

An Introduction to Quantum Computing

Lecture 18:

Solving Linear Systems of Equations: The HHL Algorithm (II)

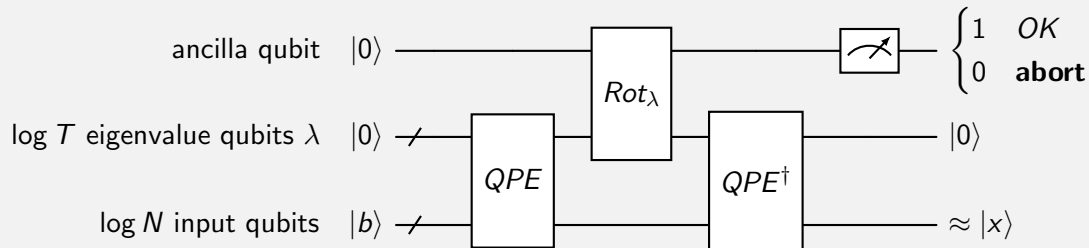
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The HHL Circuit (Algorithm)



If we measure 1 in the ancilla qubit, then the bottom quantum register will be in a state proportional to x , the solution vector we are looking for.

The 'rotation' gate Rot_λ will be defined later.

The HHL Circuit (QPE part)

Define $t_0 = O(\frac{\kappa}{\epsilon})$.

The QPE circuit is applied to the unitary U defined as

$$U = e^{iA \frac{t_0}{T}} = \sum_{j=0}^{N-1} e^{i\lambda_j \frac{t_0}{T}} |u_j\rangle\langle u_j|$$

where T is large enough to fit A 's eigenvalues (the λ_j 's).

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where T is large enough to fit A 's eigenvalues (the λ_j 's). What happens to $U|b\rangle$?

$$\begin{aligned} U|b\rangle &= U \left(\sum_{k=0}^{N-1} \beta_k |u_k\rangle \right) = \sum_{k=0}^{N-1} \beta_k U|u_k\rangle = \\ &= \sum_{k=0}^{N-1} \beta_k \left(\sum_{j=0}^{N-1} e^{i\lambda_j \frac{t_0}{T}} |u_j\rangle \langle u_j|u_k\rangle \right) = \sum_{k=0}^{N-1} \beta_k e^{i\lambda_k \frac{t_0}{T}} |u_k\rangle \end{aligned}$$

The HHL Circuit (QPE part)

Now, for $\tau = 0, 1, \dots, T - 1$ we have that

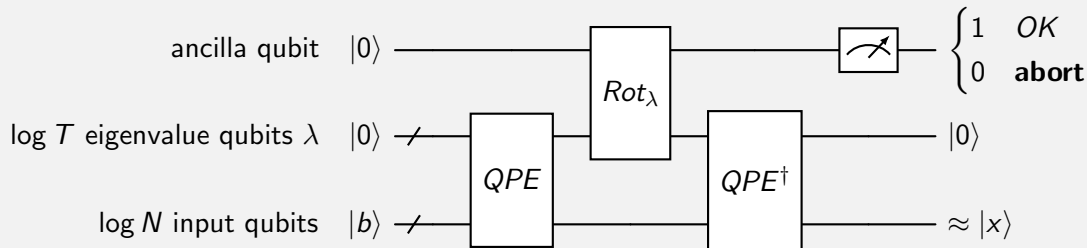
$$U^\tau |b\rangle = \sum_{k=0}^{N-1} \beta_k e^{i\lambda_k t_0 \frac{\tau}{T}} |u_k\rangle$$

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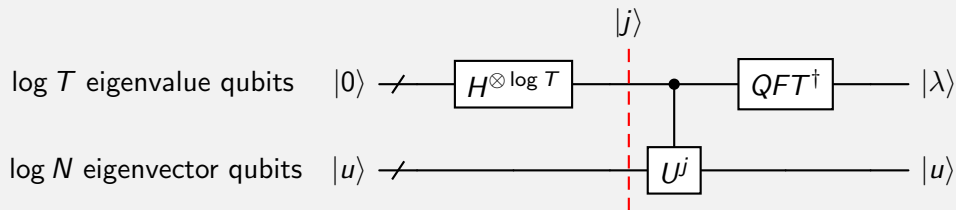
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Recall the HHL circuit:



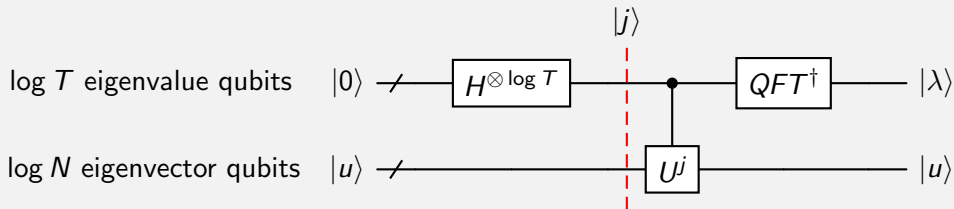
The HHL Circuit (QPE part)

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Instead of using Hadamards, we prepare the eigenvalue qubits to the state

$$|\psi\rangle = \sqrt{\frac{2}{T}} \sum_{j=0}^{T-1} \sin \frac{\pi(j + \frac{1}{2})}{T} |j\rangle$$

The HHL Circuit (QPE part)

The application of the controlled- U in the QPE gate can be described by:

$$\sum_{\tau=0}^{T-1} (|\tau\rangle\langle\tau| \otimes U^\tau) (|\psi\rangle \otimes |b\rangle) = \sqrt{\frac{2}{T}} \sum_{j=0}^{N-1} \beta_j \sum_{\tau=0}^{T-1} e^{i\lambda_j t_0 \frac{\tau}{T}} \sin \frac{\pi(\tau + \frac{1}{2})}{T} |\tau\rangle |u_j\rangle$$

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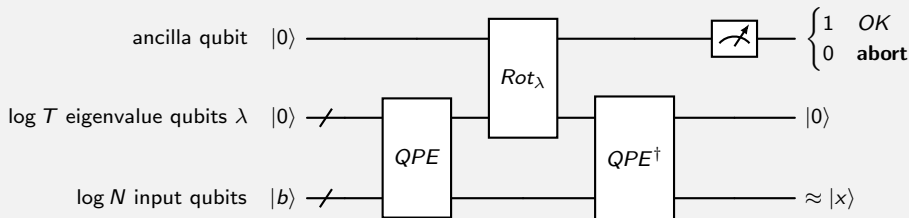
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We now apply QFT^\dagger and get

$$\frac{\sqrt{2}}{T} \sum_{j=0}^{N-1} \beta_j \sum_{\tau=0}^{T-1} \sum_{k=0}^{T-1} e^{i\frac{k}{T}(\lambda_j t_0 - 2\pi\tau)} \sin \frac{\pi(k + \frac{1}{2})}{T} |\tau\rangle |u_j\rangle = \sum_{j=0}^{N-1} \beta_j \sum_{\tau=0}^{T-1} \alpha_{j\tau} |\tau\rangle |u_j\rangle$$

where $\alpha_{j\tau} = \frac{\sqrt{2}}{T} \sum_{k=0}^{T-1} e^{i\frac{k}{T}(\lambda_j t_0 - 2\pi\tau)} \sin \frac{\pi(k + \frac{1}{2})}{T}$.

The HHL Circuit (Rotation part)



For a constant $C = O(1/\kappa)$ we rotate the ancilla qubit controlled by the eigenvalue qubits – this is the Rot_λ gate.

The state of the full system is then:

$$\sum_{j=0}^{N-1} \sum_{\tau=0}^{T-1} \beta_j \alpha_{j\tau} \left(\sqrt{1 - \frac{C^2}{\lambda_\tau^2}} |0\rangle + \frac{C}{\lambda_\tau} |1\rangle \right) |\lambda_\tau\rangle |u_j\rangle$$

where $|\lambda_\tau\rangle = |2\pi\tau/t_0\rangle$.

The HHL Circuit (Undo QPE)

$$\sum_{j=0}^{N-1} \sum_{\tau=0}^{T-1} \beta_j \alpha_{j\tau} \left(\sqrt{1 - \frac{C^2}{\lambda_\tau^2}} |0\rangle + \frac{C}{\lambda_\tau} |1\rangle \right) |\lambda_\tau\rangle |u_j\rangle$$

Next, we apply QPE^\dagger , *i.e.*, we uncompute the $|\lambda_t\rangle$'s, and obtain

$$\sum_{j=0}^{N-1} \beta_j \left(\sqrt{1 - \frac{C^2}{\lambda_j^2}} |0\rangle + \frac{C}{\lambda_j} |1\rangle \right) |\psi\rangle |u_j\rangle$$

The HHL Circuit (Undo QPE)

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Finally, we measure the ancilla qubit: if we obtain 1 then the state is

$$\sqrt{\frac{1}{\sum_{k=0}^{N-1} C^2 |\beta_k|^2 / |\lambda_k|^2}} |1\rangle |\psi\rangle \sum_{j=0}^{N-1} \beta_j \frac{C}{\lambda_j} |u_j\rangle$$

The HHL Circuit

Recall from the previous lecture that our sought after solution x can be written as

$$|x\rangle = A^{-1} |b\rangle = \sum_{j=0}^{N-1} \frac{1}{\lambda_j} |u_j\rangle \langle u_j|b\rangle = \sum_{j=0}^{N-1} \frac{\beta_j}{\lambda_j} |u_j\rangle$$

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Therefore, from the previous derivation we have that

$$\sqrt{\frac{1}{\sum_{k=0}^{N-1} C^2 |\beta_k|^2 / |\lambda_k|^2}} |1\rangle |\psi\rangle \sum_{j=0}^{N-1} \beta_j \frac{C}{\lambda_j} |u_j\rangle \approx |1\rangle |\psi\rangle |x\rangle$$

and the normalization constant in front of the sum can be estimated by sampling.