# Byzantine Fault-Tolerant and Locality-Aware Scheduling MapReduce

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#### **ABSTRACT**

MapReduce is often used to run critical jobs such as scientific data analysis. However, evidence in the literature shows that arbitrary faults do occur and can probably corrupt the results of MapReduce jobs; Moreover, ignoring data locality during task scheduling can lead to performance degradation and a pointless bigger network traffic.

We present an original MapReduce algorithm capable to tolerate arbitrary or Byzantine faults experienced by worker nodes and to resolve master node single point of failure problem; moreover, recognizing input data network locations and sizes, our algorithm performs a locality aware task scheduling, improving performance and diminishing network traffic.

Although the execution of a job with our algorithms uses more resources respect to other implementations, like Hadoop, we believe that this cost is acceptable for critical applications that require that level of fault tolerance.

#### **KEYWORDS**

MapReduce, Fault tolerance, Arbitrary failure, Data locality

#### **ACM Reference Format:**

## 1 INTRODUCTION

Various data-intensive tasks, like seismic simulation, natural language processing, machine learning, astronomical data parsing, web data mining and many other, require a processing power that exceeds the capabilities of individual

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computers; this fact imposes the use of *distributed computing*. Nowadays many famous distributed applications use thousands of computers and hundreds of other devices like network switches, routers and power units in order to provide their services to an increasing number of users in every part of the world, moving consequently an huge amount of data between computers and server. *MapReduce*, a framework developed by Google, represents a solution for processing large data sets in a distributed environment.

However, as many studies confirm, hardware component failures are frequent and they will probably happen more often in the future owing to the increasing number of computer and server connected to internet. Is been documented that in the first year of a cluster at Google there were 1000 individual machine failures and thousands of hard drive failures. A recent study of DRAM errors in a large number of servers in Google data-centres for 2.5 years concluded that these errors are more prevalent than previously believed, with more than 8% DIMM affected by errors yearly, even if protected by error correcting codes (ECC) [?]. A Microsoft study of 1 million consumer PCs shown that CPU and core chipset faults are also frequent. [?] Moreover moving large amount of data repeatedly to distant nodes is becoming the bottleneck owing to an increased network traffic causing performance degradation.

These are the reasons why to construct a distributed system in such a way it can provide its services even in the presence of failures is become so critical; consequently, to provide a *fault tolerant* cloud application represents an important goal in distributed-systems design. Moreover exploiting data locality, in order to mitigate network traffic and delay, becomes very important to improve performance.

Then the goal of this paper is to describe an *Arbitrary Fault-Tolerant Locality-Aware* (AFTLA) *MapReduce runtime system* capable to mitigate problems described above.

# 2 ARBITRARY FAULT-TOLERANT LOCALITY-AWARE MAPREDUCE

## Arbitrary fault tolerance

As known academic literature describes many type of failure, like *crash failures*; however the most serious are known as *arbitrary failures* or *Byzantine failures*, according to which a

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server may produce arbitrary responses at arbitrary times which cannot be detected as being incorrect.

Redundancy represents the key technique used to manage these kind of failure, according to which,

The key approach to tolerating a faulty process is to organize several identical processes into a group.

Our BFT MapReduce follows the approach of executing each task more than once, similarly to the works mentioned above. The chal-

Process groups are part of the solution for building fault-tolerant systems. In particular, having a group of identical processes allows us to mask one or more faulty processes in that group. In other words, we can replicate processes and organize them into a group to replace a single (vulnerable) process with a (fault tolerant) group.

An important issue with using process groups to tolerate faults is how much replication is needed. To simplify our discussion, let us consider only replicated-write systems. A system is said to be k-fault tolerant if it can survive faults in k components and still meet its specifications. If the components, say processes, fail silently, then having k+1 of them is enough to provide k-fault tolerance. If k of them simply stop, then the answer from the other one can be used.

On the other hand, if processes exhibit arbitrary failures, continuing to run when faulty and sending out erroneous or random replies, a minimum of 2k+1 processes are needed to achieve k-fault tolerance. In the worst case, the k failing processes could accidentally (or even intentionally) generate the same reply. However, the remaining k+1 will also produce the same answer, so the client or voter can just believe the majority.

# 3 SYSTEM ARCHITECTURE

In order to properly describe our MapReduce algorithm, including our arbitrary failures management system and how we exploit data locality in order to improve performance, it is necessary to describe our system architecture.

#### **Assumptions**

Our system is composed by a set of distributed processes, every of which run on *different* hosts.

We assume that our system runs *asynchronously*, that is no assumptions about process execution speeds or message delivery times are made; therefore we can normally use timeouts to conclude that a process has crashed but, occasionally, such conclusion is false. However, all processes are connected by *reliable channels*, so no messages are lost, duplicated or corrupted; that feature is guaranteed by the use of TCP connections.

Clients are always correct, because if they are not there is no point in worrying about the correctness of our system's output. Finally we assume the existence of an hash function that is *collisions-resistant*, for which it is infeasible to find two inputs that produce the same output.

Our system is composed by a set of distributed processes:

**Client Process** the clients that request the execution of jobs composed by map and reduce tasks

**Leader Primary Process** It manages the execution of word-count jobs received from clients coordinating Worker Nodes

**Backup Primary Process** It manages the execution of word-count jobs received from clients coordinating Worker Nodes

Worker Process A Worker Process executes map and reduce task scheduleted by current Leader Primary Process. In order to achieve fault tolerance, any Worker Process must be run indepently on different host. In our implementation, each process run on independent Amazon EC2 server

Worker Group All system's nodes in which worker process are running are logically split into several *Groups*, that is sets of equal worker processes, each of which execute the same commands using same input data in the same order. In a group all worker processes run independently on different host and they do not interact with each other in any way. Current Leader Primary Process can interact with groups members using a push-based approach in order to schedule map or reduce tasks. Although, for performance reasons, not always happen, when a task is sent to the group itself, all members of the group receive it.

The key property that all groups have is that when a message is sent to the group itself, all members of the group receive it.

primary coordinates all write operations

In other words, we can replicate processes and organize them into a group to replace a single (vulnerable) process with a (fault tolerant) group.

When a task is for work is generated, either by an external client or by one of the workers, it is sent to the coordinator.

as a set of Task- Trackers that execute tasks

We assume that clients are always correct, because if they are not there is no point in worrying about the correctness of the job's output.

The host where current master process is running may fail, for example by crashing or by losing network connectivity. Therefore, to ensure system availability in such a way that it can keep on providing its services, multiple master process copies of run on different host, and that a backup copy is promoted to become the new leader when the previous leader fails.

In order to decide when the current leader master process has failed and to elect a new leader, we have used a coordination service like Apache ZooKeeper.

The Mesos master stores information about the active tasks and registered frameworks in memory: it does not persist it to disk or attempt to ensure that this information is preserved after a master failover. This helps the Mesos master scale to large clusters with many tasks and frameworks. A downside of this design is that after a failure, more work is required to recover the lost in-memory master state.

Mesos consists of a master daemon that manages agent daemons running on each cluster node, and Mesos frameworks that run tasks on these agents.

The Mesos master stores information about the active tasks and registered frameworks in memory: it does not persist it to disk or attempt to ensure that this information is preserved after a master failover. This helps the Mesos master scale to large clusters with many tasks and frameworks. A downside of this design is that after a failure, more work is required to recover the lost in-memory master state.

System model. The system is composed by a set of distributed processes: the clients that request the execution of jobs composed by map and reduce tasks, the JobTracker that manages the execution of a job as explained, a set of Task-Trackers that execute tasks, the NameNode that manages access to data stored in HDFS, and a set of DataNodes where HDFS stores file blocks. We say that a process is correct if it follows the algorithm, otherwise we say it is faulty. We also use these two words to denominate a task (map or re-duce) that, respectively, returns the result that corresponds to an execution in a correct TaskTracker (correct) or not (faulty). Processes run in servers in a datacenter.

## The algorithm

In order to achieve A simplistic solution to make MapReduce Byzantine fault-tolerant given the system model would be the following. First, the JobTracker starts 2f + 1 replicas of each map task in different servers and TaskTrackers. Second, the JobTracker starts also 2f + 1 replicas of each reduce task. Each reduce task fetches the output from all map replicas, picks the most voted results, processes them and stores its output in HDFS. In the end, either the client or a special task must make the vote of the outputs to pick the most voted. An even more simplistic solution would be to run a consensus, or Byzantine agreement between each set of map task replicas and reduce task replicas. This would involve even more replicas (typically 3f + 1) and more messages exchanged.

#### Crash failure detection

Workers nodes crash faults are detected using ZooKeeper's coordination service. As known, ZooKeeper allows users to

store persistently coordination data into several hierarchically grouped nodes, called *znode*. However, ZooKeeper has the notion of *ephemeral nodes* too; these special znodes exists as long as the session that created the znode is active, that is when the session ends the znode is deleted. A ZooKeeper client establishes a session with the ZooKeeper service

At session expiration the cluster will delete any/all ephemeral nodes owned by that session and immediately notify any/all connected clients of the change

In this way, is very easy to keep check the status of worker nodes by current primary process. If any of worker node crash, ZooKeeper automatically delete znode associated to crashed server and notifies current leader.

#### **Deferred execution**

As known, arbitrary faults are very hard to detect and manage

Deferred execution. Crash faults are detected by the previously existing Hadoop mechanisms, and arbitrary faults are uncommon, so there is no point in always executing 2f+1 replicas to usually obtain the same result.

By default, current leader primary process starts only f+1 replicas of the same task, then wait results checking if they all return the same result. If a timeout elapses, or some returned results do not match, more replicas (up to f) are started, until there are f+1 matching replies.

In the best case, without Byzantine faults, only f+1 replicas are started. If arbitrary faults are uncommon, we have a < f+1 replica started reducing the overhead

# **Digest outputs**

f+1 matching outputs of a given task (maps or reduces) have to be received to be considered correct. However, tasks output can have considerable size be large therefore to move data from workers to leader is useless. can increse uselessly network traffic, worsening performance.

Digest outputs. f+1 matching outputs of maps or reduces have to be received to be considered correct. These outputs tend to be large, so it is useful to fetch one output from some task replica and compare just digests (hashes). This way, it is still possible to validate the output without generating much additional network traffic.

# **Template Styles**

The primary parameter given to the "acmart" document class is the *template style* which corresponds to the kind of publication or SIG publishing the work. This parameter is enclosed in square brackets and is a part of the documentclass command:

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- acmconf: The default proceedings template style.
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The "acmart" document class includes the "booktabs" package — https://ctan.org/pkg/booktabs — for preparing high-quality tables.

Table captions are placed *above* the table.

Because tables cannot be split across pages, the best placement for them is typically the top of the page nearest their initial cite. To ensure this proper "floating" placement of tables, use the environment **table** to enclose the table's contents and the table caption. The contents of the table itself must go in the **tabular** environment, to be aligned properly in rows and columns, with the desired horizontal and vertical rules. Again, detailed instructions on **tabular** material are found in the ETEX User's Guide.

**Table 1: Frequency of Special Characters** 

Non-English or Math	Frequency	Comments
Ø	1 in 1,000	For Swedish names
$\pi$	1 in 5	Common in math
\$	4 in 5	Used in business
$\Psi_1^2$	1 in 40,000	Unexplained usage

Immediately following this sentence is the point at which Table 1 is included in the input file; compare the placement of the table here with the table in the printed output of this document.

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You may want to display math equations in three distinct styles: inline, numbered or non-numbered display. Each of the three are discussed in the next sections.

# Inline (In-text) Equations

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# **Display Equations**

A numbered display equation—one set off by vertical space from the text and centered horizontally—is produced by the **equation** environment. An unnumbered display equation is produced by the **displaymath** environment.

Again, in either environment, you can use any of the symbols and structures available in LTEX; this section will just give a couple of examples of display equations in context. First, consider the equation, shown as an inline equation above:

$$\lim_{n \to \infty} x = 0 \tag{1}$$

Notice how it is formatted somewhat differently in the **displaymath** environment. Now, we'll enter an unnumbered Andrea Graziani (0273395)

Table 2: Some	<b>Typical</b>	Commands
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Command	A Number	Comments
\author	100	Author
\table	300	For tables
\table*	400	For wider tables

equation:

$$\sum_{i=0}^{\infty} x + 1$$

and follow it with another numbered equation:

$$\sum_{i=0}^{\infty} x_i = \int_0^{\pi+2} f$$
 (2)

just to demonstrate LATEX's able handling of numbering.

#### 13 FIGURES

The "figure" environment should be used for figures. One or more images can be placed within a figure. If your figure contains third-party material, you must clearly identify it as such, as shown in the example below.



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Figure captions are placed below the figure.

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\begin{teaserfigure}
\includegraphics[width=\textwidth]{sampleteaser}
\caption{figure caption}
\Description{figure description}
\end{teaserfigure}

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#### 15 ACKNOWLEDGMENTS

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```
\begin{acks}
...
\end{acks}
```

so that the information contained therein can be more easily collected during the article metadata extraction phase, and to ensure consistency in the spelling of the section heading.

Authors should not prepare this section as a numbered or unnumbered \section; please use the "acks" environment.

#### 16 APPENDICES

If your work needs an appendix, add it before the "\end{document}" command at the conclusion of your source document.

Start the appendix with the "appendix" command:

\appendix

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#### 17 SIGCHI EXTENDED ABSTRACTS

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- sidebar: Place formatted text in the margin.
- marginfigure: Place a figure in the margin.
- margintable: Place a table in the margin.

#### **ACKNOWLEDGMENTS**

To Robert, for the bagels and explaining CMYK and color spaces.

#### A RESEARCH METHODS

#### Part One

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#### **Part Two**

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