

V, W spazi vettoriali

B_V base di V , B_W base di W

$f: V \rightarrow W$

$B_V' // , B_W' //$

SONO ALTRE BASI DELLO STESSO VETTORE

$$[M(f)]_{B_W}^{B_V} \neq [M(f)]_{B_W'}^{B_V'}$$

$$B_V = \{v_1, \dots, v_n\} \quad B_W = \{w_1, \dots, w_m\}$$

$$B_V' = \{b_1, \dots, b_n\} \quad B_W' = \{c_1, \dots, c_m\}$$

$$v \in V \Rightarrow v = \lambda_1 \cdot v_1 + \dots + \lambda_n \cdot v_n \quad [v]_{B_V} = (\lambda_1, \dots, \lambda_n)$$

$$b_j = b_{1j} \cdot v_1 + b_{2j} \cdot v_2 + \dots + b_{nj} \cdot v_n$$

$$B = (b_{ij})_{1 \leq i, j \leq n} \in M_{n,n}(\mathbb{R}) \Rightarrow v = \mu_1(b_{11}v_1 + \dots + b_{n1}v_n) + \dots + \mu_n(b_{1n}v_1 + \dots + b_{nn}v_n) =$$

$$\left([b_1]_{B_V} \dots [b_n]_{B_V} \right) = B$$

$$v \in V \Rightarrow \exists \mu_1, \dots, \mu_n \text{ tale che } v = \mu_1 b_1 + \dots + \mu_n b_n \Leftrightarrow [v]_{B_V'} =$$

$$\Rightarrow (\mu_1 b_{11} + \mu_2 b_{12} + \dots + \mu_m b_{1m}) v_1 + \dots + (\mu_1 b_{m1} + \dots + \mu_m b_{mm}) v_m$$

$$\Rightarrow [v]_{B_v} = \begin{pmatrix} \mu_1 b_{11} + \dots + \mu_m b_{1m} \\ \vdots \\ \mu_1 b_{m1} + \dots + \mu_m b_{mm} \end{pmatrix} = B \begin{pmatrix} \mu_1 \\ \vdots \\ \mu_m \end{pmatrix} = B[v]_{B_v'}$$

$$[w]_{B_w} = C[w]_{B_w'}$$

$$v \in V \Rightarrow f(v) \in W \Rightarrow c[f(v)]_{B_w'} = [M(f)]_{B_w}^{B_v} \cdot [v]_{B_v}$$

$$[f(v)]_{B_w} = [M(f)]_{B_w}^{B_v} \cdot [v]_{B_v} \Rightarrow [f(v)]_{B_w'} = \boxed{c^{-1} [M(f)]_{B_w}^{B_v}} \cdot [v]_{B_v'}$$

$$\parallel$$

$$c[f(v)]_{B_w'} \parallel B \cdot [v]_{B_v'} \parallel [M(f)]_{B_w'}^{B_v'}$$

• definizione

$M_1, M_2 \in M_{m,n}(\mathbb{R})$ si dicono equivalenti se:

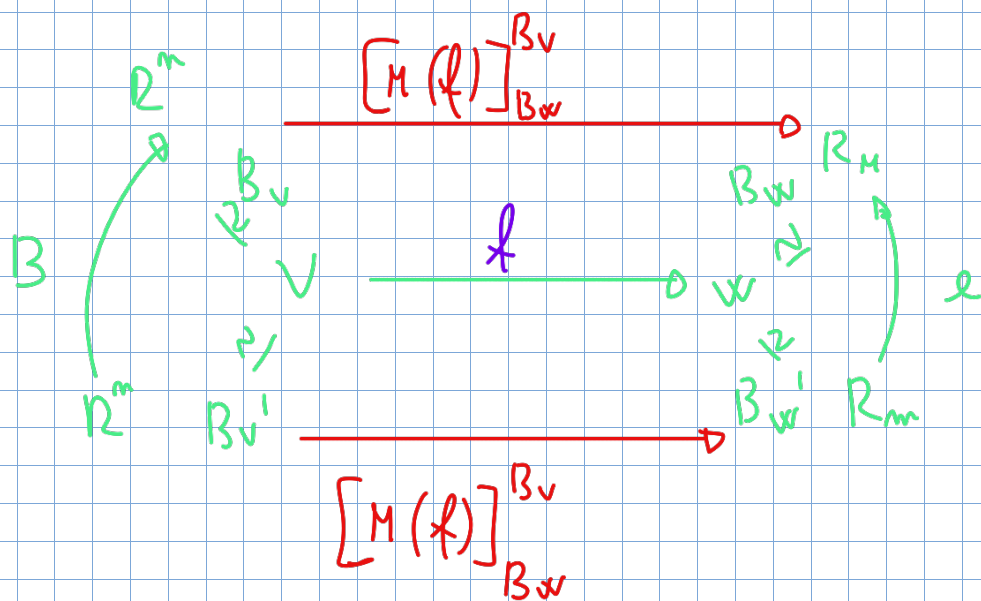
$$\exists C \in M_{m,n}(\mathbb{R}) \exists B \in M_{m,n}(\mathbb{R}) \text{ invertibili tale che } M_1 = C^{-1} M_2 \cdot B$$

Proposizione

$f: V \longrightarrow W$ omomorfismo

M_1 e M_2 rappresentano f rispetto a basi diverse

M_1 e M_2 sono simili



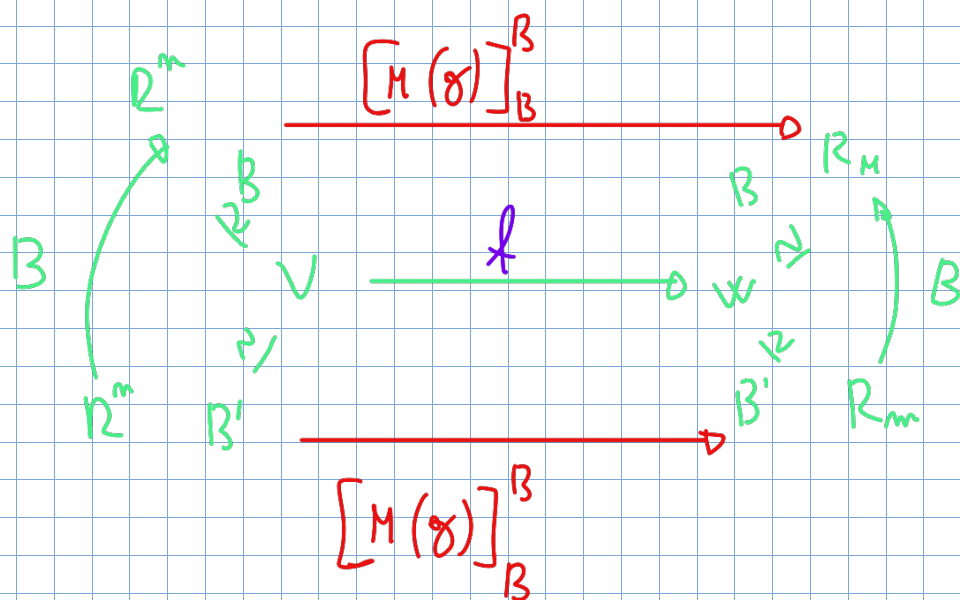
Come funziona con gli endomorfismi?

$g: V \longrightarrow V$ B, B' basi di V $B =$ matrice di cambiamento di base

BASE MATRICE

sono 2 cose diverse

$[M(g)]^{B'}_B$, $[M(g)]^{B'}_B$, ecc....



quindi $[M(\gamma)]_{B'}^B = B^{-1} [M(\gamma)]_B^B \cdot B$

$$[M(\gamma)]_B^B = [M(\gamma)]_B^B \cdot B$$

$$[M(\gamma)]_{B'}^B = B^{-1} [M(\gamma)]_B^B$$

Due matrici $M_1, M_2 \in M_{n,n}(\mathbb{R})$ sono simili se $\exists B \in M_{n,n}(\mathbb{R})$ invertibile tale che $M_1 = B^{-1} \cdot M_2 \cdot B$

Esercizi:

1)

$$f: \mathbb{R}^3 \longrightarrow \mathbb{R}^2$$
$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} \longmapsto \begin{pmatrix} x+2y+z \\ y+z \end{pmatrix}$$

1) f è lineare? Si perché è data da polinomi omogenei di primo grado

2) Scrivere $M(f)$ rispetto a \mathbb{R}^3 e \mathbb{R}^2

$$\mathcal{E}_3 = \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\} \quad \mathcal{E}_2 = \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$$

$$f\left(\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \quad f\left(\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} 2 \\ 1 \end{pmatrix}, \quad f\left(\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}\right) = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$M(f) = \begin{pmatrix} 1 & 2 & 1 \\ 0 & 1 & 1 \end{pmatrix}$$

3) $\text{Ker } f \neq 0$?

$$\text{Ker}(f) = \text{Ker}(M(f))$$

$$\begin{pmatrix} 1 & 2 & 1 \\ 0 & 1 & 1 \end{pmatrix} \xrightarrow{\text{GAUSS}} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \end{pmatrix}$$

$$\text{Ker} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \end{pmatrix} \rightarrow \begin{cases} x - z = 0 \\ y + z = 0 \end{cases} \rightarrow \begin{cases} x = z \\ y = -z \end{cases} \Rightarrow \begin{pmatrix} z \\ -z \\ z \end{pmatrix}$$

$$\ker < \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} > \rightarrow \text{é diferente de } 0$$

$$\dim(\ker(f)) = 1 = \text{null}(f) \Rightarrow 2 = \text{rk}(A) = \text{rk}(f) = \dim(\text{Im}(f))$$

2)

$$w = f\left(\begin{pmatrix} 2 \\ 1 \\ 3 \end{pmatrix}\right) = \begin{pmatrix} 7 \\ 4 \end{pmatrix}$$

$$f^{-1}(w) = \left\{ v \in V \mid f(v) = \begin{pmatrix} 7 \\ 4 \end{pmatrix} \right\} = \begin{pmatrix} 2 \\ 1 \\ 3 \end{pmatrix} + \ker f = \begin{pmatrix} 2 \\ 1 \\ 3 \end{pmatrix} + \left\langle \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} \right\rangle$$

$$v = \begin{pmatrix} x \\ y \\ z \end{pmatrix} \quad f(v) = \begin{pmatrix} x + 2y + z \\ y + z \end{pmatrix} = \begin{pmatrix} 7 \\ 4 \end{pmatrix}$$

$$\begin{cases} x + 2y + z = 7 \\ y + z = 4 \end{cases}$$

Esercizio 8 $T: \mathbb{R}^4 \rightarrow \mathbb{R}^3$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} \mapsto \begin{pmatrix} 2x_1 + x_3 \\ 2x_1 + x_2 + x_3 \\ x_2 + 2x_3 \end{pmatrix}$$

trovare $[M(f)]_{\xi_4}^{\xi_3}$

$$x_1 \begin{pmatrix} 2 \\ 2 \\ 0 \end{pmatrix} + x_2 \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} + x_3 \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix} + x_4 \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\ker f = \ker(M(f))$$

$$\begin{pmatrix} 2 & 0 & 1 & 0 \\ 2 & 1 & 1 & 0 \\ 0 & 1 & 2 & 0 \end{pmatrix} \xrightarrow{\text{GAUSS...}} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix} \xrightarrow{\text{PERCHÉ}} \begin{pmatrix} 0 \\ 0 \\ 0 \\ x_4 \end{pmatrix} \rightarrow x_4 \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

$$\ker f = \left\langle \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} \right\rangle \quad \dim(\ker(f)) = 1 = \text{null}(f)$$

$$I_m(f) = \left\langle \begin{pmatrix} 2 \\ 2 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix}, \cancel{\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}} \right\rangle$$

mettiamo la matrice e troviamo $\text{Rk} = 3$ quindi è lin. ind. ciò vuol dire che è una base di f

trova $[M(t)]_c^B$

$$T: \mathbb{R}^1 \longrightarrow \mathbb{R}^3$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} \longmapsto \begin{pmatrix} 2x_1 + x_3 \\ 2x_1 + x_2 + x_3 \\ x_2 + 2x_3 \end{pmatrix}$$

relazione alla quale facciamo riferimento

$$B = \left\{ \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}_B$$

$$C = \left\{ \begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}_C$$

$$B = \begin{pmatrix} 1 & 1 & 1 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$C = \begin{pmatrix} -1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Puoi risolvere usando queste formule

$$C^{-1} \cdot M(t)_\varepsilon^{\xi} \cdot B$$

$$T(b_1) = \begin{pmatrix} 2 \\ 3 \\ 1 \end{pmatrix} \quad T(b_2) = \begin{pmatrix} 3 \\ 3 \\ 2 \end{pmatrix} \quad T(b_3) = \begin{pmatrix} 3 \\ 1 \\ 3 \end{pmatrix} \quad T(b_4) = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$[T(b_1)]_C = \begin{pmatrix} 1 \\ 3 \\ 1 \end{pmatrix}, [T(b_2)]_C = \begin{pmatrix} 0 \\ 3 \\ 2 \end{pmatrix}, [T(b_3)]_C = \begin{pmatrix} 1 \\ 1 \\ 3 \end{pmatrix}.$$

$$[t(t_1)]_c = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$[h(t)]_c^B = \begin{pmatrix} 1 & 0 & 1 & 0 \\ 3 & 3 & 4 & 0 \\ 1 & 2 & 3 & 0 \end{pmatrix}$$