

A New Channel Allocation Scheme for Vehicle Communication Networks

Jing Xu, Wei Li, Zan Ma, and Shuo Zhang

What is this paper about?

Smart roads provide vehicles with updates on traffic, safety warnings and weather conditions. However, being **centralized systems**, they can suffer from issues such as **overloading and single points of failure**.

This paper proposes a **distributed peer-to-peer (car-to-car) communication** scheme that ensures:

- **Crucial and lightweight information** (e.g. car accidents, hazardous weather phenomena) travels on dedicated, interference-free **primary channels**;
- **High-demand information** (e.g. infotainment services) is transmitted on **secondary channels**, dynamically assigned based on each vehicle's needs.

brief, packets with high real-time requirements can be sent in $CH_1(u)$, and much quantity in the $CH_2(u)$.

The Model

Model each car as a circle given by its transmission range and build a (dynamic) intersection graph.

Let's consider the generic node u . As in a labeling problem,

- Any node at distance 1 is a first neighbour
- Any node at distance 2 is a second neighbour

that it has been received by sending ACK from node v to u . $N_1(u)$ denotes nodes which are one hop away from node u , and $N_2(u)$ denotes nodes which are two hops from node u , it is obvious that $u \notin N_1(u)$, $u \notin N_2(u)$. In this paper

We put them together to form the interference set $N(u)$ for node u .

- Bandwidth is divided in K channels, and we assume interference may occur only if two different nodes in a neighborhood use the same channel.

In protocol interference model, $\mathcal{N}(u)$ represents the nodes within two hops away from u , then $\mathcal{N}(u) = N_2(u)$. So it will generate conflicts and interferences if nodes

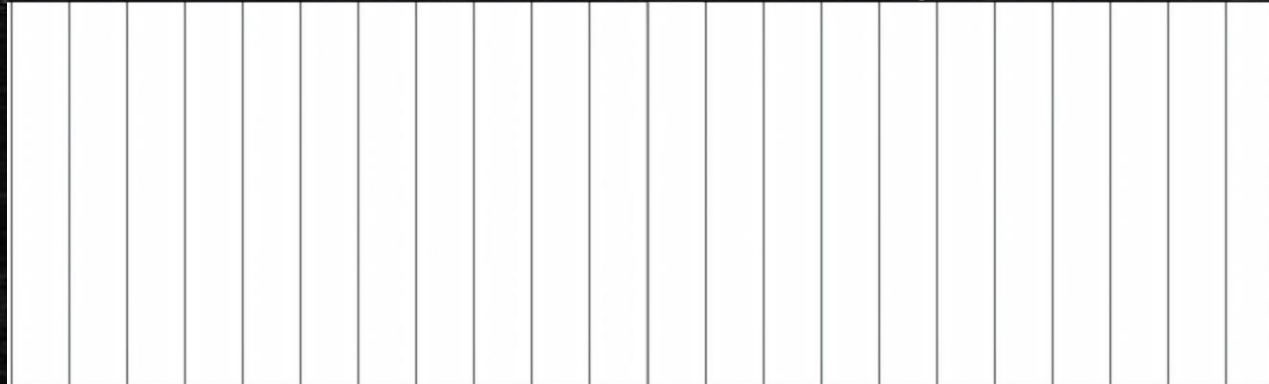
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Conceptual Framework

- Primary channels are found by some raw approximation of $L_{(1,1)}$.
- Secondary channels are then assigned by a greedy algorithm.

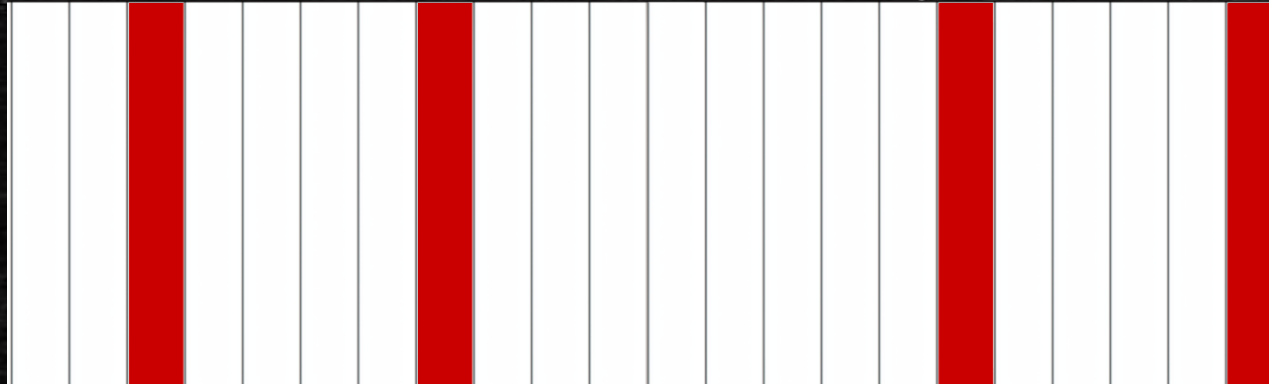
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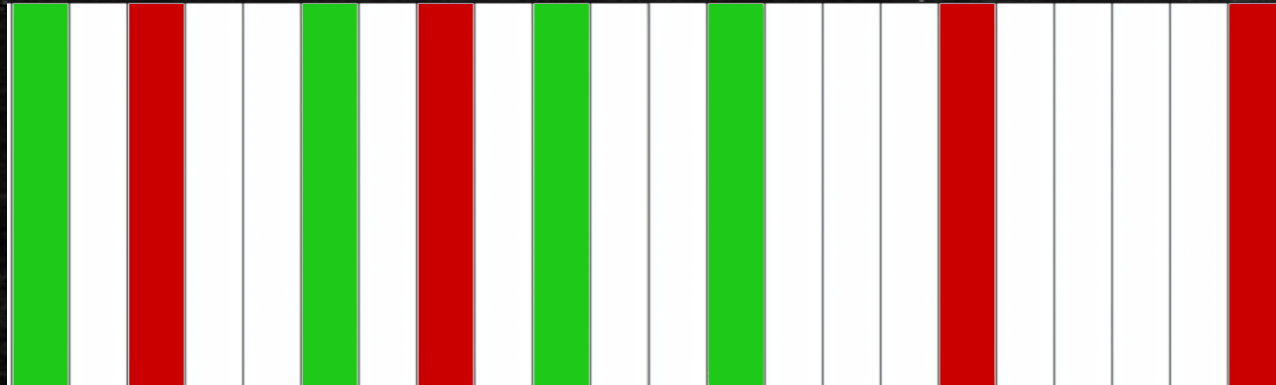
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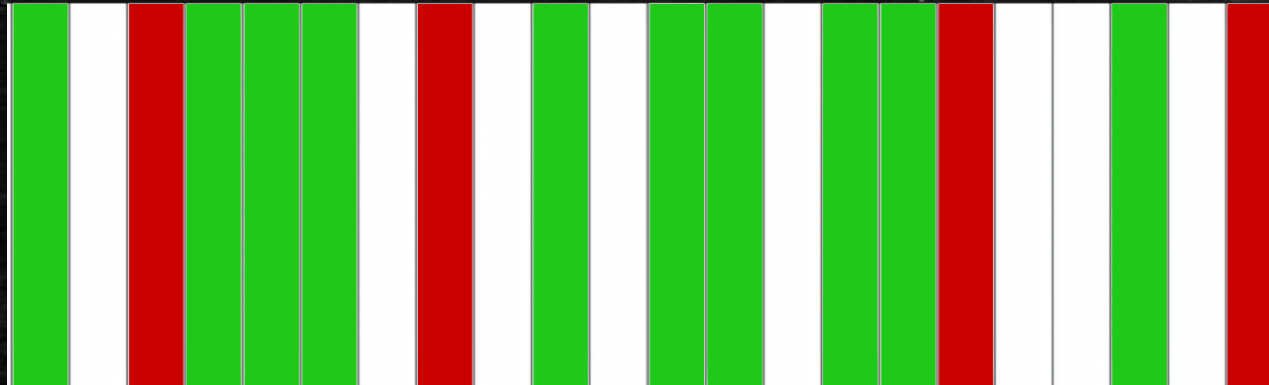
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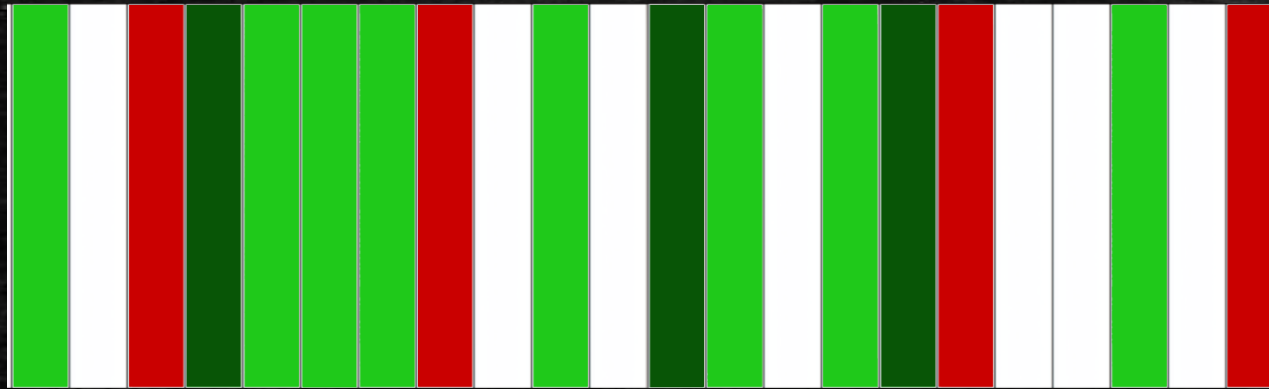
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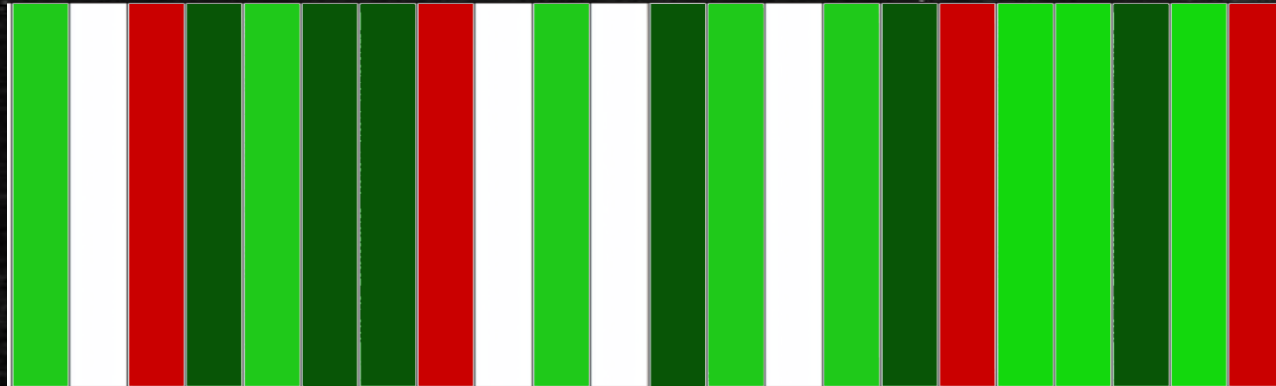
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- **Secondary channels** are then assigned by a **greedy algorithm**.



A single **secondary channel** may be **chosen by more than one node...**

Conceptual Framework

- Primary channels are found by some raw approximation of $L(1, 1)$.
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... while some others may remain unused.

Conceptual Framework

- Primary channels are found by some raw approximation of $L(1, 1)$.
- Secondary channels are then assigned by a greedy algorithm.

If a secondary channel is chosen by more than one node, we perform

Frequency Division Multiplexing (OFDMA)

on that channel, furtherly dividing it into sub-channels.

Tools for choosing the Primary Channels (I)

- Primary channels are found by some raw approximation of $L(1, 1)$.

Suppose to have a κ -bit long vector. We have 2^κ possible words w_i such that if we define the boolean sum as a bitwise OR operation we have that

- $\text{BooleanSum}(w_i, w_j)$ is still a word;
- It may happen that $\text{BooleanSum}(w_i, w_j) = w_i$. We say w_i covers w_j .

Tools for choosing the Primary Channels (II)

Given a set W of binary strings of length κ , the goal of a **Superimposed Code (SC)** is to provide a code (i.e. a set $M \subset W$) that is as robust as possible against coverings (i.e. we build a set of **codewords** that minimize covering phenomena).

It is defined as a triple (s, L, κ) where L and s are integer numbers such that if I sum s codewords in M , the result r will cover at most $L - 1$ codewords among the remaining $|M| - s$.

i.e. there are at most $L - 1$ codewords in the subset $\{M - \{s\}\}$ such that $r \text{ OR } w = r$.

Let N, t, s , and L be integers such that $1 < s < t, 1 \leq L \leq t - s$, and $N > 1$. Given a $N \times t$ binary matrix \mathcal{X} , denote the i th column of \mathcal{X} by $X(i)$, where $X(i) = (x_1(i), x_2(i), \dots, x_N(i))'$. We call $X(i)$ a codeword i of \mathcal{X} with a length N . In other words, \mathcal{X} is a *binary code* with each column corresponding to a codeword.

Suppose $N, t, s, L \in \mathbb{Z}$ satisfies $1 < s < t, 1 \leq L \leq t - s, N - 1$, for a given binary matrix \mathcal{X} with size $N \times t$, the i -th column of \mathcal{X} $X(i) = (x_1(i), x_2(i), \dots, x_N(i))'$ represents a binary code word numbered i . This kind of

Tools for choosing the Primary Channels (III)

- L is called Reliability (or Overlap Bound). Why?
- Choosing big values of L means admitting several coverages.

$L = |M| - s + 1$ means admitting the coverage of at most the whole complementary set.

Computationally easy, but useless.

- The optimal value is $L = 1$. (no codeword in the complementary set is ever covered). Such a Superimposed Code is called s -disjunctcode, and from now on we will assume to be given such a code.

(?)

The SC code where $L = 2$ also called $s - disjunct$

Tools for choosing the Primary Channels (IV)

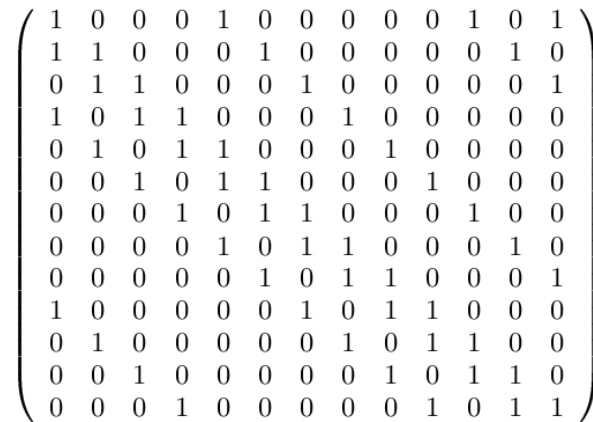
- s is called Strength. Why?
 - Choosing small values of s means that the sum of "few" codewords will cover at most one codeword among the remaining "many";
 - Choosing big values of s means that the sum of "many" codewords will cover at most one codeword among the remaining "few".
- $s = |M| - 2$ means that the sum of all the codewords but two will cover at most one of the remaining 2 codewords in the complementary set.

Tools for choosing the Primary Channels (V)

LEMMA 4.1. *Given an $(s, 1, N)$ superimposed code \mathcal{X} , for any s -subset of the codewords of \mathcal{X} , there exists at least one row at which all codewords in the s -subset contains the value 0.*

PROOF. For contradiction we assume that there is no row at which all codewords in the s -subset contain a common value 0. Then the Boolean sum of the s codewords equals $(1, 1, \dots, 1)'$, which can cover all other codewords in \mathcal{X} , contradicting to the fact that \mathcal{X} is a superimposed s -disjunct code. \square

Tools for choosing the Primary Channels (VI)



1	0	0	0	1	0	0	0	0	0	1	0	1
1	1	0	0	0	1	0	0	0	0	0	1	0
0	1	1	0	0	0	1	0	0	0	0	0	1
1	0	1	1	0	0	0	1	0	0	0	0	0
0	1	0	1	1	0	0	0	1	0	0	0	0
0	0	1	0	1	1	0	0	0	1	0	0	0
0	0	0	1	0	1	1	0	0	0	1	0	0
0	0	0	0	1	0	1	1	0	0	0	1	0
0	0	0	0	0	1	0	1	1	0	0	0	1
1	0	0	0	0	0	1	0	1	1	0	0	0
0	1	0	0	0	0	0	1	0	1	1	0	0
0	0	1	0	0	0	0	0	1	0	1	1	0
0	0	0	1	0	0	0	0	0	1	0	1	1

Figure 1: An example of a superimposed $(3, 1, 13)$ -code of size 13

Xing et al - Channel Assignment via Superimposed Code (2007)

A $(3, 1, 13)$ -code is a 3-disjunct code, meaning you can sum any subset of up to $s=3$ columns of length $N=13$ and be sure the sum won't cover any of the remaining $t-s = 13-3 = 10$ codewords.

$N=t$ is not by chance: for small s w.r.t. N , we tend to have t proportional to N .

Choosing the Primary Channels (I)

- First, we equip every node in the network with an **s-disjunct code** \mathcal{X} . We set the length K of the codeword equal to the number of orthogonal channels k_i ;
- A generic node u randomly selects a codeword $\mathcal{X}(u) = \vec{c}_u$ from the $|\mathcal{X}|$ available options, e.g.

$$\vec{c}_u = (100100101 \dots)$$

- The element $\vec{c}_u(i)$ represents channel k_i . Specifically, $k_i = 1$ means that k_i is a candidate to become the primary channel $\text{CH}_1(u)$ for node u ;
- Each node broadcasts its pair $\{\text{ID (e.g. a MAC Address)}, \vec{c}_u\}$, and forwards the pairs of its neighbors so that every neighbor reaches its whole neighborhood.
 - It's more or less like a broadcast with $\text{TTL} = 2$.
- At this point, each node u knows the ID and the codeword chosen by every node in its neighborhood, which forms its **interference set** $\mathcal{N}(u)$, i.e., the nodes that must choose disjoint CH_1 to avoid mutual interference (i.e. a labeling $L(1, 1)$).

Choosing the Primary Channels (II)

- It then calculates two elements:
 - $\text{BoolSum}(\mathcal{X}(\mathcal{N}(u) \cup u))$ - All possible CH_1 in the neighborhood, **including** u ;
 - $\text{BoolSum}(\mathcal{X}(\mathcal{N}(u)))$ - All possible CH_1 in the neighborhood, **excluding** u .
- Finally, the list of channels $\text{CH}_1(u)$ is obtained from the **XOR** of these two

$$\text{BoolSum}(\mathcal{X}(\mathcal{N}(u) \cup \{u\})) \oplus \text{BoolSum}(\mathcal{X}(\mathcal{N}(u)))$$

Or, in a simpler way,

$$\mathcal{X}(u) \text{ AND } (\text{NOT } \text{BoolSum}(\mathcal{X}(\mathcal{N}(u))))$$

How can we be sure we'll find at least one CH_1 ?

How do we know CH_1 will be non-empty?

Choosing the Primary Channels (III)

Lemma 1. *If $s \geq |\mathcal{N}(u)|$ and $\mathcal{N}(u)$ is the complete set of interferers of u for any node, the $CH_1(u)$ exists surely.*

Proof. Since \mathcal{X} is an s -disjunct code, $BoolSum(\mathcal{X}(\mathcal{N}(u)))$ does not cover $\mathcal{X}(u)$, which means that there exists at least one row in \mathcal{X} at which $\mathcal{X}(u)$ has the value 1 and all $\mathcal{X}(\mathcal{N}(u))$ have the value 0. Therefore the conclusion $CH_1(u) \neq \emptyset$ holds.

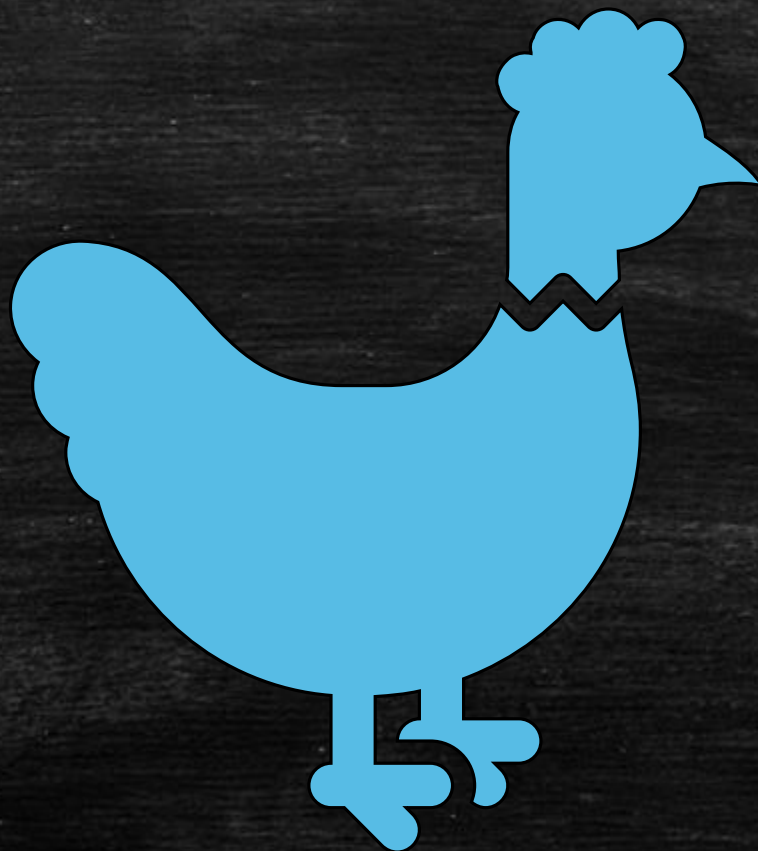
Xu et al - A New Channel Allocation Scheme
for Vehicle Communication Networks (2014)

THEOREM 5.2. *If $s \geq |\mathcal{N}(u)|$ and $\mathcal{N}(u)$ is the complete set of interferers of u for $\forall u$ in G , the channel assignment based on Algorithm 1 guarantees interference free communications in the network.*

PROOF. Since \mathcal{X} is an s -disjunct code, $BoolSum(\mathcal{X}(\mathcal{N}(u)))$ does not cover $\mathcal{X}(u)$, which means that there exists at least one row in \mathcal{X} at which $\mathcal{X}(u)$ has the value 1 and all $\mathcal{X}(\mathcal{N}(u))$ have the value 0 (see Lemma 4.1). Therefore condition $CH_1(u) \neq \emptyset$ holds. Based on Theorem 5.1, the claim holds. \square

Xing et al - Channel Assignment via Superimposed Code (2007)

Uhm...





A New Channel Allocation Scheme for Vehicle Communication Networks

Jing Xu, Wei Li, Zan Ma, and Shuo Zhang (2014)

... also known as...

Superimposed Code Based Channel Assignment in Multi-Radio Multi-Channel Wireless Mesh Networks

Kai Xing, Xiuzhen Chen, Liran Ma, Qilian Liang (2007)



Just another meme, then we get back to work

"can I copy your homework?"

"yeah just change it up a bit so it doesn't look obvious you copied"

"ok"

Superimposed Code Based Channel Assignment in Multi-Radio Multi-Channel Wireless Mesh Networks

Kai Xing, Xuuzhen Cheng & Liran Ma
Department of Computer Science
The George Washington University
Washington, DC 20052, USA
{kai.xing,cheng,lirma}@gwu.edu

Qilian Liang
Department of Electrical Engineering
The University of Texas at Arlington
Arlington, TX 76019, USA
liang@uta.edu

ABSTRACT

Motivated by the observation that channel assignment for multi-radio multi-channel mesh networks should support both unicast and local broadcast, should be interference-aware, and should result in low overall switching delay, high throughput, and low overhead, we propose two flexible localized channel assignment algorithms based on s -disjoint superimposed codes. These algorithms support the local broadcast and unicast effectively, and achieve interference-free channel assignment under certain conditions. In addition, under the primary interference constraints, the channel assignment algorithm for unicast can achieve 100% throughput with a simple scheduling algorithm such as the maximal weight independent set scheduling, and can completely avoid hidden exposed terminal problems under certain conditions. Our algorithms make no assumptions on the underlying network and therefore are applicable to a wide range of MR-MC mesh network settings. We conduct extensive theoretical performance analysis to verify our design.

Categories and Subject Descriptors

C.2.1 Network Architecture and Design: Wireless Communication

General Terms

Algorithms, Design

Keywords

Multi-radio multi-channel wireless mesh networks, interference, channel assignment, superimposed codes

[†]A broadcast to be heard by all immediate neighbors.

[‡]Under the primary interference constraints, the channel assignment algorithm for unicast can achieve 100% throughput with a simple scheduling algorithm such as the maximal weight independent set scheduling, and can completely avoid hidden exposed terminal problems under certain conditions.

A New Channel Allocation Scheme for Vehicle Communication Networks

Jing Xu, Wei Li, Zan Ma, and Shuo Zhang

University of Science and Technology of China, Anhui, China 230027
{jxu128,wei11011,sa612135,zshuo}@mail.ustc.edu.cn

Abstract. In roadway networks, the timely, reliable, and high-throughput transmission is particularly important to vehicles, e.g., for roadway safety warning applications. However, it is difficult to achieve these goals at the same time in vehicle-to-vehicle communications due to mobility, interference, etc. In this paper, we tackle this issue and propose a new channel allocation scheme based on OFDM(Orthogonal frequency-division multiplexing). Our design can achieve highly reliable transmission through dynamically allocated interference free channels demanding on timeliness, and high throughput through secondary channels for information transmission insensitive to timeliness. In our evaluation study, the results show that our scheme can provide a guarantee for reliable and high-throughput transmission.

Keywords: vehicle networks, channel allocation, reliability.

1 Introduction

With the increasing demand on high-data-rate wireless communication services, the bandwidth allocation design is expected to accommodate more users and support higher data rate on the guarantee of the quality of service. OFDMA is one of such communication systems. However, most existing OFDMA schemes are centralized and meet difficulties to satisfy users' requirements in vehicle net-

... and they did change it! Only, for way worse.

Primary Channels (Xu et al, 2014)

Algorithm 1. A distributed wireless channel allocation scheme for vehicle networks

Input: The initial information of each node u : C , $ChEstimate(u)$, $N_1(u)$, $NumCh(u)$, $R(u)$, $Rate(u)$.

Output: Each node u chooses its primary channel $CH_1(u)$ to send important information and the channel set $CH_2(u)$ to deliver large amounts of packets.

step 1: Each node broadcasts its ID and forward the received neighbor ID once, thus everyone will get the $\mathcal{N}(u)$.

step 2: $\forall u \in V$, $CH_1(u) = Channels(BoolSum(\mathcal{X}(\mathcal{N}(u) \cup \{u\}))) \oplus BoolSum(\mathcal{X}(\mathcal{N}(u)))$

▷ find the primary channels for u , and secondary channels for $\mathcal{N}(u)$, then choose one to be the $CH_1(u)$.

Like we said, **every node broadcasts its ID** (i.e. its codeword) with TTL = 2.

Then, every u is able to perform the **XOR operation** to find the channels which are primary to u and not primary to any neighbor.

But **this works only if we have at most s neighbors**.

What if we happen to have more?

Primary Channels (Xing et al, 2007)

Here the idea is the following: **we don't know if the number of neighbors is lesser or equal than s** . If that's not the case, we're not sure to find CH_1 as we discussed so far.

In case this first approach fails, **u may look for secondary channels** which are secondary also to all its neighbors.

In case this second approach also fails, rely on the "**lesser evil**" choosing the "**least-interference channel**"

Algorithm 1 Channel Assignment for Node u

Input: Codewords $X(u)$ and $\mathcal{X}(\mathcal{N}(u))$.

Output: $CH(u)$, the set of channels assigned to u .

```
1: function  $CH(u) = \text{ChannelSelect}(X(u), \mathcal{X}(\mathcal{N}(u)))$ 
2:    $CH_1(u) \leftarrow \text{Channels}(\text{BoolSum}(\mathcal{X}(\mathcal{N}(u) \cup \{u\})) \oplus$ 
       $\text{BoolSum}(\mathcal{X}(\mathcal{N}(u))))$   $\triangleright$  Find the set of primary channels
      that are secondary to all nodes in  $\mathcal{N}(u)$ .
3:   if  $CH_1(u) \neq \emptyset$  then
4:      $CH(u) \leftarrow CH_1(u)$ 
5:   else
6:      $CH_2(u) \leftarrow \text{Channels}(\overline{\text{BoolSum}(\mathcal{X}(\mathcal{N}(u) \cup \{u\}))})$   $\triangleright$ 
      Find the set of secondary channels that are secondary to
      all nodes in  $\mathcal{N}(u)$ .
7:     if  $CH_2(u) \neq \emptyset$  then
8:        $CH(u) \leftarrow CH_2(u)$ 
9:     else
10:       $CH_3(u) \leftarrow \text{Select Channels}(X(u))$  with the smallest
        row weight in  $\mathcal{X}(\mathcal{N}(u))$   $\triangleright$  Select the primary
        channels with the least row weight in  $\mathcal{N}(u)$ .
11:       $CH(u) \leftarrow CH_3(u)$ 
12:    end if
13:  end if
14: end function
```


Primary Channels (Xing et al, 2007)

Lemma 2. *If the channel set u 's first choice $CH_1(u) \neq \emptyset$, then u has no interference with its two-hop neighbor $\mathcal{N}(u)$.*

Proof. Given that $CH_1(u) \neq \emptyset$, node u picks a channel $\alpha \in CH_1(u)$. And we know that from lemma 1 in the \mathcal{X} , on the α th row,

$$\mathcal{X}(\alpha, u) = 1, \text{ but } \mathcal{X}(\alpha, \mathcal{N}(u)) = 0 \quad (\forall v \in \mathcal{N}(u))$$

In other word, the channel α is primary to u , and secondary to $\mathcal{N}(u)$. So node u can pick up a channel α from $CH_1(u)$, which will not be in interference with $\mathcal{N}(u)$.

LEMMA 5.1. *If $CH_1(u) \neq \emptyset$, node u does not interfere with any other node in $\mathcal{N}(u)$.*

PROOF. When $CH_1(u) \neq \emptyset$, node u picks up channels from $CH_1(u)$, a subset of u 's primary channel set, for transmission. $CH_1(u)$ contains channels that are primary to u but secondary to all nodes in $\mathcal{N}(u)$. For $\forall v \in \mathcal{N}(u)$, v can't use any channel from $CH_1(u)$ based on Algorithm 1 since v is assigned with either its own primary channels (from $CH_1(v)$ or $CH_3(v)$), which can't be in $CH_1(u)$, or channels that are secondary to all interferers in $\mathcal{N}(v)$ ($CH_2(v)$), which are secondary to u too since $u \in \mathcal{N}(v)$. \square

Some of the phrases and theorems that made no sense in Xu et al (2014) suddenly become clear in the framework given by Xing et al (2007).

What about the Secondary Channels?

Weren't we supposed to assign some secondary channels via some greedy algorithm?

Glad you asked.

Xing et al (2007) never mentions such an assignment, so this must be some original work.

It is. And it makes no sense.

```
step 3:  $\forall u \in V, AvailableCH(u) = C - \sum_{v \in (\{u\} \cup \mathcal{N}(u))} CH_1(v)$ . ( $C$  represents the whole channel set)
step 4:  $\forall u \in V, Priority(u) = \frac{R(u)}{Rate(u)}$ , and send it to their  $\mathcal{N}(u)$ .
step 5:  $\forall u \in V, Sort(Priority(v)), v \in (u \cup \mathcal{N}(u))$ , thus we can get each node  $u$ 's priority order  $Seq(u)$  among the nodes in  $\mathcal{N}(u)$ .
step 6:  $Token = 1$ ;
step 7:  $\forall u \in V$ , if  $Seq(u) == Token$ :  $CH_2(u) =$  the highest  $NumCh(u)$  channels on the value of  $Estimate(u)$  among the  $Available(u)$ .

        if  $|CH_2(u)| < NumCh(u)$ 
        then  $Priority(u)$  Add endif
         $Token = Token + 1$  endif.
step 8: if there exists any node  $u$  which has not been involved in the allocation scheme, turn to step 7;
        else break;
```


Choosing the Secondary Channels (I)

In brief, the idea behind the assignment is the following.

Every node has an idea of its throughput needs and of its transmission speed. Based on this, we can compute a *Priority* value for choosing the **best secondary channels** among the available ones.

The evaluation of the "best" is based on **some metrics** given by a function called *ChEstimate* (or sometimes, randomly, just *Estimate*).

Then, we initialise a global variable named *Token* and we loop over all the possible nodes u of the graph. Each node loops over *Token*, so that when the *Sequence* value (computed by means of *Priority*) is equal to the *Token* I can choose the best channels available. Somehow, it may happen that a node can't get enough channels. In this case, we just *Priority Add* (whatever it means, since it's the only occurrence in the whole paper). Even though this should be the core operation

Choosing the Secondary Channels (II)

... let's say it has a bunch of problems.

Half of the functions are never defined (e.g. $NumCh$, $ChEstimate$).

Being a global variable, $Token$ makes this a centralized algorithm, instead of a distributed one (moreover, it lacks the typical synchronization mechanisms of distributed systems, like ACKs).

It is unclear how " $CH_2(u)$ = the highest $NumCh(u)$ channels on the value of $Estimate(u)$ among the $Available(u)$ " and then " $if |CH_2(u)| < NumCh(u)$ ".

It is unclear how " $Priority(u) Add$ ". It's not even used in the loop.

OFDMA is never even mentioned but in the Introduction and in the Conclusions.

Choosing the Secondary Channels (III)

If we go back to Xing et al (2007), like we said, there's no such an assignment.

By Occam's Razor, we simply don't assign the secondary channels. Each node can rely on them for transmissions of lesser importance (e.g. infotainment), accepting the risk of interference.

At least, as long as no one provides A New Channel Allocation Scheme for Vehicle Communication Networks.

Conclusions

A simple, light and distributed scheme for finding an **approximate solution to the L(1,1) interference-free primary channel assignment** is achieved by means of an **s-disjunct code** respecting some further conditions.

Secondary channels for high throughput transmissions **have to deal with some interference**.

One should always **check the References** if something looks weird.

Since 41.59 is "very close" to 40, Xu et al's conclusions are "correct and realistic".

Actually, we make a statistics about the real probability on the Section 5. In our experiment, $K = 13$, $\mathcal{N}(u) = 4$, so the probability $\frac{K(K-1)\dots(K-\mathcal{N}(u))}{K^{\mathcal{N}(u)+1}} = 41.59\%$. The practical result is 40%, which proves our conclusion is correct and realistic.

about 40% (the theoretical probability) and the value 41.59% is very close to 40%, the best channel to send information. In other