual address space (i.e., the set of bytes addressable by each user process) is 2^m long, and ranges between [0, 2^m-1]
- Assume page (frame) size is 2^n , n < m
- The higher m-n bits of the virtual address indicates the page number

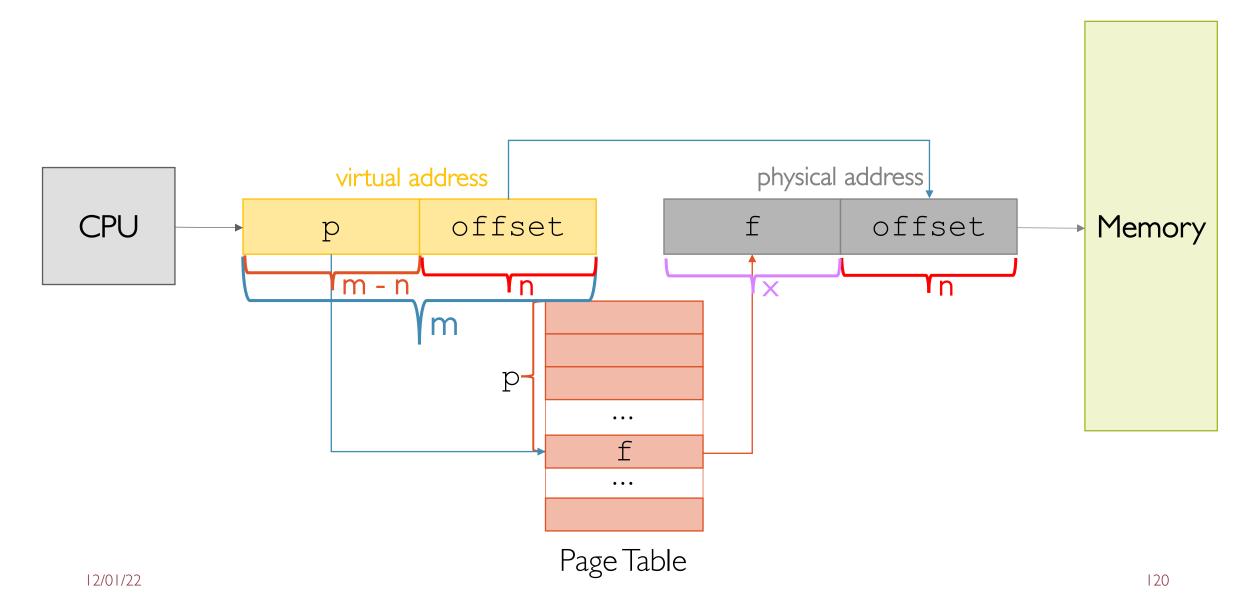
- Virtual address is made of m bits
 - Then, virtual address space (i.e., the set of bytes addressable by each user process) is 2^m long, and ranges between [0, 2^m-1]
- Assume page (frame) size is 2^n , n < m
- The higher m-n bits of the virtual address indicates the page number
- The low order **n** bits represent the **offset**

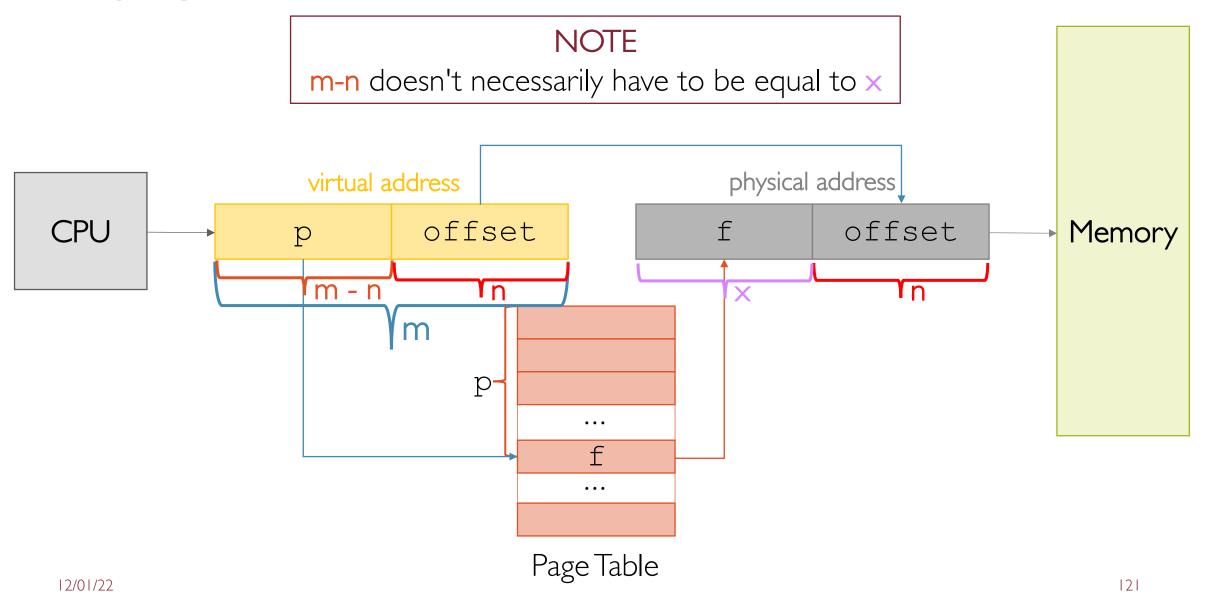


page number









- Typical values of virtual address size is m = 32 or 64 bits
 - That means the virtual address space is $2^{32} = 4GiB$ or $2^{64} = 16EiB$

- Typical values of virtual address size is m = 32 or 64 bits
 - That means the virtual address space is $2^{32} = 4GiB$ or $2^{64} = 16EiB$
- Typical values of page/frame sizes is n = 12 bits
 - That means each page/frame is $2^{12} = 4KiB$

- Typical values of virtual address size is m = 32 or 64 bits
 - That means the virtual address space is $2^{32} = 4GiB$ or $2^{64} = 16EiB$
- Typical values of page/frame sizes is n = 12 bits
 - That means each page/frame is $2^{12} = 4KiB$
- Assuming m = 32 bits, there are $2^{m-n} = 2^{20} = \sim 1$ pages/frames
 - That means page table has 2²⁰ entries (i.e., one for each page/frame)

Suppose we have a virtual memory and a physical memory, both of size M = 1024B (1KiB)

QI

How many bits are needed for a virtual/physical address (assuming single-byte addressing)

Suppose we have a virtual memory and a physical memory, both of size M = 1024B (1KiB)

QI

How many bits are needed for a virtual/physical address (assuming single-byte addressing)

RI

10 bits to address M = 1024 bytes (both for virtual and physical address)

Now, assume we use paging with page/frame size S = I6B

Q2

How big is the page table? (i.e., how many pages/entries does it have to index?)

Now, assume we use paging with page/frame size S = I6B

Q2

How big is the page table? (i.e., how many pages/entries does it have to index?)

R2

T = M / S = 1024 memory bytes / 16 bytes per page = 64 pages

Q3

What is p and offset (i.e., how many bits for p and offset?)

Q3

What is p and offset (i.e., how many bits for p and offset?)

R3

Our logical address is made of m = 10 bits

n = 4 bits are used to represent the offset, as each page/frame is S = 16 bytes m-n = 6 bits are used to represent page number p, as there are T = 64 pages

Q4

Translate the virtual address x = 42, assuming the following page table

page	frame
0	12
1	5
2	37
3	0
63	29

Q4

Translate the virtual address x = 42, assuming the following page table

page	frame
0	12
İ	5
2	37
3	0
63	29

R4

p = x div S = 42 div 16 = 2

Q4

Translate the virtual address x = 42, assuming the following page table

page	frame
0	12
I	5
2	37
3	0
63	29

R4

p = x div S = 42 div 16 = 2

Q4

Translate the virtual address x = 42, assuming the following page table

page	frame
0	12
I	5
2	37
3	0
63	29

R4

$$p = x div S = 42 div 16 = 2$$

offset = x mod $S = 42 mod 16 = 10$
10th byte from the beginning of frame 37

Suppose we still have a virtual memory and a physical memory, both of size M = 1024B

QI

So far, we have assumed that computers work on single-byte (i.e, 8-bit architecture) Modern computers however operate natively on multiple of bytes (i.e., words) rather than single-byte. Typical values of word length is: 16, 32 or 64 bits.

If we assume 32-bit architecture (i.e., word = 32 bits = 4 bytes), virtual addresses refer to words instead of bytes

How many bits are therefore needed to address the number of words available on M?

Suppose we still have a virtual memory and a physical memory, both of size M = 1024B

QI

So far, we have assumed that computers work on single-byte (i.e, 8-bit architecture) Modern computers however operate natively on multiple of bytes (i.e., words) rather than single-byte. Typical values of word length is: 16, 32 or 64 bits.

If we assume 32-bit architecture (i.e., word = 32 bits = 4 bytes), virtual addresses refer to words instead of bytes

How many bits are therefore needed to address the number of words available on M?

RI

8 bits to address M = 1024/4 = 256 4-byte words (both for virtual and physical address)

Now, assume we still use paging with page/frame size S = I6B

Q2

How big is the page table? (i.e., how many pages/entries does it have to index?)

Now, assume we still use paging with page/frame size S = I6B

Q2

How big is the page table? (i.e., how many pages/entries does it have to index?)

R2

T = M / S = 1024 memory bytes / 16 bytes per page = 64 pages

Q3

What is p and offset (i.e., how many bits for p and offset?)

Q3

What is p and offset (i.e., how many bits for p and offset?)

R3

Our logical address is now made of m = 8 bits

n = 2 bits are used to represent the offset, as each page/frame is:

S = 16 bytes = 4 * 4-byte words

m-n = 6 bits are used to represent page number p, as there are still T = 64 pages

Q4

Translate the virtual address x = 7, assuming the following page table

page	frame
0	12
	5
2	37
3	0
63	29

Q4

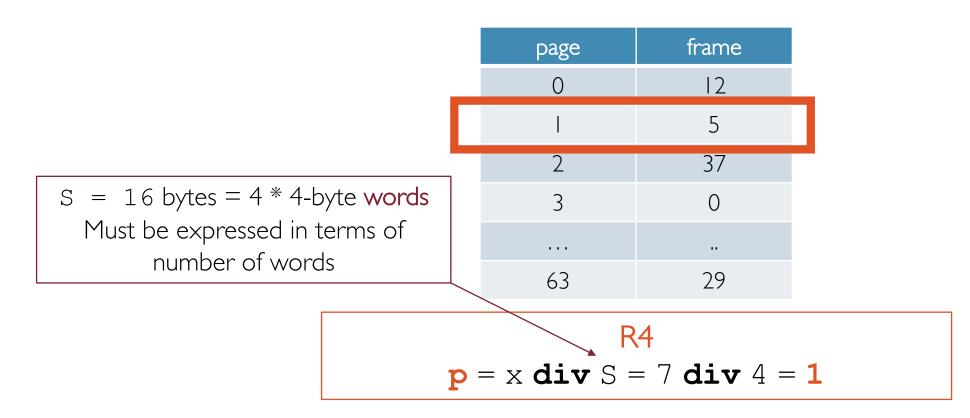
Translate the virtual address x = 7, assuming the following page table

page	frame
0	12
ļ	5
2	37
3	0
63	29

Remember: now virtual address refers to a 4-byte word!

Q4

Translate the virtual address x = 7, assuming the following page table



Q4

Translate the virtual address x = 7, assuming the following page table

page	frame	
0	12	
I	5	
2	37	
3	0	
63	29	

R4

$$p = x div S = 7 div 4 = 1$$
offset = $x mod S = 7 mod 4 = 3$
3rd word from the beginning of frame 5

• Every single time a user process references a (virtual) memory address through the CPU this has to be translated to a physical one

- Every single time a user process references a (virtual) memory address through the CPU this has to be translated to a physical one
- Where should the page table be stored?

- Every single time a user process references a (virtual) memory address through the CPU this has to be translated to a physical one
- Where should the page table be stored?
 - Registers -> PRO: very fast CON: very expensive and limited

- Every single time a user process references a (virtual) memory address through the CPU this has to be translated to a physical one
- Where should the page table be stored?
 - Registers → PRO: very fast CON: very expensive and limited
 - Main Memory → PRO: highest capacity CON: quite slow (every memory translation requires one extra memory access!)

- Every single time a user process references a (virtual) memory address through the CPU this has to be translated to a physical one
- Where should the page table be stored?
 - Registers → PRO: very fast CON: very expensive and limited
 - Main Memory → PRO: highest capacity CON: quite slow (every memory translation requires one extra memory access!)
- Trade-off solution: Translation Look-aside Buffer (TLB)

Appendix: Registers and Main Memory

- All memory accesses are equivalent: the memory hardware doesn't know what a particular part of memory is being used for
- CPU can only access its registers and main memory (any access to other devices, e.g., hard drive, requires data to be moved into main memory first)
- Access to registers is very fast, generally one clock cycle
- Access to main memory is comparatively slow, and may take several clock cycles to complete

Appendix: Cache Memory

- Bridge the gap between fast registers and slower main memory
- Cache Memory: on-chip (thereby, fast!) intermediary memory built into most modern CPUs
- Several chunks of memory transferred from main memory to the cache
- Access individual memory locations one at a time from the cache rather than from memory directly

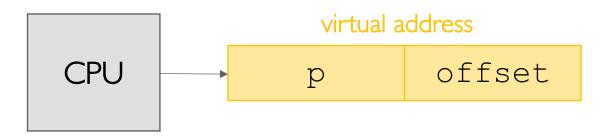
• Essentially, a very fast L1-cache

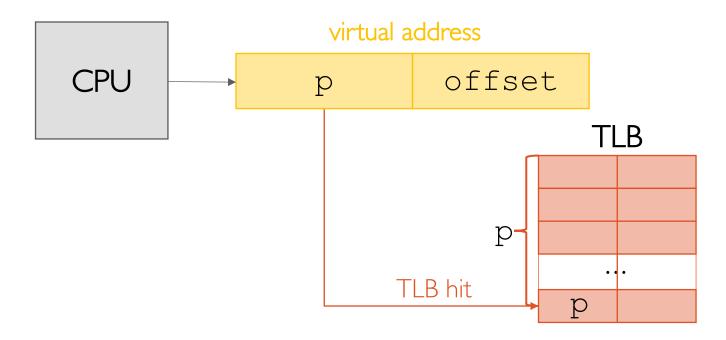
- Essentially, a very fast L1-cache
- Fully-associative memory that stores page numbers (keys) and frame numbers (values) where the former are stored

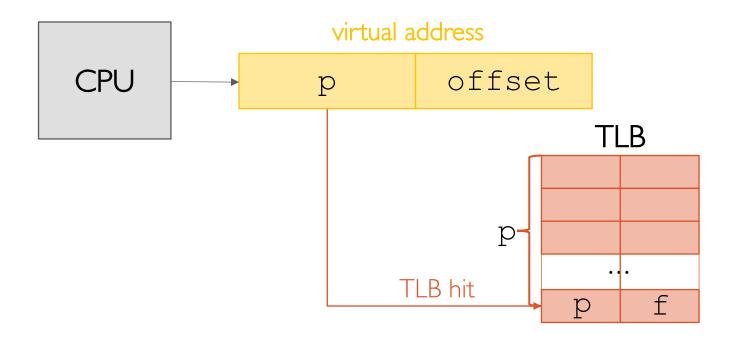
- Essentially, a very fast L1-cache
- Fully-associative memory that stores page numbers (keys) and frame numbers (values) where the former are stored
- Memory accesses obey to the "locality" principle (memory references are often "close" to each other)

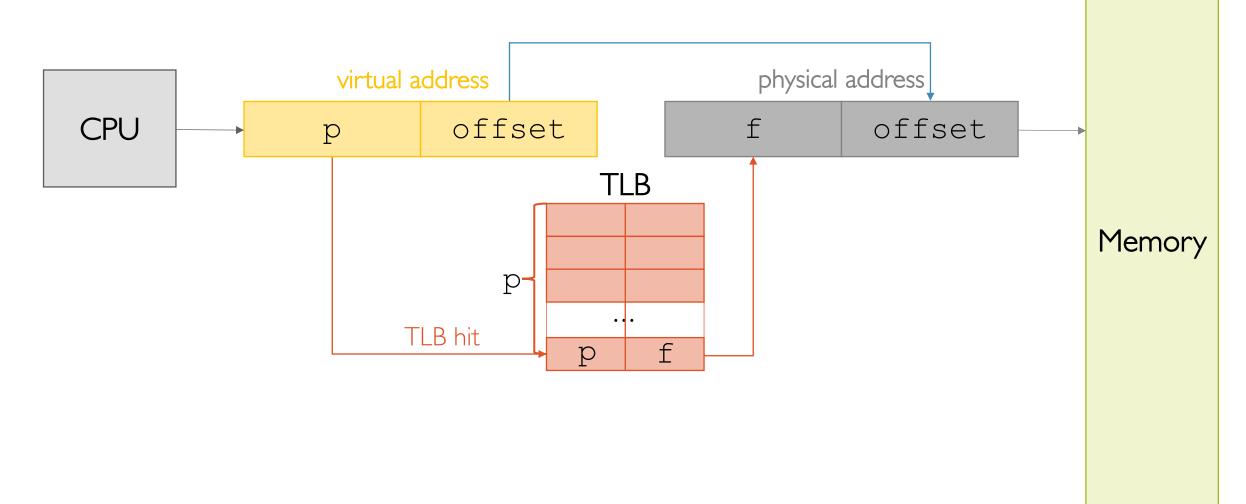
- Essentially, a very fast L1-cache
- Fully-associative memory that stores page numbers (keys) and frame numbers (values) where the former are stored
- Memory accesses obey to the "locality" principle (memory references are often "close" to each other)
- Locality still holds for address translation

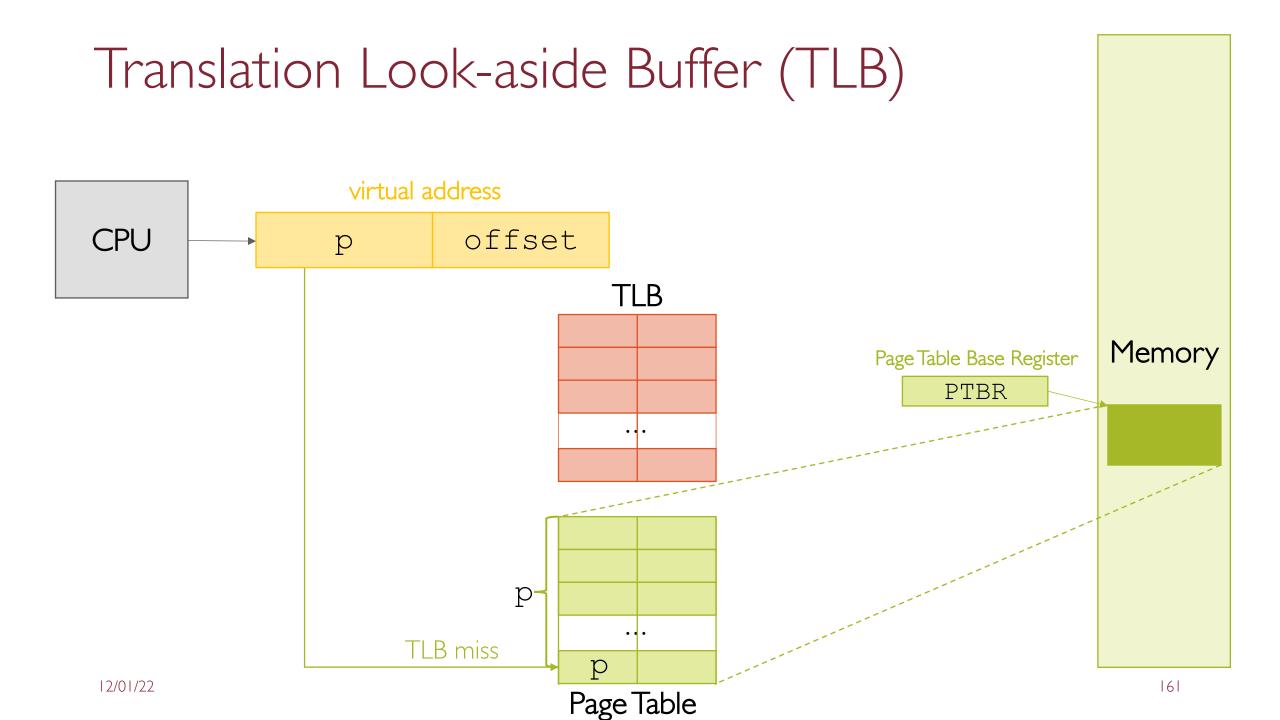
- Essentially, a very fast L1-cache
- Fully-associative memory that stores page numbers (keys) and frame numbers (values) where the former are stored
- Memory accesses obey to the "locality" principle (memory references are often "close" to each other)
- Locality still holds for address translation
- Typical TLB sizes range from 8 to 2048 entries

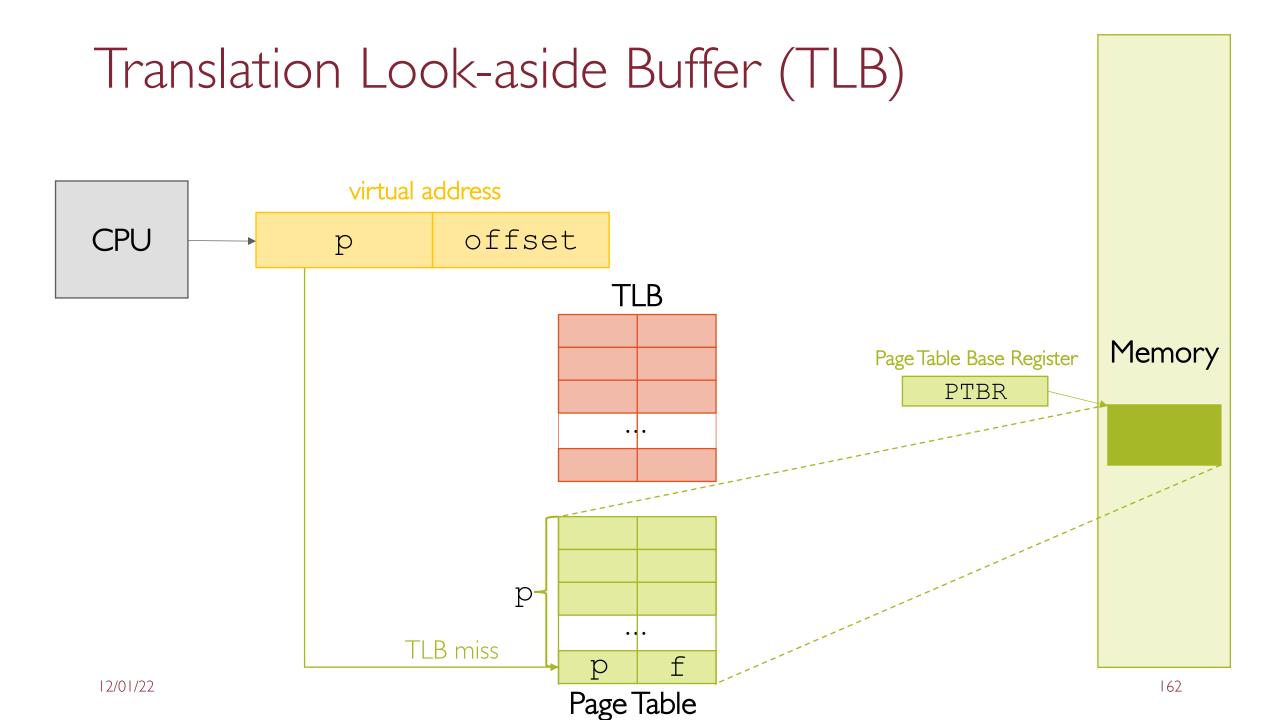


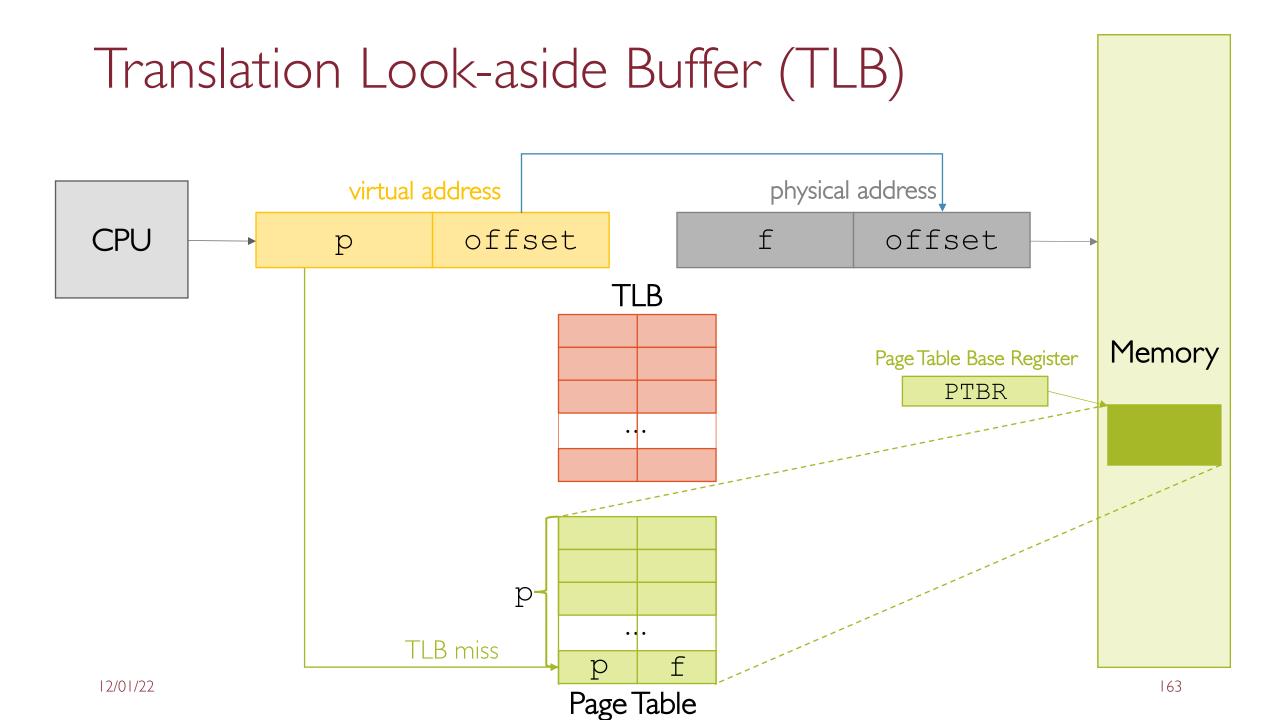


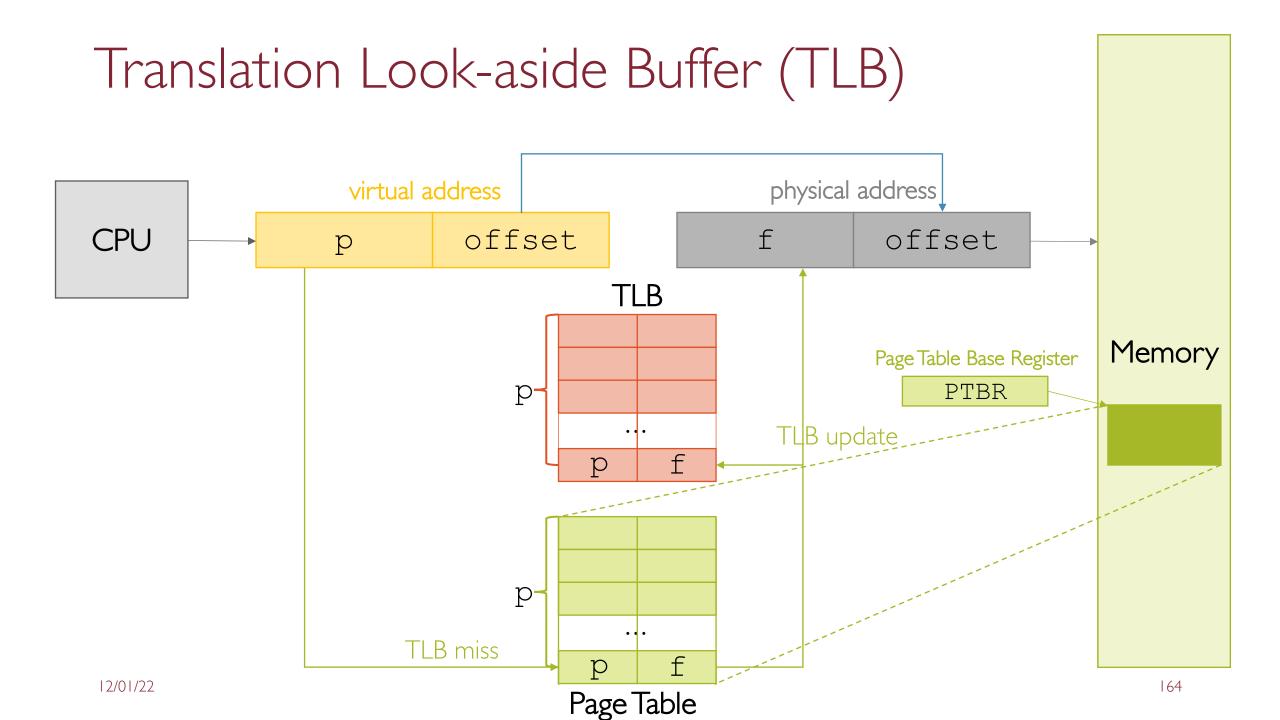












• TLB is a piece of hardware that is shared across all the processes

- TLB is a piece of hardware that is shared across all the processes
- The same page number can be mapped to different frame number depending on the process which is requesting the translation

- TLB is a piece of hardware that is shared across all the processes
- The same page number can be mapped to different frame number depending on the process which is requesting the translation
- How to deal with multiple process and a single TLB? 2 setups:

- TLB is a piece of hardware that is shared across all the processes
- The same page number can be mapped to different frame number depending on the process which is requesting the translation
- How to deal with multiple process and a single TLB? 2 setups:
 - basic: at each context switch the content of the TLB is fully flushed and cleaned (cold-start → the first accesses will generate all TLB misses)

- TLB is a piece of hardware that is shared across all the processes
- The same page number can be mapped to different frame number depending on the process which is requesting the translation
- How to deal with multiple process and a single TLB? 2 setups:
 - basic: at each context switch the content of the TLB is fully flushed and cleaned (cold-start → the first accesses will generate all TLB misses)
 - advanced: TLB entries dumped and restored within the PCB or adding a so-called process context ID (PCID) to each entry (the CPU will use a TLB entry iff the PCID of that entry corresponds to the ID of the running process)

```
t_{MA} = physical memory access time t_{TLB} = lookup time on the TLB cache (NOTE: t_{TLB} \ll t_{MA}) p = probability of TLB cache hit (i.e., hit\ ratio) T_{MA} = total time required to actually get to physical memory each time a virtual address is referenced
```

```
t_{MA} = physical memory access time t_{TLB} = lookup time on the TLB cache (NOTE: t_{TLB} \ll t_{MA}) p = probability of TLB cache hit (i.e., hit\ ratio) T_{MA} = total time required to actually get to physical memory each time a virtual address is referenced
```

without TLB

(i.e., Page Table full in memory)

```
t_{MA} = physical memory access time t_{TLB} = lookup time on the TLB cache (NOTE: t_{TLB} \ll t_{MA}) p = probability of TLB cache hit (i.e., hit\ ratio) T_{MA} = total time required to actually get to physical memory each time a virtual address is referenced
```

without TLB

(i.e., Page Table full in memory)

$$T_{MA} = 2 * t_{MA}$$

```
t_{MA} = physical memory access time t_{TLB} = lookup time on the TLB cache (NOTE: t_{TLB} \ll t_{MA}) p = probability of TLB cache hit (i.e., hit ratio)
```

 T_{MA} = total time required to actually get to physical memory each time a virtual address is referenced

without TLB

(i.e., Page Table full in memory)

$$T_{MA} = 2 * t_{MA}$$

with TLB

 t_{MA} = physical memory access time t_{TLB} = lookup time on the TLB cache (NOTE: $t_{TLB} \ll t_{MA}$) p = probability of TLB cache hit (i.e., hit ratio)

 T_{MA} = total time required to actually get to physical memory each time a virtual address is referenced

without TLB

(i.e., Page Table full in memory)

$$T_{MA} = 2 * t_{MA}$$

with TLB

$$T_{MA} = p*(\underbrace{t_{MA} + t_{TLB}}) + (1-p)*\underbrace{(2*t_{MA} + t_{TLB})}_{\text{TLB miss}}$$

 t_{MA} = physical memory access time t_{TLB} = lookup time on the TLB cache (NOTE: $t_{TLB} \ll t_{MA}$) p = probability of TLB cache hit (i.e., hit ratio)

 T_{MA} = total time required to actually get to physical memory each time a virtual address is referenced

without TLB

(i.e., Page Table full in memory)

$$T_{MA} = 2 * t_{MA}$$

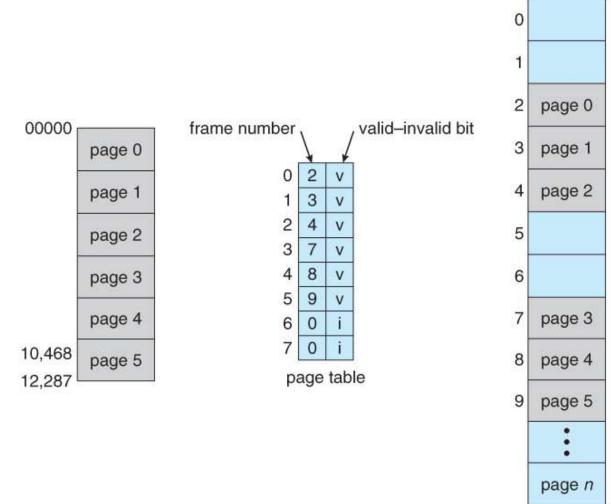
with TLB

$$T_{MA} = p*(\underbrace{t_{MA} + t_{TLB}}) + (1-p)*\underbrace{(2*t_{MA} + t_{TLB})}_{\text{TLB miss}}$$

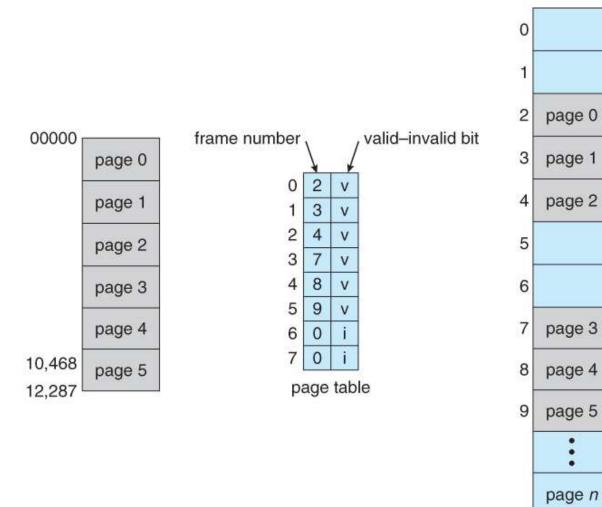
The larger the TLB the higher the probability p of hit ratio, thereby decreasing the average memory access cost

- The page table can also help to protect processes from accessing memory they shouldn't, or their own memory in correct ways
- A bit or bits can be added to the page table to classify a page as readwrite, read-only, read-write-execute, or combination of those
- Each memory reference can be checked to ensure it is accessing the memory in the appropriate mode
- Valid/invalid bits can be added to "mask off" entries in the page table that are not in use by the current process

- valid/invalid bits cannot block all illegal memory accesses, due to the internal fragmentation
- Many processes do not use all of the page table entries available,
 particularly in modern systems with very large potential page tables
- Some systems use a page-table length register (PTLR) to specify the length of the page table



valid/invalid bits can be used to flush TLB entries upon context switch if basic setup is used



valid/invalid bits can be used to flush TLB entries upon context switch if basic setup is used

any entry whose invalid bit is set will be discarded (and updated)

Initializing Memory when Starting a Process

1. Process requests for k pages

- 1. Process requests for k pages
- 2. If *k* frames are free then allocate those to the process, otherwise free frames no longer needed (swapping-out)

- 1. Process requests for k pages
- 2. If *k* frames are free then allocate those to the process, otherwise free frames no longer needed (swapping-out)
- 3. OS puts each page into a frame and sets the corresponding mapping into the page table (in main memory)

- 1. Process requests for k pages
- 2. If *k* frames are free then allocate those to the process, otherwise free frames no longer needed (swapping-out)
- 3. OS puts each page into a frame and sets the corresponding mapping into the page table (in main memory)
- 4. OS marks all previous TLB entries as invalid (i.e., flushes the cache) or restores TLB entries from saved PCB

- 1. Process requests for k pages
- 2. If *k* frames are free then allocate those to the process, otherwise free frames no longer needed (swapping-out)
- 3. OS puts each page into a frame and sets the corresponding mapping into the page table (in main memory)
- 4. OS marks all previous TLB entries as invalid (i.e., flushes the cache) or restores TLB entries from saved PCB
- 5. As process runs, OS loads TLB missed entries possibly replacing existing entries if TLB is full

Saving/Restoring Memory Upon Context Switch

- The PCB must now contain:
 - The value of the Page Table Base Register (PTBR)
 - Possibly a copy of the TLB entries

Saving/Restoring Memory Upon Context Switch

- The PCB must now contain:
 - The value of the Page Table Base Register (PTBR)
 - Possibly a copy of the TLB entries
- On a context switch:
 - Copy the PTBR value to the PCB
 - Copy the TLB to the PCB (optional)
 - Flush the TLB (if TLB is not saved to/restored from the PCB)
 - Restore the PTBR (i.e., with the value of the new running process)
 - Restore the TLB (if it was previously saved)

Sharing Pages

• Paging systems can make it very easy to share blocks of memory, since memory doesn't have to be contiguous anymore

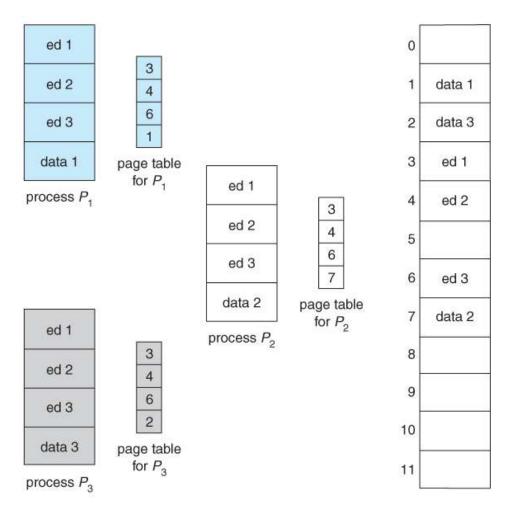
Sharing Pages

- Paging systems can make it very easy to share blocks of memory, since memory doesn't have to be contiguous anymore
- This can be done by simply duplicating page entries of different processes to the same page frames (both for code and data)

Sharing Pages

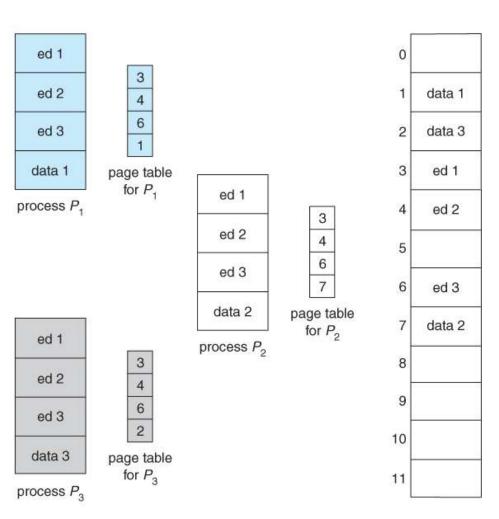
- Paging systems can make it very easy to share blocks of memory, since memory doesn't have to be contiguous anymore
- This can be done by simply duplicating page entries of different processes to the same page frames (both for code and data)
- Only if code is reentrant:
 - it does not write to or change the code (i.e., it is non self-modifying)
 - the code can be shared by multiple processes, as long as each has their own copy of the data and registers, including the instruction register

Sharing Pages: Example



3 user processes are using the editor program ed

Sharing Pages: Example



3 user processes are using the editor program ed

Only a single copy of the code of ed is actually loaded in main memory

Paging: Summary

- A big improvement over relocation
 - Eliminates the problem of external fragmentation and therefore the need for compaction
 - Allows code sharing among processes, reducing memory footprint
 - Enables processes to run when they are partially loaded

Paging: Summary

- A big improvement over relocation
 - Eliminates the problem of external fragmentation and therefore the need for compaction
 - Allows code sharing among processes, reducing memory footprint
 - Enables processes to run when they are partially loaded
- However, paging comes with its costs:
 - Virtual/Physical address translation may be time consuming
 - Hardware support like TLB cache is needed to make it efficient enough
 - OS has to be inevitably more complex