

UART Interfacing on eYFi-Mega Board

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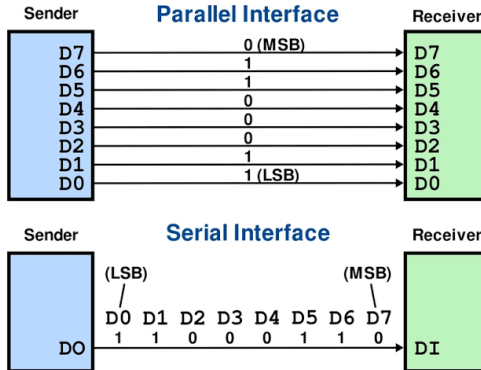
IIT Bombay
July 6, 2022



Parallel v/s Serial Interface



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Motivation for Serial Interface



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How do we send data serially?

Transmitter and Receiver must agree on the order in which the bits will be sent.



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How can this be ensured?

- Synchronous communication *OR*
- Asynchronous communication



Synchronous v/s Asynchronous



Synchronous v/s Asynchronous

Parameters	Synchronous	Asynchronous
Clock signal	Required	Not required
Overhead bits	Not required	Required
Data transmission speed	Fast	Slow
Data Tx/Rx	Blocks or frames	Bytes or character
Examples	I ² C, SPI	UART



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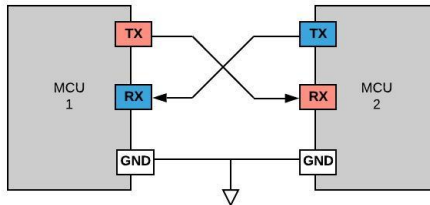
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 - ① Receive - RX
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① Data Packet

- Synchronization Bits
- Data Bits
- Parity Bits

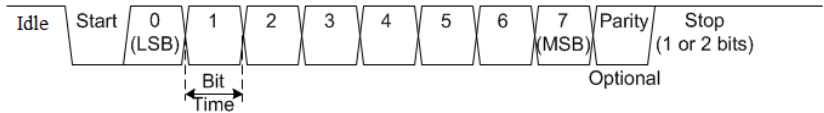
② Baud Rate



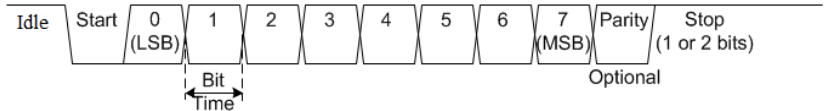
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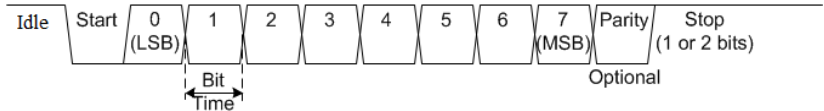


① Synchronization Bits

- Start (1 bit) - transition on idle data line from 1 to 0.
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Data Packet



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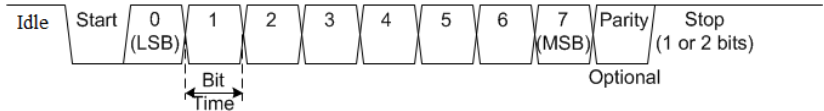
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③ Parity Bits

- Low-level and simple form of error checking.
- It can be odd or even.



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- These baud rates are achieved in micro-controller by dividing the clock frequency.



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Determine the number of packets transferred per second.



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 - ➊ **9600** \Rightarrow Baud Rate
 - ➋ **8** \Rightarrow Number of data bits in a frame
 - ➌ **N** \Rightarrow No Parity bits
 - ➍ **1** \Rightarrow 1 Stop bit
 - ➎ "**H**" \Rightarrow ASCII value = **0b01001000**
 - ➏ "**i**" \Rightarrow ASCII value = **0b01101001**
 - ➐ **Endianness** \Rightarrow Little-endian, by default



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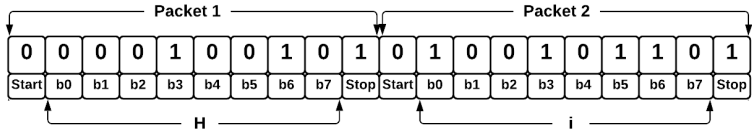
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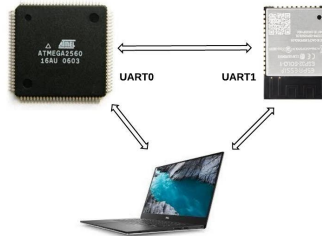
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Connection Diagram



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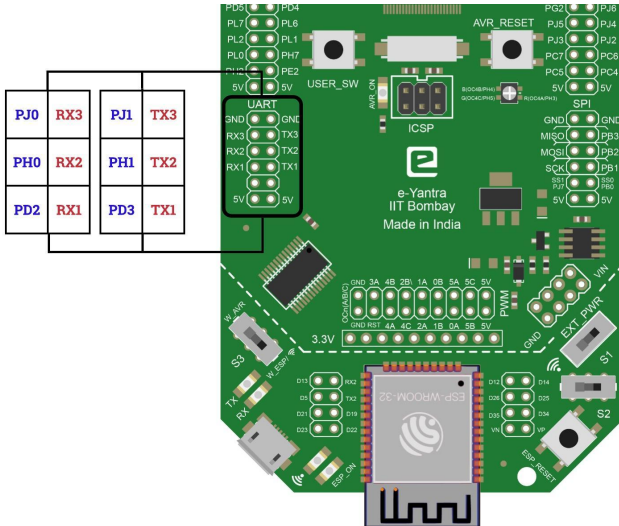
- Connection between ATmega2560 and PC
 - 1 TX0 → USB
 - 2 RX0 → USB
- Connection between ATmega2560 and ESP32
 - 1 ATmega2560:TX0 → ESP32:RX1
 - 2 ATmega2560:RX0 → ESP32:TX1



UART Header on eYFi-Mega Board



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Problem Statement



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- Write a program to read character from UART and do the following according to the character received:

Character	Action
'F'	Decrement freq by 100 ms
'S'	Increment freq by 100 ms



Thank You!

Post your queries on: helpdesk@e-yantra.org

