$$x_{2} = x_{1} + \Delta x_{fr} \frac{p_{1} - p_{0}}{p_{1}},$$

$$p_{y2} = p_{y1} + y_{1} \frac{\Delta y_{fr} - \Delta y_{fra} y_{1}^{2}}{p_{1}^{2}},$$

$$z_{2} = z_{1} + \frac{\Delta x_{fr} p_{x1} + (\Delta y_{fr} - \Delta y_{fra} y_{1}^{2}/2) y_{1}^{2}/(2p_{1})}{p_{1}},$$
where $\Delta x_{fr} \equiv \frac{F1^{2}}{24\rho_{b}},$

$$\Delta y_{fr} \equiv \frac{F1}{6\rho_{b}^{2}},$$

$$\Delta y_{fra} \equiv \frac{2}{3} \frac{1}{F1\rho_{b}^{2}},$$

$$\rho_{b} \equiv \frac{L'}{ANGLE + K0},$$

$$L' \equiv L - \frac{(ANGLE F1)^{2}}{24L}$$

$$\times \frac{\sin((ANGLE(1 - E1 - E2) - AE1 - AE2)/2)}{\sin(ANGLE/2)}.$$
(95)