

$$\begin{aligned}
x_2 &= x_1 - \Delta x_{fr} \frac{p_1 - p_0}{p_1} \, , \\
p_{y2} &= p_{y1} + y_1 \frac{\Delta y_{fr} - \Delta y_{fra} y_1^2}{p_1^2} \, , \\
z_2 &= z_1 + \frac{-\Delta x_{fr} p_{x1} + (\Delta y_{fr} - \Delta y_{fra} y_1^2/2) y_1^2/(2p_1)}{p_1} - \Delta z_{fr} \, , \\
\text{where } \Delta z_{fr} &\equiv \Delta x_{fr} (\sin(\text{ANGLE E1} + \text{AE1}) + \sin(\text{ANGLE E2} + \text{AE2})) \, .
\end{aligned}$$