

- 1) A set of drones that want communicate with the depot
- 2) The depot allocate bandwidth to the drone at each timestamp.









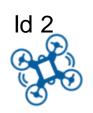






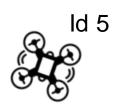


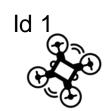
- 1) A set of drones that want communicate with the depot
- 2) The depot allocate bandwidth to the drone at each timestamp (**Time Slotted** Channel).











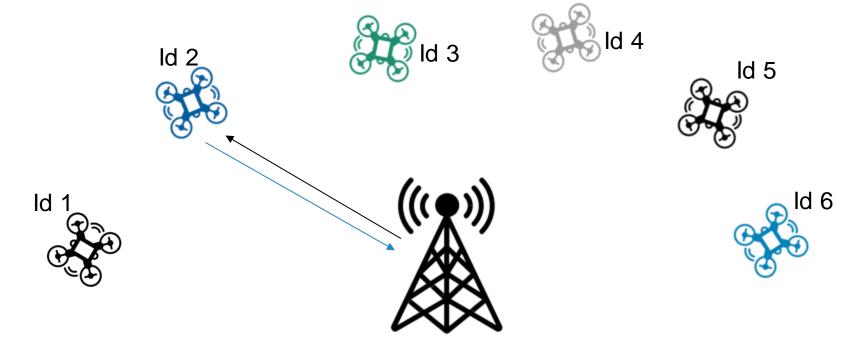






• • • • •							
time	t=i+1	t=i	t=i-1	t=4	t=3	t=2	t=1

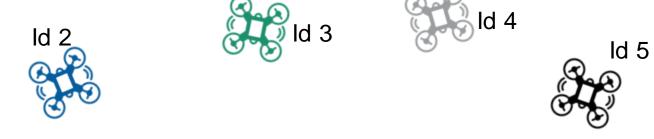
- 1) A set of drones that want communicate with the depot
- 2) The depot allocate bandwidth to the drone at each timestamp (**Time Slotted** Channel).

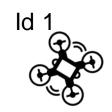


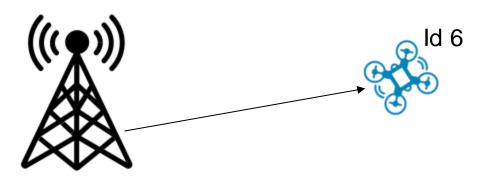


Dr.2							••	•••
t=1	t=2	t=3	t=4	t=i-1	t=i	t=i+1		time

- 1) A set of drones that want communicate with the depot
- 2) The depot allocate bandwidth to the drone at each timestamp (**Time Slotted** Channel).





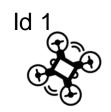


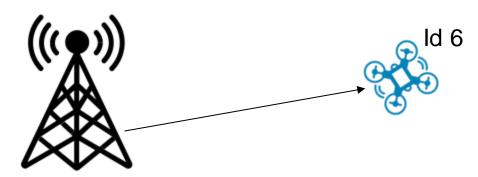


Dr.2	Dr.6						••••
t=1	t=2	t=3	t=4	t=i-1	t=i	t=i+1	time

- 1) A set of drones that want communicate with the depot
- 2) The depot allocate bandwidth to the drone at each timestamp (Time Slotted Channel).



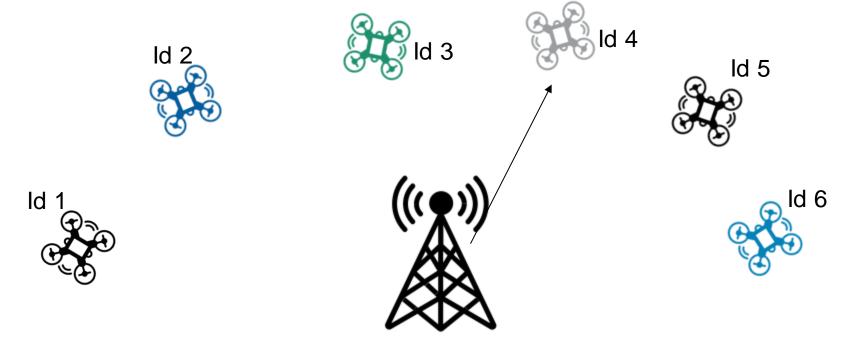






Dr.2	Dr.6	Dr.6					••••
t=1	t=2	t=3	t=4	t=i-1	t=i	t=i+1	time

- 1) A set of drones that want communicate with the depot
- 2) The depot allocate bandwidth to the drone at each timestamp (Time Slotted Channel).

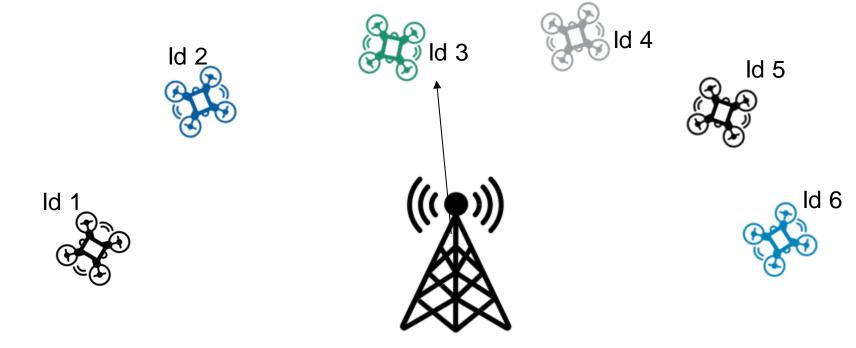






Dr.2	Dr.6	Dr.6	Dr.4				••••
t=1	t=2	t=3	t=4	t=i-1	t=i	t=i+1	time

- 1) A set of drones that want communicate with the depot
- 2) The depot allocate bandwidth to the drone at each timestamp (Time Slotted Channel).

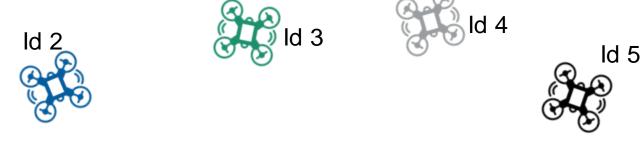


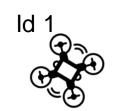


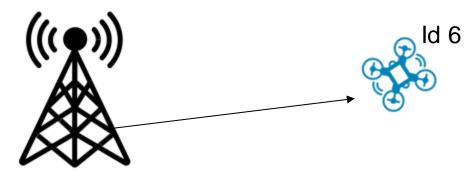


Dr.2	Dr.6	Dr.6	Dr.4	•••	Dr.3			••••
t=1	t=2	t=3	t=4		t=i-1	t=i	t=i+1	time

- 1) A set of drones that want communicate with the depot
- 2) The depot allocate bandwidth to the drone at each timestamp (**Time Slotted** Channel).









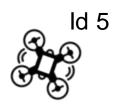
Dr.2	Dr.6	Dr.6	Dr.4	• • •	Dr.3	Dr.6	•••	•••	• • •
t=1	t=2	t=3	t=4		t=i-1	t=i	t=i+1		time

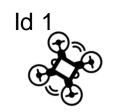
1) round robin











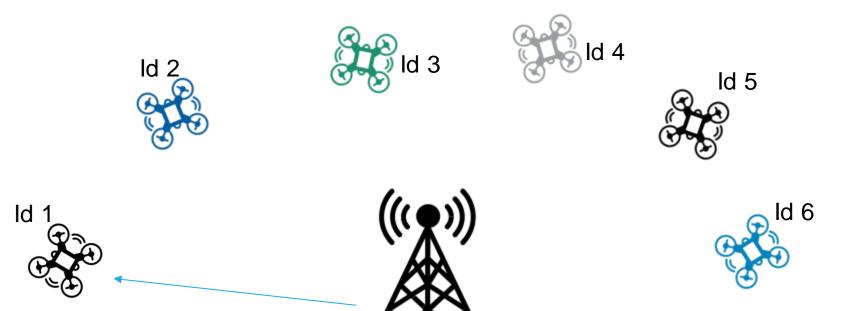






							••••
t=1	t=2	t=3	t=4	t=i-1	t=i	t=i+1	time

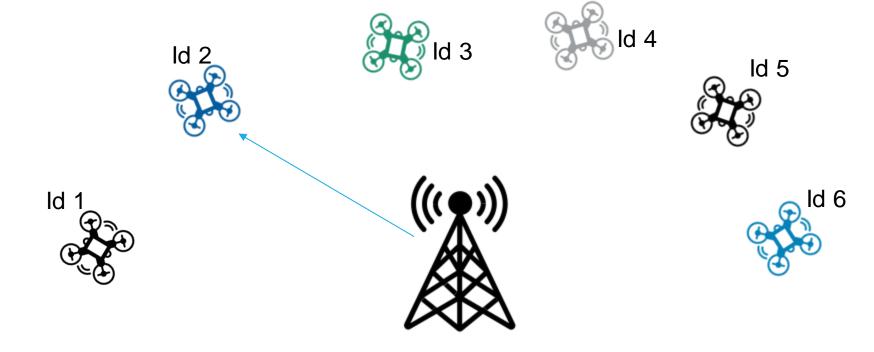
1) round robin





Dr.1							• • • • •
t=1	t=2	t=3	t=4	t=i-1	t=i	t=i+1	time

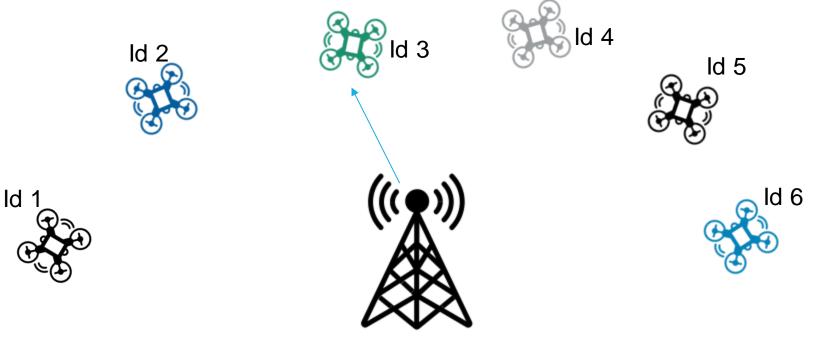
1) round robin





Dr.1	Dr.2						••••
t=1	t=2	t=3	t=4	t=i-1	t=i	t=i+1	time

1) round robin

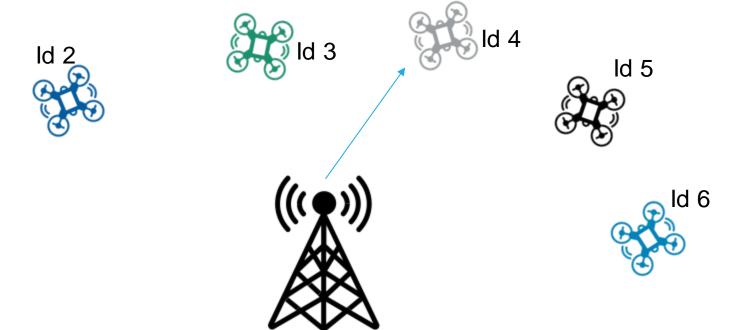






Dr.1	Dr.2	Dr.3					••••
t=1	t=2	t=3	t=4	t=i-1	t=i	t=i+1	time

1) round robin



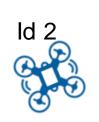




ld

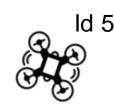
Dr.1	Dr.2	Dr.3	Dr.4	•••				••••
t=1	t=2	t=3	t=4		t=i-1	t=i	t=i+1	time

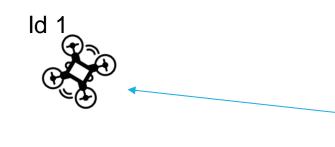
1) round robin











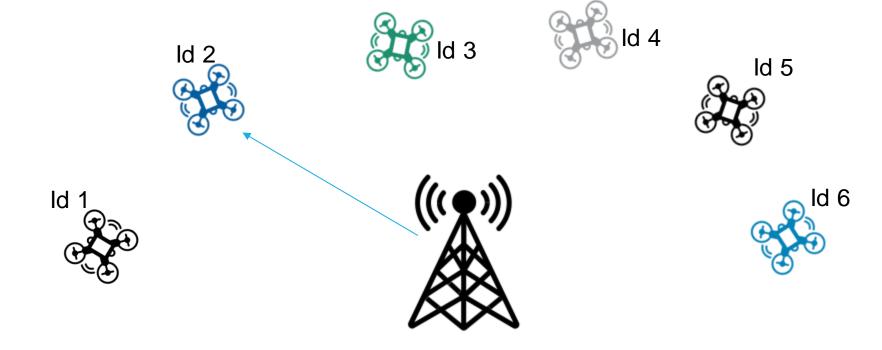






Dr.1	Dr.2	Dr.3	Dr.4	•••	Dr.1			••••
t=1	t=2	t=3	t=4		t=i-1	t=i	t=i+1	time

1) round robin

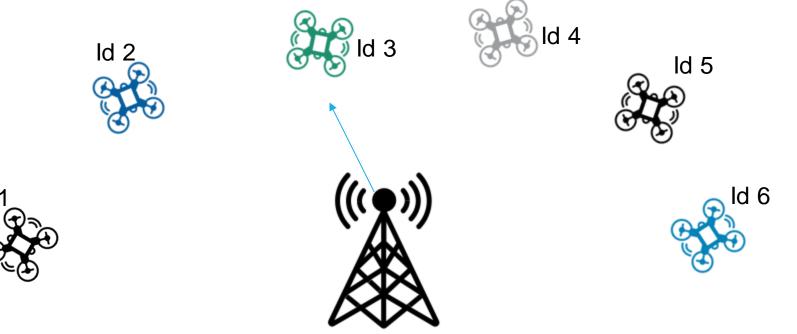






Dr.1	Dr.2	Dr.3	Dr.4	•••	Dr.1	Dr.2		••••
t=1	t=2	t=3	t=4		t=i-1	t=i	t=i+1	time

1) round robin



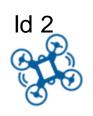


Dr.1	Dr.2	Dr.3	Dr.4	• • •	Dr.1	Dr.2	Dr.3	• • • • •
t=1	t=2	t=3	t=4		t=i-1	t=i	t=i+1	time



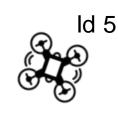
ld

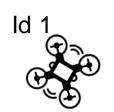
1) Why round robin may fail?











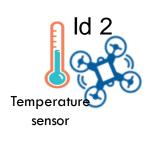


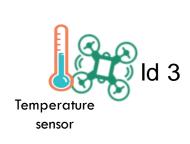




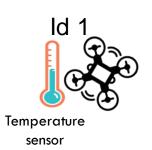
Dr.1	Dr.2	Dr.3	Dr.4	•••	Dr.1	Dr.2	Dr.3	0.0.00
t=1	t=2	t=3	t=4		t=i-1	t=i	t=i+1	time

1) Why round robin may fail?

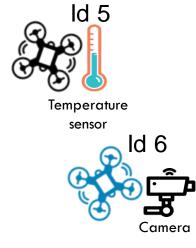














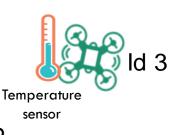
Dr.1	Dr.2	Dr.3	Dr.4	•••	Dr.1	Dr.2	Dr.3	• • • • •
t=1	t=2	t=3	t=4		t=i-1	t=i	t=i+1	time

1) Why round robin may fail?

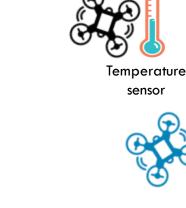
### WE SPENT SAME TIME ON EACH DRONE!

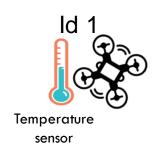
We lost data!

The drones with cameras should be queried more frequently respect to drones with temp sensors!









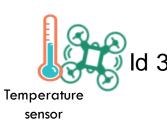


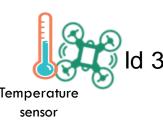


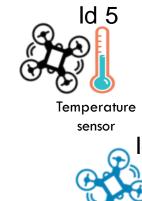


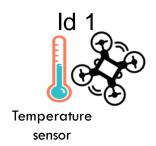
Dr.1	Dr.2	Dr.3	Dr.4	•••	Dr.1	Dr.2	Dr.3	••••
t=1	t=2	t=3	t=4		t=i-1	t=i	t=i+1	time

Why given fixed bandwidth to camera drones may be wrong?















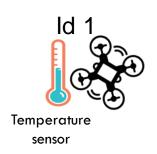
Dr.1	Dr.2	Dr.3	Dr.4	•••	Dr.1	Dr.2	Dr.3	••••
t=1	t=2	t=3	t=4		t=i-1	t=i	t=i+1	time

1) So we can just give more bandwidth to drones with a camera?

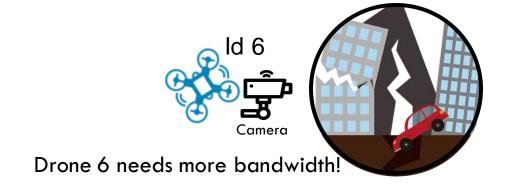
#### WE DON'T KNOW THE POSSIBLE SITUATION!

We need adaptive approach!











Dr.4	Dr.4	Dr.6	Dr.6	•••	Dr.6	Dr.6	Dr.1	••••
t=1	t=2	t=3	t=4		t=i-1	t=i	t=i+1	time



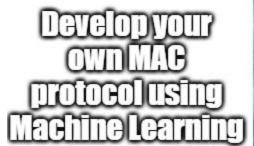


UseaRound Robinapproach



Create a **Reinforcement Learning** based MAC protocol!!





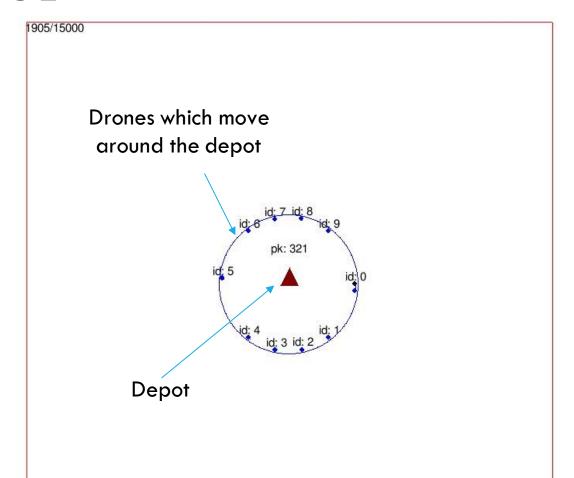




git clone https://github.com/Andrea94c/DroNETworkSimulator git checkout hmw1 python3 –m src.main

To implement: src.mac\_protocol.ai\_depot\_mac (used by the depot)

The method selects the next drone to query.









TASK: Implement the "allocate\_resource\_to\_drone" method. (DO NOT change other files)

Use it by setting:

config.MAC\_ALGORITHM = MACAlgorithm.Al

```
depot_mac_weighted.py × depot_mac_weighted.py × depot_mac.py × dep
```

If you need random generators, create them in the \_\_init\_\_
self.rnd\_for\_mac = np.random.RandomState(self.simulator.seed)



## HOMEWORK 1 — MAC PROTOCOL - FEEDBACK

To learn and adapt according the scenario, the MAC stores a feedback from the last communication.

Self.last\_feedback (when not None) contains a tuple (drone, transmission, feedback):

**Transmission** (if the current transmission was usefull or not):

False: if the drone does not send any packet (he has no alive packets)

True: if the drone sends a packet right now (he has at least one alive packet)

**Feedback** (how many packets we missed):

last

**0**: if the drone have no lost packets since last update (no packet has been generated since last communication)

a positive integer (+pos): if the drone have some lost packets. The "pos" is the number of packets lost since

communication. A packet generated and expired counts as 1.



# FEEDBACK - EXAMPLE

1. Drone A generates a new (1) packet at time t\_0 and we query it immediately.

The method returns (A, True, 0) (transmission success and no packets lost since last query)

2. Then, drone A generates **new nine (9) packets**, at time t\_1, **eight (8) expired** and **one (1) is still alive**, and we query it.

At time t\_1 it offload the last packet but the remaning (8) packets are lost as expired (not queried in time).

The method returns (A, True, 8) (good query, a new packet, but we lost 8 packets, we should query it more frequently).

3. Then, drone A generates 4 packets up to time t\_2. They all expire before we query it at time t\_3.

thus, at time t\_3 the drone A has not alive packets and we query it.

The method return (A, False, 4) (bad query, no new packet, and we also lost 4 packets, we should query it more frequently)

4. Then, drone A does not generate packets anymore. At time t\_4 the drone A has not packets and we query it.

The method return (A, False, O) (no new packets, useless query).





### FEEDBACK - EXAMPLE

Enable debug print in: config.MAC\_PRINT\_STATS = True

```
False - with feedback 4
Transmission for drone:
Transmission for drone:
                                  False - with feedback 5
Transmission for drone:
                                  True - with feedback 1
                             was
Transmission for drone:
                                  False - with feedback 0
Transmission for drone:
                                  False - with feedback 0
                             was
                                  False - with feedback 0
Transmission for drone:
                             was
                                  False - with feedback 0
Transmission for drone:
Transmission for drone:
                                  True - with feedback 0
Transmission for drone:
                                  False - with feedback 0
Transmission for drone:
                                  True - with feedback 1
                                  False - with feedback 0
Transmission for drone:
                             was
Transmission for drone:
                                  False - with feedback 0
Transmission for drone:
                                  False - with feedback 0
Transmission for drone:
                                  False - with feedback 4
Transmission for drone:
                                  False - with feedback 0
```





Python3 -m src.main (at the end of the simulation)

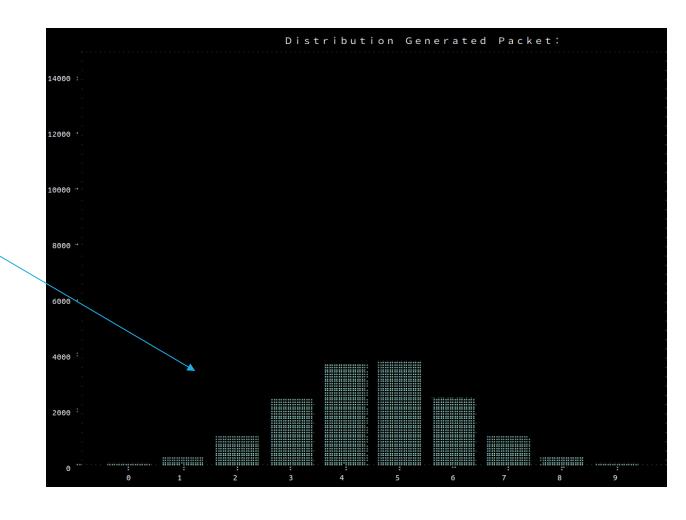
The packets generated by each drone

Enable them in:

Config.PLOT\_HISTOGRAMS = True

#### Two versions:

- config.MATPLOTLIB\_TERMINAL=Truewhich needs "pip install matplotlib-terminal"
- config.MATPLOTLIB\_TERMINAL=False Simple text print.







Python3 -m src.main (at the end of the simulation)

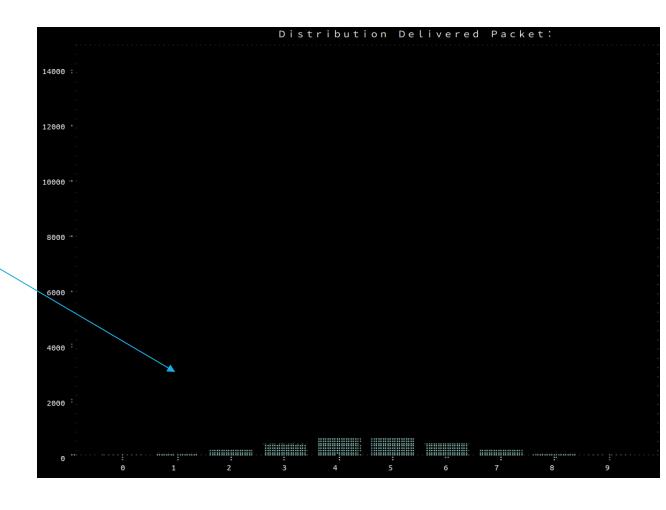
The packets collected by the depot, from each drone

### **SCORE:**

### Collected Ratio: 0.18413333333333333

(packet collected) / (packet generated)

Higher is better! This is your main goal!







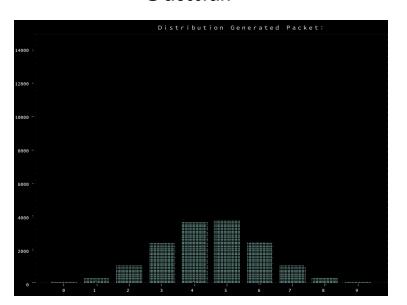
How the packets are generated? We use Stationary probability (mostly)

```
class GenerationPattern(Enum):
    GAUSSIAN = 0
    UNIFORM = 1
    FIXED_PROB = 2

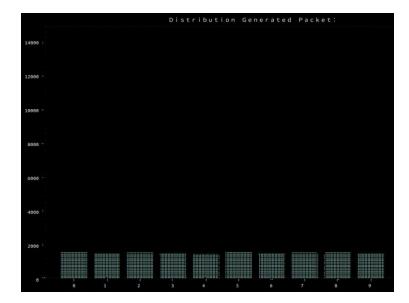
RANDOM_GENERATION_PATTERN = GenerationPattern.UNIFORM
```

Select the generation pattern

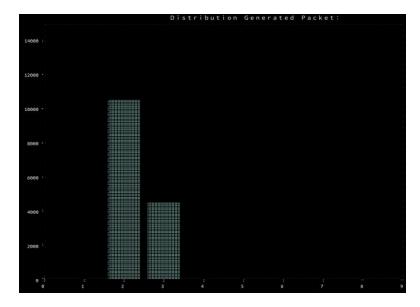
#### Gaussian



### Uniform



### With fixed probabilities







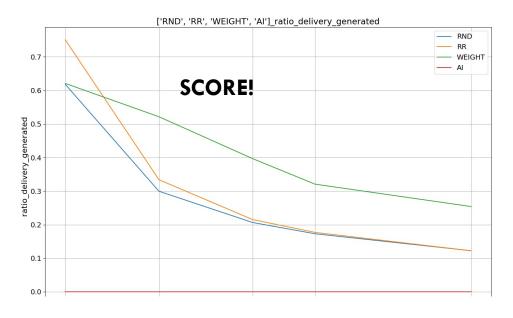
How to compare your approah/protocol? ./src/experiments/run\_mac\_experiments.sh

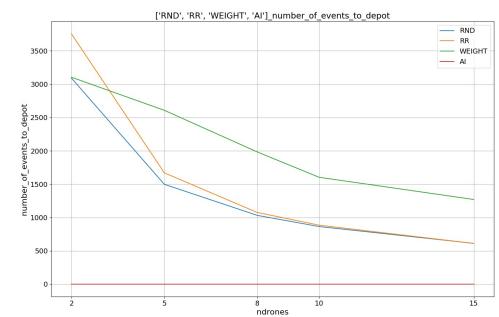
### Try different number of drones

```
The algorithms to compare
#test baselines
                    "10" "15"; # number of
                                                                                    The effectively code to run.
   for alg in "RND" "RR" "WEIGHT" "AI";
                                                                                    Remove comments to run extensive simulations;
       echo "run: ${alg} - ndrones ${nd}
                                                                                    also set i s = 0 and e s = 10.
       python3 -m src.experiments.experiment mac -nd ${nd} -i s 0 -e s 2 -alg ${alg} &
       #python3 -m src.experiments.experiment mac -nd ${nd} -i s 10 -e s 20 -alg ${alg} &
       #python3 -m src.experiments.experiment mac -nd ${nd} -i s 20 -e s 30 -alg ${alg} &
                  Avoid to much parallelism!
                                                                      How many seed to run (# experiments). range(i_s, e_s)
done;
                                        The number of seed used
wait
       Plot code
                                                                                                 Experiments to plot
python3 -m src.experiments.json and plot -nd 2 -nd 5 -nd 8 -nd 10 -nd 15 -i s 0 -e s 2 -exp suffix RND -exp suffix RR -exp suffix WEIGHT -exp suffix AI
```



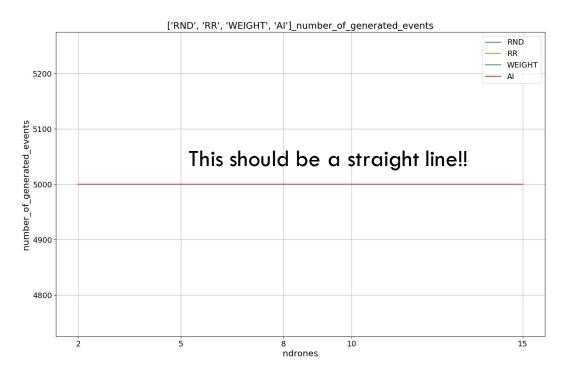
### AUTONOMOUS NETWORKING — A.A. 20/21





# HOMEWORK 1 MAC PROTOCOL - RESULTS





### HOMEWORK 1!!

**Deadline:** 23:59:59 - 03/12/2020

How: in group of 1 to 3

**Submission:** report + code

**Score:** up to 31 (30 cum laude)

**Interaction lecture:** 10:00 - 26/11/2020

FAQ: Common questions will be answered on classroom, above the homework post

**Evaluation:** approach; report; algorithm score (% of delivered packets).

Challenge: rank of top 10 algorithms.







# HOMEWORK 1 - GRADE

Homework 1: up to 31 (30 cum laude)

### If grade $\geq$ 18 then 2 options:

- 1. Stop here: final grade is scaled to 18 (oral discussion is required<sup>[1]</sup>)
- 2. Homework 2 (see next slide)

### Note:

[1] – grade can eventually increase up to 20

Suspected cases of plagiarism will be contacted to validate (or invalidate) the overall exam.





### HOMEWORK 2 - GRADE

Homework 2: up to 31 (30 cum laude)

Final homeworks grade: (grade homework 1 + grade homework 2) / 2

If final homeworks grade  $\geq$  18 then 2 options:

- 1. Stop here: final grade is round(Final homework grade / 30 \* 24) (oral discussion is required<sup>[1]</sup>)
- 2. Further integration (to be decided)

### Note:

[1] – grade can eventually increase up to 26.

Suspected cases of plagiarism will be contacted to validate (or invalidate) the overall exam.



### HOMEWORK 1 - SUBMISSION

#### How:

- email (subject=[Autonomous Networking A.A. 2020-2021] HMW1)
- Classroom

#### Format:

A zip called studentid1\_surnmane1\_studentid2\_surnmane2\_studentid3\_surnmane3.zip with:

- a brief report, at most 1000 words (images, biography and final notes are not counted). The final notes should clarify which part was mainly done by whom (50 words for each student of the team).
- A unique src file with the algorithm. Create a new name for your proposal, "algorithmname" and add the first "studentid1" at the end of the name: "algorithmname\_studentid1".

E.g., group of students made by: "Black - id: 999" and "Donald - id: 01".

They create a new algorithm called "X\_MAC", then, the delivery will be:

Zip: 999\_black\_01\_donald.zip

Inside the zip:

- 999\_black\_01\_donald\_report.txt
- 999\_black\_01\_donald\_mac\_protocol.py (which contains the algorithm class called "X\_MAC\_999")

Currently the file algorithm is called "ai\_depot\_mac.py" and the algorithm is called AIDepotMAC.

Submit <u>only</u> this file but <u>change</u> the file name and the algorithm name (see example here).





## HOMEWORK 1 - REPORT

### The report should include:

- Main approach and used techniques.
- Analysis of the performance and convergence.
- All the need additional libraries!!

Possible ML/Al libraries to use (<u>if needed</u>, <u>not mandatory</u>):

- Sklearn
- Keras
- Tensorflow

Please use only recent versions. In case of doubts write us an email. Disable any GPU usage before submit the homework.

If your model requires an intensive training phase, send to us also the persistent model to use.





# HOMEWORK 1 — END

Possible interaction to understand your score/position: <a href="https://bit.ly/hmw1\_score">https://bit.ly/hmw1\_score</a>

You can send to me your score with an email, subject '[Autonomous Networking - A.A. 2020-2021] - score'



# **CONTACTS**

### **Andrea Coletta:**

coletta@di.uniroma1.it

