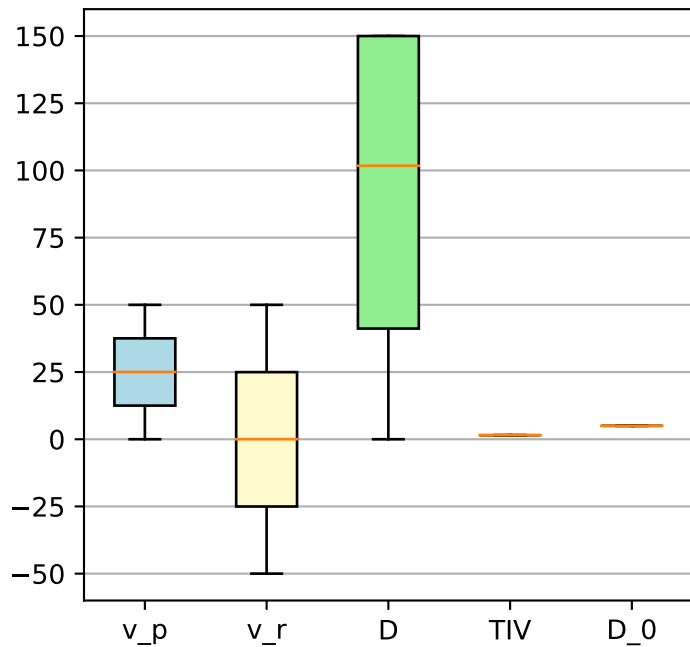


Cruise control data - input



Cruise control data - output

