Quantum Computing

Lecture |09>: **Fixed-Point Quantum Search**

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Agenda

- The "soufflé problem"
- Grover's fixed-point quantum search algorithm (2005)

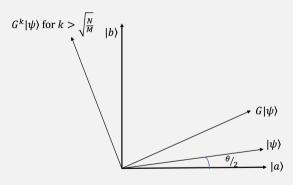
The "souffle problem"

Quantum searching is like cooking a soufflé – one needs to open the oven (stop the Grover iterations) at the right time, otherwise one risks:

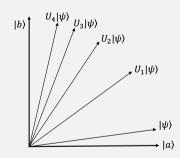
- burning the soufflé (overshooting the target states); or
- undercooking the soufflé (undershooting the targets states)

To know the right time (number of iterations), one needs to know the number of solution elements in the array.

Fixed-Point Quantum Search vs. Grover's Algorithm



Grover's algorithm overshoots the target



Grover's **fixed-point** algorithm converges to the target

The fixed-point algorithm **monotonically** moves towards the target!

Fixed-Point Quantum Search: Operators

Define the **phase shift** operators:

$$R_s = I - (1 - e^{i\theta}) |s\rangle\langle s|$$

$$R_t = I - (1 - e^{i\theta}) |t\rangle\langle t|$$

where $\theta=\frac{\pi}{3},\quad |s\rangle=$ starting state, $\quad |t\rangle=$ target state.

[Exercise: show that both operators are unitary.]

Fixed-Point Quantum Search: Operators

Let U be any unitary operator such that, for some (small) $\epsilon > 0$:

$$|\langle t|Us\rangle|^2=1-\epsilon.$$

Informally, "U drives $|s\rangle$ towards $|t\rangle$ with a probability of $(1-\epsilon)$."

Define the (unitary) operator:

$$UR_sU^{\dagger}R_tU$$
.

Now, it can be shown that $UR_s U^{\dagger} R_t U | s \rangle$ gets to $|t\rangle$ with a probability of $(1 - \epsilon^3)$.

Fixed-Point Quantum Search: Towards the Algorithm

More formally, by denoting $U_{ts} = \langle t | U_s \rangle$ it can be shown that

$$UR_s U^{\dagger} R_t U |s\rangle = U |s\rangle \left[e^{i\theta} + |U_{ts}|^2 (e^{i\theta} - 1)^2\right] + |t\rangle U_{ts} (e^{i\theta} - 1).$$
 (1)

Now, to know how close the state above is to $|t\rangle$, we compute the squared norm of:

$$egin{aligned} |t\rangle\!\langle t| \left[U|s
angle \left[e^{i heta} + |U_{ts}|^2(e^{i heta}-1)^2
ight] + |t
angle \, U_{ts}(e^{i heta}-1)
ight] \ = |t
angle \left[U_{ts}[e^{i heta} + |U_{ts}|^2(e^{i heta}-1)^2] + U_{ts}(e^{i heta}-1)
ight] \ = |t
angle \, U_{ts}[2e^{i heta}-1 + |U_{ts}|^2(e^{i heta}-1)^2] \end{aligned}$$

which is simply $\left|U_{ts}[2e^{i\theta}-1+|U_{ts}|^2(e^{i\theta}-1)^2]\right|^2$ since $\||t\rangle\|=1$. A bit more work \dots

Fixed-Point Quantum Search: Towards the Algorithm

Recalling that $\theta = \frac{\pi}{3}$, we get that the sought after deviation from $|t\rangle$ is:

$$\left|U_{ts}[2e^{i heta}-1+|U_{ts}|^2(e^{i heta}-1)^2]
ight|^2=\left|U_{ts}\left(-rac{1}{2}|U_{ts}|^2+irac{\sqrt{3}}{2}(2-|U_{ts}|^2)
ight)
ight|^2$$

Finally, recalling that $|U_{ts}|^2 = (1 - \epsilon)$, we get

$$\left|U_{ts}\left(-\frac{1}{2}|U_{ts}|^2+i\frac{\sqrt{3}}{2}(2-|U_{ts}|^2)\right)\right|^2=1-\epsilon^3$$

and therefore the deviation from $|t\rangle$ has been **reduced** from ϵ to ϵ^3 !

Fixed-Point Quantum Search: the Algorithm

Given U satisfying $|U_{ts}|^2 = 1 - \epsilon$, we define the **recursive** sequence of operators:

$$U_0=U$$

$$U_m=U_{m-1}R_sU_{m-1}^\dagger R_tU_{m-1} \qquad {
m for} \ m\geqslant 1$$

It can be shown that:

$$|\langle t|U_m s\rangle|^2 = 1 - \epsilon^{2q_m+1}$$
 $q_m = \#$ of queries to the oracle

This is (unfortunately) similar to a classical probabilistic algorithm where the failure probability drops as ϵ^{q+1} after q oracle queries. The quantum advantage is thus lost.

Better Fixed-Point Quantum Search

- A 2014 paper proposed a fixed-point quantum algorithm that monotonically converges to the target state while **retaining quadratic advantage** over classical algorithms.
- The algorithm involves phase-shift operators that are parameterized with angles different from $\frac{\pi}{3}$ and again involves building a sequence of operators using said phase shifts, the oracle, and the unitary which prepares the starting state.
- Reference: Fixed-Point Quantum Search with an Optimal Number of Queries.
 Physical Review Letters 113, 210501 (2014).

Proof of Claim (1)

Need to show that $UR_sU^{\dagger}R_tU|s\rangle=U|s\rangle\left[e^{i\theta}+|U_{ts}|^2(e^{i\theta}-1)^2\right]+|t\rangle\;U_{ts}(e^{i\theta}-1).$

First, let us massage the operator form (and define $P_s = |s\rangle\langle s|$ and $P_t = |t\rangle\langle t|$):

$$\begin{split} UR_s U^\dagger R_t U = & U(I - (1 - e^{i\theta})P_s)U^\dagger (I - (1 - e^{i\theta})P_t)U \qquad [\text{expand } R_s \text{ and } R_t] \\ = & (U - (1 - e^{i\theta})UP_s)U^\dagger (U - (1 - e^{i\theta})P_tU) \\ = & (I - (1 - e^{i\theta})UP_sU^\dagger)(U - (1 - e^{i\theta})P_tU) \\ = & U - (1 - e^{i\theta})P_tU - (1 - e^{i\theta})UP_s + (1 - e^{i\theta})^2UP_sU^\dagger P_tU \end{split}$$

Proof of Claim (1)

Now, we apply the previous (massaged) operator to $|s\rangle$:

$$\begin{array}{l} \mathit{UR}_{s}\mathit{U}^{\dagger}\mathit{R}_{t}\mathit{U}\left|s\right\rangle = \mathit{U}\left|s\right\rangle - (1-e^{i\theta})\mathit{P}_{t}\mathit{U}\left|s\right\rangle - (1-e^{i\theta})\mathit{UP}_{s}\left|s\right\rangle + (1-e^{i\theta})^{2}\mathit{UP}_{s}\mathit{U}^{\dagger}\mathit{P}_{t}\mathit{U}\left|s\right\rangle \\ = & \left[\mathsf{apply}\;\mathsf{projectors};\; \mathit{U}_{ts} = \langle t|\mathit{Us}\rangle\right] \\ \mathit{U}\left|s\right\rangle - (1-e^{i\theta})\left|t\right\rangle \mathit{U}_{ts} - (1-e^{i\theta})\mathit{U}\left|s\right\rangle + (1-e^{i\theta})^{2}\mathit{UP}_{s}\mathit{U}^{\dagger}\left|t\right\rangle \mathit{U}_{ts} = \\ \mathit{U}\left|s\right\rangle - (1-e^{i\theta})\left|t\right\rangle \mathit{U}_{ts} - (1-e^{i\theta})\mathit{U}\left|s\right\rangle + (1-e^{i\theta})^{2}\mathit{U}\left|s\right\rangle \langle s|\mathit{U}^{\dagger}\left|t\right\rangle \mathit{U}_{ts} = \\ \mathit{U}\left|s\right\rangle - (1-e^{i\theta})\left|t\right\rangle \mathit{U}_{ts} - (1-e^{i\theta})\mathit{U}\left|s\right\rangle + (1-e^{i\theta})^{2}\mathit{U}\left|s\right\rangle \langle s|\mathit{U}^{\dagger}t\right\rangle \mathit{U}_{ts} \\ = & \left[\mathsf{adjoint}\;\mathsf{property}\right] \end{array}$$

 $U|s\rangle - (1-e^{i\theta})|t\rangle U_{ts} - (1-e^{i\theta})U|s\rangle + (1-e^{i\theta})^2 U|s\rangle \langle Us|t\rangle U_{ts} =$

Proof of Claim (1)

Resuming from the last equality:

$$egin{aligned} U\ket{s}-(1-e^{i heta})\ket{t}U_{ts}-(1-e^{i heta})U\ket{s}+(1-e^{i heta})^2U\ket{s}ra{Us}\ket{t}U_{ts} \ &= & [U_{ts}^*=ra{Us}\ket{t}] \ U\ket{s}-(1-e^{i heta})\ket{t}U_{ts}-(1-e^{i heta})U\ket{s}+(1-e^{i heta})^2U\ket{s}\ket{U_{ts}}^2 = \ &= & [ext{algebra}] \ U\ket{s}ra{e^{i heta}}+\ket{U_{ts}}^2(e^{i heta}-1)^2]+\ket{t}U_{ts}(e^{i heta}-1). \end{aligned}$$