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The Cutting-Stock Problem

Algoritmi e Modelli per l'Ottimizzazione Discreta

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1 Analytical model

The Cutting-stock problem (CSP) is the problem concerning cutting standardsized pieces of stock material, called *rolls*, into pieces of specified sizes, **minimizing material wasted**.

1.1 ILP Formulation

In order to formalize that problem as an **integer linear programming** (**ILP**), suppose that stock material width is equal to W, while m customers want n_i rolls, each of which is wide w_i , where i = 1, ..., m. Obliviously $w_i \leq W$.

As known, the first known ILP formulation of CSP was presented in 1939 by **Kantorovich**¹, which is reported below:

$$(P1) \quad min \quad \sum_{k \in K} y_k$$

$$s.t. \quad \sum_{k \in K} x_i^k \ge n_i, \qquad i = 1, ..., m \qquad (demand)$$

$$\sum_{i=1}^{k} w_i x_i^k \le W y_k, \qquad \forall k \in K \quad (width limitation)$$

$$x_i^k \in \mathbb{Z}_+, y_k \in \{0, 1\}$$

Where:

K = Index set of available rolls.

$$y_k = \begin{cases} 1, & \text{if roll } k \text{ is cut} \\ 0, & \text{otherwise} \end{cases}$$
 (2)

 x_k^i = Number of times item *i* is cut on roll *k*.

Although is very easy to implement that formulation, its performances are very bad in practice due to a poor linear program relaxation of (P1).

Fortunately, an alternative and stronger ILP formulation exists and it is due to **Gilmore and Gomory**; to describe it, we had to know the following:

- A pattern $j \in J$ is described by the vector $(a_{1j}, a_{2j}, ..., a_{mj})$, where a_{ij} represents the number of final rolls of width w_i obtained from cutting a raw roll according to pattern j.
- In this model we have an integer variable x_j for each pattern $j \in J$, indicating how many times pattern j is used; in other words it represents how many raw rolls are cut according to pattern j.

The Gilmore and Gomory ILP formulation (P2) is reported below:

 $^{^{1} \}verb|https://arxiv.org/ftp/arxiv/papers/1606/1606.01419.pdf|$

(P2)
$$min \sum_{j=1}^{n} x_j$$

 $s.t. \sum_{j=1}^{n} a_{ij}x_j \ge n_i, i = 1, ..., m (demand)$ (3)
$$x_j \in \mathbb{Z}_+, j = 1, ..., n$$

Where n represents the total number of cutting patterns satisfying following relations:

$$\sum_{i=1}^{m} w_i a_{ij} \le W$$

$$a_{ij} \in \mathbb{Z}_+$$
(4)

Observe that each column of 3 (P2) represents a cutting patter.

Is very important to understand that the number of existing cutting patterns is **exponentially large**; it could be as many as $\frac{m!}{\bar{k}!(m-\bar{k})!}$ where \bar{k} is the average number of items in each cutting patterns.²

Since, as we said, the number of possible patterns grows exponentially, it can easily run into the millions, therefore become impractical to generate and enumerate all possible cutting patterns.

Even if we had a way of generating all existing cutting pattern, that is all columns, the **standard simplex algorithm** will need to calculate the reduced cost for each non-basic variable, which is, from a computational point of view, impossible when n is huge because is very easy for any computer to go **out of memory**.

This is the reason according to which we have adopt and implemented another better approach to solve (P2): the **column generation method**.

²http://opim.wharton.upenn.edu/guignard/915_2015/slides/LR/CG/lecture_IP8.pdf

1.2 CSP resolution algorithm

In order to properly describe the method used to solve (P2), we had to introduce the so called **Restricted Master Problem** (**RPM**), which is the LP relaxation of (P2). Its formulation is shown in 5.

Obliviously (RPM) solutions could be *fractional*; in that case is possible to *round up* the fractional solution to get a feasible solution to (P2); we will make further considerations about that later.

$$(RPM) \quad min \quad \sum_{j \in P} x_j$$

$$s.t. \quad \sum_{j \in P} a_{ij} x_j \ge n_i, \quad i = 1, ..., m \quad (demand)$$

$$x_j \ge 0, j \in P$$
 (5)

The dual problem of (RPM) is:

$$(DRPM) \quad max \quad \sum_{i=1}^{m} n_i \pi_i$$

$$s.t. \quad \sum_{i=1}^{m} a_{ij} \pi_i \le 1 \qquad j \in P,$$

$$\pi_i > 0, i = 1, ..., m$$

$$(6)$$

Resolution method is based on **column generation algorithm**, which main idea is to solve the CSP by starting with just a few patterns, **generating**, **when needed**, **additional columns**, that could improve current optimal solution of the linear relaxation (RPM).

To be more precise, the new columns (patterns) are found by solving an auxiliary optimization problem, called **slave problem** (SP), which, as you can see below, is a **knapsack problem**. As known, knapsack problems can be resolved efficiently in O(mW) time using dynamic programming or branch and bound method. (SP) ILP formulation is:

(SP)
$$\max \sum_{i=1}^{m} \pi_i y_i$$

s.t. $\sum_{i=1}^{m} w_i y_i \leq W$ (feasible cutting pattern) (7)
 $y_i \in \mathbb{Z}_+, i = 1, ..., m$

where $y = (y_1, ..., y_m)$ represents a column $(a_{1j}, ..., a_{mj})^T$ (that is a cutting pattern).

In order to find a new column capable to improve current (RPM) optimal solution, we have to resolve (SP) in the dual variables, finding the column with the **most negative reduced cost**.

Given the optimal dual solution $\bar{\pi}$ of (RPM), the reduced cost of column $j \in \{1, ..., n\} \setminus P$ is:

$$\sum_{i=1}^{m} a_{ij}\bar{\pi} \tag{8}$$

A naive way of finding the new column:

$$min\{1 - \sum_{i=1}^{m} a_{ij}\bar{\pi} \mid j \in \{1, ..., n\} \setminus P\}$$
 (9)

which is impractical because we are not able to list all cutting patterns in real applications. Therefore we can look for a column (cut pattern) such that:

$$\kappa = \min 1 - \sum_{i=1}^{m} a_{ij} = 1 - \max \sum_{i=1}^{m} \pi_i y_i$$
 (10)

- 1. Heuristically initialize columns of (RPM) with a subset of pattern $P' \subset P$. In our computational model, we have used very simple patterns according to which a stock roll is cut into $\lfloor \frac{W}{w_i} \rfloor$ rolls of width w_i (where i=1,...,m).
- 2. Repeat until $\kappa \geq 0$:
 - (a) Solve (RPM) and let $\bar{\pi}$ the optimal dual solution of (RPM).
 - (b) Identify a column $p \in P$ that could reduce the objective function value solving (SP) in dual variables; if $\kappa \geq 0$, add the new column $y = (y_1, ..., y_m)$ to (RPM).

2 Computational Model

Let's start now the description of our resolver implementation in which, as known, we will turn all mathematical variables described above into a collection of data structures, classes and variables that, collectively, are able to resolve CSP problems.

Our application, compatible with *Gurobi* ILP solver³, is been implemented using Java programming language while GUI is rendered through OpenJFX 12⁴ API; however, we preferred to omit a detailed description of all classes involved into GUI rendering because they are just too technical and so not relevant for the purposes of this report.

Application's source code is available on GitHub⁵, famous web-based hosting service for version control using git; we remind that L^AT_EX source code of this report is available too.⁶

2.1 The CSP instance

A generic CSP instance has been implemented and represented using a Java class called CuttingStockInstance, shown in Listing 1. In addition to several getter and setter methods, that class has two very important features:

- It has got a final double type field, called maxItemLength, which is used to hold the stock material width value W.
- Through a list data structure, it holds a reference to all items required by customers through an ArrayList<> type field, called items.

As you can see from Listing 1, that list contains m CuttingStockItem type instances which, obliviously, represent all specific items request by each customer. To be more precise, every CuttingStockItem type instances i, where i=1,...,m, contains two double type fields, called length and amount, which are used respectively to hold a reference to w_i and n_i , that is the length and the amount of rolls required by m-th customer.

Listing 1: CuttingStockInstance class implementation.

```
public class CuttingStockInstance {

private final double maxItemLength;
private ArrayList < CuttingStockItem > items;

public CuttingStockInstance(double maxItemLength) {
    this.maxItemLength = maxItemLength;
    this.items = new ArrayList <>();
}

public void addItems(double amount, double length) {
    this.items.add(new CuttingStockItem(amount, length))
    ;
}
```

³https://www.gurobi.com/

⁴https://openjfx.io/

⁵Source code available on https://github.com/AndreaG93/AMOD-Project

 $^{^6 \}mathrm{See}\ \mathtt{https://github.com/AndreaG93/AMOD-Report}$

```
}
13
14
        public double getMaxItemLength() {
15
             return maxItemLength;
16
17
18
        public ArrayList < CuttingStockItem > getItems() {
19
             return items;
20
21
   }
22
```

2.2 ILP solver

Obliviously, in order to resolve any CSP problem is necessary to design a way to represent a *generic* ILP, which implementation, generally, depends by which *ILP solver* you decide to use.

To ensure low coupling between our application and the adopted ILP solver, any ILP is been represented by a Java interface called LinearProblem: that interface, as you can see in Listing 2, exports *only* necessary methods for CSP resolution.

In that way, is possible, for our application, to work with any ILP solver, as long as properly adapters, implementing all methods required by our interface, are provided. Actually, only one adapter class, called GurobiLinearProblem, compatible with *Gurobi* ILP solver, containing all method implementations required by LinearProblem interface, is provided by default.

Listing 2: Some methods exported by LinearProblem interface.

```
LinearProblemSolution getSolution() throws Exception;
  LinearProblemSolution getDualSolution() throws Exception;
  void setObjectiveFunctionType(LinearProblemType type) throws Exception;
  void changeObjectiveFunctionCoefficients(double[] newCoefficients) throws
      Exception;
  void addConstraint(double[] coefficients, MathematicalSymbol symbol, double
9
      value) throws Exception;
  void setVariables(int totalNumberOfVariables, double lowerBound, double
10
      upperBound, VariableType varType) throws Exception;
  void setObjectiveFunction(double[] coefficients, LinearProblemType type) throws
11
      Exception;
  void addNewColumn(double newVariableLowerBound, double newVariableUpperBound,
      double value, VariableType varType, double[] columnCoefficient) throws
      Exception;
  double[] getColumnCoefficient(int index) throws Exception;
```

2.3 CSP solver

A generic CSP problem is represented by CuttingStockProblem type instance, which has has several very important duties like:

• Allocation, initialization and management of all LinearProblem type instance necessary for CSP resolution.

In fact, every CuttingStockProblem type instance holds a reference to two LinearProblem instances called masterProblem and knapsackSubProblem, respectively used to represent the the restricted master problem (RPM) and the slave problem (SP).

In order to properly initialize the restricted master problem according to what has been said in previous section, is enough to invoke buildMasterProblem method, which is shown below. Another method, called buildKnapsackSubProblem, is used, instead, for (SP) initialization.

Listing 3: buildMasterProblem() method implementation.

```
private void buildMasterProblem() throws Exception {
2
       ArrayList < CuttingStockItem > cuttingStockItems = instance.getItems();
3
       double maxItemLength = instance.getMaxItemLength();
       int numberOfVariables = cuttingStockItems.size();
5
       double[] coefficientObjectiveFunction = new double[numberOfVariables];
       \textbf{this}. \texttt{masterProblem.setVariables} (\texttt{numberOfVariables} \ , \ \texttt{O}, \ \texttt{GRB.INFINITY} \ ,
9
           VariableType.REAL);
10
       Arrays.fill(coefficientObjectiveFunction, 1);
11
12
       this.masterProblem.setObjectiveFunction(coefficientObjectiveFunction,
13
           LinearProblemType.min);
       for (int index = 0; index < numberOfVariables; index++) {</pre>
16
            CuttingStockItem currentItem = cuttingStockItems.get(index);
17
18
            double[] constraintCoefficients = new double[numberOfVariables];
19
20
            constraintCoefficients[index] = ((int) (maxItemLength / currentItem.
21
                getLength());
22
            this.masterProblem.addConstraint(constraintCoefficients,
                MathematicalSymbol.GREATER_EQUAL, currentItem.getAmount());
       }
23
   }
24
```

- Allocation and management of a timer which, according to project requirements, is been implemented in order to stop our resolver once a time limit, fixed to 20 seconds, is reached. If timer expires, an approximate solution will be displayed.
- CSP problem resolution using the algorithm described in 1.2. That algorithm is been implemented into executeColumnGenerationAlgorithm method, which is shown in Listing 4:

Listing 4: executeColumnGenerationAlgorithm() method implementation.

```
private void executeColumnGenerationAlgorithm() throws Exception {
       Map<Integer, CuttingStockPattern> currentSolution;
       {\tt Linear Problem Solution \ master Problem Dual Solution;}
3
       LinearProblemSolution knapsackSubProblemSolution;
       int[] currentIntegerSolution;
5
       double[] currentMasterProblemDualSolution;
6
       double currentWaste;
7
       while (!this.timeOut) {
            this.masterProblemSolution = this.masterProblem.getSolution();
10
           masterProblemDualSolution = this.masterProblem.getDualSolution();
            currentIntegerSolution = this.masterProblemSolution.
               getIntegerSolutions();
            \verb|currentMasterProblemDualSolution| = \verb|masterProblemDualSolution|.
               getRealSolutions();
15
            this.cuttingStockSolution.addObjectiveFunctionRealValue(this.
16
               masterProblemSolution.getRealValueOfObjectiveFunction());
            this.cuttingStockSolution.addObjectiveFunctionIntegerValue(this.
17
               masterProblemSolution.getIntegerValueOfObjectiveFunction());
            currentSolution = buildSolutionPatterns(currentIntegerSolution);
           currentWaste = computeWasteFromPattern(currentSolution);
20
21
           this.cuttingStockSolution.setCspSolutionPatterns(currentSolution);
22
23
           if (this.cuttingStockSolution.addWasteValueCheckingForMinimumValue(
24
               currentWaste)) {
                {\color{blue} \textbf{this}}. \ \texttt{cuttingStockSolution.setCspSolutionPatternsMinimumWaste} (
25
                    currentSolution);
                this.cuttingStockSolution.
                    setObjectiveFunctionValues_MinimumWaste(this.
                    masterProblemSolution.getIntegerValueOfObjectiveFunction());
27
           this.knapsackSubProblem.changeObjectiveFunctionCoefficients(
               currentMasterProblemDualSolution);
           knapsackSubProblemSolution = this.knapsackSubProblem.getSolution();
29
30
           if (1 - knapsackSubProblemSolution.getRealValueOfObjectiveFunction()
31
                < 0) {
                double[] newColumn = knapsackSubProblemSolution.getRealSolutions
                this.masterProblem.addNewColumn(0.0, GRB.INFINITY, 1.0,
                    VariableType.REAL, newColumn);
                this.cuttingStockSolution.increaseTotalNumberOfColumnsAdded();
35
           } else
36
                break;
37
38
        this.timer.cancel();
39
40
```

As you can see above, executeColumnGenerationAlgorithm method is used to collect some data which are strictly necessary for charts generation, concerning, for example, restricted master problem objective function value trend. All data collected, including final solutions, are hold by CuttingStockSolution type instance.

Anyway, ${\tt CuttingStockProblem}$ class includes other very useful method including:

buildSolutionPatterns which is used to build all patterns which belongs to solutions

 $\label{lem:computeWasteFromPattern} \ \ {\rm used,\ instead,\ to\ compute\ rolls\ waste\ according\ to} \\ \ \ {\rm specified\ patterns}$

2.4 Solutions visualization

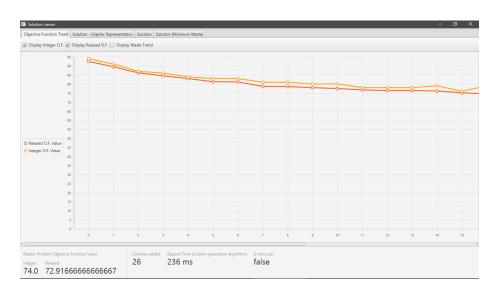


Figure 1: Class diagram of our model (main classes and methods only are showed)

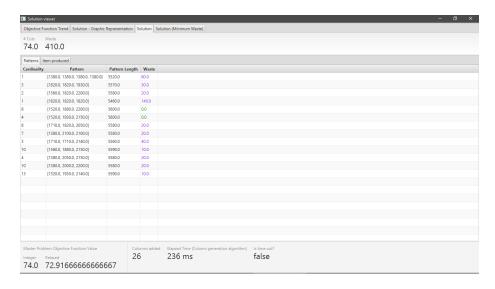


Figure 2: Class diagram of our model (main classes and methods only are showed)

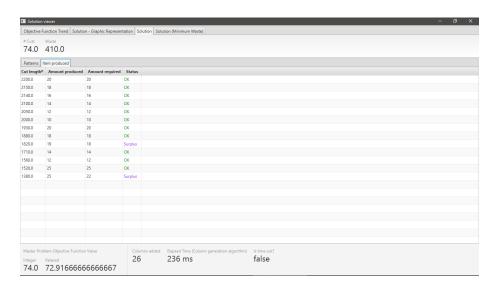


Figure 3: Class diagram of our model (main classes and methods only are showed) $\,$

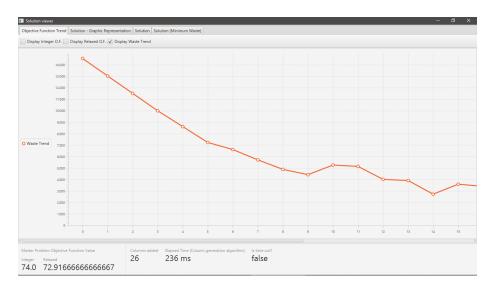


Figure 4: Class diagram of our model (main classes and methods only are showed)



Figure 5: Class diagram of our model (main classes and methods only are showed) $\,$